# Control Flow

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# Contents

1	Pro	gram Graphs	1
	1.1	Control Flow Graphs	2
		1.1.1 The if Statement	2
		1.1.2 do, while, and for Loops	2
		1.1.3 case Structure	2
		1.1.4 try-catch Exceptions	3
2	Cov	erage	3
	2.1	Statement Coverage	3
	2.2	Segment Coverage	3
	2.3	Branch Coverage	3
	2.4	Condition Coverage	4
	2.5	Condition/Decision Coverage	4
	2.6	Multple Condition Coverage	4
	2.7		5
	2.8		5
	2.9		5

# 1 Program Graphs

Given a program written in an imperative programing language, its program graph is a directed graph in which

- nodes are statement fragments (or complete statements)
- edges represent flow of control

### 1.1 Control Flow Graphs

Models all executions of a method by describing control structures:

- nodes are statements or sequences of statements (basic blocks)
- edges are transfers of control
  - an edge  $(s_1, s_2)$  indicates that  $s_1$  may be followed by  $s_2$  in an execution

Basic block: sequence of statements such that if the first statement is executed all statements will be (no branches)

- intermediate statements not shown if there is  $\leq 1$  exiting edge and  $\leq 1$  entering edge
- has one entry point and one exit point

Sometimes annotated with branch predicates and defs.

#### 1.1.1 The if Statement

From source code to CFG there is an issue about branching:

- in a CFG, nodes corresponding to branching should not contain any assignemnts
- return nodes must be distinct

Short circuiting conditions must be shown with separate branches for each condition.

#### 1.1.2 do, while, and for Loops

Can have:

- dummy nodes for condition checking or initializing loops
- nodes to implicitly increment loop

do loops will branch at last step, while loops branch at first

#### 1.1.3 case Structure

Cases without breaks fall through to the next case

#### 1.1.4 try-catch Exceptions

Both throw and catching each type of exception must be shown separately.

## 2 Coverage

#### 2.1 Statement Coverage

Has the following characteristics:

- achieved when all statements in a method have been executing at least once.
  - faults cannot be discovered if the parts containing them are not executed
- equivalent to covering all nodes in a CFG
- executing a statement is a weak guarantee of correctness, but easy to achieve

$$Statement\ Coverage = \frac{\#\ of\ executed\ statements}{total\ \#\ of\ statements}$$

Most used in industry with coverage target at 80-90%.

Problems include:

- predicate may be tested for only one value
- loop bodies may be iterated only once
- not all branches (cases) are necessarily covered

### 2.2 Segment Coverage

Counts segments (basic blocks) rather than statements

 $\bullet$  can produce drastically different numbers since it does not account for # of statements per segment

#### 2.3 Branch Coverage

Has the following characteristics:

• achieved when every branch from a node is executed at least once

- at least one true and one false evaluation for each predicate
- can be achieved with D+1 paths in a CFG with D 2-way branching nodes and no loops
  - less if there are loops

Branch Coverage = 
$$\frac{\text{\# of executed branches}}{\text{total } \text{\# of branches}}$$

#### Problems include:

- short-circuit evaluation means that many predicates might not be evaluated
- compound predicate treated as a single statement
  - if n clauses,  $2^n$  combinations but only 2 tested
- only a subset of all entry-exit paths is tested

### 2.4 Condition Coverage

Has the following characteristics:

- condition coverage reports the true or false outcome of each condition
- measures the conditions independently of each other
- can fail to consider short-circuit

$$\label{eq:condition} \text{Coverage} = \frac{\# \text{ of conditions that are both T and F}}{\text{total } \# \text{ of conditions}}$$

#### 2.5 Condition/Decision Coverage

Also called branch and condition coverage, it is computed by considering both branch and condition coverage measures.

## 2.6 Multple Condition Coverage

All combinations of condition constituents in decisions are considered when calculating coverage.

• also implies condition and branch coverage

#### 2.7 Modified Condition/Decision Coverage (MC/DC)

**Key idea**: test important combinations of conditions and limiting testing costs

- extend branch and decision coverage with the requirement that each condition should affect the decision outcome independently
- in other words, each condition should be evaluated one time to true and one time to false, and this with affecting the decision's outcome

#### 2.8 Path Coverage

Has the following characteristics:

- test case for each possible path, though some are infeasible and number could be infinite
- key is to determine critical paths

#### 2.9 Loop Coverage

Loops are highly fault-prone

- every loop involves a decision to traverse the loop or not
- can do boundary value analysis on the index variable

Has the following characteristics:

- minimal coverage should execute the loop body 0, 1, and 2+ times
- single loop should have more extensive coverage with setting loop control variable to:
  - $-\min 1, \min, \min + 1$
  - typical
  - $\max 1, \max, \max + 1$
- for nested loop, start at the innermost loop
  - set all outer loops to min value
  - set all other loops to typical values
  - test cases for a single loop for the innermost loop

- move up in nested loop level
- $-\,$  if outermost loop done, do cases for single loop for all loops in the nest simultanously