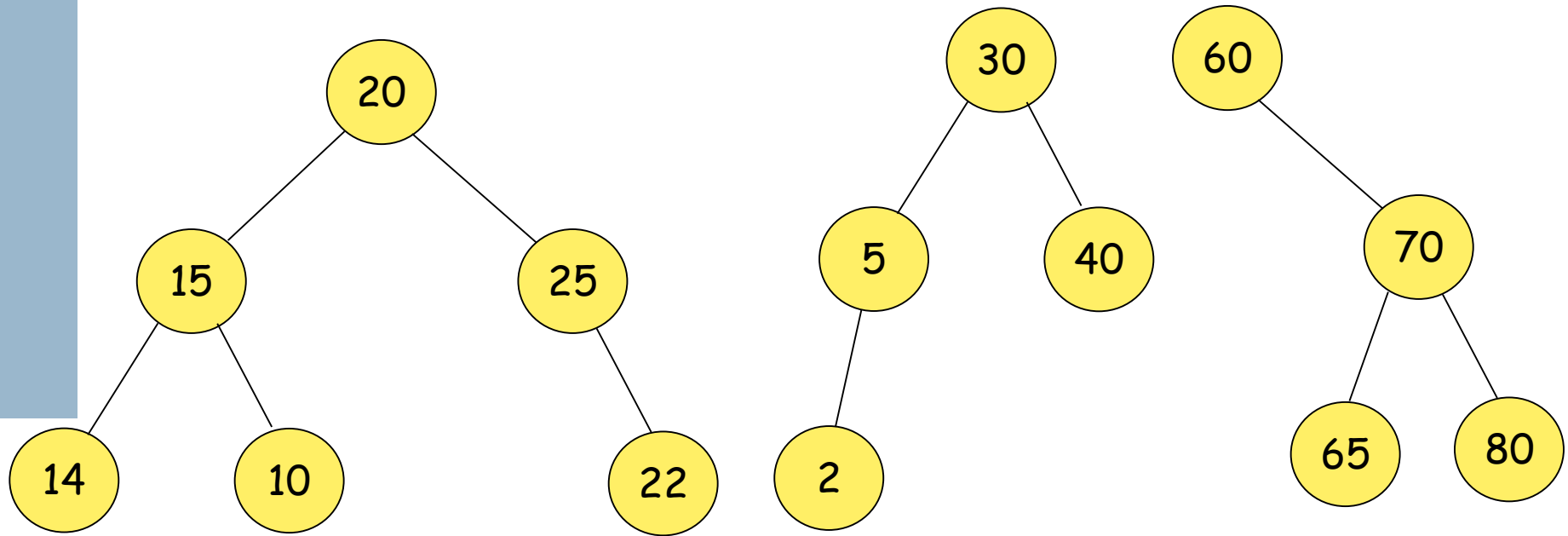


# Binary Search Tree

- Definition: A binary search tree is a binary tree. It may be empty. If it is not empty then it satisfies the following properties:
  - Every node has exactly one key and no two nodes have the same key (i.e., the keys in the tree are distinct)
  - The keys (if any) in the left subtree are smaller than the key in the root.
  - The keys (if any) in the right subtree are larger than the key in the root.
  - The left and right subtrees are also binary search trees.
- Inorder traversal of BST results in ascending order of elements

# Binary Trees



Not binary  
search tree

Binary search  
trees

# Recursive function to create a BST

```
Nodeptr CreateBST(Nodeptr root, int item){
    if (root==NULL){
        root = getnode();
        root->data= item;
        root->lchild=root->rchild = NULL;
        return root;
    }
    else
        if (item<root->data)
            root->lchild = CreateBST(root->lchild, item);
        else
            if (item>root->data)
                root->rchild = CreateBST(root->rchild, item);
            else
                printf("Duplicates are not allowed\n");
    return root;
}
```

# Searching in A Binary Search Tree

- If the root is NULL, then this is an empty tree. No search is needed.
- If the root is not NULL, compare the  $x$  with the key of root.
  - If  $x$  equals to the key of the root, then it's done.
  - If  $x$  is less than the key of the root, then no elements in the right subtree can have key value  $x$ . We only need to search the left tree.
  - If  $x$  larger than the key of the root, only the right subtree is to be searched.

# Searching a BST

```
typedef struct node *Nodeptr;
struct node{
    int data;
    Nodeptr rchild;
    Nodeptr lchild;
};
Nodeptr search(Nodeptr root,int key)
{
    /* return a pointer to the node that contains key.
       If there is no such node, return NULL */

    if (root==NULL) return NULL;
    if (key == root->data) return root;
    if (key < root->data)
        return search(root->lchild, key);
    return search(root->rchild,key);
}
```

# Iterative Searching Algorithm

```
Nodeptr itersearch(Nodeptr root, int key)
{
    while (root) {
        if (key == root->data) return root;
        if (key < root->data)
            root = root->lchild;
        else root = root->rchild;
    }
    return NULL;
}
```

## Other operations:

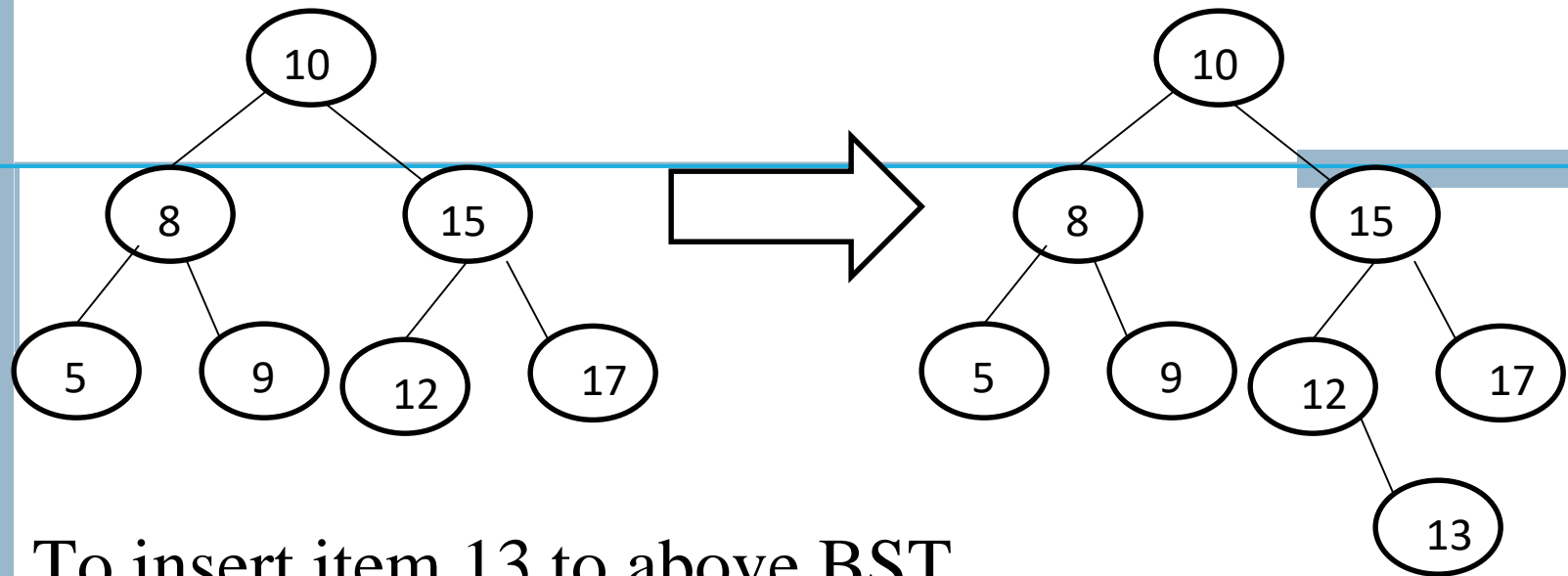
1. Finding the maximum element in BST: maximum element will always be the last right child in a BST. Move to the rightmost node in a BST and you will end up in the maximum element.
2. Finding the minimum element: Move to the leftmost child and you will reach the least element in BST.
3. Finding the height of a tree: height is nothing but maximum level in the tree plus one. It can be easily found using recursion.

