

Example 3: Write Newton's form of interpolation polynomial for the data

$x_i$	0	1	$\frac{2}{3}$	$\frac{1}{3}$
$y_i$	1	0	$\frac{1}{2}$	0.866

Answer: Set up the triangular table for computation

0	$\boxed{1}$			
1	0	$\boxed{-1}$		
$\frac{2}{3}$	0.5	-1.5	$\boxed{-0.75}$	
$\frac{1}{3}$	0.8660	-1.0981	-0.6029	$\boxed{0.4413}$

So we have

$$a_0 = 1, a_1 = -1, a_2 = -0.75, a_3 = 0.4413$$

Then,

$$P_3(x) = \boxed{1} + \cancel{0x} \boxed{-1}x + \boxed{-0.75}x(x-1) + 0.4413x(x-1)\left(x-\frac{2}{3}\right)$$

$\boxed{1P-1}$

Flexibility of Newton's form: easy to add additional points to interpolate

The recursion is initiated with

$$f[x_i] = y_i, \quad i=0,1,2,\dots$$

$$\text{Then, } f[x_0, x_1] = \frac{f[x_1] - f[x_0]}{x_1 - x_0}$$

$$f[x_1, x_2] = \frac{f[x_2] - f[x_1]}{x_2 - x_1}, \dots$$

$$f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_1, x_0]}{x_2 - x_0},$$

$$f[x_1, x_2, x_3] = \frac{f[x_2, x_3] - f[x_2, x_1]}{x_3 - x_1}$$

For a general step, we have

$$f[x_0, x_1, \dots, x_k] = \frac{f[x_1, x_2, \dots, x_k] - f[x_0, x_1, \dots, x_{k-1}]}{x_k - x_0}$$

P-2

The constants  $a_k$ 's in the Newton's form are computed as :

$$a_0 = f[x_0], a_1 = f[x_0, x_1], \dots, a_k = f[x_0, x_1, \dots, x_k]$$

We compute the  $f[\dots]$ 's through the following table :

$x_0$	$f[x_0] = y_0$			
$x_1$	$f[x_1] = y_1$	$f[x_0, x_1]$ $= \frac{f[x_1] - f[x_0]}{x_1 - x_0}$		
$x_2$	$f[x_2] = y_2$	$f[x_1, x_2]$ $= \frac{f[x_2] - f[x_1]}{x_2 - x_1}$	$f[x_0, x_1, x_2]$	
$\vdots$		$\vdots$	$\vdots$	
$x_n$	$f[x_n] = y_n$	$f[x_{n-1}, x_n]$ $= \frac{f[x_n] - f[x_{n-1}]}{x_n - x_{n-1}}$	$f[x_{n-2}, x_{n-1}, x_n]$	$\vdots$

$$(*) \rightarrow f[x_0, x_1, \dots, x_n]$$

The diagonal elements give us the  $a_i$ 's.