

Hypotheses Testing: General Subspace Idea

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We recall the example that we were dealing with previously. It involved the two classes of models described below.

$$\begin{aligned}y_{ij} &= \mu + \alpha_i + \epsilon_{ij} \\i &= 1, 2, 3, \quad j = 1, 2 \\ \epsilon_{ij} &\sim (0, \sigma^2), \quad \sigma^2 > 0 \\ \mu, \alpha_1, \alpha_2, \alpha_3 &\in \mathbb{R}\end{aligned}\tag{1}$$

and,

$$\begin{aligned}y_{ij} &= \mu + \epsilon_{ij} \\i &= 1, 2, 3, \quad j = 1, 2 \\ \epsilon_{ij} &\sim (0, \sigma^2), \quad \sigma^2 > 0 \\ \mu &\in \mathbb{R}\end{aligned}\tag{2}$$

There is something special about these classes of models in the sense that (2) is not only a subset of (1), but is in fact its subspace. To understand this, we consider their design matrices. (1) has the design matrix

$$\begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix} \quad (3)$$

whereas (2) has the design matrix

$$\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \quad (4)$$

It can be easily verified that column space of (4) is a subspace of column space of (3).

In general, we will be given two models. These are described below.

$$\begin{aligned} \vec{y} &= X\vec{\beta} + \vec{\epsilon} \\ \vec{\epsilon} &\sim N(\vec{0}, \sigma^2 I), \quad \sigma^2 > 0 \\ \vec{\beta} &\in \mathbb{R}^p \end{aligned}$$

and,

$$\begin{aligned} \vec{y} &= X_1\vec{\beta} + \vec{\epsilon} \\ \vec{\epsilon} &\sim N(\vec{0}, \sigma^2 I), \quad \sigma^2 > 0 \\ \vec{\beta} &\in \mathbb{R}^q \\ \mathcal{C}(X_1) &\subseteq \mathcal{C}(X) \end{aligned}$$

Note that we have made one more assumption here. We assume that the errors are not only mean $\vec{0}$ and variance $\sigma^2 I$, but are also jointly normal. This is a typical assumption under which we perform our tests of hypotheses because we need the distribution of the test statistic. So, we need a full distributional assumption and the normal distribution assumption is the most natural one since it makes the mathematics simple.

The first set of models, which basically gives us a family of distributions, is believed to be a good fit. What it means is that the true distribution of our data lies in this family of distributions. So, \vec{y} will lie pretty close to column space of X . Thus, we assume based on whatever goodness of fit we have done, domain knowledge, diagnostics, etc., that we have a good fit.

Now, someone gives us a restricted set of models which is same as the first one except that we now have X_1 in place of X . X_1 need not be made up only of columns chosen from that of X . It may be an entirely different design matrix. As we have mentioned earlier, $\vec{\beta}$ is just an indexing parameter. So, $\vec{\beta}$ in the first and second models is possibly different. In the first model, $\vec{\beta}$ lies in \mathbb{R}^p and in the second model, it lies in \mathbb{R}^q . That is, we assume that X is order $n \times p$ and X_1 is order $n \times q$. n remains the same as our observation vector is the same. We also assume that column space of X_1 is inside column space of X . That is what we mean when we say that the second model is a subspace of the first model.

One simple way to visualise this is: it is possible to put restrictions on $\vec{\beta}$ of the first model such that the first model is reduced to the second model. As in our last example, if we put the restriction that all the α_i 's are equal, then (1) gets reduced to (2) and that is a simple proof that the second model is indeed a subspace of the first model.