

# Forecasting and Simulation

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Machine Learning Group  
Leuphana University of Lüneburg

## **Course General Information**

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## Lecturers

- Ulf Brefeld (Lecture)
- Yannick Rudolph (Exercise)
- [brefeld@leuphana.de](mailto:brefeld@leuphana.de)
- [yannick.rudolph@leuphana.de](mailto:yannick.rudolph@leuphana.de)

# Grading and Tutorial

- Written exam (see myStudy)
- Tutorials
  - Regular exercise sheets ( $\sim$  weekly)
  - Practical questions
  - Discussions
- Each tutorial
  - You mark all tasks you worked on (solved or tried to solve)
  - We discuss solutions together
- You need 50% of the marks to pass the tutorial

# Recap Overview

- Calculus
- Linear Algebra
- Probability Theory
- Supervised Machine Learning

# Calculus Recap

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## Sum and Product

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  - $\sum_{i=1}^n a_i$
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  - $\sum_{a \in A} a$ , for  $A = \{a_1, a_2, \dots, a_n\}$
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- For  $I = \emptyset$  or  $A = \emptyset$ : the sum is equal to zero
- Product:  $a_1 \cdot a_2 \cdot \dots \cdot a_n$ 
  - $\prod_{i=1}^n a_i = a_1 \cdot a_2 \cdot a_3 \cdot \dots \cdot a_n$
- For  $I = \emptyset$  or  $A = \emptyset$ , the product is equal to one

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- $\binom{n}{k}$  = number of combinations with  $k$  elements from a set with  $n$  elements

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$$\begin{aligned}f'(x) &= (a \cdot x^2 + b \cdot x + c)' \\&= (a \cdot x^2)' + (b \cdot x)' + c' \\&= a \cdot (x^2)' + b \cdot x' + c' \\&= 2ax + b\end{aligned}$$

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- Linearity

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- Primitive (antiderivative) function:  $F' = f$

$$\int_a^b f(x)dx = [F(x)]_a^b = F(b) - F(a)$$

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$$\begin{aligned}\int_u^v f(x) dx &= \int_u^v (a \cdot x^2 + b \cdot x + c) dx \\&= \int_u^v a \cdot x^2 dx + \int_u^v b \cdot x dx + \int_u^v c dx \\&= a \cdot \int_u^v x^2 dx + b \cdot \int_u^v x dx + c \cdot \int_u^v 1 dx \\&= a \cdot \left[ \frac{1}{3} x^3 \right]_u^v + b \cdot \left[ \frac{1}{2} x^2 \right]_u^v + c \cdot [x]_u^v \\&= \frac{a}{3} (v^3 - u^3) + \frac{b}{2} (v^2 - u^2) + c (v - u)\end{aligned}$$

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- $\exp(x)' = \exp(x)$

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- $\log'(x) = \frac{1}{x}$
- Natural logarithm:  $\ln(x) = \log_a(x)$  when  $a = e$

# Linear Algebra Recap

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$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_d \end{pmatrix} \in \mathbb{R}^d$$

- Multiplication by a scalar  $c \in \mathbb{R}$

$$c\mathbf{x} = \begin{pmatrix} cx_1 \\ cx_2 \\ \vdots \\ cx_d \end{pmatrix}$$

- Addition of two vectors  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d$

$$\mathbf{x} + \mathbf{y} = \begin{pmatrix} x_1 + y_1 \\ x_2 + y_2 \\ \vdots \\ x_d + y_d \end{pmatrix}$$

- Transpose

$$\mathbf{x}^T = (x_1 \ x_2 \ \dots \ x_d)$$

- Inner product of two vectors  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d$

$$\mathbf{x}^\top \mathbf{y} = \langle \mathbf{x}, \mathbf{y} \rangle = x_1 y_1 + x_2 y_2 + \dots + x_d y_d = \sum_{i=1}^d x_i y_i \in \mathbb{R}$$