# Insertion To A Binary Search Tree

---

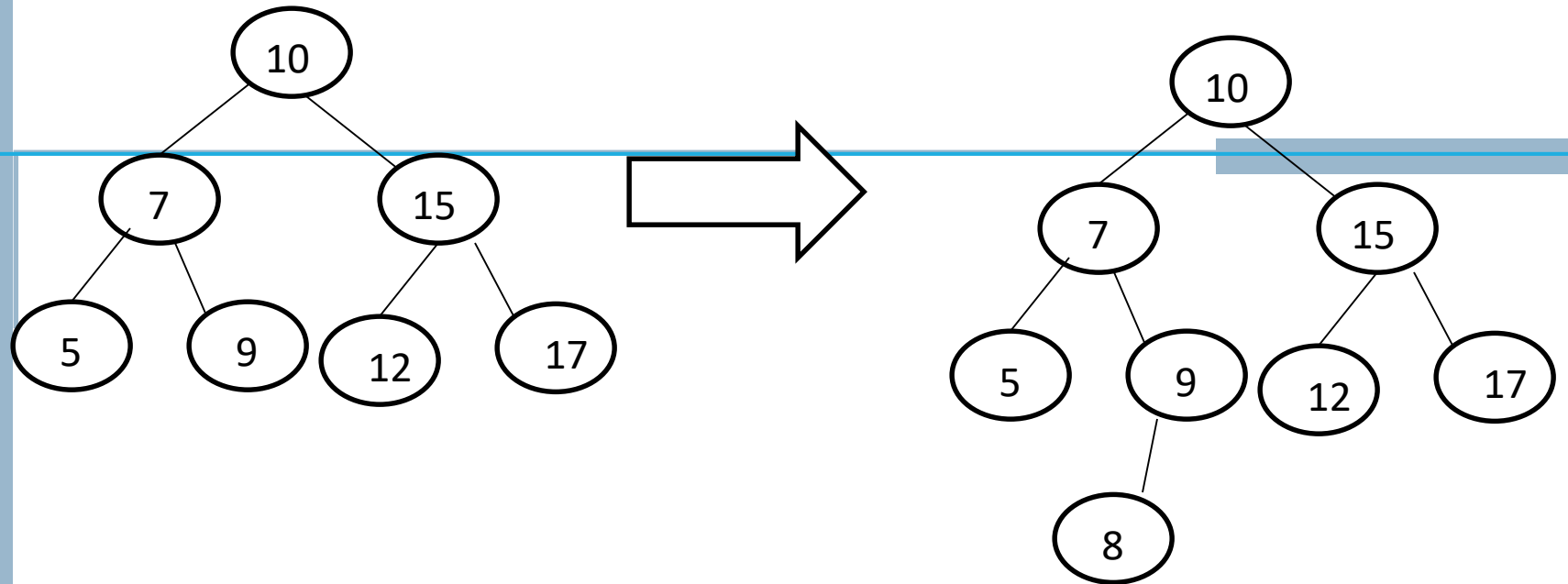
- Before insertion is performed, a search must be done to make sure that the value to be inserted is not already in the tree.
  - If the search fails, then we know the value is not in the tree. So it can be inserted into the tree.
  - If item is lesser than the root item, move to left or else move to the right of root node.
  - This process is repeated until the correct position is found.
-





To insert item 13 to above BST

- Compare with the root item.  $13 > 10$ , hence move to right and reach 15.
- Now  $13 < 15$ , So go to left and reach 12.
- $13 > 12$ , hence move right.
- Now the correct position is found and hence insert the new node to the right of 12.



To insert 8 into the above tree

- Compare with root item.  $8 < 10$ , hence move left and reach 7.
- Now  $8 > 7$ . So move right and reach 9.
- $8 < 9$ . Move left and the correct position is obtained.
- Insert 8 to the left of 9.

# Insertion Into A Binary Search Tree

```
typedef struct node *Nodeptr;

struct node{
    int data;
    Nodeptr rchild;
    Nodeptr lchild;
};

void Insert(Nodeptr *root, int item){

    Nodeptr temp= getnode();
    temp->data = item;
    temp->lchild = NULL;
    temp->rchild = NULL;
    if (*root==NULL) {
        *root = temp; return;
    }

    Nodeptr parent, cur;
```

```
/*traverse until correct position is
found*/

    parent=NULL;
    cur=*root;
    while(cur){
        parent=cur;
        if (item==cur->data ){
            printf("Duplicates Not allowed");
            free(temp);
            return;
        }
        else if (item<cur->data)
            cur=cur->lchild;
        else
            cur=cur->rchild;
    }
    if (item<parent->data)
        parent->lchild = temp;
    else
        parent->rchild = temp;
    return;
}
```

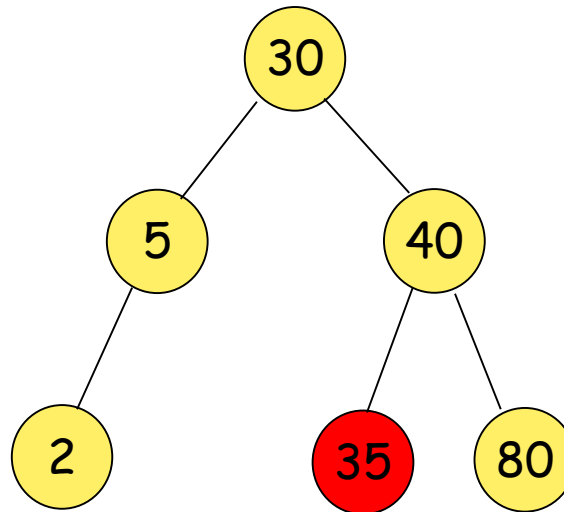
# Deletion From A Binary Search Tree

---

- Delete a leaf node
    - A leaf node which is a right child of its parent
    - A leaf node which is a left child of its parent
  - Delete a non-leaf node
    - A node that has one child
    - A node that has two children
      - Replaced by the largest element in its left subtree, or
      - Replaced by the smallest element in its right subtree
-

