# **Using Bluetooth**

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#### 8 Comments

Trying to communicate with a remote device with no other familiar protocol? Bluetooth provides an easy answer with well-documented specs and straightforward programming APIs.

## Register with the Service Directory Protocol (SDP) Server

The SDP server is an integral part of a Bluetooth system. Services register with the local SDP; remote devices query the SDP to find out how to connect to particular services. In our example, we're going to register the HSP service.

BlueZ provides a tool for communicating with local and remote SDP servers: sdptool. To view the list of services offered by your machine, run this command: dptool browse local. We can use this command to determine whether our program has correctly registered with the SDP server. Here's output from my SDP server:

```
Browsing FF:FF:FF:00:00:00 ...
      Service Name: Headset Audio Gateway
     Service RecHandle: 0x10000
     Service Class ID List:
        "Headset Audio Gateway" (0x1112)
        "Generic Audio" (0x1203)
     Protocol Descriptor List:
"L2CAP" (0x0100)
"RFCOMM" (0x0003)
 8
 9
10
          Channel: 12
11
    Profile Descriptor List:
        "Headset" (0x1108)
Version: 0x0102
12
13
14
15
    Service Name: Hands-Free Audio Gateway
16
17
     Service RecHandle: 0x10001
     Service Class ID List:
        "Handsfree Audio Gateway" (0x111f)
19
        "Generic Audio" (0x1203)
Protocol Descriptor List:
"L2CAP" (0x0100)
"RFCOMM" (0x0003)
23
         Channel: 13
     Profile Descriptor List:
        "Handsfree" (0x111e)
          Version: 0x0105
```

Notice that the first two entries reference headset and hands-free; those services need to be disabled so they don't interfere with our program. On my machine, I had to modify/etc/Bluetooth/audio.conf. Under the [General] section, add this line:

```
1 Disable=Headset, Gateway ? ♦
```

After modifying the config file, restart Bluetooth by running sudo service Bluetooth restart, and check that the SDP server no longer has references to the headset or hands-free profiles.

The next piece of code, Listing Two, shows how to register the the headset (HS) side of the headset profile. The code is largely borrowed from <u>two sources</u> I found on the Web.

### **Listing Two**

```
sdp profile desc t desc;
 15
             uuid t root_uuid, l2cap_uuid, rfcomm_uuid;
sdp_list_t *12cap_list = 0,
 16
 17
 18
                             *rfcomm_list = 0,
 19
                             *root_l\bar{i}st = 0,
 20
                             *proto list = 0,
 21
                             *access proto list = 0;
 22
23
             sdp_data_t *channel_d = 0;
 24
25
26
27
28
             int err = 0;
             sdp_session_t *session = 0;
             sdp record t *record = sdp record alloc();
 29
 30
       // set the name, provider, and description
 31
             sdp_set_info_attr(record, service_name, service_prov, service_dsc);
 32
33
34
       // service class ID (HEADSET)
             sdp uuid16 create(&hs uuid, HEADSET SVCLASS ID);
 35
 36
             if (!(root_list = sdp_list_append(0, &hs_uuid)))
 37
                   return -1;
 38
 39
             sdp_uuid16_create(&ga_uuid, GENERIC_AUDIO_SVCLASS_ID);
 40
 41
             if (!(root_list = sdp_list_append(root_list, &ga_uuid)))
 42
                   return -1;
 43
             if (sdp_set_service_classes(record, root_list) < 0)
    return -1;</pre>
 44
 45
 46
 47
             sdp_list_free(root_list, 0);
 48
             root list = 0;
 49
 50
       // make the service record publicly browsable
 51
             sdp uuid16 create(&root uuid, PUBLIC BROWSE GROUP);
 52
 53
             root_list = sdp_list_append(0, &root_uuid);
sdp_set_browse_groups( record, root_list );
 54
 55
 56
       // set I2cap information
             sdp_uuid16_create(&l2cap_uuid, L2CAP_UUID);
l2cap_list = sdp_list_append( 0, &l2cap_uuid );
proto_list = sdp_list_append( 0, l2cap_list );
 57
 58
 59
 60
 61
 62
             sdp_uuid16_create(&rfcomm_uuid, RFCOMM_UUID);
channel d = sdp_data_alloc(SDP_UINT8, &channel);
rfcomm_Tist = sdp_list_append(0, &rfcomm_uuid);
 63
 64
 65
 66
             sdp_list_append( rfcomm_list, channel_d );
             sdp_list_append( proto_list, rfcomm_list );
 67
 68
       // attach protocol information to service record
 69
70
71
72
73
             access_proto_list = sdp_list_append( 0, proto_list );
             sdp_set_access_protos( record, access_proto_list );
             sdp uuid16 create(&desc.uuid, HEADSET PROFILE ID);
 74
75
76
77
       // set the version to 1.0
             desc.version = 0x0100;
 78
79
             if (!(root_list = sdp_list_append(NULL, &desc)))
                   return -1;
 80
             if (sdp_set_profile_descs(record, root_list) < 0)
    return -1;</pre>
 81
 82
 83
       \ensuremath{//} connect to the local SDP server and register the service record
 84
 85
             session = sdp_connect( BDADDR_ANY, BDADDR_LOCAL, SDP_RETRY_IF_BUSY );
 86
             err = sdp_record_register(session, record, 0);
 87
        // cleanup
 88
 89
             sdp data free( channel d );
             sdp_list_free( l2cap_list, 0 );
sdp_list_free( rfcomm_list, 0 );
sdp_list_free( root_list, 0 );
sdp_list_free( access_proto_list, 0 );
 90
 91
 92
 93
 94
 95
             while (1)
 96
                   sleep(5000);
 97
 98
             return err;
 99
        }
100
101
```

