

CS 352 - ASSIGNMENT 2

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MCQ Answers:

Question 1:

Answer: Option A) Creates a vector of 5 equally spaced points between 1 and 10.

Question 2:

Answer: Option B) $A .* B$

Question 3:

Answer: Option B) The solution to the linear system $A \times C = B$.

Question 4:

Answer: Option B) `unique(v)`

Question 5:

Answer: Option B) Equal to 3

Coding Problems

Question 1

Code:

```
q1.m x +
/MATLAB Drive/CG LAB 2/q1.m
1 % Answering part a - Creating a vector from 1 to 20 with an increment of 2.
2 vector = 1:2:20;
3 disp('Vector from 1 to 20 with an increment of 2:');
4 disp(vector);
5
6 % Answering part b - Finding and printing the square of each element in the vector.
7 squared_vector = vector.^2;
8 disp('Square of each element in the vector:');
9 disp(squared_vector);
10
11 % Answering part c - Extracting and printing all even numbers from the vector.
12 even_numbers = vector(mod(vector, 2) == 0);
13 disp('Even numbers from the vector:');
14 disp(even_numbers);
15 |
```

Result:

```
Command Window
>> q1
Vector from 1 to 20 with an increment of 2:
    1     3     5     7     9    11    13    15    17    19

Square of each element in the vector:
    1     9    25    49    81   121   169   225   289   361

Even numbers from the vector:
>>
```

Question 2

Code:

```
q2.m x +
/MATLAB Drive/CG LAB 2/q2.m
1 % Answering part a - Defining a 3x3 matrix A with random integers.
2 A = randi([1, 10], 3, 3);
3 disp('Matrix A:');
4 disp(A);
5
6 % Answering part b - Calculating the determinant of A.
7 det_A = det(A);
8 disp('Determinant of A:');
9 disp(det_A);
10
11 % Answering part c - Finding and printing the transpose of A.
12 transpose_A = A.';
13 disp('Transpose of A:');
14 disp(transpose_A);
15
```

Result:

```
Command Window
>> q2
Matrix A:
     9    10     3
    10     7     6
     2     1    10

Determinant of A:
   -316

Transpose of A:
     9    10     2
    10     7     1
     3     6    10

>>
```

Question 3

Code:

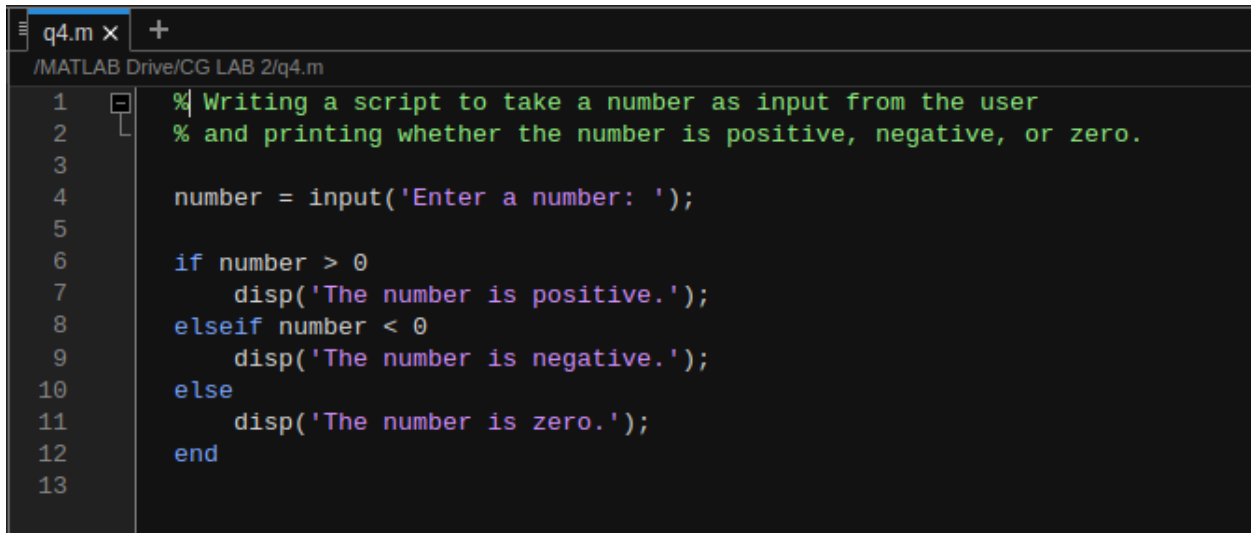
```
q3.m x +  
/MATLAB Drive/CG LAB 2/q3.m  
1 % Solving the system of equations using the matrix method.  
2 % System of equations:  
3 % 2x + y + z = 5  
4 % x - y + z = 2  
5 % x + y + z = 4  
6  
7 % Coefficient matrix A and constant matrix B  
8 A = [2, 1, 1; 1, -1, 1; 1, 1, 1];  
9 B = [5; 2; 4];  
10  
11 solution = A \ B;  
12 disp('Solution of the system of equations (x, y, z):');  
13 disp(solution);  
14
```