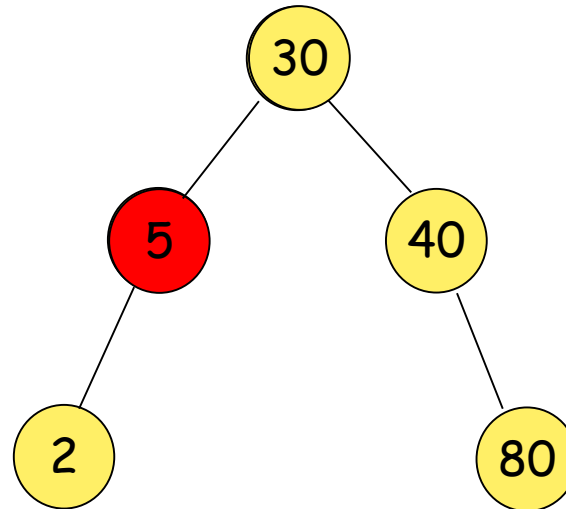
# Deleting From A Binary Search Tree

---



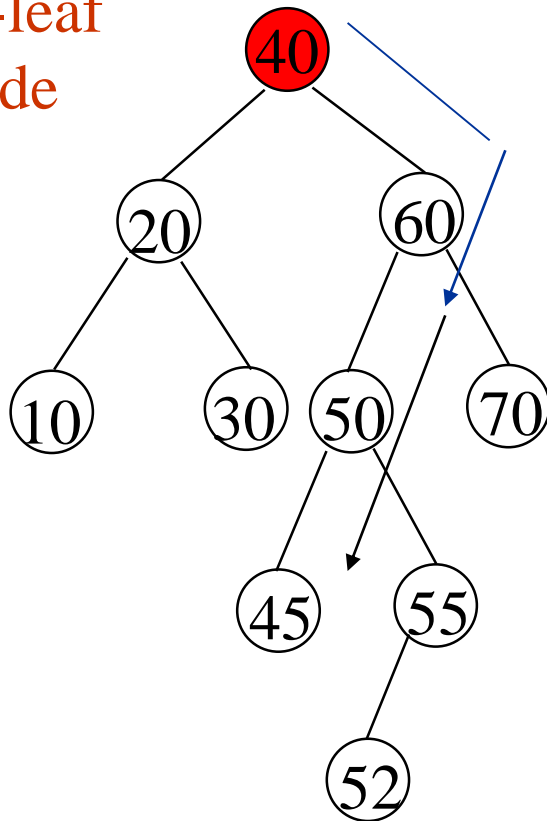
# Deleting From A Binary Search Tree

non-leaf  
node

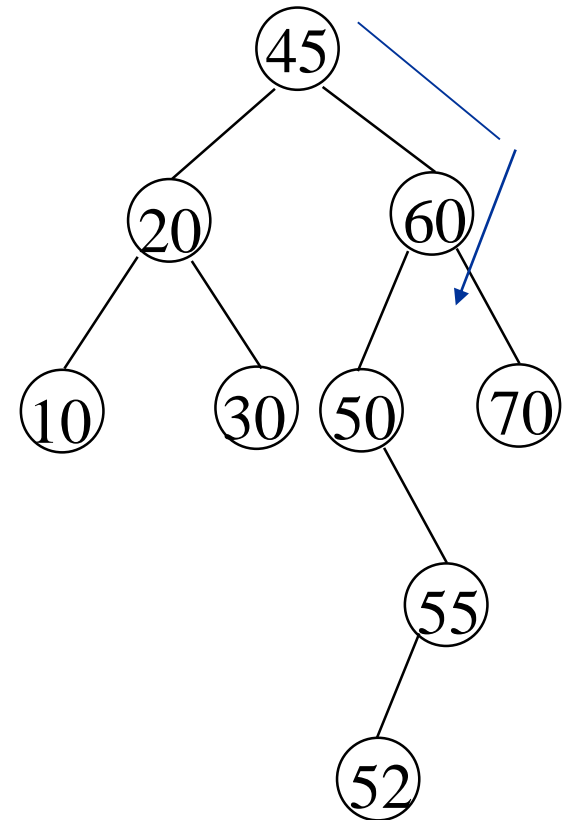


# Deletion from a Binary Search Tree

non-leaf  
node



Before deleting 40



After deleting 40

## Function for BST Delete ( Replaced by the smallest element in its right subtree)

```
void Delete(Nodeptr *root, int item){
    Nodeptr parent, cur;
    Nodeptr q, succ;

    if (*root== NULL){
        printf("Empty Tree\n"); return;
    }
    //traverse the tree until the item is found or entire tree is traversed
    parent = NULL;
    cur = *root;
    while(cur && (cur->data!= item)){
        parent = cur;
        if (item<cur->data)
            cur = cur->lchild;
        else
            cur = cur->rchild;
    }
    if (cur==NULL) {
        printf("Item Not Found\n");
        return;
    }
}
```



## Function for BST Delete ( Replaced by the smallest element in its right subtree)

```
//item found and check for case 1
if (cur->lchild == NULL) //node to be deleted has empty left subtree
    q = cur->rchild;    //get the address of right subtree
else if (cur->rchild == NULL) //node to be deleted has empty right subtree
    q = cur->lchild;    //get the address of left subtree
else //interior node
{
    //find inorder successor->smallest element in the right subtree
    parent = cur;
    succ = cur->rchild; //get address of rightchild of node to be deleted*/

    while (succ->lchild){ //move to the leftmost node of succ
        parent = succ;
        succ = succ->lchild;
    }
    cur->data = succ->data; //exchange the data of current and succ;
    cur = succ;
    q = cur->rchild;
}
```

## Function for BST Delete ( Replaced by the smallest element in its right subtree)

```
    if (parent == NULL){  
        free(cur);  
        *root = q;  
        return;  
    }  
    if (cur == parent->lchild)  
        parent->lchild = q;  
    else  
        parent->rchild = q;  
    free(cur);  
    return;  
}
```

# Construct a binary tree from its inorder and preorder traversals

inorder [4, 2, 1, 7, 5, 8, 3, 6]

preorder [1, 2, 4, 3, 5, 7, 8, 6]

Step 1: select root from preorder

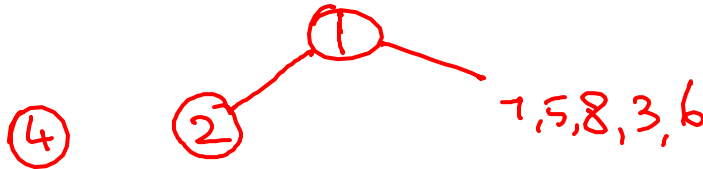
①

Step 2: Look for <sup>nodes of</sup> LST and RST of root in inorder

LST  
(4, 2)

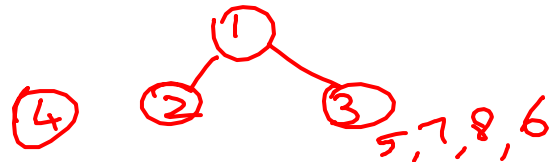
RST  
(7, 5, 8, 3, 6)

Step 3: select root of LST from preorder

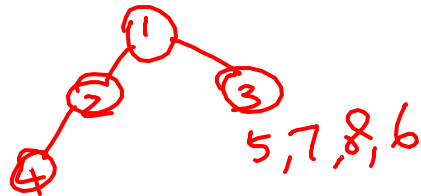


Step 4: Select root of RST from preord

inorder [4, 2, 1, 7, 5, 8, 3, 6]  
preorder [1, 2, 4, 3, 5, 7, 8, 6]



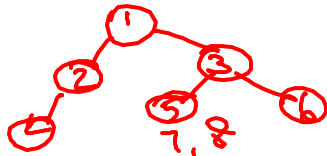
Step 5: Look for LST & RST of 2 in inorder



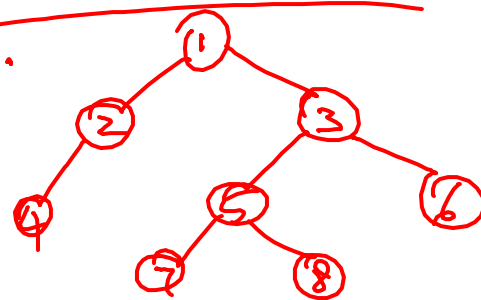
Step 6: Select LST & RST of 3 from inorder



Step 7: Select root of LST of 3



Step 8:



