

Lab 7: Process Synch. And Mutex(II)

1.Objective

- Understanding the deadlock and use some methods to avoid it

2.Syllabus

- Understand the concepts and principle of process deadlock
- Implement the process communication using C or C++

3.Prerequisite

- C or C++ language
- Computer which run Linux system (e.g. Ubuntu)
- Understand the concept of process deadlock

4.Concepts and Principles of Deadlock

Please refer to the chapter 6 of the text book. The main contents have been lectured in the sixth week, 11/14/2016. The slide of this chapter can be found in the course website: <http://www.thinkmesh.net/ose/>.

5.Experimental Contents

5.1 Producer-Consumer Problem (Semaphore)

Description: Implement a simple deadlock example. The file name is “**deadlock.c**”.

Note: please modify the program to avoid deadlock. If it can run, show me your result. If not, tell me why.

```
#include <stdio.h>
#include <pthread.h>
#include <unistd.h>
#include <stdlib.h>
#include <string.h>

void *clean(char *name);

pthread_mutex_t brush, bucket;

int main(int argc, char *argv[])
{
    const int n = 2;
    pthread_t cleaners[n];
    char *names[] = {"Ivanon", "Petrov"};
    int i;
    pthread_mutex_init(&brush, NULL);
    pthread_mutex_init(&bucket, NULL);
    for(i = 0; i < n; i++) pthread_create(&cleaners[i], NULL, clean, (void *)names[i]);
    for(i = 0; i < n; i++) pthread_join(cleaners[i], NULL);
    pthread_mutex_destroy(&brush);
```

```

        pthread_mutex_destroy(&bucket);
        return 0;
    }

    void *clean(char *name)
    {
        printf("%s starts work...\n", name);
        usleep(rand() % 1000000);
        if(name[0] == 'T')
        {
            usleep(rand() % 1000000);
            pthread_mutex_lock(&bucket);
            printf("%s takes bucket...\n", name);
            usleep(rand() % 1000000);
            pthread_mutex_lock(&brush);
            printf("%s takes brush...\n", name);
        }
        else
        {
            usleep(rand() % 1000000);
            pthread_mutex_lock(&brush);
            printf("%s takes brush...\n", name);
            usleep(rand() % 1000000);
            pthread_mutex_lock(&bucket);
            printf("%s takes bucket...\n", name);
        }
        printf("%s have finished cleaning!\n", name);
        usleep(rand() % 1000000);
        pthread_mutex_unlock(&brush);
        printf("%s puts brush...\n", name);
        usleep(rand() % 1000000);
        pthread_mutex_unlock(&bucket);
        printf("%s puts bucket...\n", name);
        printf("%s have finished work!\n", name);
        pthread_exit(NULL);
    }
}

```

Descriptions:

1. **pthread_mutex_init** : initialises the mutex referenced by mutex with attributes specified by attr.
 2. **pthread_mutex_destroy** : destroy the mutex object referenced by mutex.
 3. **pthread_mutex_lock** : locks the mutex object referenced by mutex
 4. **pthread_mutex_unlock** : release the mutex object referenced by mutex
-

