### Heaps, Binary Heaps and Heapsort

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#### Heapsort

#### Heapsort

• Like Merge-sort it's worst case time complexity is  $O(n \log n)$ .

• Like Quick-sort it is an in place algorithm.

ullet # of elements stored outside the input array at any time:  $\mathcal{O}(1)$ .

• Combines the better attributes of the two sorting algorithms.

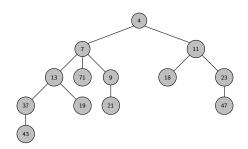
## Heapsort (Cont.)

- Introduces a different algorithm design technique:
  - the use of a data structure to manage information during the execution of the algorithm.
  - This data structure is called a heap.
- Apart from heapsort it also makes an efficient priority queue.
- The term heap was originally coined in the context of heapsort.
- But it has since come to refer to as garbage-collection storage provided by programming languages like Lisp and Java.
- But heap data structure is not garbage-collected storage!

#### Heaps

## Heap

A **Min-Heap** is a (rooted) tree data structure where the value stored in a node less than or equal to the value stored in each of its children.



# Heap (Cont.)

• The lowest/highest priority element is always stored at the root.

It is not a sorted structure.

• It can be regarded as being partially ordered.

• It is useful when it is necessary to repeatedly remove the object with the lowest/highest priority.

#### **Basic Operations**

#### **Query Operations:**

• FIND-MIN(H): Report the smallest key stored in the heap.

#### **Modifying Operations:**

- CREATEHEAP(H): Create an empty heap H.
- INSERT(x, H): Insert a new key with value x into the heap H.
- EXTRACT-MIN(H): Delete the smallest key from H.
- DECREASE-KEY $(p, \Delta, H)$ : Decrease the value of the key p by amount  $\Delta$ .
- MERGE( $H_1, H_2$ ): Merge two heaps  $H_1$  and  $H_2$ .

#### **Variants**

- 2-3 heap
- B-heap
- Beap
- Binary heap
- Binomial heap
- Brodal queue
- d-ary heap
- Fibonacci heap
- K-D Heap
- Leaf heap

- Leftist heap
- Pairing heap
- Radix heap
- Randomized meldable heap
- Skew heap
- Soft heap
- Ternary heap
- Treap
- Weak heap

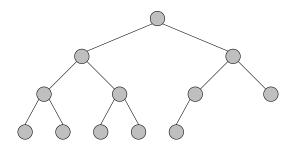
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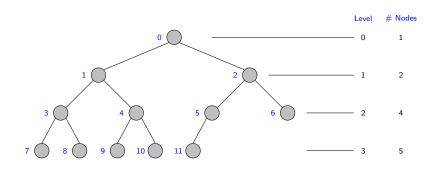
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Can we implement a binary tree using an array?

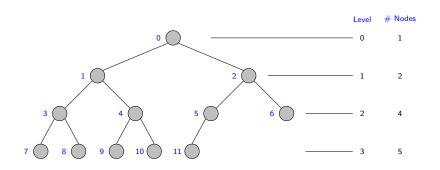
Yes, in some special cases.



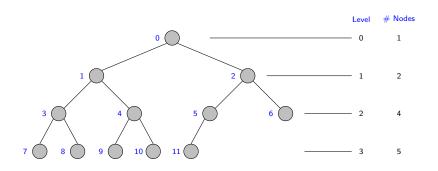
A complete binary of 12 nodes.



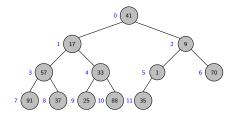
Can you see a relationship between label of a node and labels of its children?



- The label of the **leftmost node** at level  $i = 2^i 1$ .
- The label of a **node** v at level i occurring at  $k^{th}$  place from left  $= 2^i + k 2$ .
- The label of the **left** child of v is  $= 2 \cdot (2^i + (k-2)) + 1$ .
- The label of the **right** child of v is  $= 2 \cdot (2^i + (k-2)) + 2$ .

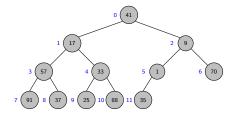


- Let v be a node with label j.
- Label of **left child**(v) = 2j + 1.
- Label of **right child**(v) = 2j + 2.
- Label of **parent** $(v) = \lfloor (j-1)/2 \rfloor$ .

