```
In [1]:
1
 # from google.colab import drive
2 # drive.mount('/content/gdrive')
In [2]:
1 # !pip install mne
In [3]:
1 # !pip install --pre torch torchvision -f https://download.pytorch.org/whl/nightly
In [4]:
1
  2
     ___ \/\__ __\/\ \ / //\ \/\ \__\\/\ __\\/\ \
3
  # \ \ \\ \ \/__ \ \__/\ \ \/__/ \ \\\ \\ \\ \\__/\ \\ \/__/_/
4
   5
   6
    7
     8
                1 1/ \1 1
9
  10
11
  import mne
12
  import numpy as np
13
  import pandas as pd
14
  import matplotlib.pyplot as plt
15
  import torch
16
 from torch import nn
17
 import random
18
 from torch.utils.data import Dataset, DataLoader
19
20
 from mne.decoding import Vectorizer
  torch.manual seed(42)
21
<torch. C.Generator at 0x7f96c7a8d510>
```

```
In [5]:
   DEVICE = "cuda" if torch.cuda.is_available() else "cpu"
1
   print(DEVICE)
2
cuda
In [6]:
1 # Path to training data
   train_path = "/home/deepak/learning_project/student/BrainAge/training/"
In [7]:
1 # Path to testing data (public test set)
  test path = "/home/deepak/learning project/student/BrainAge/testing flat/"
In [8]:
   condition_ec = "EC" # closed eyes condition
1
   condition_eo = "EO" # closed eyes condition
2
   train_subj = 1100 # use 1100 of the 1200 training subjects for training
3
   val_subj = 100 # use 100 of the 1200 training subjects for validation
4
   test_subj = 400 # use 10 instead of 400 testing subjects, for demonstration purpo
5
```

```
In [9]:
     class CustomDataset(Dataset):
  1
         def __init__(self, path, subj, ages, start):
  2
  3
             self.path = path
             self.subj = subj
  4
  5
             self.ages = ages
             self.start = start
  6
         def __len__(self):
  7
             return self.subj
  8
         def getitem (self, idx):
  9
             s = idx + self.start
 10
             fname = f"subj{s:04}_{condition_eo}_raw.fif.gz"
 11
             raw = mne.io.read raw(self.path + fname, preload=True, verbose='warning')
 12
             d = raw.get data()
 13
 14
             ft = d.shape[-1]
             data eo = torch.zeros(1, 129, 10000)
 15
             data eo[:, :, :ft] = -200 * torch.tensor(d)
 16
             fname = f"subj{s:04}_{condition_ec}_raw.fif.gz"
 17
             raw = mne.io.read raw(self.path + fname, preload=True, verbose='warning')
 18
             d = raw.get data()
 19
             ft = d.shape[-1]
 20
             data_ec = torch.zeros(1, 129, 20000)
 21
             data_ec[:, :, :ft] = -200 * torch.tensor(d)
 22
             data = (data_eo, data_ec)
 23
 24
             age = self.ages[idx]
 25
             return data, age
In [10]:
    # get the age to predict from the CSV file
    meta = pd.read csv(train path + "train subjects.csv")
  2
  3
    y_train = []
    for age in meta.age[:1200]:
  4
  5
         y train.append(age)
    print(np.min(y_train), np.mean(y_train), np.median(y_train), np.max(y_train))
  6
 5.005932 10.356727775833333 9.58795299999999 21.899041
In [11]:
     train_data = CustomDataset(train_path, train_subj, y_train[:train_subj], 1)
```

```
In [12]:
    val_data = CustomDataset(train_path, val_subj, y_train[train_subj:train_subj+val_s
  1
In [13]:
     # DataLoader
  1
    batch_size = 8
  2
  3
  4
    train_loader = DataLoader(
  5
         train_data,
         batch_size=batch_size,
  6
  7
         num_workers=1
  8
  9
 10