How to Run: gcc -o deadlock deadlock.c -lpthread
./deadlock

5.2 Deadlock Detection

Description: Implement the deadlock detection. The file name is “**detection.c**”. **Note:** please modify the program inputing arguments, and consider detected processing and output results. If it can run, show me your result. If not, tell me why.

```
//detection.c
#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>
#include <stdbool.h>
#include <string.h>
#include <fcntl.h>
#include <sys/stat.h>
#include <sys/types.h>
#include <unistd.h>

pthread_t sender;
pthread_t receiver;
char line[100];
char *owners[20];
char *requesters[20];
char *probes[3];
char *token;
char *procNum;
char *resource;
char *resourceOwner;
int i,status,ownersCounter,requesterCounter,fd;
bool isBlocked = false;
bool isDeadlocked = false;
void *senderThread();
void *receiverThread();
void findOwner();

int main(int argc, char *argv[])
{
    // Check arguments -> Display usage if incorrect arguments
    if (argc != 3){
        printf("Arguments: <file> <process #>\n");
        exit(1);
    }
    else{
        // Get process number argument
        procNum = argv[2];
        // Open configuration file
        FILE *file = fopen(argv[1],"r");
        if (file == 0){
            printf("Error opening file.\n");
        }else{
            // Opened file successfully.
            // Store configuration file
            while (fgets(line,100,file) != NULL){
                printf("Parsing Line: %s\n",line);
            }
        }
    }
}
```

```

// If the line read contains owns, store it in owners array
if (strstr(line,"owns") != NULL){

    token = strtok(line, " ");
    while (token != NULL){
        // Don't need to store 'owns'
        if (!strcmp(token,"owns")){
            token = strtok(NULL, " ");
            continue;
        }
        // Allocate space and copy token into array
        owners[ownersCounter] = malloc(strlen(token) + 1);
        strcpy(owners[ownersCounter], token);
        token = strtok(NULL, " ");
        ownersCounter++;
    }
}
else{
    // We have a request line, see if it is my own proces, block if
    it is

    if (strstr(line,procNum)){

        token = strtok(line, " ");
        while (token != NULL){
            // Don't need to store 'requests'
            if (!strcmp(token,"requests")){
                token = strtok(NULL, " ");
                continue;
            }
            // Allocate space and copy token into array
            requesters[requesterCounter] = malloc(strlen(token)
+ 1);

            strcpy(requesters[requesterCounter], token);
            token = strtok(NULL, " ");
            requesterCounter++;
        }
        isBlocked = true;
    }
}

}
printf("**** Done reading configuration ****\n");
fclose(file);

// If process is blocked, find the owner of resource i'm blocked on and
form probe

if (isBlocked){
    findOwner();
}

}
}

```

```

    // Create sender thread
    if ((status = pthread_create(&sender, NULL, senderThread, NULL)) != 0){
        fprintf(stderr, "Error creating thread - Status: %d: %s\n", status,
strerror(status));
        exit (1);
    }

    // Create receiver thread
    if ((status = pthread_create(&receiver, NULL, receiverThread, NULL)) != 0){
        fprintf(stderr, "Error creating thread - Status: %d: %s\n", status,
strerror(status));
        exit (1);
    }

    // Main thread - loop while not deadlocked
    while (!isDeadlocked) {
        // do nothing while not deadlocked
    }

    printf("**** System is deadlocked ****\n");
    return 1;
}

/*
 * Sending thread, sends probes every 10 seconds.
 */
void *senderThread(){
    while (isBlocked){
        // Sends a Probe to the process owning the resource it is blocked on
        fd = open(resourceOwner, O_WRONLY);
        printf("%s is Writing %s:%s:%s\n", procNum, probes[0], probes[1],
probes[2]);
        write(fd, probes[0], sizeof(char) * 2);
        write(fd, probes[1], sizeof(char) * 2);
        write(fd, probes[2], sizeof(char) * 2);
        close(fd);
        printf("%s wrote to the pipe.\n", procNum);
        sleep(10);
    }
    return NULL;
}

/*
 * Receiving thread, constantly looking for a probe
 * that wants to contact the process.
 */
void *receiverThread(){
    while (1){
        // Listen for probe - Look for any pipe with a name equivalent to process
number

```

```

// this means there is a process that wishes to contact me
fd = open(procNum, O_RDONLY);
if (fd < 0){
    // There is no pipe with my name. Noone wants to contact me
}else{
    if (isBlocked){
        read(fd,probes[0],sizeof(char) * 2);
        read(fd,probes[1],sizeof(char) * 2);
        read(fd,probes[2],sizeof(char) * 2);
        printf("%s has
read %s:%s:%s\n",procNum,probes[0],probes[1],probes[2]);
        // Check probe blocked and receiving process. If same =
deadlocked

        if (!strcmp(probes[0],probes[2])){
            printf("%s detected deadlock because %s
= %s\n",procNum,probes[0],probes[2]);
            close (fd);
            unlink (procNum);
            isDeadlocked = true;
        }
        strcpy(probes[1],procNum);
        strcpy(probes[2],resourceOwner);
    }else{
        printf("%s is not blocked and received a probe.
discarding.\n",procNum);
    }
    }
    sleep(5);
}
return NULL;
}

/*****
* Called when the process is blocking. Find the owner
* of the resource the process is blocked on, and forms
* the probe.
*****/

void findOwner(){
    printf("***** %s is blocking *****\n",procNum);
    // Search through requesters. Find the resource i'm blocked on
    while (1){
        if (!strcmp(requesters[i],procNum)){
            resource = requesters[i+1];
            break;
        }
        i++;
    }
    i = 0;
    // Search through owners. Find the owner of the resource i'm blocked on
    while (1){