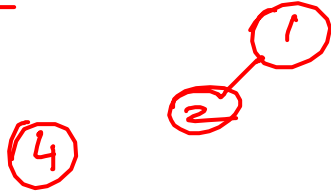
## Construct a binary tree from its inorder and postorder traversals

inorder  $[4, 2, 1, 7, 5, 8, 3, 6]$   
postorder  $[4, 2, 7, 8, 5, 6, 3, 1]$

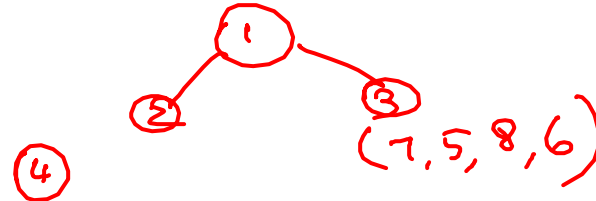
Step 1: select root from postorder

Step 2: LST & RST of ① for inorder  
(4, 2) (7, 5, 8, 3, 6)

Step 3: root of LST of ①



Step 4: Select root of RST of ① from



```
bool printAncestors(struct node *root, int target)
```

```
{
```

```
    if (root == NULL)
```

```
        return false;
```

```
    if (root->data == target)
```

```
        return true;
```

```
    if ( printAncestors(root->left, target) ||  
        printAncestors(root->right, target) )
```

```
    {
```

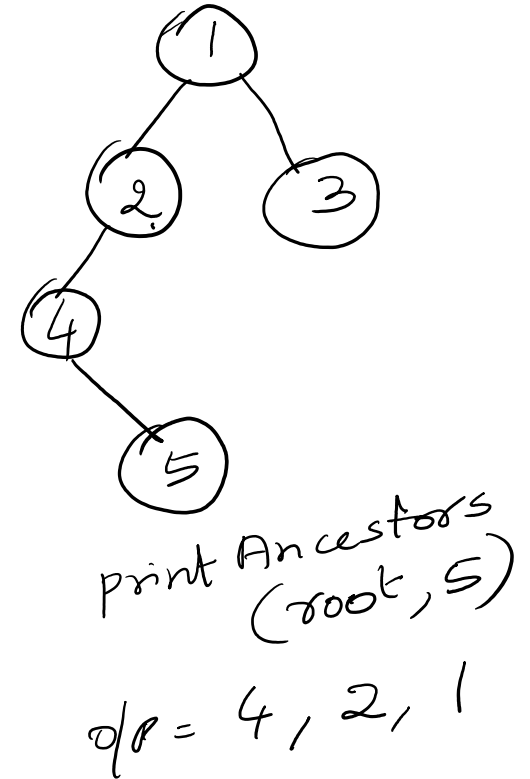
```
        printf("%d ", root->data );
```

```
        return true;
```

```
    }
```

```
    return false;
```

```
}
```



# Threaded Binary Tree

---

- Threads

- In a linked representation of a binary tree, there are more NULL links than actual pointers.
  - In a binary tree with  $n$  nodes containing  $2n$  links, there are  $n+1$  NULL links.
  - Perlis and Thornton devised a way to make use of NULL links.
  - Here the NULL links are replaced by pointers, called *threads*, to other nodes in the tree.
-

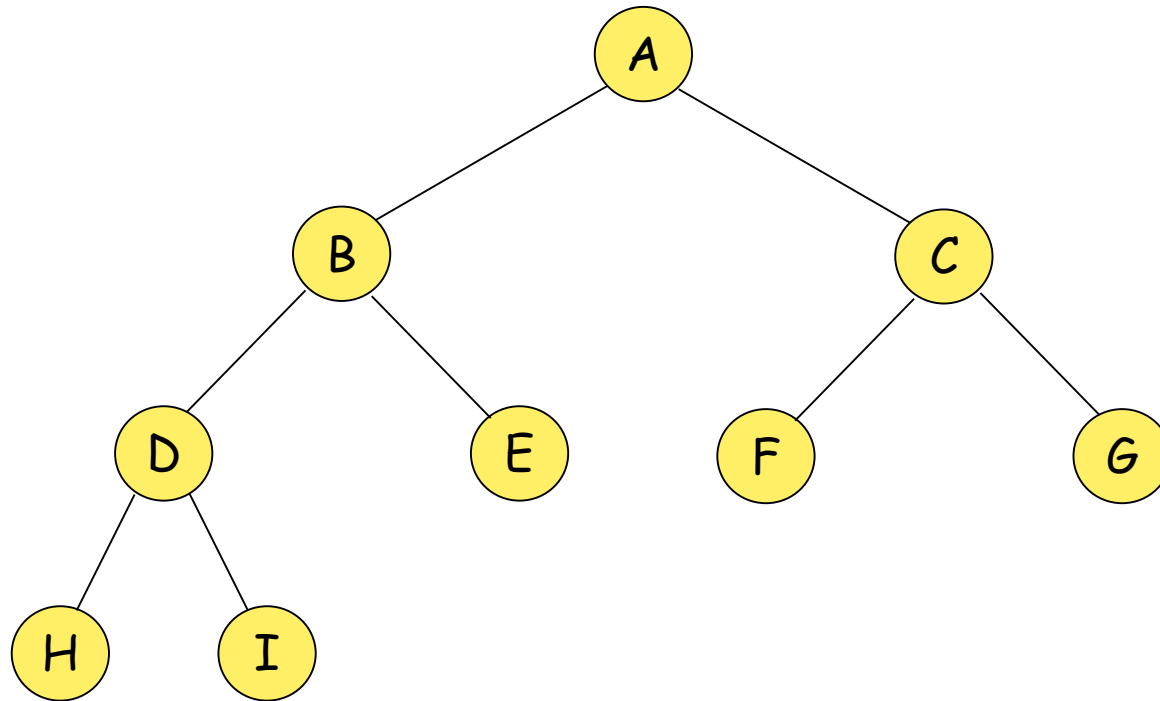
# Threaded Binary Tree

---

- Threading Rules
    - A NULL RightChild field at node p is replaced by a pointer to the node that would be visited after p when traversing the tree in inorder. That is, it is replaced by the inorder successor of p.
    - A NULL LeftChild link at node p is replaced by a pointer to the node that immediately precedes node p in inorder (i.e., it is replaced by the inorder predecessor of p).
-