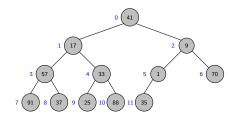


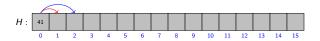
Can we implement a complete binary tree using an array? Yes!

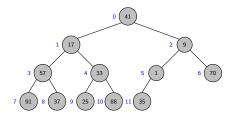
**Advantage:** It is the most compact representation.

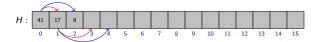


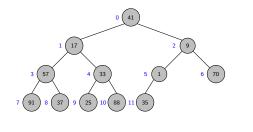


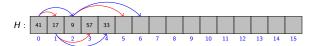


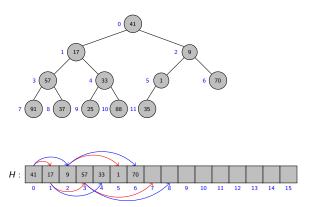


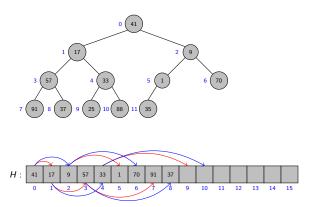


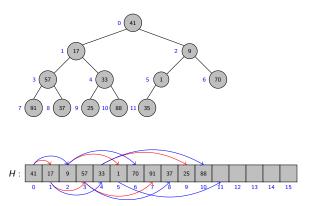


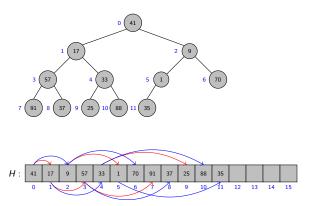








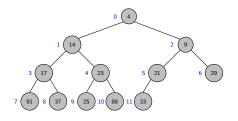




#### Binary Heap

# Binary (Min) Heap

**Definition:** It is a complete binary tree satisfying the heap property at each node.



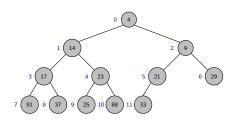


### Implementation of a Binary Heap

H[]: An array of size n used for storing the binary heap.

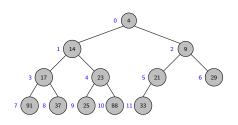
size: A variable for the total number of keys currently in the heap.

# FIND-MIN(H)





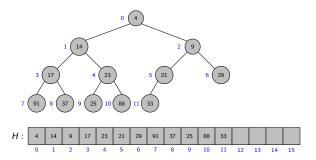
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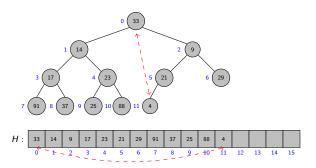
Return H[0]

**Goal:** Deletes the smallest key from H.



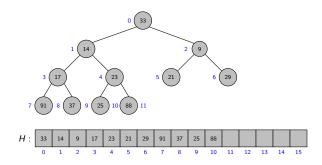
**Goal:** Deletes the smallest key from H.

Challenge: Preserve the complete binary tree structure as well as the heap property!



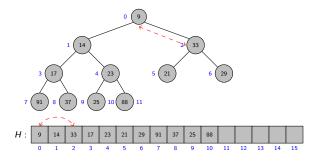
• swap(H[0], H[size - 1]).

**Goal:** Deletes the smallest key from H.



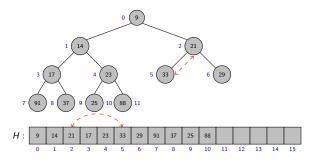
- swap(H[0], H[size 1]).
- size = size 1.

**Goal:** Deletes the smallest key from H.



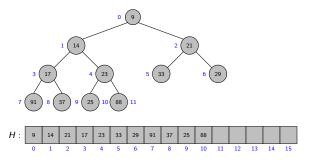
- swap(H[0], H[size 1]).
- size = size 1
- While x > key[left[x]] or x > key[right[x]], then
  - $swap(x, min\{left[x], right[x]\})$ .

