

Introduction to Machine Learning

Linear Regression

Varun Chandola

Computer Science & Engineering
State University of New York at Buffalo
Buffalo, NY, USA
chandola@buffalo.edu



University at Buffalo
Department of Computer Science
and Engineering
School of Engineering and Applied Sciences



Linear Regression

- Problem Formulation
- Geometric Interpretation
- Learning Parameters

Recap

- Issues with Linear Regression

Bayesian Linear Regression

Bayesian Regression

- Estimating Bayesian Regression Parameters
- Prediction with Bayesian Regression

Handling Non-linear Relationships

- Handling Overfitting via Regularization

Taking the next step

Hypothesis Space, \mathcal{H}

- ▶ Conjunctive
- ▶ Disjunctive
 - ▶ Disjunctions of k attributes
- ▶ Linear hyperplanes
- ▶ $\mathbf{c}_* \notin \mathcal{H}$
- ▶ Non-linear network

Input Space, \mathbf{x}

- ▶ $\mathbf{x} \in \{0, 1\}^d$
- ▶ $\mathbf{x} \in \mathbb{R}^d$

Input Space, y

- ▶ $y \in \{0, 1\}$
- ▶ $y \in \{-1, +1\}$
- ▶ $y \in \mathbb{R}$

Linear Regression

- ▶ There is one scalar **target** variable y (instead of hidden)
- ▶ There is one vector **input** variable x
- ▶ Inductive bias:

$$y = \mathbf{w}^T \mathbf{x}$$

Linear Regression Learning Task

Learn \mathbf{w} given training examples, $\langle \mathbf{X}, \mathbf{y} \rangle$.

Two Interpretations

1. Probabilistic Interpretation

- ▶ y is assumed to be normally distributed

$$y \sim \mathcal{N}(\mathbf{w}^\top \mathbf{x}, \sigma^2)$$

- ▶ or, equivalently:

$$y = \mathbf{w}^\top \mathbf{x} + \epsilon$$

where $\epsilon \sim \mathcal{N}(0, \sigma^2)$

- ▶ y is a *linear combination* of the input variables
- ▶ Given \mathbf{w} and σ^2 , one can find the *probability distribution* of y for a given \mathbf{x}

2. Geometric Interpretation

- ▶ Fitting a straight line to d dimensional data

$$y = \mathbf{w}^\top \mathbf{x}$$

$$y = \mathbf{w}^\top \mathbf{x} = w_1x_1 + w_2x_2 + \dots + w_dx_d$$

- ▶ Will pass through origin
- ▶ Add intercept

$$y = w_0 + w_1x_1 + w_2x_2 + \dots + w_dx_d$$

- ▶ Equivalent to adding another column in \mathbf{X} of 1s.

Learning Parameters - MLE Approach

- Find \mathbf{w} and σ^2 that maximize the likelihood of training data

$$\begin{aligned}\hat{\mathbf{w}}_{MLE} &= (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y} \\ \hat{\sigma}_{MLE}^2 &= \frac{1}{N} (\mathbf{y} - \mathbf{X}\mathbf{w})^\top (\mathbf{y} - \mathbf{X}\mathbf{w})\end{aligned}$$

Learning Parameters - Least Squares Approach

- ▶ Minimize *squared loss*

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^N (y_i - \mathbf{w}^\top \mathbf{x}_i)^2$$

- ▶ Make prediction $(\mathbf{w}^\top \mathbf{x}_i)$ as close to the target (y_i) as possible
- ▶ Least squares estimate

$$\hat{\mathbf{w}} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$$

Gradient Descent Based Method

- ▶ Minimize the squared loss using *Gradient Descent*

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^N (y_i - \mathbf{w}^\top \mathbf{x}_i)^2$$

- ▶ Why?

Recap - Linear Regression

Geometric

$$y = \mathbf{w}^\top \mathbf{x}$$

1. Least Squares

$$\hat{\mathbf{w}} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$$

2. Gradient Descent

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^N (y_i - \mathbf{w}^\top \mathbf{x}_i)^2$$

Bayesian

$$p(y) = \mathcal{N}(\mathbf{w}^\top \mathbf{x}, \sigma^2)$$

1. Maximum Likelihood Estimation

$$\hat{\mathbf{w}} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$$

$$\hat{\sigma}_{MLE}^2 = \frac{1}{N} \sum_{i=1}^N (\mathbf{y} - \mathbf{X}\mathbf{w})^\top (\mathbf{y} - \mathbf{X}\mathbf{w})$$

Issues with Linear Regression

1. Not truly Bayesian
2. Susceptible to outliers
3. *Too simplistic* - Underfitting
4. No way to control overfitting
5. Unstable in presence of correlated input attributes
6. Gets “confused” by unnecessary attributes

