APS 1080 - Exercise 1

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1. Anatomy

Read the code and observe how the concepts of the course thus far relate to it. Comment on these correspondences.

- The code defines a Tic-Tac-Toe game that can be played by two players. It defines a "State" class that represents the state of a game. In this case, the states are represented by possible configurations of the board, which are 3^9 = 19,683 possibilities.
- The code contains many boards in the all_states variable, which uses combinatons of 0,1, and -1. 1 is to represent '*', which is the human player, and -1 to represent 'x', which is the computer's symbol.
- The Judger class initializes two players, player1 and player2 and assigns the signs to each other. P1's symbol is 1 ('*') and P2's symbol is -1 ('x').

What does an RL agent solve?

The RL agent would learn to play the game optimally by repeatedly playing the game and receiving rewards or penalties based on its performance. The agent would learn to make decisions that maximize its chances of winning the gamge by adjusting its strategy based on the rewards and penalties it receives.

The agent is solving a decision-making problem where it needs to choose an action to take in each state (or position) of the game so as to maximize its rewards. The goal of the agent is to win the game, or draw if it can't win, by choosing moves that result in the best outcomes based on the current state of the game. The agent interacts with the environment, in this case the tic-tac-toe game, by taking actions, observing the results of the actions and receiving rewards, and updating its policy based on the observed outcomes. The policy is a mapping from states to actions that the agent takes, and the objective is to learn a good policy through trial-and-error and reinforcement from rewards.

What should a RL agent have inside of it? Do you observe these in the program?

The RL agent should have the following components:

1. **State Representation:** The agent needs to have a way of representing the current state of the game board. This could be done using a 2D array, where each element

represents the state of a particular cell on the board. This code has a State object, which contains a 3x3 numpy array that is stored in the data attribute. The variable all_states contains all the possible board configurations. As stated above, the all_states variables contains ~6k possible combinations of 1, -1, and 0 to represent the human player, the computer, and empty cells respectively.

- 2. **Action**:The actions in this game are the placement of a chessman (represented by 1 or -1) in a given position on the board.
- 3. **Reward**: The reward in this game is the end result, either a win, a loss, or a draw. A win is represented by a 1, a loss by -1, and a draw by 0.
- 4. **Policy**: The Player object contains a dictionary called estimations, which gets updated using a backup function. The code ends up saving these learned estimations as a policy in a .bin file. Note that estimations are not available for the HumanPlayer object and only for the AI player with the Player class.
- 5. **Model**: the model in this code is implicit in the state and the transition from one state to the next through the actions.

2. Instrumentation and Play

Modify the code so it trains against you interactively. Instrument the code to print the value function as it learns, and also when it takes an exploit vs explore action.

The self.estimations attribute in the Player object contains a dictionary with the policy values. They get initialized to 0.5 values but get updated as the AI trains itself.

For example, in one realization, this was a value before in the estimations dictionary for state 9841: 9841.0: 0.4999386591027. However, the value of this state changed in the estimations dictionary after updating: 9841.0: 0.5000613408972999.

The following code leverages exploration exploitation by using an \$\epsilon\$ greedy approach, the act() function selects the next positions at random. However, the *risk tolerance* or willing to choose a next position at random will only take place if a random number is below \$\epsilon\$. In this case, if \$\epsilon\$ is set to 0.01, that means that less that a random position will be selected less than 1% of the time.

Let the agent train against you for N games. Comment on how the agent's competence increases as N increases.