Result:

```
Command Window  
>> q3  
Solution of the system of equations (x, y, z):  
    1  
    1  
    2  
  
>>
```

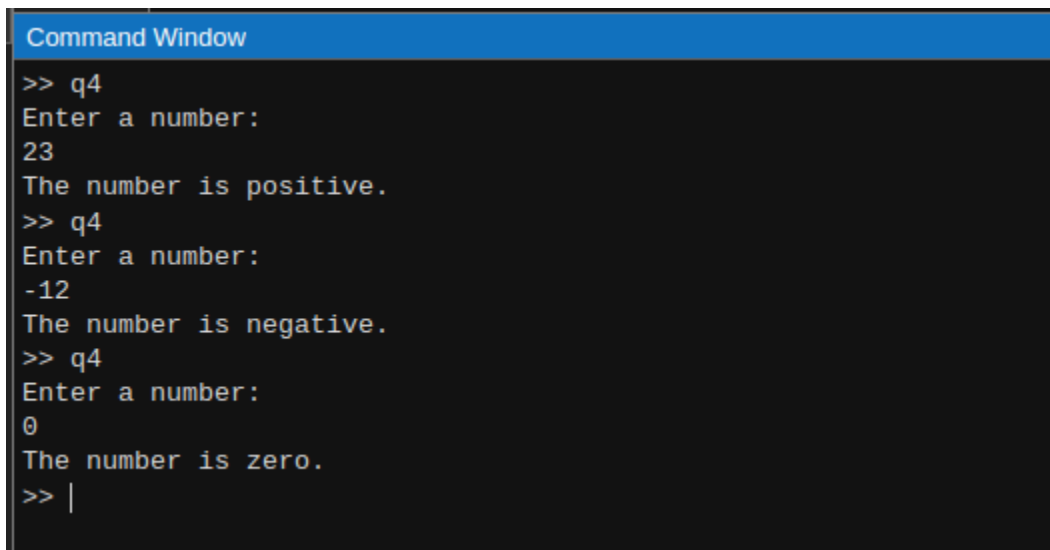
Question 4

Code:



```
q4.m x +
/MATLAB Drive/CG LAB 2/q4.m
1 % Writing a script to take a number as input from the user
2 % and printing whether the number is positive, negative, or zero.
3
4 number = input('Enter a number: ');
5
6 if number > 0
7     disp('The number is positive.');
```

Result:



```
Command Window
>> q4
Enter a number:
23
The number is positive.
>> q4
Enter a number:
-12
The number is negative.
>> q4
Enter a number:
0
The number is zero.
>> |
```

Question 5

Code:

```
q5.m x +
/MATLAB Drive/CG LAB 2/q5.m
1 % Answering part a - Representing the polynomial 3x^2 + 2x + 1 as a vector.
2 poly = [3, 2, 1]; % Coefficients of 3x^2 + 2x + 1
3 disp('Polynomial:');
4 disp('3x^2 + 2x + 1');
5
6 % Answering part b - Finding the derivative of the polynomial and printing it.
7 derivative_poly = poly(1:end-1) .* (length(poly)-1:-1:1);
8 disp('Derivative of the polynomial:');
9 disp(derivative_poly); % 6x + 2
10
11 % Answering part c - Calculating and displaying the value of the polynomial at x=5.
12 x = 5;
13 poly_value = polyval(poly, x);
14 disp(['Value of the polynomial at x = 5: ', num2str(poly_value)]);
15
```

