# Minimum Spanning Trees

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## 1 Spanning Trees

For a connected graph G=(V,E), a spanning tree in G is a tree of the form (V,A) with A a subset of E (a tree with edges from E that covers all vertices).

The goal is to find a spanning tree with minimal weight.

## 2 Kruskal's Algorithm

GreedyMST(G):
A = []

```
sort edges by increasing weight
for k = 1, ..., m:
   if e_k does not create a cycle in A:
        append e_k to A
```

#### 2.1 Augmenting Sets without Cycles

Claim: Let G be a connected graph and let A be a subset of the edges of G. If (V, A) has no cycle and |A| < n - 1, then one can find an edge e not in A such that  $A \cup \{e\}$  still has no cycle.

#### **Proof**:

- in any graph, # vertices # connected components  $\leq \#$  edges
- for (V, A), this gives n c < n 1 so c > 1
- take any edge on a path that connects two components

#### 2.2 Properties of the Output

Claim: If the output is  $A = [e_1, \ldots, e_r]$  then (V, A) is a spanning tree r = n - 1.

#### Proof:

- (V, A) has no cycle
- suppose (V, A) is not a spanning tree, then there exists an edge e not in A such that  $(V, A \cup \{e\})$  still has no cycle
  - for the case where  $w(e) < w(e_1)$ , this is impossible since  $e_1$  has the smallest weight
  - for the case where  $w(e_i) < w(e) < w(e_{i+1})$ , this is impossible since at the moment we had inserted  $e_{i+1}$ , we decided not to include e which means that e created a loop with  $e_1, \ldots, e_i$
  - for the case where  $w(e_r) < w(e)$ , this is impossible since if it was included in A since there is no loop in  $A \cup \{e\}$

#### 2.3 Exchanging Edges

Claim: Let (V, A) and (V, T) be 2 spanning trees and let e be an edge in t but not in A. Then there is some edge e' in A but not in T such that

(V, T + e' - e) is still a spanning tree. Further, e' is on the cycle that e creates in A.

#### **Proof**:

- consider  $e = \{v, w\}$
- (V, A + e) contains a cycle  $c = v, w, \dots, v$
- removing e from T splits (V, T e) into two connected components  $T_1, T_2$
- c starts in  $T_1$ , crosses over to  $T_2$ , so it contains another edge e' between  $T_2$  and  $T_1$
- e' is in A but not in T
- (V, T + e' e) is a spanning tree

### 2.4 Correctness: Exchange Argument

Let A be the output of the algorithm, (V, T) be any spanning tree. If  $T \neq A$ , let e be an edge in T but not in A. This means there is an edge e' in A but not in T such that (V, T + e' - e) is a spanning tree and e' is on the cycle that e creates in A.

During the algorithm, we considered e but rejected it because it created a cycle in A. All other elements in this cycle have smaller (or equal) weight, so  $w(e') \leq w(e)$  and so T' = T + e' - e has weight  $\leq w(T)$  and one more common element with A. This continues.

## 3 Data Structures for Kruskal's Algorithm

Operations possible on disjoint sets of vertices are:

- find: identify which set contains a given vertex
- union: replace 2 sets by their union

#### 3.1 Implementation

```
GreedyMST_UnionFind(G):
    T = []
    U = {{v1}, ..., {vn}}
    sort edges by increasing weight
```

```
for k in range(1, m):
    if U.find(ek.1) != U.find(ek.2):
        U.union(U.find(ek.1), U.find(ek.2))
        append ek to T
```

#### 3.2 Linked List

Uses an array of linked lists for U.

To do find, add an array of indices where X[i] is the set that contains i.

In the worst case for this, find is O(1) but union traverses one of the linked lists, updates the corresponding entries of X, and concatenates 2 linked lists, so union worst case is  $\Theta(n)$ .

This gives Kruskal's Algorithm to be  $O(m \log(m))$  in sorting edges, O(m) for find, O(n) for union, and overall worst case  $O(m \log(m) + n^2)$ .

#### 3.3 Simple Heuristics for Union

#### 3.3.1 Modified Union

Each set in  $\overline{U}$  keeps track of its size and only traverse the smaller list.

Also, add a pointer to the trail of the lists to concatenate in O(1).

#### 3.3.2 Key Observation

Worst case for 1 union is still  $\Theta(n)$  but better total time:

- for any given vertex v, the size of the set containing v at least doubles when we update X[v], so X[v] updated at most  $\log(n)$  times
- so the total cost of union per vertex is  $O(\log(n))$