    val_loader = DataLoader(
         val_data,
 11
         batch_size=batch_size,
 12
 13
         num_workers=1
 14
In [14]:
    e = torch.ones(4,5)
  1
  2
    e[2,2] = 9.3
  3
    np.around(e).int()
 tensor([[1, 1, 1, 1, 1],
       [1, 1, 1, 1, 1],
       [1, 1, 9, 1, 1],
       [1, 1, 1, 1, 1]], dtype=torch.int32)
```

```
In [15]:
 1
    class AgeNET(nn.Module):
        def conv block(self, in channels, out channels, kernel, stride, pool):
 2
 3
             return nn.Sequential(
                 nn.Conv2d(in_channels=in_channels, out_channels=out_channels, kernel_s
 4
 5
                 nn.LeakyReLU(),
                 nn.AvgPool2d(kernel size=(1, pool), stride=(1, pool))
 6
 7
             ).to(DEVICE)
 8
        def __init__(self, sampling_rate, num_T, num_C):
             super(). init ()
 9
10
             self.device = torch.device(DEVICE)
11
             print(DEVICE)
             self.to(DEVICE)
12
             self.pool = 3
13
14
             self.state = 0
             self.Time1 eo = self.conv block(1, num T, (1, sampling rate//2), 1, self.p
15
             self.Time2_eo = self.conv_block(1, num_T, (1, sampling_rate//4), 1, self.p
16
17
             self.Time3_eo = self.conv_block(1, num_T, (1, sampling_rate//8), 1, self.p
             self.Time1 ec = self.conv block(1, num T, (1, sampling rate//2), 1, self.p
18
             self.Time2_ec = self.conv_block(1, num_T, (1, sampling_rate//4), 1, self.p
19
             self.Time3_ec = self.conv_block(1, num_T, (1, sampling_rate//8), 1, self.p
20
             self.BN_T_eo = nn.BatchNorm2d(num_T).to(DEVICE)
21
             self.BN_T_ec = nn.BatchNorm2d(num_T).to(DEVICE)
22
             self.Chan1_eo = self.conv_block(num_T, num_C, (129, 1), 1, self.pool)
23
24
             self.Chan2_eo = self.conv_block(num_T, num_C, (65, 1), (64, 1), self.pool)
             # self.Chan3_eo = self.conv_block(num_T, num_C, (32, 1), (32, 1), self.poo
25
             self.Chan1_ec = self.conv_block(num_T, num_C, (129, 1), 1, self.pool)
26
             self.Chan2_ec = self.conv_block(num_T, num_C, (65, 1), (64, 1), self.pool)
27
             # self.Chan3_ec = self.conv_block(num_T, num_C, (32, 1), (32, 1), self.poo
28
29
             self.BN C eo = nn.BatchNorm2d(num C).to(DEVICE)
             self.BN C ec = nn.BatchNorm2d(num C).to(DEVICE)
30
             size_eo, size_ec = self.get_size()
31
             print(size_eo, size_ec)
32
             self.fc eo = nn.Sequential(
33
34
                nn.Flatten(),
35
                 nn.Linear(in_features=size_eo, out_features=1024, bias=True),
36
                 nn.BatchNorm1d(1024),
37
                nn.ReLU()
38
39
             self.fc ec = nn.Sequential(
                nn.Flatten(),
40
```

```
41
                nn.Linear(in_features=size_ec, out_features=2048, bias=True),
42
                nn.BatchNorm1d(2048),
                nn.ReLU()
43
            )
44
            self.classifier = nn.Sequential(
45
                nn.Linear(in_features=3072, out_features=1024, bias=True),
46
47
                nn.BatchNorm1d(1024),
48
                nn.ReLU(),
49
                nn.Dropout(p=0.01, inplace=False),
                # nn.Linear(in features=4096, out features=2048, bias=True),
50
                # nn.BatchNorm1d(2048),
51
                # nn.ReLU(),
52
53
                # nn.Dropout(p=0.003, inplace=False),
