CPE301 – SPRING 2019

Design Assignment 5

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Primary Github address: https://github.com/armonlatifi

Directory: https://github.com/armonlatifi/sub_da/tree/master/DA5

Submit the following for all Labs:

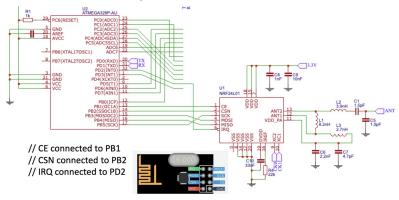
1. In the document, for each task submit the modified or included code (only) with highlights and justifications of the modifications. Also, include the comments.

- Use the previously create a Github repository with a random name (no CPE/301, Lastname, Firstname). Place all labs under the root folder ESD301/DA, sub-folder named LABXX, with one document and one video link file for each lab, place modified asm/c files named as LabXX-TYY.asm/c.
- 3. If multiple asm/c files or other libraries are used, create a folder LabXX-TYY and place these files inside the folder.
- 4. The folder should have a) Word document (see template), b) source code file(s) and other include files, c) text file with youtube video links (see template).

1. COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS

List of Components used:

- Assembler
- Simulator
- Debugger
- Breadboard
- Atmega328P
- Wires
- Xplained mini
- Micro usb
- Atmel studio 7
- LM34
- Nrf24I01



2. INITIAL/MODIFIED/DEVELOPED CODE OF TASK 1/A

receive.c

void read_adc(void);

```
#define F CPU 1600000UL //set clock speed
#define BAUD 9600 //set baud rate
#define MYUBRR F_CPU/16/BAUD-1 //calculate Baud
#include <avr/io.h>
#include <avr/interrupt.h>
#include <stdbool.h>
#include <string.h>
#include <util/delay.h>
#include "nrf24l01.h"
#include "nrf24l01-mnemonics.h"
nRF24L01 *setup_rf(void);
void process_message(char *message);
inline void prepare led pin(void);
inline void set led high(void);
inline void set_led_low(void);
volatile bool rf_interrupt = false;
```

```
void adc_init(void); //set up ADC
void USART init( unsigned int ubrr );
void USART tx string(char *data); //prints stirng usart
volatile unsigned int adc temp;
char outs[20]; //array
int main(void) {
        uint8_t address[5] = \{0x20, 0x30, 0x40, 0x51, 0x61\};
        prepare_led_pin();
                adc_init(); //initialize ADC
                 USART_init(MYUBRR);
                USART_tx_string("Connected!\r\n"); //connection successful
                 _delay_ms(125);
        sei(); //interrupts
        nRF24L01 *rf = setup_rf();
        nRF24L01_listen(rf, 0, address);
        uint8_t addr[5];
        nRF24L01_read_register(rf, CONFIG, addr, 1);
        while (true) {
                 if (rf_interrupt) {
                         rf_interrupt = false;
                         while (nRF24L01_data_received(rf)) {
                                 nRF24L01Message msg;
                                 nRF24L01 read received data(rf, &msg);
                                 process_message((char *)msg.data);
                                 USART_tx_string(msg.data);
                         nRF24L01_listen(rf, 0, address);
                }
        return 0;
nRF24L01 *setup_rf(void) {
        nRF24L01 *rf = nRF24L01_init();
        rf->ss.port = &PORTB;
        rf->ss.pin = PB2;
        rf->ce.port = &PORTB;
        rf->ce.pin = PB1;
        rf->sck.port = &PORTB;
        rf->sck.pin = PB5;
        rf->mosi.port = &PORTB;
        rf->mosi.pin = PB3;
        rf->miso.port = &PORTB;
        rf->miso.pin = PB4;
        //setup interrupts on falling edge
        EICRA |= _BV(ISC01);
        EIMSK |= _BV(INT0);
        nRF24L01_begin(rf);
        return rf;
}
void process_message(char *message) {
        if (strcmp(message, "ON") == 0)
        set_led_high();
```

```
else if (strcmp(message, "OFF") == 0)
        set_led_low();
inline void prepare_led_pin(void) {
        DDRB \mid= _BV(PB0);
        PORTB \&= \sim_BV(PB0);
inline void set_led_high(void) {
        PORTB = BV(PB0);
inline void set_led_low(void) {
        PORTB \&= \sim_BV(PB0);
}
void adc_init(void)
        ADMUX = (0 << REFS1)|
                                        (1<<REFS0)|
                                        (0<<ADLAR)|
                                        (0<<MUX2)
                                        (1 << MUX1)|
                                        (0<<MUX0);
        ADCSRA = (1<<ADEN)| //enables ADC
                                         (0<<ADSC)
                                         (0<<ADATE)|
                                         (0<<ADIF)
                                         (0<<ADIE)|
                                         (1<<ADPS2)|
                                         (0<<ADPS1)|
                                        (1<<ADPS0);
void read_adc(void) {
        unsigned char i =4;
        adc_temp = 0; //initialize
        while (i--) {
                ADCSRA |= (1<<ADSC);
                while(ADCSRA & (1<<ADSC));
                adc_temp+= ADC;
                _delay_ms(50);
        adc_temp = adc_temp / 4;
}
void USART_init( unsigned int ubrr ) {
        UBRR0H = (unsigned char)(ubrr>>8);
        UBRR0L = (unsigned char)ubrr;
        UCSR0B = (1 << TXEN0);
        UCSROC = (3 << UCSZOO);
}
void USART_tx_string( char *data ) {
        while ((*data != '\0')) {
                while (!(UCSR0A & (1 <<UDRE0)));
                UDR0 = *data;
```