Putting a Prior on \mathbf{w}

- ▶ “Penalize” large values of \mathbf{w}
- ▶ A zero-mean Gaussian prior

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{w}|0, \tau^2 I)$$

- ▶ What is posterior of \mathbf{w}

$$p(\mathbf{w}|\mathcal{D}) \propto \prod_i \mathcal{N}(y_i|\mathbf{w}^\top \mathbf{x}_i, \sigma^2) p(\mathbf{w})$$

- ▶ Posterior is also Gaussian

Posterior Estimates of the Weight Vector

- ▶ MAP estimate of \mathbf{w}

$$\arg \max_{\mathbf{w}} \sum_{i=1}^N \log \mathcal{N}(y_i | \mathbf{w}^\top \mathbf{x}_i, \sigma^2) + \log \mathcal{N}(\mathbf{w} | 0, \tau^2 I)$$

Parameter Estimation for Bayesian Regression

- ▶ Prior for \mathbf{w}

$$\mathbf{w} \sim \mathcal{N}(\mathbf{w}|\mathbf{0}, \tau^2 \mathbf{I}_D)$$

- ▶ Posterior for \mathbf{w}

$$\begin{aligned} p(\mathbf{w}|\mathbf{y}, \mathbf{X}) &= \frac{p(\mathbf{y}|\mathbf{X}, \mathbf{w})p(\mathbf{w})}{p(\mathbf{y}|\mathbf{X})} \\ &= \mathcal{N}(\bar{\mathbf{w}} = (\mathbf{X}^\top \mathbf{X} + \frac{\sigma^2}{\tau^2} \mathbf{I}_N)^{-1} \mathbf{X}^\top \mathbf{y}, \sigma^2 (\mathbf{X}^\top \mathbf{X} + \frac{\sigma^2}{\tau^2} \mathbf{I}_N)^{-1}) \end{aligned}$$

- ▶ Posterior distribution for \mathbf{w} is also Gaussian
- ▶ What will be MAP estimate for \mathbf{w} ?

Prediction with Bayesian Regression

- ▶ For a new \mathbf{x}^* , predict y^*
- ▶ Point estimate of y^*

$$y^* = \hat{\mathbf{w}}_{MLE}^\top \mathbf{x}^*$$

- ▶ Treating y as a Gaussian random variable

$$p(y^*|\mathbf{x}^*) = \mathcal{N}(\hat{\mathbf{w}}_{MLE}^\top \mathbf{x}^*, \hat{\sigma}_{MLE}^2)$$

$$p(y^*|\mathbf{x}^*) = \mathcal{N}(\hat{\mathbf{w}}_{MAP}^\top \mathbf{x}^*, \hat{\sigma}_{MAP}^2)$$

Full Bayesian Treatment

- ▶ Treating y and \mathbf{w} as random variables

$$p(y^*|\mathbf{x}^*) = \int p(y^*|\mathbf{x}^*, \mathbf{w})p(\mathbf{w}|\mathbf{X}, \mathbf{y})d\mathbf{w}$$

- ▶ This is also *Gaussian*!

Handling Non-linear Relationships

- ▶ Replace \mathbf{x} with non-linear functions $\phi(\mathbf{x})$

$$p(y|\mathbf{x}, \boldsymbol{\theta}) \sim \mathcal{N}(\mathbf{w}^\top \phi(\mathbf{x}))$$

- ▶ Model is still linear in \mathbf{w}
- ▶ Also known as **basis function expansion**

Example

$$\phi(x) = [1, x, x^2, \dots, x^d]$$

- ▶ Increasing d results in more complex fits

How to Control Overfitting?

- ▶ Use simpler models (linear instead of polynomial)
 - ▶ Might have poor results (underfitting)
- ▶ Use regularized complex models

$$\hat{\Theta} = \arg \min_{\Theta} J(\Theta) + \alpha R(\Theta)$$

- ▶ $R()$ corresponds to the penalty paid for complexity of the model

Examples of Regularization

Ridge Regression

$$\hat{\mathbf{w}} = \arg \min_{\mathbf{w}} J(\mathbf{w}) + \alpha \|\mathbf{w}\|^2$$

- ▶ Also known as l_2 or *Tikhonov* regularization
- ▶ Helps in reducing impact of correlated inputs

Least Absolute Shrinkage and Selection Operator - LASSO

$$\hat{\mathbf{w}} = \arg \min_{\mathbf{w}} J(\mathbf{w}) + \alpha |\mathbf{w}|$$

- ▶ Also known as l_1 regularization
- ▶ Helps in feature selection – favors sparse solutions

Parameter Estimation for Ridge Regression

Exact Loss Function

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^N (y_i - \mathbf{w}^\top \mathbf{x}_i)^2 + \frac{1}{2} \lambda \|\mathbf{w}\|_2^2$$

MAP Estimate of \mathbf{w}

$$\hat{\mathbf{w}}_{MAP} = (\lambda \mathbf{I}_D + \mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$$

References