54
                # nn.Linear(in features=2048, out features=1024, bias=True),
55
                # nn.BatchNorm1d(1024),
                # nn.ReLU(),
56
57
                # nn.Dropout(p=0.002, inplace=False),
58
                nn.Linear(in features=1024, out features=512, bias=True),
59
                nn.BatchNorm1d(512),
60
                nn.ReLU(),
                nn.Dropout(p=0.001, inplace=False),
61
62
                nn.Linear(in_features=512, out_features=256, bias=True),
63
                nn.BatchNorm1d(256),
64
                nn.ReLU(),
                nn.Linear(in_features=256, out_features=64, bias=True),
65
66
                nn.BatchNorm1d(64),
67
                nn.ReLU(),
68
            )
69
              self.last_layer = []
70
              for j in out_len:
71
                  self.last layer.append(
72
   #
                      nn.Sequential(
73
                           nn.Linear(in features=64, out features=j, bias=True, device=
74
                          nn.ReLU()
75
                       )
   #
76
                  )
77
            self.1 10 = nn.Sequential(
78
                        nn.Linear(in_features=64, out_features=25, bias=True),
                         nn.ReLU()
79
                    )
80
            self.l l1 = nn.Sequential(
81
```

```
82
                          nn.Linear(in_features=64, out_features=1, bias=True),
 83
                          nn.ReLU()
                      )
 84
 85
         def forward(self, x_eo, x_ec):
             y = self.Time1_eo(x_eo)
 86
 87
             out_eo = y
             y = self.Time2_eo(x_eo)
 88
 89
             out_eo = torch.cat((out_eo, y), dim=-1)
 90
             y = self.Time3 eo(x eo)
             out_eo = torch.cat((out_eo, y), dim=-1)
 91
 92
             y = self.Time1 ec(x ec)
             out ec = y
 93
 94
             y = self.Time2_ec(x_ec)
 95
             out ec = torch.cat((out ec, y), dim=-1)
 96
             y = self.Time3_ec(x_ec)
 97
             out_ec = torch.cat((out_ec, y), dim=-1)
 98
             out_eo = self.BN_T_eo(out_eo)
             out_ec = self.BN_T_ec(out_ec)
 99
             z = self.Chan1_eo(out_eo)
100
101
             out_f_eo = z
             z = self.Chan2 eo(out eo)
102
103
             out_f_eo = torch.cat((out_f_eo, z), dim=2)
             # z = self.Chan3_eo(out_eo)
104
             # out_f_eo = torch.cat((out_f_eo, z), dim=2)
105
             z = self.Chan1_ec(out_ec)
106
107
             out_f_ec = z
108
             z = self.Chan2_ec(out_ec)
             out_f_ec = torch.cat((out_f_ec, z), dim=2)
109
110
             # z = self.Chan3_ec(out_ec)
111
             # out_f_ec = torch.cat((out_f_ec, z), dim=2)
             out_f_eo = self.BN_C_eo(out_f_eo)
112
             out f ec = self.BN C ec(out f ec)
113
114
             out = torch.cat((self.fc_eo(out_f_eo), self.fc_ec(out_f_ec)), dim=-1)
115
             out = self.classifier(out)
116
             if self.state == 0:
                 out = self.l l0(out)
117
118
             else:
119
                 out = self.l l1(out)
120
             return out
         def set state(self, st):
121
122
             self.state = st
```

```
123
         def get_size(self):
124
             d_eo = torch.ones(1, 1, 129, 10000).to(DEVICE)
             d_ec = torch.ones(1, 1, 129, 20000).to(DEVICE)