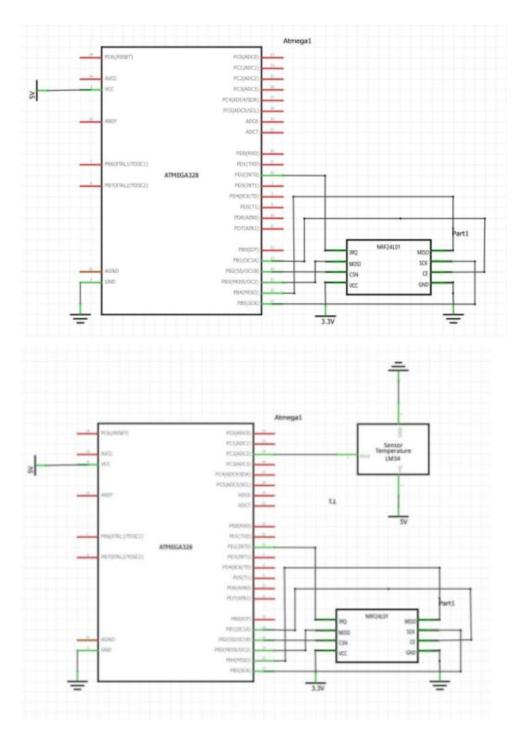
```
data++;
        }
}
ISR(INT0 vect) {
        rf interrupt = true;
}
transmit.c
#define F CPU 16000000UL //set clock speed
#define BAUD 9600 //set baud rate
#define MYUBRR F_CPU/16/BAUD-1
#include <avr/io.h>
#include <avr/interrupt.h>
#include <stdbool.h>
#include <string.h>
#include <util/delay.h>
#include "nrf24l01.h"
#include "nrf24l01-mnemonics.h"
nRF24L01 *setup_rf(void);
void process message(char *message);
inline void prepare led pin(void);
inline void set led high(void);
inline void set_led_low(void);
volatile bool rf interrupt = false;
void read adc(void);
void adc init(void);
void USART_init( unsigned int ubrr );
void USART_tx_string(char *data); //prints string
volatile unsigned int adc temp;
char outs[20];
int main(void) {
        uint8_t address[5] = \{0x20, 0x30, 0x40, 0x51, 0x61\};
        prepare_led_pin();
        adc_init();
        USART_init(MYUBRR);
        USART_tx_string("Connected\r\n"); //connection successful
        _delay_ms(125);
        sei(); //interrupts
        nRF24L01 *rf = setup_rf();
        nRF24L01 listen(rf, 0, address);
        uint8 t addr[5];
        nRF24L01 read register(rf, CONFIG, addr, 1);
        while (true) {
                if (rf_interrupt) {
                         rf interrupt = false;
                         while (nRF24L01 data received(rf)) {
                                  nRF24L01Message msg;
                                  nRF24L01_read_received_data(rf, &msg);
                                  process_message((char *)msg.data);
                                  USART_tx_string(msg.data);
                         }
```

```
nRF24L01_listen(rf, 0, address);
                }
        return 0;
nRF24L01 *setup rf(void) {
        nRF24L01 *rf = nRF24L01_init();
        rf->ss.port = &PORTB;
        rf->ss.pin = PB2;
        rf->ce.port = &PORTB;
        rf->ce.pin = PB1;
        rf->sck.port = &PORTB;
        rf->sck.pin = PB5;
        rf->mosi.port = &PORTB;
        rf->mosi.pin = PB3;
        rf->miso.port = &PORTB;
        rf->miso.pin = PB4;
        //interrupt on falling edge
        EICRA |= _BV(ISC01);
        EIMSK |= _BV(INT0);
        nRF24L01_begin(rf);
        return rf;
}
void process message(char *message) {
        if (strcmp(message, "ON") == 0)
        set_led_high();
        else if (strcmp(message, "OFF") == 0)
        set_led_low();
inline void prepare_led_pin(void) {
        DDRB \mid= _BV(PB0);
        PORTB \&= \sim_BV(PB0);
inline void set_led_high(void) {
        PORTB = BV(PB0);
inline void set_led_low(void) {
        PORTB \&= \sim_BV(PB0);
}
void adc_init(void)
        ADMUX = (0 << REFS1)|
                                         (1<<REFS0)|
                                         (0<<ADLAR)
                                         (0<<MUX2)
                                         (1 << MUX1)|
                                         (0<<MUX0);
        ADCSRA = (1<<ADEN)| //enables ADC
                                         (0<<ADSC)
                                         (0<<ADATE)
                                         (0<<ADIF)|
                                         (0<<ADIE)|
                                         (1<<ADPS2)|
```