- As the number of epochs increases, the win rate for both players decreases. This could be because it is possible to force Tic-Tac-Toe to a draw in the worst case scenario.
- If you decrease the number of times it trains against itself, it becomes significantly dumber. I changed it to only train itself 10 times and winning against it was trivial.

```
#
       # Copyright (C)
       # 2016 - 2018 Shangtong Zhang(zhangshangtong.cpp@gmail.com)
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                                                                     #
       # 2016 Jan Hakenberg(jan.hakenberg@gmail.com)
       # 2016 Tian Jun(tianjun.cpp@gmail.com)
                                                                     #
       # 2016 Kenta Shimada(hyperkentakun@gmail.com)
                                                                     #
       # Permission given to modify the code as long as you keep this
       # declaration at the top
       import numpy as np
       import pickle
       BOARD ROWS = 3
       BOARD COLS = 3
       BOARD SIZE = BOARD ROWS * BOARD COLS
       class State:
          def init (self):
              # the board is represented by an n * n array,
              # 1 represents a chessman of the player who moves first,
              # -1 represents a chessman of another player
              # 0 represents an empty position
              self.data = np.zeros((BOARD ROWS, BOARD COLS))
              self.winner = None
              self.hash val = None
              self.end = None
           # compute the hash value for one state, it's unique
           def hash(self):
              if self.hash_val is None:
                  self.hash val = 0
                  for i in np.nditer(self.data):
                     self.hash val = self.hash val * 3 + i + 1
              return self.hash val
           # check whether a player has won the game, or it's a tie
           def is end(self):
              if self.end is not None:
                  return self.end
              results = []
              # check row
              for i in range(BOARD ROWS):
```

```
results.append(np.sum(self.data[i, :]))
    # check columns
    for i in range(BOARD_COLS):
        results.append(np.sum(self.data[:, i]))
    # check diagonals
    trace = 0
    reverse_trace = 0
    for i in range(BOARD_ROWS):
        trace += self.data[i, i]
        reverse_trace += self.data[i, BOARD_ROWS - 1 - i]
    results.append(trace)
    results.append(reverse_trace)
    for result in results:
        if result == 3:
            self.winner = 1
            self.end = True
            return self.end
        if result == -3:
            self.winner = -1
            self.end = True
            return self.end
    # whether it's a tie
    sum_values = np.sum(np.abs(self.data))
    if sum_values == BOARD_SIZE:
        self.winner = 0
        self.end = True
       return self.end
    # game is still going on
    self.end = False
   return self.end
# @symbol: 1 or -1
# put chessman symbol in position (i, j)
def next state(self, i, j, symbol):
   new state = State()
   new_state.data = np.copy(self.data)
   new_state.data[i, j] = symbol
   return new state
# print the board
def print_state(self):
    for i in range(BOARD ROWS):
       print('----')
       out = '| '
        for j in range(BOARD COLS):
            if self.data[i, j] == 1:
               token = '*'
            elif self.data[i, j] == -1:
               token = 'x'
            else:
               token = '0'
            out += token + ' | '
        print(out)
    print('----')
```

```
def get all states impl(current state, current symbol, all states):
         for i in range(BOARD ROWS):
                  for j in range(BOARD_COLS):
                            if current_state.data[i][j] == 0:
                                     new state = current_state.next_state(i, j, current_symbol)
                                     new_hash = new_state.hash()
                                     if new hash not in all states:
                                               is_end = new_state.is_end()
                                               all_states[new_hash] = (new_state, is_end)
                                               if not is_end:
                                                        get_all_states_impl(new_state, -current_symbol, all_states_impl(new_state, -current_symbol, all_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(new_states_impl(ne
def get_all_states():
         current symbol = 1
         current_state = State()
         all states = dict()
         all_states[current_state.hash()] = (current_state, current_state.is_end())
         get_all_states_impl(current_state, current_symbol, all_states)
         return all states
# all possible board configurations
all_states = get_all_states()
class Judger:
         # Oplayer1: the player who will move first, its chessman will be 1
         # @player2: another player with a chessman -1
         def init (self, player1, player2):
                  self.p1 = player1
                  self.p2 = player2
                  self.current player = None
                  self.pl.symbol = 1
                  self.p2 symbol = -1
                  self.pl.set symbol(self.pl symbol)
                  self.p2.set symbol(self.p2 symbol)
                  self.current state = State()
         def reset(self):
                  self.pl.reset()
                  self.p2.reset()
         def alternate(self):
                  while True:
                            yield self.p1
                            yield self.p2
         # Oprint state: if True, print each board during the game
         def play(self, print_state=False):
                  alternator = self.alternate()
                  self.reset()
                  current state = State()
                  self.pl.set state(current state)
                  self.p2.set_state(current_state)
                  if print state:
                            current state.print state()
                  while True:
                            player = next(alternator)
                            i, j, symbol = player.act()
```

```
next state hash = current state.next state(i, j, symbol).hash()
            current_state, is_end = all_states[next_state_hash]
            self.pl.set_state(current_state)
            self.p2.set_state(current_state)
            if print_state:
                current_state.print_state()
            if is end:
                return current_state.winner
# AI player
class Player:
    # @step_size: the step size to update estimations
    # @epsilon: the probability to explore