125
126
             y = self.Time1_eo(d_eo)
127
             out_eo = y
             y = self.Time2_eo(d_eo)
128
129
             out_eo = torch.cat((out_eo, y), dim=-1)
130
             y = self.Time3_eo(d_eo)
131
             out_eo = torch.cat((out_eo, y), dim=-1)
132
             y = self.Time1 ec(d ec)
133
             out ec = y
134
             y = self.Time2 ec(d ec)
135
             out_ec = torch.cat((out_ec, y), dim=-1)
136
             y = self.Time3_ec(d_ec)
137
             out_ec = torch.cat((out_ec, y), dim=-1)
138
             out_eo = self.BN_T_eo(out_eo)
139
             out_ec = self.BN_T_ec(out_ec)
140
             z = self.Chan1 eo(out eo)
141
             out_f_eo = z
142
             z = self.Chan2_eo(out_eo)
             out_f_eo = torch.cat((out_f_eo, z), dim=2)
143
144
             # z = self.Chan3_eo(out_eo)
145
             # out_f_eo = torch.cat((out_f_eo, z), dim=2)
             z = self.Chan1_ec(out_ec)
146
147
             out_f_ec = z
148
             z = self.Chan2_ec(out_ec)
149
             out_f_ec = torch.cat((out_f_ec, z), dim=2)
             # z = self.Chan3_ec(out_ec)
150
151
             # out_f_ec = torch.cat((out_f_ec, z), dim=2)
152
             return torch.numel(out_f_eo), torch.numel(out_f_ec)
```

```
In [16]:

1 model_A = AgeNET(128, 9, 6).to(DEVICE)

cuda
14940 29934
```

```
In [17]:

1 DEVICE

'cuda'

In [18]:

1 model_A = model_A.to(DEVICE)
```

Layer (type)	Output Shape	Param #
Conv2d-1	[-1, 9, 129, 9937]	585
LeakyReLU-2	[-1, 9, 129, 9937]	0
AvgPool2d-3	[-1, 9, 129, 828]	0
Conv2d-4	[-1, 9, 129, 9969]	297
LeakyReLU-5	[-1, 9, 129, 9969]	0
AvgPool2d-6	[-1, 9, 129, 830]	0
Conv2d-7	[-1, 9, 129, 9985]	153
LeakyReLU-8	[-1, 9, 129, 9985]	0
AvgPool2d-9	[-1, 9, 129, 832]	0
Conv2d-10	[-1, 9, 129, 19937]	585
LeakyReLU-11	[-1, 9, 129, 19937]	0
AvgPool2d-12	[-1, 9, 129, 1661]	0
Conv2d-13	[-1, 9, 129, 19969]	297
LeakyReLU-14	[-1, 9, 129, 19969]	0
AvgPool2d-15	[-1, 9, 129, 1664]	0
Conv2d-16	[-1, 9, 129, 19985]	153
LeakyReLU-17	[-1, 9, 129, 19985]	0
AvgPool2d-18	[-1, 9, 129, 1665]	0
BatchNorm2d-19	[-1, 9, 129, 2490]	18
BatchNorm2d-20	[-1, 9, 129, 4990]	18
Conv2d-21	[-1, 6, 1, 2490]	6,972
LeakyReLU-22	[-1, 6, 1, 2490]	0
AvgPool2d-23	[-1, 6, 1, 830]	0
Conv2d-24	[-1, 6, 2, 2490]	3,516
LeakyReLU-25	[-1, 6, 2, 2490]	0
AvgPool2d-26	[-1, 6, 2, 830]	0
Conv2d-27	[-1, 6, 1, 4990]	6,972
LeakyReLU-28	[-1, 6, 1, 4990]	0
AvgPool2d-29	[-1, 6, 1, 1663]	0
Conv2d-30	[-1, 6, 2, 4990]	3,516
LeakyReLU-31	[-1, 6, 2, 4990]	0
AvgPool2d-32	[-1, 6, 2, 1663]	0
BatchNorm2d-33	[-1, 6, 3, 830]	12
BatchNorm2d-34	[-1, 6, 3, 1663]	12
Flatten-35	[-1, 14940]	0
Linear-36	[-1, 1024]	15,299,584
BatchNorm1d-37	[-1, 1024]	2,048
ReLU-38	[-1, 1024]	0
Flatten-39	[-1, 29934]	0
Linear-40	[-1, 2048]	61,306,880
BatchNorm1d-41	[-1, 2048]	4,096
ReLU-42	[-1, 2048]	0
Linear-43	[-1, 1024]	3,146,752
BatchNorm1d-44	[-1, 1024]	2,048
ReLU-45	[-1, 1024]	0
Dropout-46	[-1, 1024]	0
Linear-47	[-1, 512]	524,800
BatchNorm1d-48	[-1, 512]	1,024
ReLU-49	[-1, 512]	0
Dropout-50	[-1, 512]	0
Di opode 30	[-, 5-2]	O

Linear-51	[-1, 256]	131,328
BatchNorm1d-52	[-1, 256]	512
ReLU-53	[-1, 256]	0
Linear-54	[-1, 64]	16,448
BatchNorm1d-55	[-1, 64]	128
ReLU-56	[-1, 64]	0
Linear-57	[-1, 25]	1,625
ReLU-58	[-1, 25]	0

Total params: 80,460,379
Trainable params: 80,460,379
Non-trainable params: 0

Input size (MB): 12696075.44