Result:

```
Command Window
>> q5
Polynomial:
3x^2 + 2x + 1
Derivative of the polynomial:
     6     2

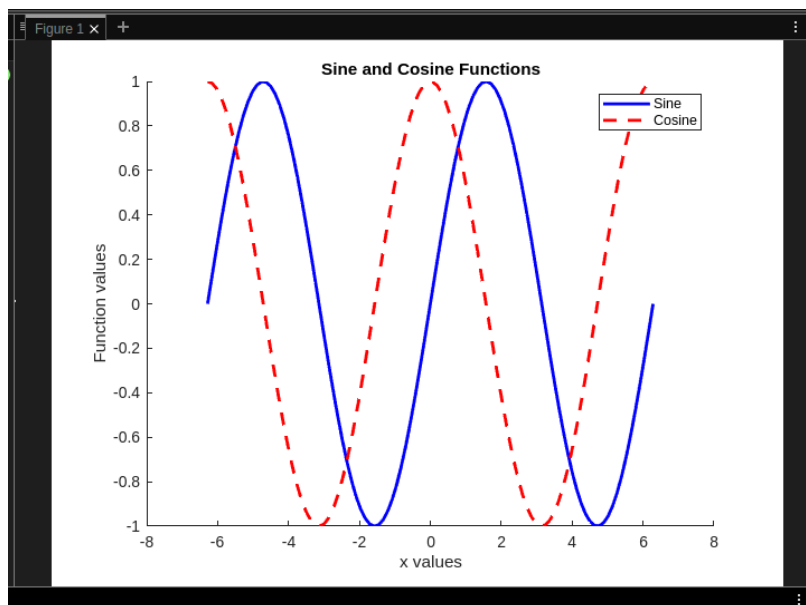
Value of the polynomial at x = 5: 86
>>
```

Question 6

Code:

```
q6.m x +
/MATLAB Drive/CG LAB 2/q6.m
1 % Answering part a, b, and c - Plotting sine and cosine functions
2 % for x values between  $-2\pi$  and  $2\pi$  with different colours, styles, legend,
3
4 x = linspace(-2*pi, 2*pi, 100);
5
6 % Sine and cosine functions
7 y_sin = sin(x);
8 y_cos = cos(x);
9
10 figure;
11 hold on;
12 |
13 % Sine plot (blue line)
14 plot(x, y_sin, 'b-', 'LineWidth', 2);
15
16 % Cosine plot (red dashed line)
17 plot(x, y_cos, 'r--', 'LineWidth', 2);
18
19 % Adding title, labels, and legend
20 title('Sine and Cosine Functions');
21 xlabel('x values');
22 ylabel('Function values');
23 legend('Sine', 'Cosine');
24
25 hold off;
```

Result:

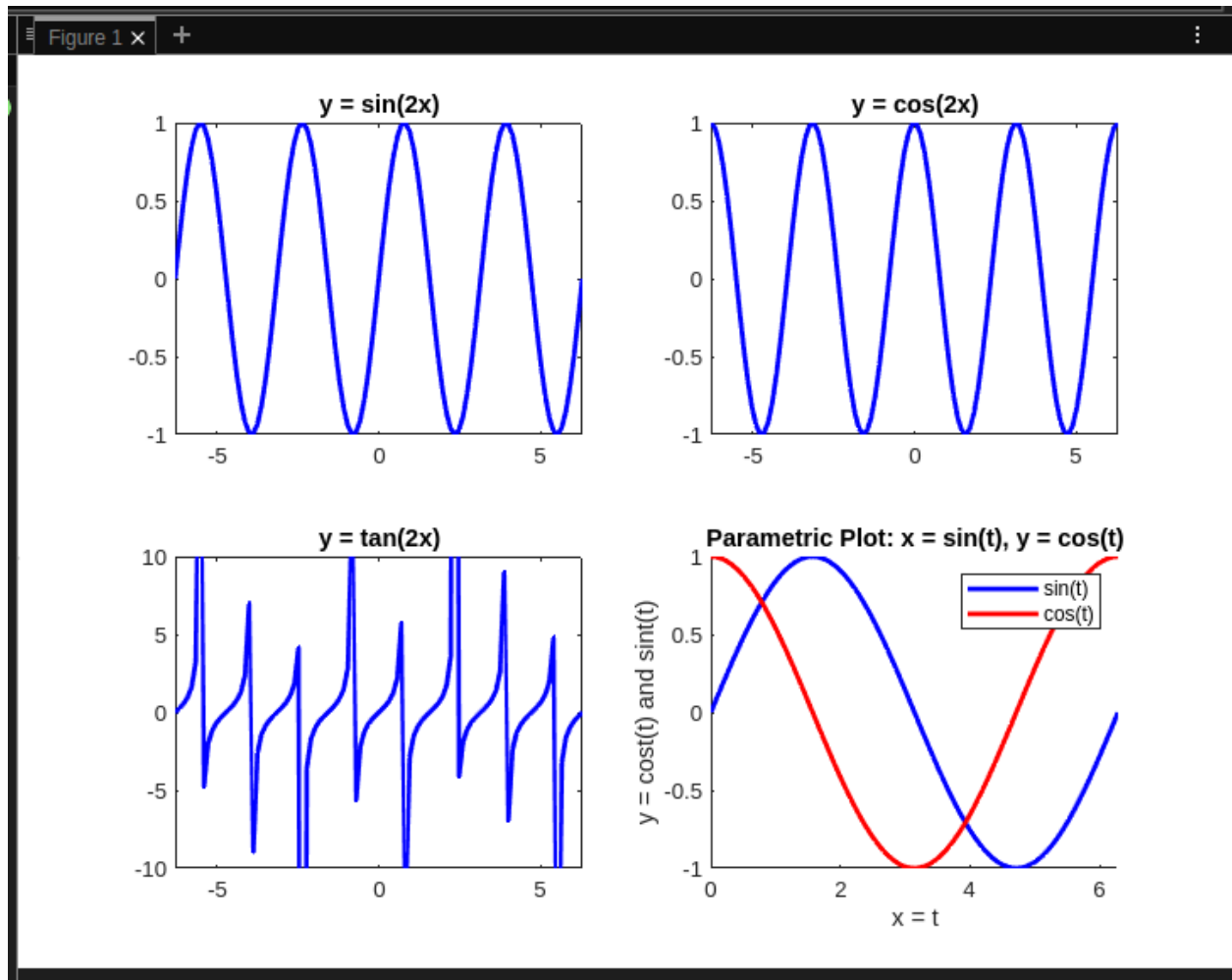


Question 7

Code:

```
q7.m x +
/MATLAB Drive/CG LAB 2/q7.m
1 % Answering part a - Creating subplots for y = sin(2x), y = cos(2x), and y = tan(2x).
2 % Also, using the fourth subplot for a parametric plot of x = sin(t), y = cos(t) for t from 0 to 2π.
3
4 t = linspace(0, 2*pi, 100);
5 x = linspace(-2*pi, 2*pi, 100);
6 y_sin2x = sin(2*x);
7 y_cos2x = cos(2*x);
8 y_tan2x = tan(2*x);
9
10 figure;
11
12 % Subplot 1: y = sin(2x)
13 subplot(2, 2, 1);
14 plot(x, y_sin2x, 'b-', 'LineWidth', 2);
15 title('y = sin(2x)');
16
17 % Subplot 2: y = cos(2x)
18 subplot(2, 2, 2);
19 plot(x, y_cos2x, 'b-', 'LineWidth', 2);
20 title('y = cos(2x)');
21
22 % Subplot 3: y = tan(2x)
23 subplot(2, 2, 3);
24 plot(x, y_tan2x, 'b-', 'LineWidth', 2);
25 title('y = tan(2x)');
26 ylim([-10, 10]); % Limiting y-axis values to avoid extreme values of tan
27
28 % Subplot 4: Parametric plot of x = sin(t), y = cos(t)
29 subplot(2, 2, 4);
30 hold on;
31 plot(t, sin(t), 'b-', 'LineWidth', 2); % Plot sin(t) in blue
32 plot(t, cos(t), 'r-', 'LineWidth', 2); % Plot cos(t) in red
33 title('Parametric Plot: x = sin(t), y = cos(t)');
34 xlabel('x = t');
35 ylabel('y = cost(t) and sint(t)');
36 legend('sin(t)', 'cos(t)');
37 hold off;
38
```


Result:



For Code , refer GitHub:

<https://github.com/arnavjain2710/Computer-Graphics-Lab/tree/main/LAB%202>