    def init (self, step size=0.1, epsilon=0.1):
        self.estimations = dict()
        self.step size = step size
        self.epsilon = epsilon
        self.states = []
        self.greedy = []
        self.symbol = 0
    def reset(self):
        self.states = []
        self.greedy = []
    def set_state(self, state):
        self.states.append(state)
        self.greedy.append(True)
    def set symbol(self, symbol):
        self.symbol = symbol
        for hash val in all states:
            state, is end = all states[hash val]
            if is end:
                if state.winner == self.symbol:
                    self.estimations[hash_val] = 1.0
                elif state.winner == 0:
                    # we need to distinguish between a tie and a lose
                    self.estimations[hash val] = 0.5
                    self.estimations[hash val] = 0
                self.estimations[hash val] = 0.5
    # update value estimation
    def backup(self):
        states = [state.hash() for state in self.states]
        print("Printing Estimations from Value Function BEFORE Updating...")
        print(self.estimations)
        print("Printing Greedy from backup function BEFORE Updating...")
        print(self.greedy)
        for i in reversed(range(len(states) - 1)):
            state = states[i]
            td error = self.greedy[i] * (
                self.estimations[states[i + 1]] - self.estimations[state]
```

```
self.estimations[state] += self.step size * td error
        print("Printing Estimations from Value Function AFTER Updating...")
        print(self.estimations)
        print("Printing Greedy from backup function BEFORE Updating...")
        print(self.greedy)
    # choose an action based on the state
    def act(self):
        state = self.states[-1]
        next_states = []
        next positions = []
        for i in range(BOARD_ROWS):
            for j in range(BOARD_COLS):
                if state.data[i, j] == 0:
                    next_positions.append([i, j])
                    next_states.append(state.next_state(
                        i, j, self.symbol).hash())
        if np.random.rand() < self.epsilon:</pre>
            action = next_positions[np.random.randint(len(next_positions))]
            action.append(self.symbol)
            self.greedy[-1] = False
            return action
        values = []
        for hash_val, pos in zip(next_states, next_positions):
            values.append((self.estimations[hash_val], pos))
        # to select one of the actions of equal value at random due to Python's
        np.random.shuffle(values)
        values.sort(key=lambda x: x[0], reverse=True)
        action = values[0][1]
        action.append(self.symbol)
        return action
    def save policy(self):
       with open('policy_%s.bin' % ('first' if self.symbol == 1 else 'second')
            pickle.dump(self.estimations, f)
    def load policy(self):
        with open('policy %s.bin' % ('first' if self.symbol == 1 else 'second')
            self.estimations = pickle.load(f)
            print("self.estimations from load policy() function")
            print(self.estimations)
# human interface
# input a number to put a chessman
# | q | w | e |
# | a | s | d |
# | z | x | c |
class HumanPlayer:
    def init (self, **kwargs):
        self.symbol = None
        self.keys = ['q', 'w', 'e', 'a', 's', 'd', 'z', 'x', 'c']
        self.state = None
    def reset(self):
        pass
```

```
def set state(self, state):
        self.state = state
    def set symbol(self, symbol):
        self.symbol = symbol
    def act(self):
        self.state.print_state()
        key = input("Input your position:")
        data = self.keys.index(key)
        i = data // BOARD COLS
        j = data % BOARD COLS
        return i, j, self.symbol
def train(epochs, print_every_n=500):
    player1 = Player(epsilon=0.01)
    player2 = Player(epsilon=0.01)
    judger = Judger(player1, player2)
    player1 win = 0.0
    player2_win = 0.0
    for i in range(1, epochs + 1):
        winner = judger.play(print_state=False)
        if winner == 1:
            player1 win += 1
        if winner == -1:
            player2_win += 1
        if i % print_every_n == 0:
            print('Epoch %d, player 1 winrate: %.02f, player 2 winrate: %.02f'
        player1.backup()
        player2.backup()
        judger.reset()
    player1.save policy()
    player2.save policy()
def compete(turns):
    player1 = Player(epsilon=0)
    player2 = Player(epsilon=0)
    judger = Judger(player1, player2)
    player1.load policy()
    player2.load policy()
    player1 win = 0.0
    player2 win = 0.0
    for _ in range(turns):
        winner = judger.play()
        if winner == 1:
            player1 win += 1
        if winner == -1:
            player2_win += 1
        judger.reset()
    print('%d turns, player 1 win %.02f, player 2 win %.02f' % (turns, player1
# The game is a zero sum game. If both players are playing with an optimal stra
# So we test whether the AI can guarantee at least a tie if it goes second.
def play():
   while True:
        player1 = HumanPlayer()
        player2 = Player(epsilon=0)
```

```
judger = Judger(player1, player2)
    player2.load_policy()
    winner = judger.play()
    if winner == player2.symbol:
        print("You lose!")
    elif winner == player1.symbol:
        print("You win!")
    else:
        print("It is a tie!")

# train(int(1e5))
# train(10)
# compete(int(1e3))
# play()
In [2]: # compete(int(3))
```

```
self.estimations from load policy() function
{9841.0: 0.4999514633194276, 16402.0: 0.5, 14215.0: 0.5, 14944.0: 0.5, 14701.
0: 0.5, 14782.0: 0.5, 14755.0: 0.5, 14764.0: 0, 14758.0: 0.5, 14749.0: 0.5, 14
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7637.0: 0.5, 7661.0: 0.5, 9121.0: 0.5, 9124.0: 0.5, 8881.0: 0.5, 8882.0: 0, 90
43.0: 0.5, 9044.0: 0, 9097.0: 0.5, 9098.0: 0, 9123.0: 0.5, 9122.0: 0.5, 8879.
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0.5, 9581.0: 0.5, 9605.0: 0.5, 9769.0: 0.5, 9772.0: 0.5, 9745.0: 0.5, 9746.0:
0, 9771.0: 0.5, 9770.0: 0.5, 9743.0: 0.5, 9767.0: 0.5, 9823.0: 0.5, 9826.0: 0.
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5, 3041.0: 0.5, 3203.0: 0.5, 3257.0: 0.5, 3275.0: 0.5, 7657.0: 0.5, 7658.0: 0.
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5, 9116.0: 0.5, 8873.0: 0.5, 9035.0: 0.5, 9089.0: 0.5, 9107.0: 0.5, 9601.0: 0.
5, 9602.0: 0.5, 9521.0: 0.5, 9575.0: 0.5, 9593.0: 0.5, 9763.0: 0.5, 9764.0: 0.
5, 9737.0: 0.5, 9755.0: 0.5, 9817.0: 0.5, 9818.0: 0.5, 9809.0: 0.5, 9835.0: 0.
5, 9836.0: 0.5, 9843.0: 0.5, 9842.0: 0.5, 3281.0: 0.5, 7655.0: 0.5, 9113.0: 0.
5, 9599.0: 0.5, 9761.0: 0.5, 9815.0: 0.5, 9833.0: 0.5, 9839.0: 0.5}
```