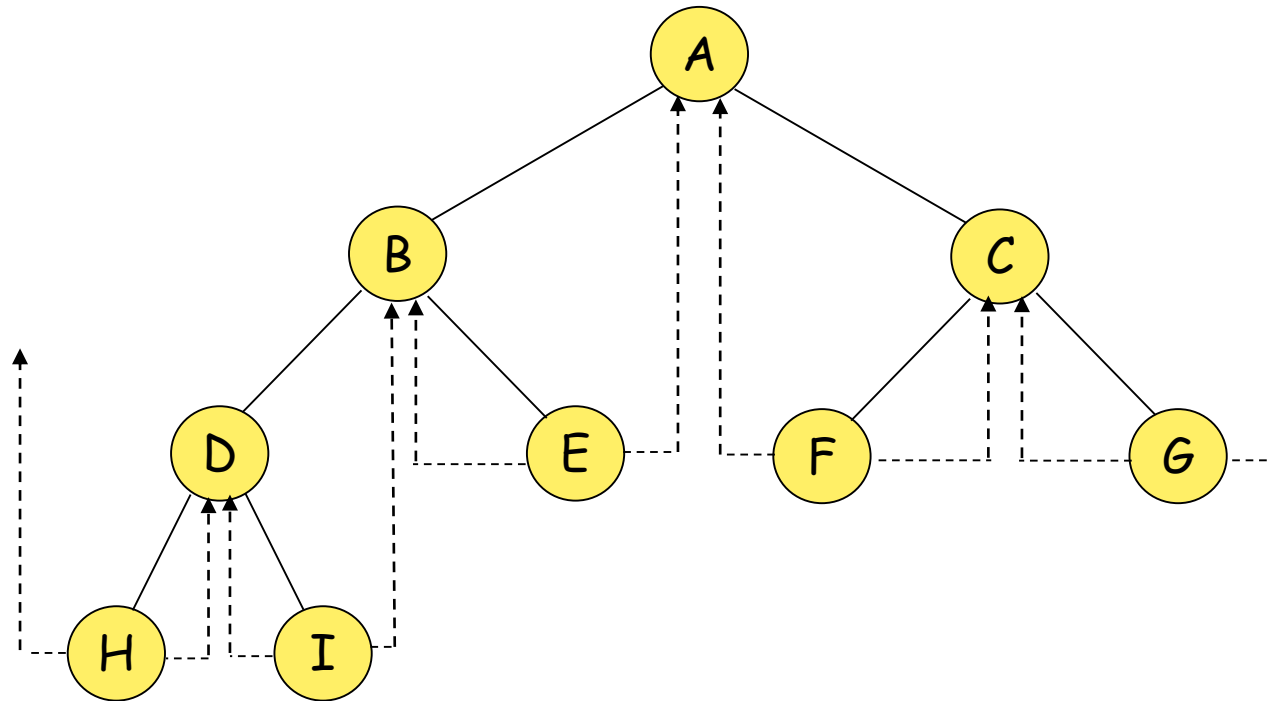
# A Binary Tree



Inorder sequence: H, D, I, B, E, A, F, C, G



# Threaded Tree Corresponding to Given Binary Tree



Inorder sequence: H, D, I, B, E, A, F, C, G



# Threads

- To distinguish between normal pointers and threads, two boolean fields, LeftThread and RightThread, are added to the record in memory representation.
  - t->leftThread= TRUE  
⇒ t->lchild is a **thread**
  - t->leftThread= FALSE  
⇒ t->lchild is a **pointer** to the left child.
  - t->rightThread= TRUE  
⇒ t->rchild is a **thread**
  - t->rightThread= FALSE  
⇒ t->rchild is a **pointer** to the right child.

# Threaded Binary Tree Node Structure Declaration

---

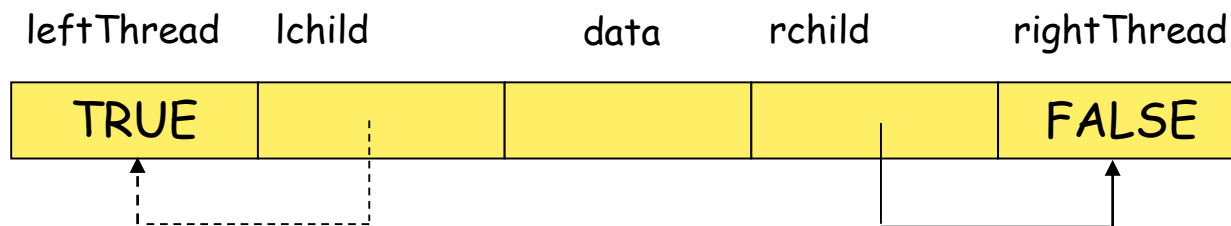
```
typedef struct threadedTree *threadedPointer;
```

```
struct threadedTree{  
    short int leftThread;  
    threadedPointer lchild;  
    char data;  
    threadedPointer rchild;  
    short int rightThread;  
};
```

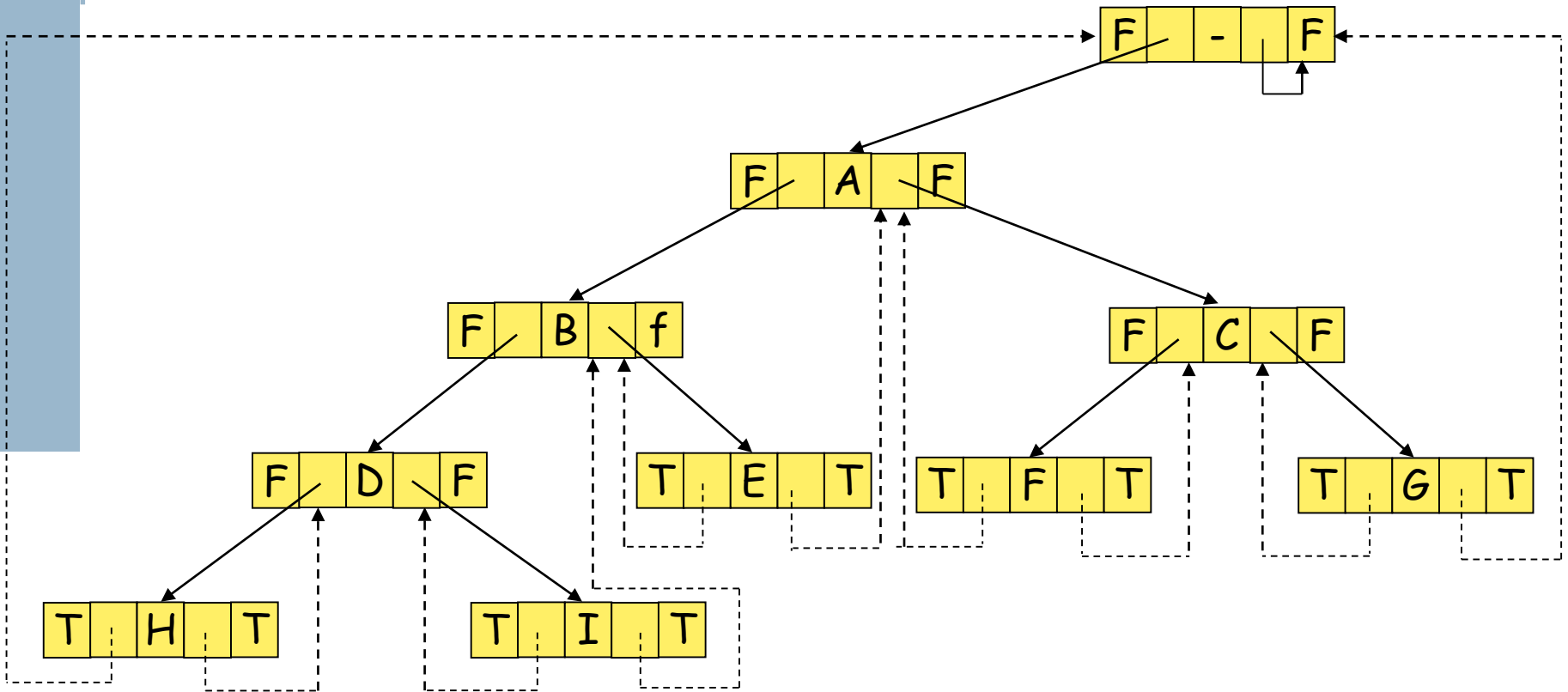
---

# Threads (Cont.)

- To avoid dangling threads, a head node is used in representing a binary tree.
- The original tree becomes the left subtree of the head node.
- Empty Binary Tree



# Memory Representation of Threaded Tree



# Finding the inorder successor without stack

- By using the threads, we can perform an inorder traversal without making use of a stack.

```
threadedPointer insucc(threadedPointer node)
{ //Return the inorder successor of node
    threadedPointer temp = node-> rchild;
    if (node->rightThread==FALSE)
        while (temp->leftThread==FALSE)
            temp = temp -> lchild;
    return temp;
}
```

# Inorder Traversal of a threaded Binary Tree

```
void tinorder(threadedPointer treehead)
{
    threadedPointer temp = treehead;
    while(1){
        temp = insucc(temp);
        if (temp == treehead) break;
        printf("%c", temp->data);
    }
}
```