```

```

        if (!strcmp(owners[i],resource)){
            resourceOwner = owners[i-1];
            break;
        }
        i++;
    }
    // Create pipe/file
    mkfifo(resourceOwner,0666);
    printf("%s created the pipe %s\n",procNum,resourceOwner);
    // Form probe for blocked process
    probes[0] = malloc(strlen(procNum) + 1);
    strcpy(probes[0], procNum);
    probes[1] = malloc(strlen(procNum) + 1);
    strcpy(probes[1], procNum);
    probes[2] = malloc(strlen(resourceOwner) + 1);
    strcpy(probes[2], resourceOwner);
    i = 0;
}

```

//state1.data

P1 owns r2
 P1 requests r1
 P2 owns r1
 P2 owns r3
 P2 requests r4
 P3 owns r4

//state2.data

P1 owns r2
 P1 requests r1
 P2 owns r1
 P2 owns r3
 P2 requests r4
 P3 owns r4
 P3 requests r2

Function interpret:

1. **pthread_create**: create a new thread.

How to Run: gcc -o detection detection.c -lpthread
 ./detection state1.data 3

5.3 Banker Algorithm

Description: The Banker's algorithm is a resource allocation and deadlock avoidance algorithm developed by Edsger Dijkstra.

Implement the program. The file name is “**banker.c**”. **Note:** please consider and modify resources. If it can run, show me your result. If not, tell me why.

```
#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>

#define resourceTypeQuan 3
#define processQuan 5

int i = 0; //Switch on C99 mode or we cannot initialize variable in for loop
int j = 0;
pthread_mutex_t mutex; //mutex lock for access to global variable

int initResourceVector [resourceTypeQuan];
//available, max, allocation, need
int availResourceVector [resourceTypeQuan];
int allocMatrix [processQuan][resourceTypeQuan] =
{{1,1,0},{1,3,0},{0,0,2},{0,1,1},{0,2,0}};
int maxMatrix [processQuan][resourceTypeQuan] =
{{5,5,5},{3,3,6},{3,5,3},{7,1,4},{7,2,2}};
int needMatrix [processQuan][resourceTypeQuan];

int requestResource(int processID,int requestVector[]);
int releaseResource(int processID,int releaseVector[]);
int ifGreaterThanNeed(int processID,int requestVector[]);
int ifEnoughToRelease(int processID,int releaseVector[]);
int ifInSafeMode();
int ifEnoughToAlloc();
void printNeedMatrix();
void printAllocMatrix();
void printAvailable();
void printReqOrRelVector(int vec[]);
void *customer(void* customerID);

int main(int argc, char const *argv[])
{
    if(argc != resourceTypeQuan + 1)
    {
        printf("Quantity of parameter is not correct.\n");
        return -1;
    }
    for(i = 0; i < resourceTypeQuan; i++)
    {
```



```

    initResourceVector[i] = atoi(argv[i+1]);//argv[0] is name of program
    availResourceVector[i] = initResourceVector[i];
}

//initialize needMatrix
for (i = 0; i < processQuan; ++i)
{
    for (j = 0; j < resourceTypeQuan; ++j)
    {
        needMatrix[i][j] = maxMatrix[i][j] - allocMatrix[i][j];
    }
}

printf("Available resources vector is:\n");
printAvailable();

printf("Initial allocation matrix is:\n");
printAllocMatrix();

printf("Initial need matrix is:\n");
printNeedMatrix();

pthread_mutex_init(&mutex,NULL);//declared at head of code
pthread_attr_t attrDefault;
pthread_attr_init(&attrDefault);
pthread_t *tid = malloc(sizeof(pthread_t) * processQuan);
int *pid = malloc(sizeof(int) * processQuan);//customer's ID, for banker's
algorithm, not pthread
//initialize pid and create threads
for(i = 0; i < processQuan; i++)
{
    *(pid + i) = i;
    pthread_create((tid+i), &attrDefault, customer, (pid+i));
}
//join threads
for(i = 0; i < processQuan; i++)
{
    pthread_join(*(tid+i),NULL);
}
return 0;
}

void *customer(void* customerID)
{