**Goal:** Deletes the smallest key from H.

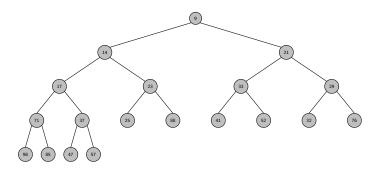


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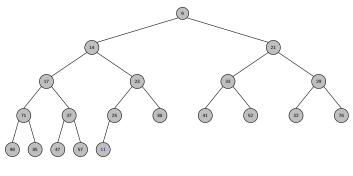
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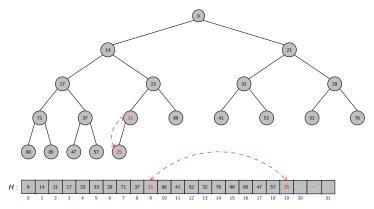
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- Complexity: # swaps =  $\mathcal{O}(\#$  levels in binary heap) =  $\mathcal{O}(\log n)$  (show it!).



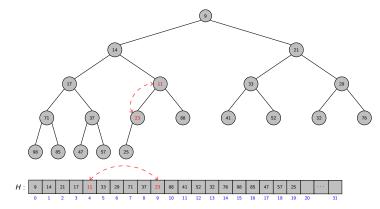




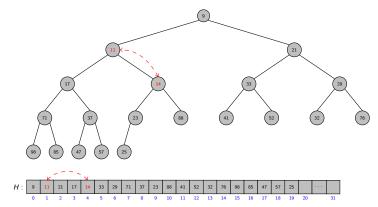
- H: 9 14 21 17 23 33 29 71 37 25 88 41 52 32 76 98 85 47 57 11 ...
- H[size] = x.
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# INSERT(x, H) (Cont.)

```
Begin i \leftarrow size(H);
H[size] \leftarrow x;
size(H) \leftarrow size(H) + 1;
while (i > 0 \text{ and } H[i] < H[\lfloor (i-1)/2 \rfloor])
swap(H[i], H[\lfloor (i-1)/2 \rfloor]);
i \leftarrow \lfloor (i-1)/2 \rfloor;
End
```