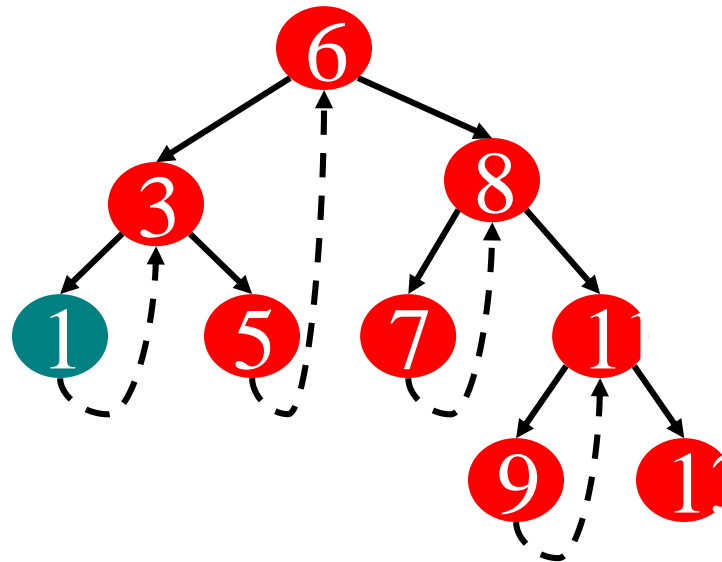


# Threaded Tree Traversal

---

- We start at the leftmost node in the tree, print it, and follow its right thread
- If we follow a thread to the right, we output the node and continue to its right
- If we follow a link to the right, we go to the leftmost node, print it, and continue

