

# MA 203 Complex Analysis and Differential Equations-II

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Lecture-2

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# Recap

- Periodic functions of period  $2\pi$
- Orthogonality of the trigonometric system
- The *Fourier series* representation of  $f$
- A Fourier series for  $f$  does NOT always converge to  $f$ ;
- Piecewise smooth and representation by a Fourier series
- An example

Let  $f : \text{Dom}(f) \subset \mathbb{R} \rightarrow \mathbb{R}$  be a periodic function with period  $2L$ .

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The idea is to employ a change of scale that gives a periodic function  $g(y)$  of period  $2\pi$ .

We introduce a new variable  $y$  and a new function

$$g : \text{Dom}(g) \subset \mathbb{R} \rightarrow \mathbb{R} \quad \text{by} \quad g(y) = f\left(\frac{L}{\pi}y\right).$$

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$$g : Dom(g) \subset \mathbb{R} \rightarrow \mathbb{R} \quad \text{by} \quad g(y) = f\left(\frac{L}{\pi}y\right).$$

Now,  $g$  is a periodic function with period  $2\pi$ . Hence, the Fourier series for the function  $g(y) = f\left(\frac{L}{\pi}y\right)$  is given by

$$\frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos ny + b_n \sin ny), \quad (1)$$

where

$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} g(y) \cos ny \, dy, \quad n = 0, 1, 2, 3, \dots \quad (2a)$$

$$b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} g(y) \sin ny \, dy, \quad n = 1, 2, 3, \dots \quad (2b)$$

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Now, using the scale  $y = \pi x/L$ , we have  $dy = (\pi/L) dx$ , the Fourier series for the function  $f(x) = g\left(\frac{\pi x}{L}\right)$  is given by [use the scaling in (1) and (2)]

$$\frac{a_0}{2} + \sum_{n=1}^{\infty} \left[ a_n \cos\left(\frac{n\pi}{L}x\right) + b_n \sin\left(\frac{n\pi}{L}x\right) \right] \quad (3)$$



with the Fourier coefficients given by

$$\begin{aligned} a_n &= \frac{1}{\pi} \int_{-\pi}^{\pi} g(y) \cos ny \, dy = \frac{1}{\pi} \int_{-L}^L g\left(\frac{\pi}{L}x\right) \cos\left(\frac{n\pi}{L}x\right) \times \frac{\pi}{L} dx \\ &= \frac{1}{L} \int_{-L}^L f(x) \cos\left(\frac{n\pi}{L}x\right) dx, \quad n = 0, 1, 2, 3, \dots \end{aligned}$$

(4a)

with the Fourier coefficients given by

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with the Fourier coefficients given by

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(4b)

Here, the fact  $g(\pi x/L) = f(x)$  has been used.  
This leads to the following definition.

# Definition 1 (Fourier series of a function with period $p = 2L$ )

Let  $f(x)$  be a periodic function with period  $2L$ . The series

$$\frac{a_0}{2} + \sum_{n=1}^{\infty} \left[ a_n \cos \left( \frac{n\pi}{L} x \right) + b_n \sin \left( \frac{n\pi}{L} x \right) \right], \quad (5)$$

with the coefficients

$$a_n = \frac{1}{L} \int_{-L}^L f(x) \cos \left( \frac{n\pi}{L} x \right) dx, \quad n = 0, 1, 2, 3, \dots \quad (6a)$$

$$b_n = \frac{1}{L} \int_{-L}^L f(x) \sin \left( \frac{n\pi}{L} x \right) dx, \quad n = 1, 2, 3, \dots, \quad (6b)$$

is referred to as the *Fourier series* of  $f(x)$ . The coefficients  $a_0, a_1, a_2, a_3, \dots, b_1, b_2, b_3, \dots$  in (5) are again referred to as the *Fourier coefficients* of  $f(x)$ .

## Definition 2

A function  $f : [a, b] \rightarrow \mathbb{R}$  is said to be **piecewise smooth** (or sectionally smooth) if this interval can be divided into a finite number of subintervals such that

- 1  $f$  has a continuous derivative  $f'$  in the interior of each of these subintervals,
- 2 and both  $f(x)$  and  $f'(x)$  approach finite limits as  $x$  approaches either endpoint of each of these subintervals from its interior.