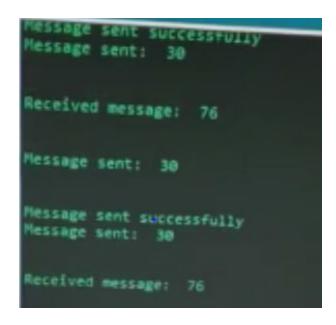
```
(0<<ADPS1)|
                                         (1<<ADPS0);
void read_adc(void) {
        unsigned char i =4;
        adc_temp = 0; //initialize
        while (i--) {
                ADCSRA |= (1<<ADSC);
                while(ADCSRA & (1<<ADSC));
                adc_temp+= ADC;
                _delay_ms(50);
        adc_temp = adc_temp / 4; //take the average of a few samples
}
void USART_init( unsigned int ubrr ) {
        UBRR0H = (unsigned char)(ubrr>>8);
        UBRR0L = (unsigned char)ubrr;
        UCSR0B = (1 << TXEN0); //enable receiver
        UCSR0C = (3 \ll UCSZ00);
}
void USART_tx_string( char *data ) {
        while ((*data != '\0')) {
                while (!(UCSR0A & (1 <<UDRE0)));
                UDR0 = *data;
                data++;
       }
}
ISR(INT0_vect) {
        rf_interrupt = true;
}
```

3. SCHEMATICS

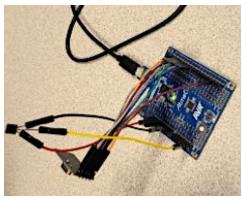
Use fritzing.org



4. SCREENSHOTS OF EACH TASK OUTPUT (ATMEL STUDIO OUTPUT)



5. SCREENSHOT OF EACH DEMO (BOARD SETUP)



6. GITHUB LINK OF THIS DA

https://github.com/armonlatifi/sub_da/tree/master/DA5

Student Academic Misconduct Policy

http://studentconduct.unlv.edu/misconduct/policy.html

"This assignment submission is my own, original work".

Armon Latifi