```

```

int processID = *(int*)customerID;

while(1)
{
    //request random number of resources
    sleep(1);
    int requestVector[resourceTypeQuan];

    //Because i is global variable, we should lock from here
    //lock mutex for accessing global variable and printf
    pthread_mutex_lock(&mutex);
    //initialize requestVector
    for(i = 0; i < resourceTypeQuan; i++)
    {
        if(needMatrix[processID][i] != 0)
        {
            requestVector[i] = rand() % needMatrix[processID][i];
        }
        else
        {
            requestVector[i] = 0;
        }
    }

    printf("Customer %d is trying to request resources:\n",processID);
    printReqOrRelVector(requestVector);
    //requestResource() will still return -1 when it fail and return 0 when
succeed in allocate, like textbook says
    //although I put the error message output part in the requestResource
function
    requestResource(processID,requestVector);
    //unlock
    pthread_mutex_unlock(&mutex);

    //release random number of resources
    sleep(1);
    int releaseVector[resourceTypeQuan];
    //Because i is global variable, we should lock from here
    //lock mutex for accessing global variable and printf
    pthread_mutex_lock(&mutex);
    //initialize releaseVector
    for(i = 0; i < resourceTypeQuan; i++)
    {

```

```

        if(allocMatrix[processID][i] != 0)
        {
            releaseVector[i] = rand() % allocMatrix[processID][i];
        }
        else
        {
            releaseVector[i] = 0;
        }
    }
    printf("Customer %d is trying to release resources:\n",processID);
    printReqOrRelVector(releaseVector);
    //releaseResource() will still return -1 when it fail and return 0 when
succeed in allocate, like textbook says
    //although I put the error message output part in the releaseResource
function
    releaseResource(processID,releaseVector);
    //unlock
    pthread_mutex_unlock(&mutex);
}
}

int requestResource(int processID,int requestVector[])
{
    //whether request number of resources is greater than needed
    if (ifGreaterThanNeed(processID,requestVector) == -1)
    {
        printf("requested resources is bigger than needed.\n");
        return -1;
    }
    printf("Requested resources are not more than needed.\nPretend to allocate...\n");

    //whether request number of resources is greater than needed
    if(ifEnoughToAlloc(requestVector) == -1)
    {
        printf("There is not enough resources for this process.\n");
        return -1;
    }

    //pretend allocated
    for (i = 0; i < resourceTypeQuan; ++i)
    {
        needMatrix[processID][i] -= requestVector[i];
        allocMatrix[processID][i] += requestVector[i];
        availResourceVector[i] -= requestVector[i];
    }
}

```

```

    }
    printf("Checking if it is still safe...\n");

    //check if still in safe status
    if (ifInSafeMode() == 0)
    {
        printf("Safe. Allocated successfully.\nNow available resources vector
is:\n");
        printAvailable();
        printf("Now allocated matrix is:\n");
        printAllocMatrix();
        printf("Now need matrix is:\n");
        printNeedMatrix();
        return 0;
    }
    else
    {
        printf("It is not safe. Rolling back.\n");
        for (i = 0; i < resourceTypeQuan; ++i)
        {
            needMatrix[processID][i] += requestVector[i];
            allocMatrix[processID][i] -= requestVector[i];
            availResourceVector[i] += requestVector[i];
        }
        printf("Rolled back successfully.\n");
        return -1;
    }
}

int releaseResource(int processID,int releaseVector[])
{
    if(ifEnoughToRelease(processID,releaseVector) == -1)
    {
        printf("The process do not own enough resources to release.\n");
        return -1;
    }

    //enough to release
    for(i = 0; i < resourceTypeQuan; i++)
    {
        allocMatrix[processID][i] -= releaseVector[i];
        needMatrix[processID][i] += releaseVector[i];
        availResourceVector[i] += releaseVector[i];
    }
}