In other words, we may say that  $f$  is piecewise smooth on  $[a, b]$  if both  $f$  and  $f'$  are piecewise continuous on  $[a, b]$ .

### Theorem 3 (Representation by a Fourier series)

Let  $f : [-L, L] \rightarrow \mathbb{R}$  be periodic with period  $2L$  and *be piecewise smooth* in the interval  $[-L, L]$ . Then, the Fourier series of  $f$ , i.e.,  $S_f(x)$  converges at every point  $x$  to the value

$$\frac{f(x+) + f(x-)}{2} \quad (7)$$

where  $f(x+)$  is the right hand limit of  $f$  at  $x$  and  $f(x-)$  is the left hand limit of  $f$  at  $x$ . In particular, if  $f$  is also continuous at  $x$ , the value (7) reduces to  $f(x)$  and  $S_f(x) = f(x)$ .

# Fourier series of even and odd functions

## Definition 4

A function  $f : \text{Dom}(f) \subset \mathbb{R} \rightarrow \mathbb{R}$  is said to be an **even** function if  $f(-x) = f(x)$  for all  $x$  and a function  $g : \text{Dom}(g) \subset \mathbb{R} \rightarrow \mathbb{R}$  is said to be an **odd** function if  $g(-x) = -g(x)$  for all  $x$ .

- 1** For an even function  $f$  and an odd function  $g$ , we have the following:

$$\int_{-L}^L f(x) \, dx = 2 \int_0^L f(x) \, dx \quad \text{and} \quad \int_{-L}^L g(x) \, dx = 0.$$

Therefore, it is not difficult to obtain the following theorem.

## Theorem 5

- (i) *The Fourier series of an even function  $f$  of period  $2L$  is a **Fourier cosine series***

$$\frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos\left(\frac{n\pi}{L}x\right), \quad (8)$$

*with the coefficients*

$$a_n = \frac{2}{L} \int_0^L f(x) \cos\left(\frac{n\pi}{L}x\right) dx, \quad n = 0, 1, 2, 3, \dots \quad (9a)$$



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- (ii) *The Fourier series of an odd function  $f$  of period  $2L$  is a **Fourier sine series***

$$\sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi}{L}x\right), \quad (10)$$

*with the coefficients*

$$b_n = \frac{2}{L} \int_0^L f(x) \sin\left(\frac{n\pi}{L}x\right) dx, \quad n = 1, 2, 3, \dots \quad (11)$$

# Even function of period $2\pi$

- 1 Even function of period  $2\pi$ :** If  $f(x)$  is even and  $L = \pi$ , the Fourier series of  $f(x)$  is the Fourier cosine series, given by

$$\frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos nx \quad (12)$$

with coefficients

$$a_n = \frac{2}{\pi} \int_0^{\pi} f(x) \cos nx \, dx, \quad n = 0, 1, 2, 3, \dots \quad (13)$$

# Odd function of period $2\pi$

- 1 Odd function of period  $2\pi$ :** If  $f(x)$  is odd and  $L = \pi$ , the Fourier series of  $f(x)$  is the Fourier sine series, given by

$$\sum_{n=1}^{\infty} b_n \sin nx \quad (14)$$

with coefficients

$$b_n = \frac{2}{\pi} \int_0^{\pi} f(x) \sin nx \, dx, \quad n = 1, 2, 3, \dots \quad (15)$$

# Contents

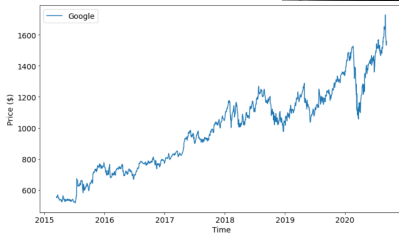
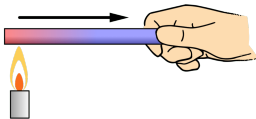
- Classification of linear second order PDE's in two variables.
- Laplace, wave, and heat equations using separation of variables.
- D' Alembert solution to the wave equations.
- Vibration of a circular membrane.
- Heat equation in the half space.