102

The code essentially builds lists of values that are registered with the SDP server. The constants used in the code, like HEADSET\_SVCCLASS\_ID and GENERIC\_AUDIO\_SVC\_CLASS\_ID, are defined specifically from the HSP profile. The values for the headset side of the profile are listed on page 220 of the HSP profile document. Page 221 lists the values for the audio gateway side of the profile.

When a Bluetooth program exits, any services registered with the SDP server are removed. The test program waits in an infinite loop so you can run sdptool and verify that the service is indeed registered. Here's what the service should look like when you run the sdptool command:

```
Service Name: HSP service
     Service Description: HSP
3
     Service Provider: nebland software, LLC
4
     Service RecHandle: 0x10003
5
    Service Class ID List:
       "Headset" (0x1108)
      "Generic Audio" (0x1203)
   Protocol Descriptor List:
       "L2CAP" (0x0100)
"RFCOMM" (0x0003
10
                (0x0003)
        Channel: 3
11
12
    Profile Descriptor List:
13
       "Headset" (0x1108)
14
         Version: 0x0100
```

The SDP code registers a specific profile with the SDP server. Besides describing the profile that our service provides (HSP in this example), the code also tells the service what RFCOMM channel we will accept connections on. Remote devices that want to use our HSP service will query the SDP server and extract the channel that we registered. When a connection to our service is initiated, the remote device will connect to channel 3.

You might notice that the SDP record is missing the optional parameter that specifies whether remote volume control is supported. It seems that sdp\_attr\_add or sdp\_attr\_add\_new could be used to add a value for the constant SDP\_ATTR\_REMOTE\_AUDIO\_VOLUME\_CONTROL to the SDP record, but it didn't seem to work. At least, when I added the parameter, it did not show up in the listing produced by sdptool.

#### **Listening for RFCOMM Connections**

When a device initiates an HSP connection, the first connection created between the devices is through RFCOMM. As long as this connection is active, the headset can assume that the audio gateway will, at any moment, initiate a SCO connection. SCO connections are covered shortly.

The code in Listing Three creates a RFCOMM socket and listens for connections on channel 3.

#### **Listing Three**

```
#include "btinclude.h"
                                                                                                                2
 3
      uint8 t channel = 3;
 4
 5
      int main()
                                  int sock;
     // socket descriptor for local listener
    // socket descriptor for remote client
                                     int client;
10
         unsigned int len = sizeof(struct sockaddr rc);
11
     // local rfcomm socket address
12
                                struct sockaddr_rc remote;
     // remote rfcomm socket address
13
                                   struct sockaddr_rc local;
14
          char pszremote[18];
     // initialize a bluetooth socket
17
          sock = socket(AF BLUETOOTH, SOCK STREAM, BTPROTO RFCOMM);
18
19
           local.rc family = AF BLUETOOTH;
20
21
     // TODO: change this to a local address if you know what
     // address to use
           local.rc bdaddr = *BDADDR ANY;
24
           local.rc_channel = channel;
25
     // bind the socket to a bluetooth device
26
           if (bind(sock, (struct sockaddr *)&local,
```

```
sizeof(struct sockaddr rc)) < 0)</pre>
                   return -1;
30
31
     // set the listening queue length
          if (listen(sock, 1) < 0)
               return -1;
          printf("accepting connections on channel: %d\n", channel);
36
37
     // accept incoming connections; this is a blocking call
38
          client = accept(sock, (struct sockaddr *)&remote, &len);
39
40
          ba2str(&remote.rc bdaddr, pszremote);
41
          printf("received connection from: %s\n", pszremote);
```

If you're familiar with BSD-style socket programming, this example should look very familiar. If not, here are the basic steps:

- 1. Create a socket: line 17
- 2. Set the Bluetooth address and channel number: lines 23, and 24. If you want to use a specific Bluetooth device, use the str2ba(...) function to convert the string to a bdaddr\_t. For exmaple: str2ba("00:11:22:33:44:55:66", &local.rc\_bdaddr);
- 3. Bind the socket to the address and channel: line 27
- 4. Set the number of clients to queue up to wait for a connection handshake (additional clients will be refused): 35
- 5. Wait for/accept client connections: line 42

A successful call to accept will return a full duplex socket descriptor. The functions send and recvshould be used to send data to, and receive data from the remote device. This connection is used to exchange AT commands.

The AT commands and formats for HSP are defined starting on page 215 of the document. Various actions initiated on the handset, like adjusting the volume, will generate an AT command, telling our program of the event. Our program responds to the event by printing out the command and returning the AT OK command. In a real implementation, the service should adjust the hardware (turn the volume down, for example) as requested by the remote client.

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