#### Complexity?

# INSERT(x, H) (Cont.)

**Complexity:**  $\mathcal{O}(\log n)$ .

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End
```

- DECREASE-KEY $(p, \Delta, H)$ : Decrease the value of the key p by amount  $\Delta$ .
  - Similar to INSERT(x, H).
  - Do it as an exercise!
  - Complexity?

• MERGE( $H_1$ ,  $H_2$ ): Merge two heaps  $H_1$  and  $H_2$ .

- DECREASE-KEY $(p, \Delta, H)$ : Decrease the value of the key p by amount  $\Delta$ .
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  - Complexity:  $\mathcal{O}(n)$ .
  - **Note:** Searching for p takes  $\mathcal{O}(n)$
  - Can you do it in  $\mathcal{O}(\log n)$ ?

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  - Complexity:  $\mathcal{O}(n)$ .
  - Needs some additional information called MAP!
  - Map: Stores the index corresponding to each key.

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- MERGE( $H_1$ ,  $H_2$ ): Merge two heaps  $H_1$  and  $H_2$ .
  - Complexity:  $\mathcal{O}(n \log n)$
  - Can you do it in  $\mathcal{O}(n)$ ?

Building a Binary heap

# Building a Binary Heap Incrementally

**Problem:** Given elements  $\{x_0, \ldots, x_{n-1}\}$ , build a binary heap H storing them.

#### Building a Binary Heap Incrementally

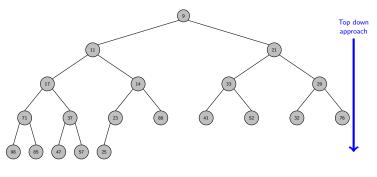
**Problem:** Given elements  $\{x_0, \dots, x_{n-1}\}$ , build a binary heap H storing them.

Trivial Solution: Build the Binary heap incrementally.

CREATEHEAP(H):

for i = 0 to n - 1

INSERT $(x_i, H)$ ;





- Consider a complete binary tree of height h with k leaf nodes in the last level.
- The total number of nodes  $n = (2^h 1) + k$ .
- Therefore, number of leaf nodes is equal to

$$k + (2^{h-1} - \lceil k/2 \rceil) = 2^{h-1} + \lfloor k/2 \rfloor$$
  
=  $\left[ \frac{1}{2} \{ 2^h + k - 1 \} \right] = \lceil n/2 \rceil$ 

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- Time complexity for inserting a leaf node =  $\mathcal{O}(\log n)$
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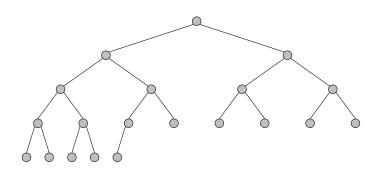
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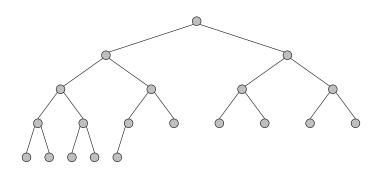
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**Conclusion:**  $\mathcal{O}(n)$  algorithm  $\Rightarrow$  each leaf nodes must take  $\mathcal{O}(1)$ .

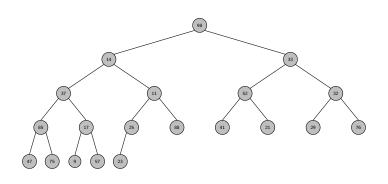




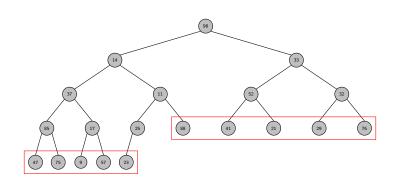
• Heap Property: Every node stores values smaller than its children.



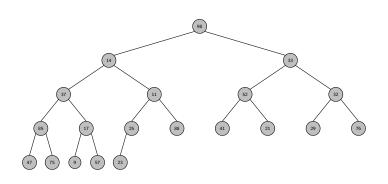
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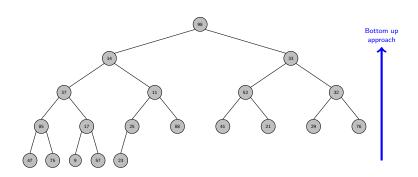
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- Question: In any complete binary tree, how many nodes satisfy the heap property?



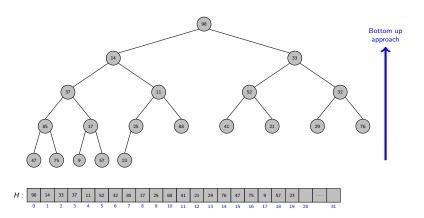
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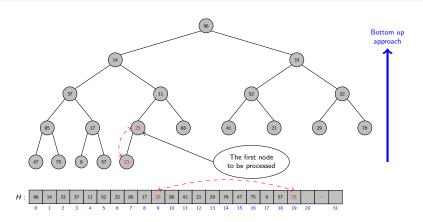
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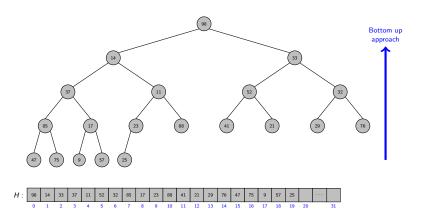
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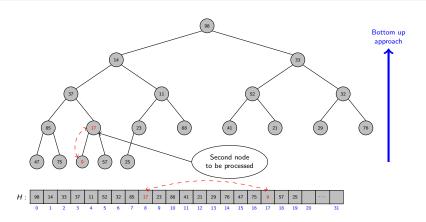
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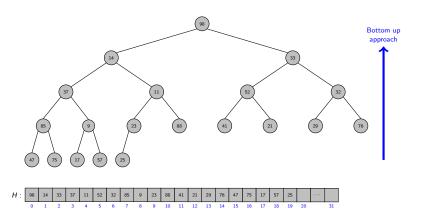
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- Leaving all the leaf nodes, process the elements in the decreasing order of their index and set the heap property for each of them.



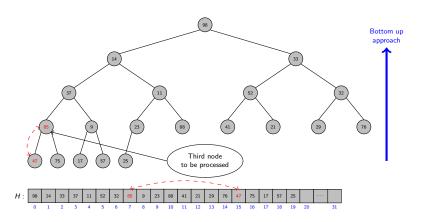
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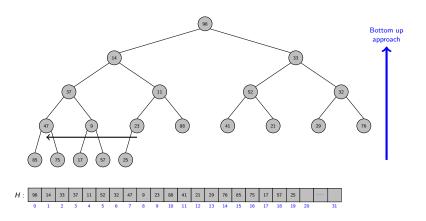
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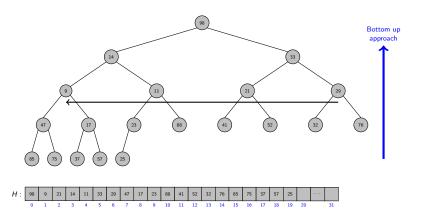
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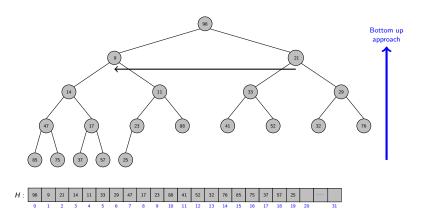
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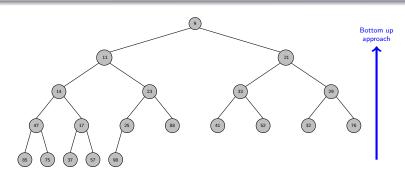
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- The heap property holds for all the leaf nodes.
- Leaving all the leaf nodes, process the elements in the decreasing order of their index and set the heap property for each of them.
- Let v be a node corresponding to index i in H.
- The process of restoring heap property at i called HEAPIFY(i, H).

# HEAPIFY(i, H)

For node i, compare its value with those of its children

- If it is greater than any of its children
  - Swap it with smallest child
  - and move down ...
- Else stop.

# HEAPIFY(i, H)