# Why PDE?

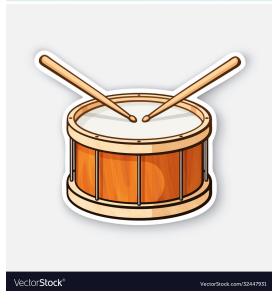
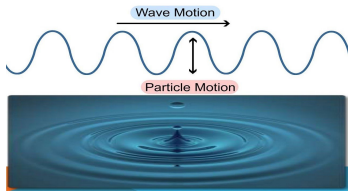
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# PDE

## Definition 6

A *partial differential equation* (PDE) is an equation involving one or more partial derivatives of an (unknown) function, let us say  $u$ , that depends on two or more variables, often time  $t$  and one or several variables in space.



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**The independent variables will be denoted by  $x$  and  $y$ , while the dependent variable by  $u$ , i.e., by  $u = u(x, y)$ .**

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$$\frac{\partial u}{\partial t} = u \frac{\partial u}{\partial x} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^3 u}{\partial z^3}, \quad u_{xx} + u u_y + u_{yz} = x^2 + y^2 + u$$

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## Definition 9

A PDE is said to be **linear** if the dependent variable and its partial derivatives occur only in the first degree and are not multiplied. A partial differential equation which is not linear is called a **non-linear**.

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A PDE is said to be **semilinear** if the highest order terms are linear and the coefficients of the highest order derivatives are functions of independent variables only.

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## Example 12

- 1 Linear PDE:  $a(x, y)u_x + b(x, y)u_y + c(x, y)u = f(x, y)$
- 2 Semi-linear PDE:  $a(x, y)u_x + b(x, y)u_y = f(x, y, u)$
- 3 Quasi-linear PDE:  $a(x, y, u)u_x + b(x, y, u)u_y = f(x, y, u)$

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## Definition 13

A **linear** PDE is said to be *homogeneous* if each of its terms contains either the unknown function  $u$  or one of its partial derivatives. Otherwise, the PDE is called *nonhomogeneous* or *inhomogeneous*.



## Example 14

- |       |  |                                    |
|-------|--|------------------------------------|
| (i)   | $\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$  | One-dimensional wave equation      |
| (ii)  | $\frac{\partial u}{\partial t} = c^2 \frac{\partial^2 u}{\partial x^2}$  | One-dimensional heat equation      |
| (iii) | $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$  | Two-dimensional Laplace equation   |
| (iv)  | $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x, y)$  | Two-dimensional Poisson equation   |
| (v)   | $\frac{\partial^2 u}{\partial t^2} = \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$ | Two-dimensional wave equation      |
| (vi)  | $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 0$            | Three-dimensional Laplace equation |

PDEs (i)–(iii), (v) and (vi) are homogeneous while (iv) is nonhomogeneous for  $f(x, y) \neq 0$ .

# Method of forming PDEs

## Remark 1

Second-order PDEs are the most important ones in applications. Our syllabus contains only linear second-order homogeneous PDEs in two variables. These are one-dimensional wave equation, one-dimensional heat equation and two-dimensional Laplace equation.

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**Proof.**

**We have,**

$$x^2 + y^2 + (z - a)^2 = b^2. \quad (16)$$

**(16) contains two arbitrary constants a and b. Differentiating (16) partially with respect to x, we get**

$$2x + 2(z - a) \frac{\partial z}{\partial x} = 0 \implies \boxed{x + (z - a)p = 0} \quad \text{where } p = \frac{\partial z}{\partial x}. \quad (17)$$

**Again differentiating (16) partially with respect to y, we get**

$$2y + 2(z - a) \frac{\partial z}{\partial y} = 0 \implies \boxed{y + (z - a)q = 0} \quad \text{where } q = \frac{\partial z}{\partial y}. \quad (18)$$

**(17)  $\times$  q - (18)  $\times$  p, we get**

$$xp - yq = 0 \implies \boxed{x \frac{\partial z}{\partial y} - y \frac{\partial z}{\partial x} = 0}. \quad (19)$$