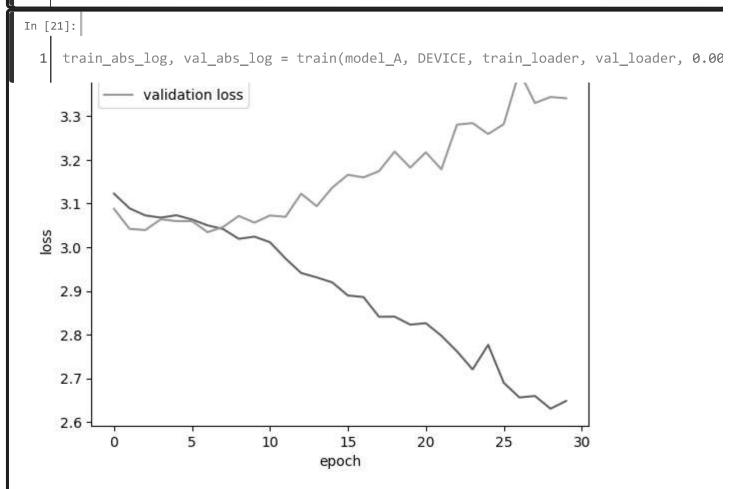
Forward/backward pass size (MB): 1726.25

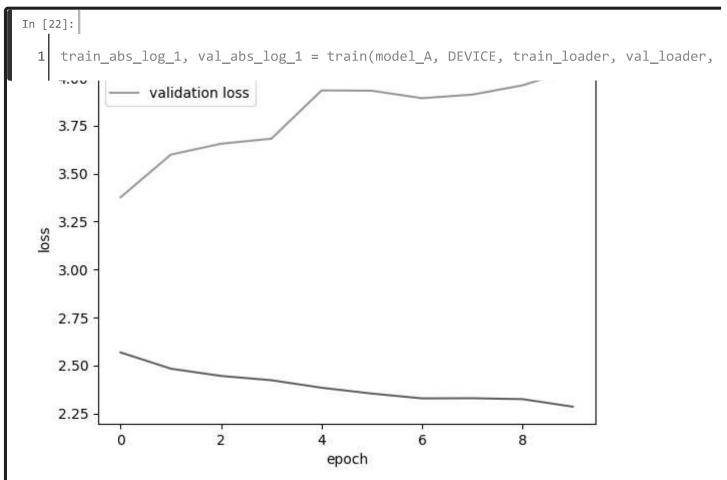
Params size (MB): 306.93

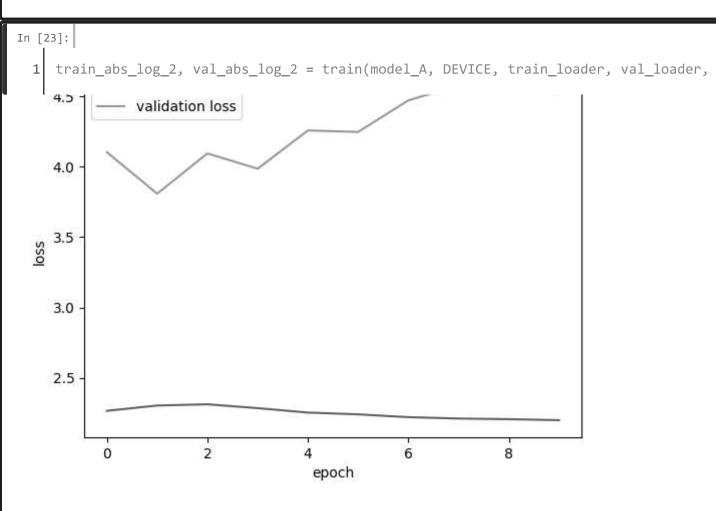
Estimated Total Size (MB): 12698108.62

```
In [20]:
    def train(model, device, train_loader, val_loader, lr, epochs):
 1
 2
        train_abs_log = []
 3
        train_log = []
 4
        val_log = []
 5
        val_abs_log = []
 6
        model.train()
 7
        abs_loss = nn.L1Loss(reduction='mean')
 8
        lossfunc = nn.CrossEntropyLoss(reduction='mean')
 9
        optimizer = torch.optim.NAdam(model.parameters(), lr=lr)
10
        f = plt.figure()
        for epoch in range(epochs):
11
            train abs loss = 0.0
12
            train loss = 0.0
13
            print(f"Epoch #{1 + epoch:02}: ")
14
15
            for data, age in train loader:
16
17
                 data_eo, data_ec = data
                 data_eo = data_eo.to(device)
                                                       # shape = (batch_size, 1, 129,
18
19
                data_ec = data_ec.to(device)
                                                       # shape = (batch_size, 1, 129,
                batch size = age.size(0)
20
                optimizer.zero_grad()
21
                output = model(data_eo, data_ec) # shape = (batch_size, 25)
22
                 loss = lossfunc(output, np.around(age).to(torch.int64).to(device))
23
24
                loss.backward()
25
                optimizer.step()
26
                 print(i)
27
                 i += batch size
                train abs loss += abs loss(torch.argmax(output, dim=-1), age.to(DEVICE
28
29
                 train loss += loss.item() * batch size
30
            train abs loss /= train subj
            train_loss /= train_subj
31
            train_abs_log.append(train_abs_loss)
32
            train log.append(train loss)
33
34
            val abs loss = 0.0
            val loss=0.0
35
            for data, age in val loader:
36
37
                 data eo, data ec = data
38
                 data_eo = data_eo.to(device)
                                                       # shape = (batch_size, 129, 100
39
                 data_ec = data_ec.to(device)
                                                        # shape = (batch_size, 129, 200
                 batch size = age.size(0)
40
```

```
41
                output = model(data_eo, data_ec) # shape = (batch_size, 25)
42
                loss = lossfunc(output, np.around(age).to(torch.int64).to(device))
43
               val_abs_loss += abs_loss(torch.argmax(output, dim=-1), age.to(DEVICE))
44
45
               val_loss += loss.item() * batch_size
           val_abs_loss /= val_subj
46
47
           val_loss /= val_subj
48
           val_abs_log.append(val_abs_loss)
49
           val_log.append(val_loss)
           print(f"CrossEntropyLoss: train = {train_loss}, validation = {val_loss
50
           print(f"mean absolute error: train = {train_abs_loss}, validation = {val_
51
52
           plt.clf()
           plt.plot(train_log, label='train loss')
53
           plt.plot(val_log, label='validation loss')
54
55
           plt.xlabel('epoch')
56
           plt.ylabel('loss')
57
           plt.title('Loss')
58
           plt.legend()
59
           plt.show()
60
        return train_abs_log, val_abs_log
