



# Riemannian and Complex Geometry

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— Exercises —

## 2.1 Vector fields and differential forms

**Exercise 2.1.** Let  $f: M \rightarrow N$  be a smooth map between smooth manifolds. Let  $X_1, X_2$  be vector fields on  $M$  and  $Y_1, Y_2$  be vector fields on  $N$  such that  $(df)(X_i) = Y_i$  for  $i = 1, 2$ . Show that

$$(df)([X_1, X_2]) = [Y_1, Y_2].$$

**Exercise 2.2.** In each of the following cases, compute  $d\omega$  and  $F^*\omega$ , and verify by direct computation that  $F^*(d\omega) = d(F^*\omega)$ .

1.  $M = N = \mathbb{R}^2$ ;  $F(s, t) = (st, e^t)$ ;  $\omega = xdy$ .
2.  $M = \mathbb{R}^2$ ,  $N = \mathbb{R}^3$ ;  $F(\theta, \varphi) = ((\cos \varphi + 2) \cos \theta, (\cos \varphi + 2) \sin \theta, \sin \varphi)$ ;  $\omega = ydz \wedge dx$ .
3.  $M = \{(u, v) \in \mathbb{R}^2 : u^2 + v^2 < 1\}$ ,  $N = \mathbb{R}^3 \setminus \{0\}$ ;  $F(u, v) = (u, v, \sqrt{1 - u^2 - v^2})$ ;

$$\omega = \frac{xdy \wedge dz + ydz \wedge dx + zdx \wedge dy}{(x^2 + y^2 + z^2)^{3/2}}.$$

**Exercise 2.3.** Define a 2-form  $\omega$  on  $\mathbb{R}^3$  by

$$\omega = xdy \wedge dz + ydz \wedge dx + zdx \wedge dy.$$

1. Compute  $\omega$  in spherical coordinates  $(\rho, \varphi, \theta)$  defined by

$$(x, y, z) = (\rho \sin \varphi \cos \theta, \rho \sin \varphi \sin \theta, \rho \cos \varphi).$$

2. Compute  $d\omega$  in both Cartesian and spherical coordinates and verify that both expressions represent the same 3-form.

3. Let  $\iota_{\mathbb{S}^2} : \mathbb{S}^2 \rightarrow \mathbb{R}^3$  be the natural inclusion. Compute the pullback  $\iota_{\mathbb{S}^2}^* \omega$  to  $\mathbb{S}^2$ , using coordinates  $\varphi, \theta$  on the open subset where these coordinates are defined.
4. Show that  $\iota_{\mathbb{S}^2}^* \omega$  is a nowhere-vanishing 2-form on  $\mathbb{S}^2$ .

**Exercise 2.4.** Show that there is a smooth vector field on  $\mathbb{S}^2$  that vanishes at exactly one point.

**Exercise 2.5** (hairy ball theorem). There exists a nowhere-vanishing vector field on  $\mathbb{S}^n$  if and only if  $n$  is odd. Prove this by showing that the following are equivalent:

1. There exists a nowhere-vanishing vector field on  $\mathbb{S}^n$ .
2. There exists a continuous map  $V : \mathbb{S}^n \rightarrow \mathbb{S}^n$  satisfying  $V(x) \perp x$  (with respect to the Euclidean dot product on  $\mathbb{R}^{n+1}$ ) for all  $x \in \mathbb{S}^n$ .
3. The antipodal map  $\alpha$  is homotopic<sup>1</sup> to  $\text{id}_{\mathbb{S}^n}$ .
4. The antipodal map  $\alpha$  is orientation-preserving.
5.  $n$  is odd.

## 2.2 Orientation

**Exercise 2.6.** Prove that a real projective space  $\mathbb{RP}^n$  is orientable if and only if  $n$  is odd.

**Exercise 2.7.** Prove that a complex projective space  $\mathbb{CP}^n$  is always orientable.

## 2.3 De Rham cohomology

**Exercise 2.8.** Let  $\omega$  be the  $(n-1)$ -form on  $\mathbb{R}^n \setminus \{0\}$  defined by

$$\omega = |x|^{-n} \sum_{i=1}^n (-1)^{i-1} x^i dx^1 \wedge \cdots \wedge \widehat{dx^i} \wedge \cdots \wedge dx^n.$$

Show that  $\omega$  is closed but not exact on  $\mathbb{R}^n \setminus \{0\}$ .

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<sup>1</sup>Let  $f, g : X \rightarrow Y$  be two continuous maps between topological spaces. Then  $f$  is *homotopic* to  $g$  if there exists a continuous map  $F : X \times [0, 1] \rightarrow Y$  such that  $F(x, 0) = f(x)$  and  $F(x, 1) = g(x)$ .