```

```

    printf("Release successfully.\nNow available resources vector is:\n");
    printAvailable();
    printf("Now allocated matrix is:\n");
    printAllocMatrix();
    printf("Now need matrix is:\n");
    printNeedMatrix();
    return 0;
}

```

```

int ifEnoughToRelease(int processID,int releaseVector[])
{
    for (i = 0; i < resourceTypeQuan; ++i)
    {
        if (releaseVector[i] <= allocMatrix[processID][i])
        {
            continue;
        }
        else
        {
            return -1;
        }
    }
    return 0;
}

```

```

int ifGreaterThanNeed(int processID,int requestVector[])
{
    for (i = 0; i < resourceTypeQuan; ++i)
    {
        if (requestVector[i] <= needMatrix[processID][i])
        {
            continue;
        }
        else
        {
            return -1;
        }
    }
    return 0;
}

```

```

int ifEnoughToAlloc(int requestVector[])
{
    //first element of requestVector is processID
    for (i = 0; i < resourceTypeQuan; ++i)

```

```

{
    if (requestVector[i] <= availResourceVector[i])
    {
        continue;
    }
    else
    {
        return -1;
    }
}
return 0;
}

```

```

void printNeedMatrix()
{
    for (i = 0; i < processQuan; ++i)
    {
        printf("{ ");
        for (j = 0; j < resourceTypeQuan; ++j)
        {
            printf("%d, ", needMatrix[i][j]);
        }
        printf("}\n");
    }
    return;
}

```

```

void printAllocMatrix()
{
    for (i = 0; i < processQuan; ++i)
    {
        printf("{ ");
        for (j = 0; j < resourceTypeQuan; ++j)
        {
            printf("%d, ", allocMatrix[i][j]);
        }
        printf("}\n");
    }
    return;
}

```

```

void printAvailable()
{
    for (i = 0; i < resourceTypeQuan; ++i)

```

```

    {
        printf("%d, ",availResourceVector[i]);
    }
    printf("\n");
    return;
}

void printReqOrRelVector(int vec[])
{
    for (i = 0; i < resourceTypeQuan; ++i)
    {
        printf("%d, ",vec[i]);
    }
    printf("\n");
    return;
}

int ifInSafeMode()
{
    int ifFinish[processQuan] = {0};//there is no bool type in old C
    int work[resourceTypeQuan];//temporary available resources vector
    for(i = 0; i < resourceTypeQuan; i++)
    {
        work[i] = availResourceVector[i];
    }
    int k;
    for(i = 0; i < processQuan; i++)
    {
        if (ifFinish[i] == 0)
        {
            for(j = 0; j < resourceTypeQuan; j++)
            {
                if(needMatrix[i][j] <= work[j])
                {
                    if(j == resourceTypeQuan - 1)//means we checked whole
vector, so this process can execute
                    {
                        ifFinish[i] = 1;
                        for (k = 0; k < resourceTypeQuan; ++k)
                        {
                            work[k] += allocMatrix[i][k];
                            //execute and release resources
                        }
                        //if we break here, it will not check all process, so we
should reset i to let it check from beginning

```

//If we cannot find any runnable process from beginning to the end in i loop, we can determine that

//there is no any runnable process, but we cannot know if we do not reset i.

i = -1;*//at the end of this loop, i++, so -1++ = 0*

break;*//in loop j, break to loop i and check next*

runnable process

}

resources is enough

else*//not finished checking all resource, but this kind*

{

continue;

}

}

else*//resources not enough, break to loop i for next process*

{

//because there is no change happened, so we do not need to reset i in this condition.

break;

}

}

}

else

{

continue;

}

}

//there are two condition if we finish loop i

//1. there is no process can run in this condition.

//2. all processes are runned, which means it is in safe status.

for(i = 0; i < processQuan; i++)

{

if (ifFinish[i] == 0)

{

//not all processes are runned, so it is condition 1.

return -1;

}

else

{

continue;

}

}

//finished loop, so it is condition 2

return 0;

}

How to Run: gcc -o banker banker.c -lpthread
./banker 5 5 5

6. Conclusion

In this chapter, three experiments have been complete. They have shown how to avoid the processes deadlock.