- Outer product of two vectors  $\mathbf{x} \in \mathbb{R}^{d_1}, \mathbf{y} \in \mathbb{R}^{d_2}$

$$\mathbf{xy}^\top = \begin{pmatrix} x_1 y_1 & \dots & x_1 y_{d_2} \\ \vdots & \ddots & \vdots \\ x_{d_1} y_1 & \dots & x_{d_1} y_{d_2} \end{pmatrix} \in \mathbb{R}^{d_1 \times d_2}$$

- Length of a vector  $\mathbf{x} \in \mathbb{R}^d$

$$\|\mathbf{x}\|_2 = \sqrt{\mathbf{x}^\top \mathbf{x}} = \sqrt{x_1^2 + \dots + x_d^2} \in \mathbb{R}$$

- Angle between vectors  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d$

$$\cos(\theta) = \frac{\mathbf{x}^\top \mathbf{y}}{\|\mathbf{x}\|_2 \cdot \|\mathbf{y}\|_2}$$

A matrix can be seen as a collection of vectors

$$\mathbf{A} = \begin{pmatrix} a_{11} & \dots & a_{1m} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nm} \end{pmatrix} = \begin{pmatrix} | & & | \\ \mathbf{a}_1 & \dots & \mathbf{a}_m \\ | & & | \end{pmatrix} \in \mathbb{R}^{n \times m}$$

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- Addition of two matrices  $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times m}$

$$\mathbf{A} + \mathbf{B} = \begin{pmatrix} a_{11} + b_{11} & \dots & a_{1m} + b_{1m} \\ \vdots & \ddots & \vdots \\ a_{n1} + b_{n1} & \dots & a_{nm} + b_{nm} \end{pmatrix}$$

- Multiplication of a vector  $\mathbf{x} \in \mathbb{R}^m$  by a matrix  $\mathbf{A} \in \mathbb{R}^{n \times m}$

$$\mathbf{Ax} = \mathbf{b} \in \mathbb{R}^n$$

$$b_i = \sum_{j=1}^m a_{ij}x_j$$

- Multiplication of two matrices  $\mathbf{A} \in \mathbb{R}^{n_1 \times m}$  and  $\mathbf{B} \in \mathbb{R}^{m \times n_2}$

$$\mathbf{AB} = \mathbf{C} \in \mathbb{R}^{n_1 \times n_2}$$

$$c_{ij} = \sum_{k=1}^m a_{ik}b_{kj}$$

- Inverse of a matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$

$$\mathbf{A}\mathbf{A}^{-1} = \mathbf{A}^{-1}\mathbf{A} = \mathbf{I}$$

Whenever you can avoid calculating the inverse of a matrix AVOID IT!  
E.g. solving the linear equation system  $\mathbf{A}\mathbf{x} = \mathbf{b}$  for  $\mathbf{x}$  is much better than working with the inverse:  $\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$

- Norm: function  $\| \cdot \| : \mathbb{R}^d \rightarrow \mathbb{R}_0^+$
- Properties ( $x, y \in \mathbb{R}^d$  and  $\lambda \in \mathbb{R}$ )
  - $\|x\| = 0 \implies x = 0$
  - $\|\lambda x\| = |\lambda| \cdot \|x\|$
  - $\|x + y\| \leq \|x\| + \|y\|$
- $p$ -Norm ( $p \geq 1$ )

$$\|x\|_p = \left( \sum_{i=1}^d |x_i|^p \right)^{\frac{1}{p}}$$

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- 1-Norm:  $\|x\|_1 = \sum_{i=1}^d |x_i|$ .
- Euclidean norm (2-norm):  $\|x\|_2 = \sqrt{\sum_{i=1}^d x_i^2}$ .
- Maximum norm ( $p \rightarrow \infty$ ):  $\|x\|_\infty = \max_i |x_i|$ .