```







```
In [ ]:
    def train_L(model, loss_func, device, train_loader, val_loader, lr, epochs):
 1
 2
       train_abs_log = []
 3
       val_abs_log = []
 4
       model.train()
 5
        abs_loss = loss_func
 6
       optimizer = torch.optim.NAdam(model.parameters(), lr=lr)
 7
       f = plt.figure()
 8
       for epoch in range(epochs):
 9
           train abs loss = 0.0
10
            print(f"Epoch #{1 + epoch:02}: ")
            i = 0
11
            for data, age in train loader:
12
                data eo, data ec = data
13
                data_eo = data_eo.to(device)
14
                                                      # shape = (batch_size, 1, 129,
                data_ec = data_ec.to(device)
15
                                                      # shape = (batch_size, 1, 129,
                batch size = age.size(0)
16
17
                optimizer.zero_grad()
                output = model(data_eo, data_ec) # shape = (batch_size, 25)
18
19
                loss = abs_loss(torch.squeeze(output), age.float().to(device))
                loss.backward()
20
                optimizer.step()
21
22
                print(i)
                i += batch size
23
24
                train_abs_loss += loss.item() * batch_size
25
            train_abs_loss /= train_subj
26
            train_abs_log.append(train_abs_loss)
27
            val abs loss = 0.0
            for data, age in val loader:
28
29
                data eo, data ec = data
                data eo = data eo.to(device)
                                                      # shape = (batch size, 129, 100
30
                data_ec = data_ec.to(device)
                                                      # shape = (batch size, 129, 200
31
                batch size = age.size(0)
32
                output = model(data eo, data ec) # shape = (batch size, 25)
33
34
                print(output)
                print(age)
35
                loss = abs loss(torch.squeeze(output), age.float().to(device))
36
37
38
                val_abs_loss += loss.item() * batch_size
39
            val_abs_loss /= val_subj
            val abs log.append(val abs loss)
40
```

```
41
              print(f"mean absolute error: train = {train_abs_loss}, validation = {val_
 42
              plt.clf()
              plt.plot(train_abs_log, label='train loss')
 43
              plt.plot(val_abs_log, label='validation loss')
 44
 45
              plt.xlabel('epoch')
              plt.ylabel('loss')
 46
 47
              plt.title('Loss')
 48
              plt.legend()
 49
              plt.show()
 50
          return train_abs_log, val_abs_log
In [29]:
     model_A.set_state(1)
In [37]:
     train_L(model_A, nn.L1Loss(reduction='mean'), DEVICE, train_loader, val_loader, 0.
 ([2.314322156906128,
   2.0543491112102163,
   1.905966567993164,
   1.8039553785324096,
   1.6943501112677835,
   1.6155094714598222,
   1.5890673858469182,
   1.474887121373957,
   1.4691239057887684,
   1.4140368791060014],
  [2.878715238571167,
   2.9833662128448486,
   2.8866349983215334,
   2.887751216888428,
   2.9465968132019045,
   2.956333570480347,
   2.7572300910949705,
   3.0312032747268676,
   2.9802655029296874,
   3.0485591506958007])
In [ ]:
     train_L(model_A, nn.L1Loss(reduction='mean'), DEVICE, val_loader, val_loader, 0.00
 In [ ]:
  1
```