**This represents PDE of all spheres whose centre lie on z-axis.**





**Method 2: By eliminating arbitrary functions: Form the PDE from  $z = f(x^2 - y^2)$ .**

**Proof.**

**Differentiating the above equation partially with respect to  $x$  and  $y$ , we get**

$$p = \frac{\partial z}{\partial x} = f'(x^2 - y^2)2x \quad (20)$$

$$q = \frac{\partial z}{\partial y} = f'(x^2 - y^2)(-2y). \quad (21)$$

**Dividing (20) by (21) we get**

$$\frac{p}{q} = -\frac{x}{y} \implies y \frac{\partial z}{\partial x} + x \frac{\partial z}{\partial y} = 0. \quad (22)$$



## Classification of linear second-order PDEs in two variables

The general second-order linear PDE has the following form:

$$A u_{xx} + B u_{xy} + C u_{yy} + D u_x + E u_y + F u = G, \quad (23)$$

where the coefficients  $A, B, C, D, F$  and the free term  $G$  are in general functions of the independent variables  $x$  and  $y$ , but do not depend on the unknown function  $u$ . The classification of second-order equations depends on the form of the leading part of the equations consisting of the second-order terms. So, for simplicity of notation, we combine the lower-order terms and rewrite the above equation in the following form

$$A u_{xx} + B u_{xy} + C u_{yy} + I(x, y, u, u_x, u_y) = 0. \quad (24)$$

The type of the above equation depends on the sign of the quantity

$$\Delta(x, y) = B^2(x, y) - 4A(x, y) C(x, y), \quad (25)$$

which is called the *discriminant* for (24). The classification of second-order linear PDEs is given by the following.

## Definition 15

At the point  $(x_0, y_0)$ , the second-order linear PDE (24) is called

- (i) *elliptic*, if  $\Delta(x_0, y_0) < 0$
- (ii) *parabolic*, if  $\Delta(x_0, y_0) = 0$
- (iii) *hyperbolic*, if  $\Delta(x_0, y_0) > 0$

## Remark 2

- 1 For each of these categories, equation (24) and its solutions have distinct features.
- 2 In general, a second order equation may be of one type at a specific point, and of another type at some other point.
- 3 The terminology is motivated from the equation

$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0,$$

which—for  $A, B, C, D, E, F$  being constants—represents a conic section in the  $xy$ -plane and the different types of conic sections arising are determined by  $B^2 - 4AC$ .

## Remark 3

- 1 The canonical examples of the elliptic, parabolic and hyperbolic PDEs are the two-dimensional Laplace equation, one-dimensional heat equation and one-dimensional wave equations, i.e.,

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \quad (\text{Laplace equation})$$

$$\frac{\partial u}{\partial t} = c^2 \frac{\partial^2 u}{\partial x^2} \quad (\text{Heat equation})$$

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} \quad (\text{Wave equation})$$

Let  $u$  denotes the dependent variable in a boundary value problem (BVP).

#### Definition 16 (Dirichlet condition)

A condition that prescribes the values of  $u$  itself along a portion of the boundary is known as a *Dirichlet condition*.

#### Definition 17 (Neumann condition)

A condition that prescribes the values of the normal derivatives  $\partial u / \partial \hat{n}$  on a portion of the boundary is known as a *Neumann condition*. Here,  $\hat{n}$  denotes the unit outward normal to the boundary.

#### Definition 18 (Robin condition)

A condition that prescribes the values of  $hu + \partial u / \partial \hat{n}$  at boundary points is known as a *Robin condition*. Here,  $h$  is either a constant or a function of the independent variables.

#### Definition 19 (Cauchy condition)

If a PDE in  $u$  is of second order with respect to one of the independent variables  $t$  (time) and if the values of both  $u$  and  $u_t$  are prescribed at  $t = 0$ , the boundary condition is known as a *Cauchy-type* condition with respect to  $t$ .

**Definition 20 (Two-dimensional Laplace equation)**

The two-dimensional Laplace equation is given by

$$\nabla^2 u := \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0. \quad (26)$$

Note: the Laplace equation is also referred to as the *potential equation*.