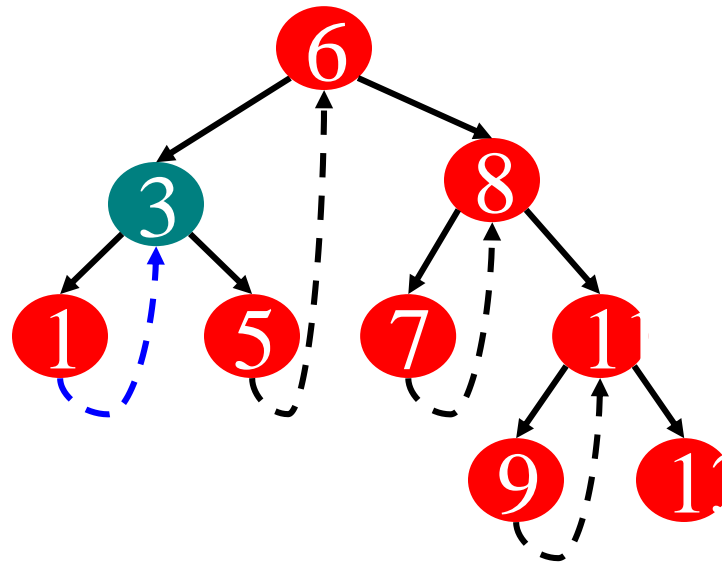
# Threaded Tree Traversal



Output  
1

Start at leftmost node, print it

# Threaded Tree Traversal

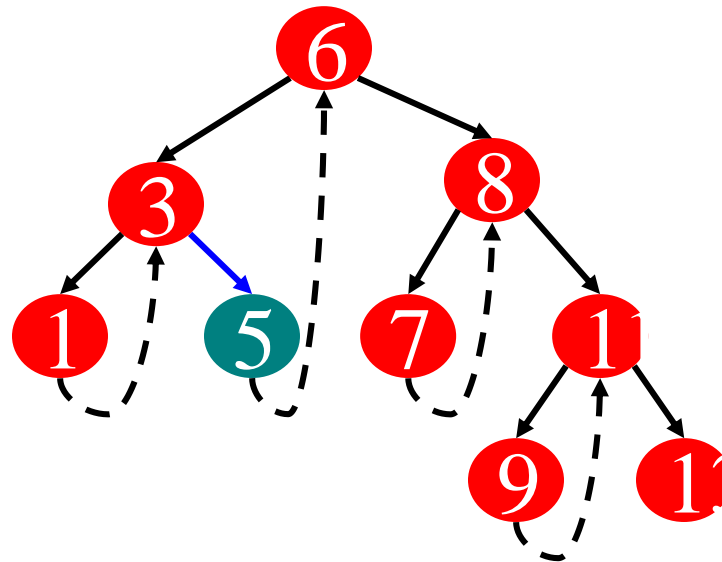


Output

1  
3

Follow thread to right, print node

# Threaded Tree Traversal

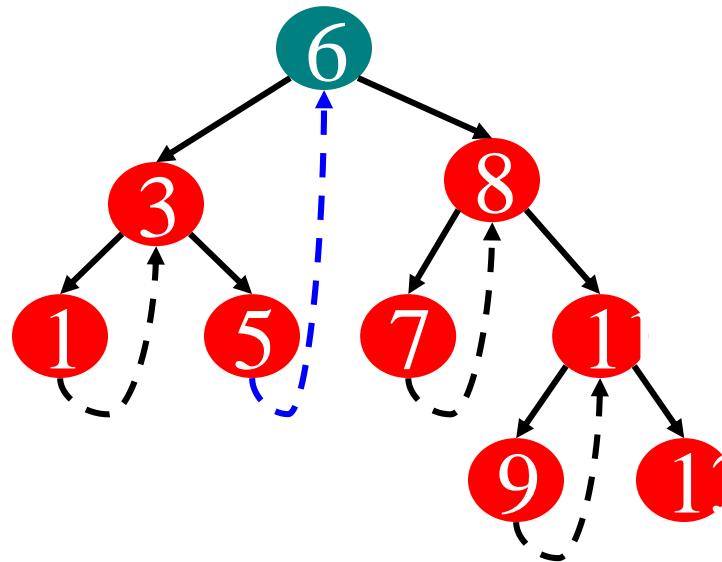


Output

1  
3  
5

Follow link to right, go to  
leftmost node and print

# Threaded Tree Traversal

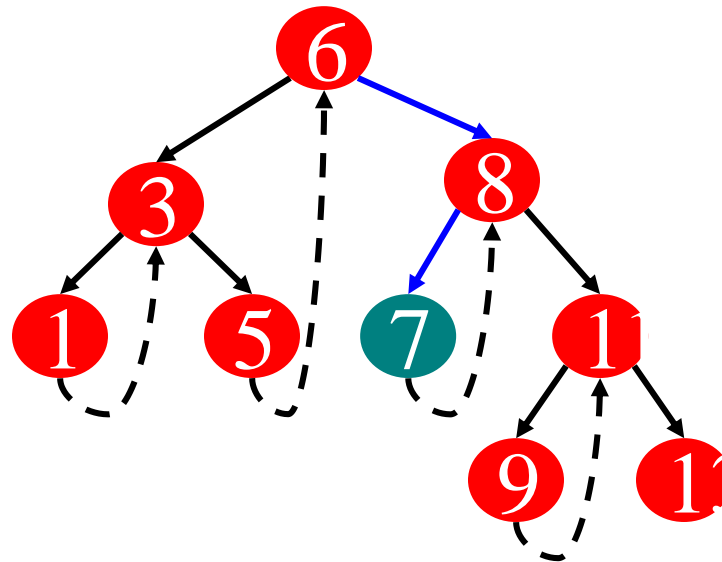


Output

1  
3  
5  
6

Follow thread to right, print node

# Threaded Tree Traversal

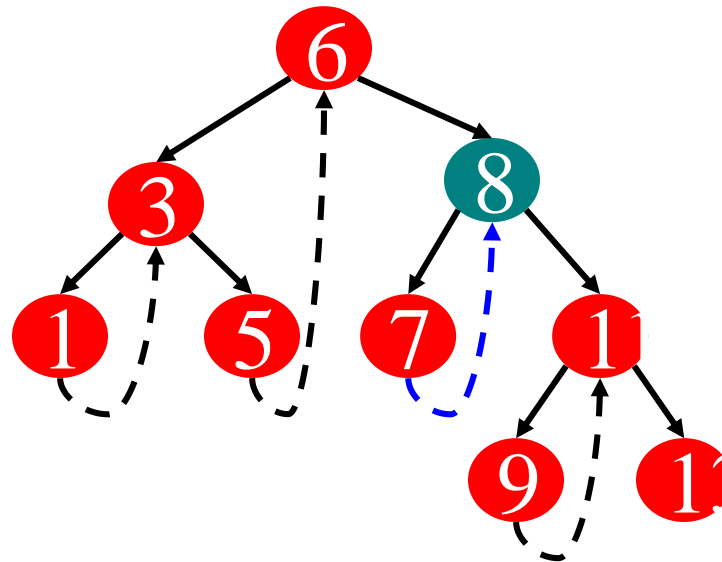


Output

1  
3  
5  
6  
7

Follow link to right, go to  
leftmost node and print

# Threaded Tree Traversal

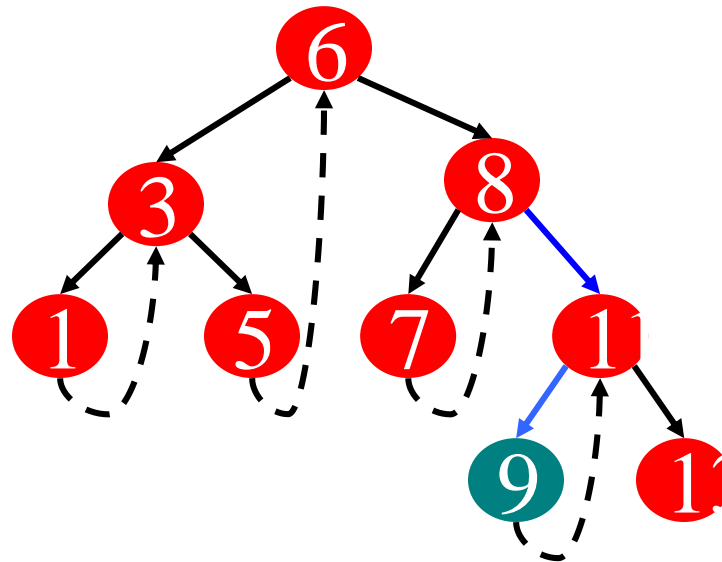


Output

1  
3  
5  
6  
7  
8

Follow thread to right, print node

# Threaded Tree Traversal



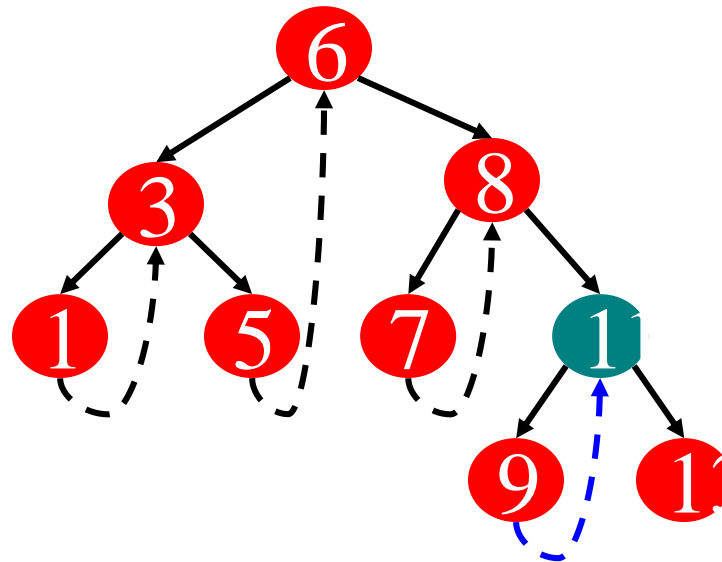
## Output

1  
3  
5  
6  
7  
8  
9

Follow link to right, go to leftmost node and print



# Threaded Tree Traversal

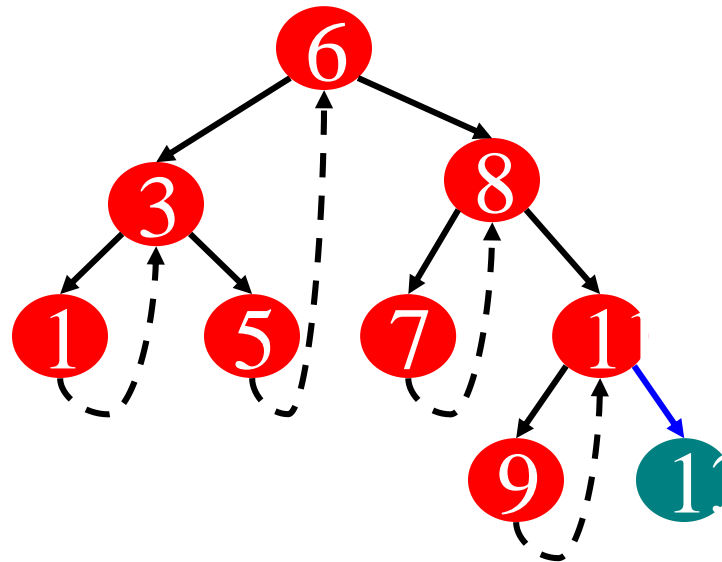


Output

1  
3  
5  
6  
7  
8  
9  
11

Follow thread to right, print node

# Threaded Tree Traversal



Output

1  
3  
5  
6  
7  
8  
9  
11  
13

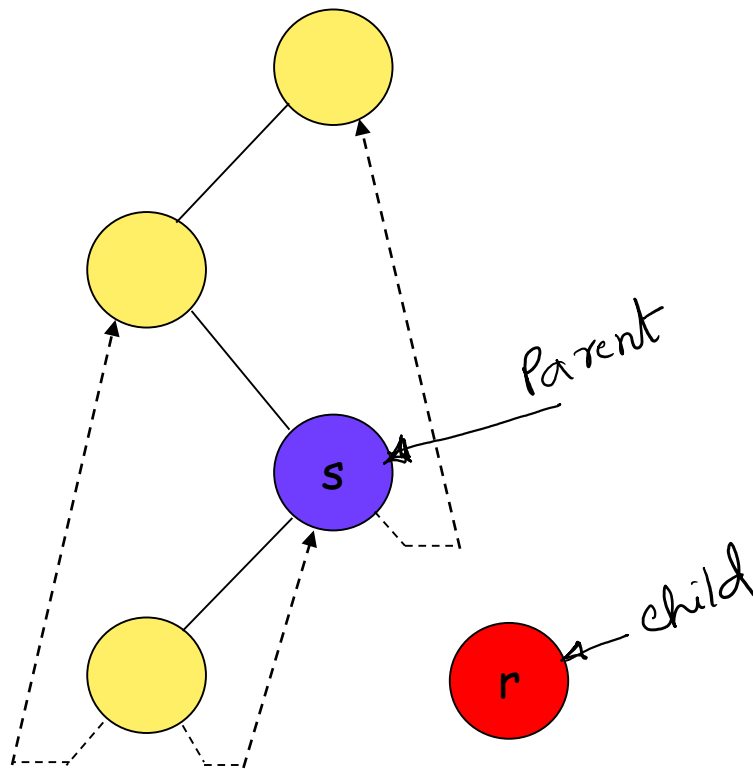
Follow link to right, go to  
leftmost node and print