# Probability Theory Recap

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- Additionally
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  - Expressing information
- Generic tool to express uncertainty, information, and coupling

## (Discrete) Random Variables

- Intuitively: probability of *random variable*  $X$  taking on value  $x$
- *Example*
  - A dice roll ( $X$ ) can result in  $\{1, \dots, 6\}$
  - What is the probability of  $X = x$  for  $x \in \{1, \dots, 6\}$

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- A bit more formally
  - Domain of  $X$ :  $\text{dom}(X)$  (or *sample space*  $\Omega$ )
    - Set of possible values of a random variable
    - Mutually exclusive: only one will happen
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    - Set of possible values of a random variable
    - Mutually exclusive: only one will happen
    - Collectively exhaustive: at least one will happen
  - Space of events  $\mathcal{F} = \{E : E \subset \Omega\}$  and  $A, B, \emptyset, \Omega \in \mathcal{F}$ 
    - For event  $E \in \mathcal{F}$ ,  $P(E) = \sum_{x \in E} P(X = x)$
    - $P(A) \in [0, 1]$
    - $P(\Omega) = 1$  (sure event)
    - $P(\emptyset) = 0$  (impossible event)
    - If  $A \cap B = \emptyset$  then  $P(A \cup B) = P(A) + P(B)$

# (Discrete) Random Variables

- Notation
  - Random variable  $X$  (capital letter)
  - Value  $x \in \text{dom}(X)$  is taken by  $X$  (lower case letter)
  - $P(X = x) \in \mathbb{R}$ :  $x \in \text{dom}(X) \rightarrow$  probability in  $[0, 1]$
  - For event  $E \subset \Omega$ 
    - $P(E)$ : probability of  $X$  taking a value  $x \in E$
    - $P(E) = \sum_{x \in E} P(X = x)$

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*Example* Two binary RV: Cavity ( $X$ ) and Toothache ( $Y$ )

$P(X, Y)$	$Y = T$	$Y = F$
$X = T$	0.04	0.06
$X = F$	0.01	0.89



# Joint Probability Distributions

- Two random variables:  $X, Y$
- Joint probability distribution:  $P(X = x, Y = y)$ 
  - Probability that  $X = x$  and  $Y = y$
- In logic:  $X = x \wedge Y = y$ 
  - Not so in joint probability distributions

*Example* Two binary RV: Cavity ( $X$ ) and Toothache ( $Y$ )

$P(X, Y)$	$Y = T$	$Y = F$
$X = T$	0.04	0.06
$X = F$	0.01	0.89

We write:  $P(X = F, Y = T) = 0.01$

## Joint Probability Distributions – Definitions

Marginal probability of  $X$  given  $P(X, Y)$

$$P(X) = \sum_Y P(X, Y)$$

$P(X, Y)$	$Y = T$	$Y = F$	$P(X)$
$X = T$	0.15	0.20	0.35
$X = F$	0.05	0.60	0.65
$P(Y)$	0.20	0.80	

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Extends for more than two variables (vector of variables)

$$X = (X_1, \dots, X_n)$$

$$P(X_1, \dots, X_{n-1}, X_n)$$

$$P(X_n|X_1, \dots, X_{n-1})$$

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- Correlations, interdependence, and coupling
  - Expressed in terms of joint probability distributions

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- Thomas Bayes (1702–1761)
- Trivial implication of marginal and conditional probability
- Important: interpretation and use

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$$P(\text{cause}|\text{effect}) = \frac{P(\text{effect}|\text{cause})}{P(\text{effect})} P(\text{cause})$$



## Bayesian Inference – Example (by @xamat)

- Bad COVID antibody test kit
  - 95% sensitivity and specificity
  - 5% chance of being wrong (both sides)
    - $1 - \text{sensitivity|specificity}$
- Population with COVID antibodies: 5%

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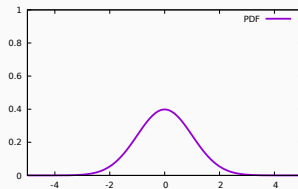
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- Probability density function (PDF)  
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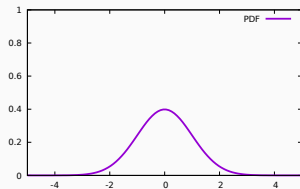
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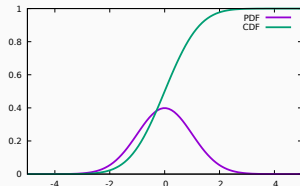
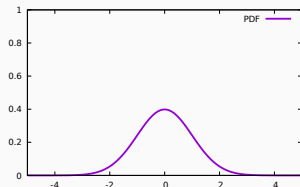
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- Cumulative distribution function  
(CDF)  $F(x) = P(X \leq x)$

$$F(x) = \int_{-\infty}^x f(t)dt$$



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- Inference problem: compute  $P(Y|E)$
- Issue: size of table  $P(Y_{1:k}, E_{1:m}, H_{1:n})$  is  $d^{k+m+n}$ 
  - $d$ : number of possible values for each variable
  - If all binary variables:  $2^{k+m+n}$
  - Remember those  $H_{1:n}$ ?

