Project Purpose

This project aims to build a simple computer system with a CPU and memory. In this system, a program is available in memory, and the CPU executes the program line by line and ends the program at the end.

Implementation

The program is written in C language, which includes several functions as described below:

```
91
      /* CPU Initialize */
 92 > void CPU init(int t){ ···
      /* Memory Initialize */
107 > void Mem_init(char f[12]){ ···
127
      /* READ Memory */
128
129 > int Read memory(int addr, int wpd, int rpd){...
142
      /* WRITE Memory */
144 > void writeMemory(int addr, int data, int wpd){...
155
156
      /* RUN Memory */
157 > void runMemory(int wtpd, int rdpd){...
      /* Fetch Data */
189 > int fetch(int wtpd, int rdpd){...
      /* Instruction set */
194 > void Instruction_set(int wtpd, int rdpd){ ···
      /* RUN CPU */
410 > void runCPU(int wtpd, int rdpd){...
438
439
      /* Driver */
440 > int main(int argc, char* argv[]){...
```

First, I am Initialized the CPU by setting the registers to 0. Also, Get the Timer interrupted by a cmd argument from the user.

Same for Memory, I have Initialized the Memory and get the sample.txt from cmd argument by the user.

```
/* Memory Initialize */
void Mem_init(char f[12]){
   // load a program into Mem
   int offset = 0;
   // open text file
   FILE* fp = fopen(f, "r");
   // load the file into Memory
   while (!feof(fp)){
       char buff[LineBuffer_size] = "";
       // read each line into buffer
       fgets(buff, sizeof(buff), fp);
       // data line
       // convert char to instruction
       if (buff[0] >= '0' &&buff[0] <= '9')</pre>
        Mem[offset++] = atoi(buff);
       else if (buff[0] == '.')
       offset = atoi(&buff[1]);
```

The two mentioned arguments are Implemented in the Driver function as below:

```
Mem_init(argv[2]);
.
CPU_init(t);
```

Also, I have created a function to interact with Memory, access the system addresses, and return the data from memory.

I have created single char for interacting with Memory:

```
r: read
w: write
E: end
/* READ Memory */
int Read_memory(int addr, int wpd, int rpd){
    if (Mode == User_mode && addr >= Timer_interrupt){
       printf("Memory violation: accessing system address %d in user mode\n", addr);
        // error occur, exit
       write(wpd, "E", sizeof(char));
        exit(-1);
    int tmp;
    write(wpd, "r", sizeof(char));  // signal
    write(wpd, &addr, sizeof(addr)); // address
    read(rpd, &tmp, sizeof(tmp)); // return data
    return tmp;
/* WRITE Memory */
void writeMemory(int addr, int data, int wpd){
    // Memory Protection
    if (Mode == User_mode && addr >= Timer_interrupt){
       printf("Memory violation: accessing system address %d in user Mode\n", addr);
       write(wpd, "E", sizeof(char)); // End processes
        exit(-1);
   write(wpd, "w", sizeof(char)); // signal
    write(wpd, &addr, sizeof(addr)); // address
    write(wpd, &data, sizeof(data)); // data
```

Then, I have created an Instruction set function as project description: So, the CPU can get Instructions rules from this function.

```
/* Instruction set */
void Instruction_set(int wtpd, int rdpd){
   switch (IR) {
       // Load the value into the AC
       case Load value:
          AC = fetch(wtpd, rdpd);
          break;
       // Load the value at the address into the AC
       case Load_addr:
           int addr = fetch(wtpd, rdpd);
           AC = Read_memory(addr, wtpd, rdpd);
       // Load the value from the address found in the given address into the AC
       case LoadInd_addr:
           int addr = fetch(wtpd, rdpd);
           addr = Read_memory(addr, wtpd, rdpd);
           AC = Read_memory(addr, wtpd, rdpd);
           break:
       // Load the value at (address+X) into the AC
       case LoadIdxX_addr:
           // Calculate address
           int addr = fetch(wtpd, rdpd) + X;
           AC = Read_memory(addr, wtpd, rdpd);
```

In the end, the Run CPU function can run the program by using the Instruction set function.

```
/* RUN CPU */
void runCPU(int wtpd, int rdpd){
   do {
       // if User_mode
        if (Mode == User_mode)
           Counter++;
        // fetch instruction to register
        IR = fetch(wtpd, rdpd);
        // execute it
        Instruction_set(wtpd, rdpd);
        // check timer interrupt flag
        if (Mode == User_mode && Counter == Counter_set){
           Counter = 0; // clear timer

Mode = Kernel_mode; // set Kernel_mode to access interrupt handler
           int tmp = SP;
           SP = Sys_stack;
           writeMemory(SP, tmp, wtpd);
           writeMemory(SP, PC, wtpd);
           PC = Timer_interrupt;
    } while (IR != End);
    write(wtpd, "E", sizeof(char));
```

The Driver function (main) contains creation processes and pipes. Also, run the Memory and CPU functions.

```
/*Create pipe*/
// read pipe
int rdpd[2];
// write pipe
int wtpd[2];
// if pipe failed
if (pipe(rdpd) == -1 || pipe(wtpd) == -1)
{
    printf("pipe has been failed.\n");
    exit(1);
}

// create two process: CPU, Memory
int pid = fork();
```

Personal Experience

This was the first time I designed a straightforward system by building and recognizing memory and CPU performance, and I had a lot of fun.

One thing that I was a problem with was creating a variable inside the switch statement.

So, I didn't know that we must use {} inside the case statement if we want to create a variable inside it.

So that one consumed a lot of time to debug...:]

```
// Load the value at the address into the AC
case Load_addr:

{
   int addr = fetch(wtpd, rdpd);
   AC = Read_memory(addr, wtpd, rdpd);
   break;
}
```