# Inserting A Node to A Threaded Binary Tree

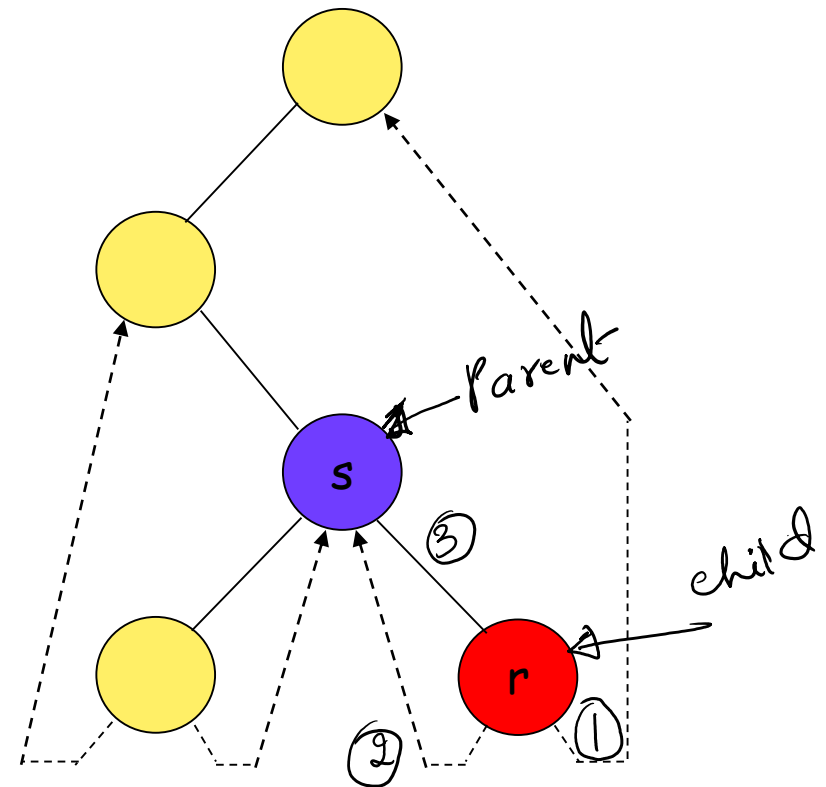
- Inserting a node  $r$  as the right child of a node  $s$ .
  - If  $s$  has an empty right subtree, then the insertion is simple (as shown in diagram next slide)
  - If the right subtree of  $s$  is not empty, then, this right subtree is made the right subtree of  $r$  after insertion. When this is done,  $r$  becomes the inorder predecessor of a node that has a `leftThread==TRUE` field, and consequently there is an thread which has to be updated to point to  $r$ . The node containing this thread was previously the inorder successor of  $s$ . Figure illustrates the insertion for this case.

# Insertion of r As A Right Child of s in A Threaded Binary Tree

case (a) (Empty rt subtree for s)



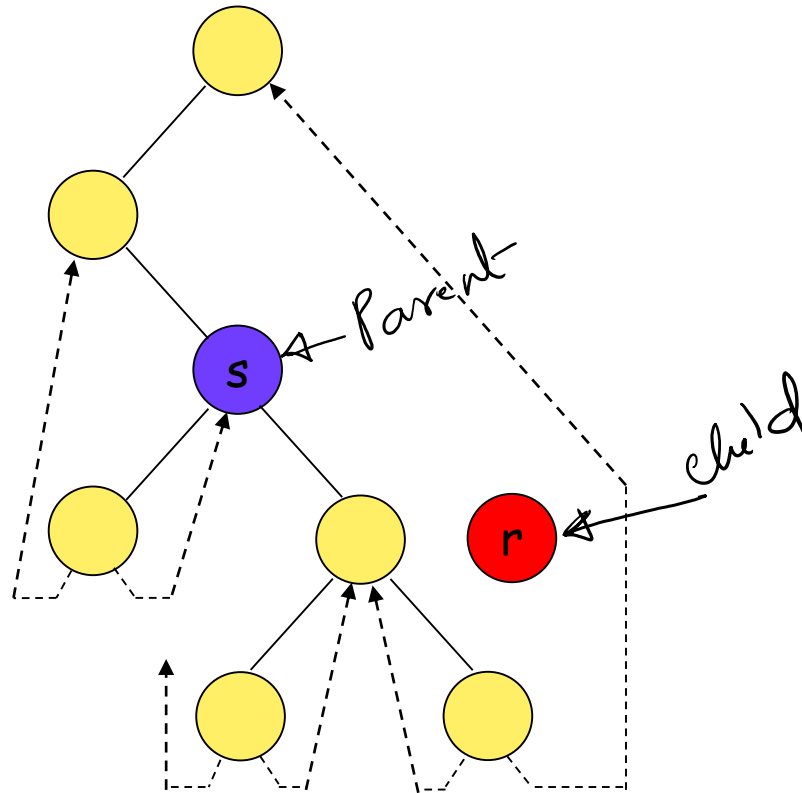
before



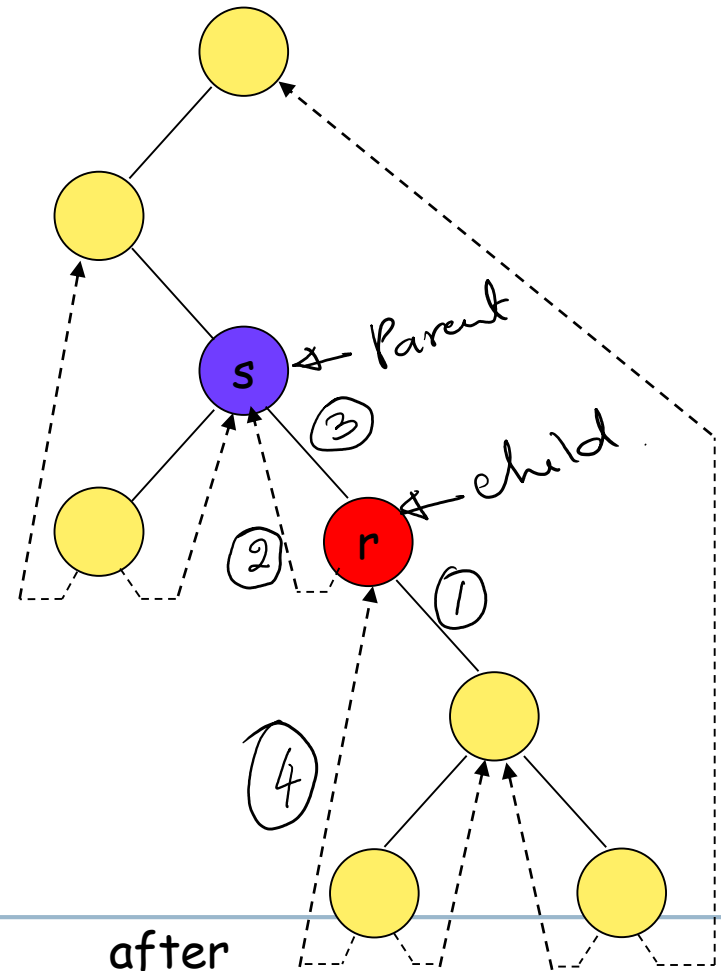
after

# Insertion of r As A Right Child of s in A Threaded Binary Tree (Cont.)

Case (b) (nonempty right subtree for s)



before



after