| 0 | 0 | 0 |

| 0 | 0 | 0 |

0 0 0 0

```
KeyboardInterrupt
                                                   Traceback (most recent call last)
        /var/folders/tp/tgqd8prn2x1g474v7zwrxq7r0000gn/T/ipykernel 79414/3863113020.py
        in <module>
        ---> 1 play()
        /var/folders/tp/tgqd8prn2x1g474v7zwrxq7r0000gn/T/ipykernel 79414/1677033148.py
        in play()
            345
                        judger = Judger(player1, player2)
            346
                        player2.load_policy()
        --> 347
                        winner = judger.play()
            348
                        if winner == player2.symbol:
                            print("You lose!")
            349
        /var/folders/tp/tgqd8prn2x1g474v7zwrxq7r0000gn/T/ipykernel_79414/1677033148.py
        in play(self, print state)
            162
                       while True:
            163
                           player = next(alternator)
        --> 164
                            i, j, symbol = player.act()
            165
                            next_state_hash = current_state.next_state(i, j, symbol).h
        ash()
            166
                            current_state, is_end = all_states[next_state_hash]
        /var/folders/tp/tgqd8prn2x1g474v7zwrxq7r0000gn/T/ipykernel_79414/1677033148.py
        in act(self)
            291
                   def act(self):
            292
                        self.state.print state()
        --> 293
                        key = input("Input your position:")
            294
                        data = self.keys.index(key)
            295
                        i = data // BOARD COLS
        ~/opt/anaconda3/envs/pytorchenv/lib/python3.7/site-packages/ipykernel/kernelba
        se.py in raw_input(self, prompt)
           1179
                            self. parent ident["shell"],
           1180
                            self.get parent("shell"),
        -> 1181
                            password=False,
           1182
                        )
           1183
        ~/opt/anaconda3/envs/pytorchenv/lib/python3.7/site-packages/ipykernel/kernelba
        se.py in input request(self, prompt, ident, parent, password)
           1217
                            except KeyboardInterrupt:
           1218
                                # re-raise KeyboardInterrupt, to truncate traceback
                                raise KeyboardInterrupt("Interrupted by user") from No
        -> 1219
           1220
                            except Exception:
           1221
                                self.log.warning("Invalid Message:", exc info=True)
        KeyboardInterrupt: Interrupted by user
In [ ]: break
In []:
        # play()
In [ ]: len(all_states.keys())
In [ ]: all states.keys()
```

```
In [ ]: all_states[9841.0][0].data
In [ ]: all_states[16402.0][0].data
In [ ]: all_states[9575][0].data
In [ ]:
```