```
Begin
   n \leftarrow size(H) - 1;
   Flag \leftarrow true;
   while (i \le |(n-1)/2| and Flag = true)
      min \leftarrow i;
      if (H[i] > H[2i + 1])
         \min \leftarrow 2i + 1;
      if (2i + 2 \le n \text{ and } H[min] > H[2i + 2])
         \min \leftarrow 2i + 2:
      if (\min \neq i)
         swap(H[i], H[min]);
         i \leftarrow min;
      else
         Flag \leftarrow false;
End
```

# Complexity

• How many nodes of height *h* can there be in a complete binary tree of *n* nodes?

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- **Note:** Each sub-tree is also a complete binary tree.
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- : the # nodes of height h is bounded above by  $\frac{n}{2^h}$ .
- Hence, time complexity of building a heap is given by

$$\sum_{h=1}^{\log n} \frac{n}{2^h} \cdot \mathcal{O}(h) \leq cn \sum_{h=1}^{\log n} \frac{h}{2^h} < cn \sum_{h=1}^{\infty} \frac{h}{2^h}$$

$$= cn \cdot \frac{(1/2)}{(1-1/2)^2} \quad [\because \sum_{i=1}^{\infty} ix^i = \frac{x}{(1-x)^2} \text{ for } |x| < 1]$$

$$= 2cn = \mathcal{O}(n).$$

#### Heapsort

### Heapsort

• Build heap *H* on the given *n* elements.

```
    While (H is not empty)
    x ← EXTRACT-MIN(H);
    print x;
```

• Complexity:  $\mathcal{O}(n \log n)$ .

#### Heapsort

#### Homework:

- Implement a BINARY-MAX-HEAP in C.
- Use it to sort numbers in an decreasing order.
- For a given n,
  - Take (fixed) *m* many random inputs of size *n* each.
  - Compute the average time take by your Heapsort program.
- Repeat the above process for  $n = 4, 5, \dots, 1000$ .
- Plot the values in a graph where *x*-axis is *n* and *y*-axis denotes the average time taken for each *n*.

Thank You for your kind attention!

#### Books and Other Materials Consulted

Introduction to Algorithms by Thomas H Cormen, Charles E Leiserson, Ronald L Rivest, Clifford Stein.

Taken from Prof. Surendar Baswana (CSE, IIT Kanpur) lecture slides.

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# Questions!!