# Cheat Sheet (1)

- Random variable  $X$ 
  - Values  $x \in \text{dom}(x) \rightarrow$  probabilities  $P(X = x) \in [0, 1]$
- Probability distribution of  $X$ 
  - Table (array) of probabilities for each value  $x \in \text{dom}(X)$
  - Normalization:  $\sum_X P(X) = 1$
- Joint distribution  $P(X, Y)$ 
  - Table (matrix) of probabilities for each value  $x, y \in \text{dom}(X) \times \text{dom}(Y)$
- Marginal  $P(X) = \sum_Y P(X, Y)$ 
  - Summing along columns/rows ( $Y$ )
- Conditional  $P(X|Y) = \frac{P(X,Y)}{P(Y)}$ 
  - Normalizing each column/row ( $Y$ )

## Cheat Sheet (2)

- Properties

$$P(X, Y) = P(X|Y) P(Y) = P(Y|X) P(X)$$

$$P(X_1, \dots, X_n) = \prod_{i=1}^n P(X_i | X_1, \dots, X_{i-1})$$

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- Inference: to compute

$$P(Y_{1:k} | E_{1:m}) = \frac{P(Y_{1:k}, E_{1:m})}{P(E_{1:m})} \propto \sum_{H_{1:n}} P(Y_{1:k}, E_{1:m}, H_{1:n})$$

# Supervised Machine Learning Recap

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  - Find  $f : X \rightarrow Y$
  - Deterministic mapping:  $y = f(x)$
  - Set of inputs:  $X$
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  - Set of inputs:  $X$
  - Set of target variables:  $Y$  (outputs)
- Relation between  $X$  and  $Y$ 
  - Joint probability distribution:  $P(X, Y)$
  - Generally unknown



## Supervised Machine Learning (cont.)

- If  $P(X, Y)$  was known

$$P(Y|X) = \frac{P(X, Y)}{P(X)}$$

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$$f(x) = \operatorname{argmax}_{y \in Y} P(y|x)$$

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- $P(X, Y)$ : usually not necessary
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- Learn a model for  $P(Y|X)$  directly
- Or even
  - Learn deterministic  $f : X \rightarrow Y$  instead of  $P(Y|X)$
  - Find  $f(x)$  that minimizes generalization error
    - Error for new and unseen  $x \in X$

# Generalization Error

Generalization error of  $f(x)$  (theoretical risk) is the expected loss

$$R[f] = \int_{X \times Y} \ell(x, y, f) dP(X, Y)$$

where  $\ell : X \times Y \times F \rightarrow \mathbb{R}_0^+$  is a *loss function*

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- BUT: joint probability  $P(X, Y)$  is still unknown
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- Solution
  - Approximate  $R[f]$  using an  $N$ -sample (training set)

$$\mathcal{D} = \{(x_n, y_n)\}_{n=1 \dots N} \in X \times Y$$

drawn *independently and identically distributed* (iid) from  $P(X, Y)$



# Empirical Risk Minimization

Minimize the empirical risk on  $\mathcal{D} = \{(x_n, y_n)\}_{n=1 \dots N}$

$$\hat{R}_{\mathcal{D}}[f] = \frac{1}{N} \sum_{n=1}^N \ell(x_n, y_n, f)$$

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- *Example* regression tasks on the squared loss

$$\ell(x, y, f) = (f(x) - y)^2$$

$$\hat{R}_{\mathcal{D}}[f] = \frac{1}{N} \sum_{n=1}^N (f(x_n) - y_n)^2$$