

# 9.1.7

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## Question:

Solve the differential equation  $y''' + 2y'' + y' = 0$  with initial conditions  $y(0) = 1, y'(0) = -1$ , and  $y''(0) = 1$

## Solution:

Variable	Description
$n$	Order of given differential equation
$y_i$	$i$ th derivative of the function in the equation
$c$	constant in the equation
$a_i$	coefficient of $i$ th derivative of the function in the equation
$\mathbf{V}(t)$	Vector containing all 1 and $y_i$ from $i = 0$ to $i = n - 1$
$\mathbf{V}'(t)$	Vector containing 1 and $y'_i$ from $i = 0$ to $i = n - 1$
$A$	the coefficient matrix that transforms each $y_i$ to its derivative
$h$	the stepsize between each $t$ we are taking
$t_o$	The start time from which we are plotting
$t_f$	The end time at which we stop plotting

TABLE 0: Variables Used

Theoretical Solution: We apply the Laplace transform to each term in the equation. The Laplace transforms for the derivatives of  $y(t)$  are:

$$\mathcal{L}y'(t) = sY(s) - y(0) \quad (0.1)$$

$$\mathcal{L}y''(t) = s^2Y(s) - sy(0) - y'(0) \quad (0.2)$$

$$\mathcal{L}y'''(t) = s^3Y(s) - s^2y(0) - sy'(0) - y''(0) \quad (0.3)$$

Now, applying the Laplace transform to the entire differential equation:

$$\mathcal{L}\{y''' + 2y'' + y'\} = 0 \quad (0.4)$$

$$\mathcal{L}\{y'''(t)\} + 2\mathcal{L}\{y''(t)\} + \mathcal{L}\{y'(t)\} = 0 \quad (0.5)$$

$$(s^3Y(s) - s^2y(0) - sy'(0) - y''(0)) + 2(s^2Y(s) - sy(0) - y'(0)) + (sY(s) - y(0)) = 0 \quad (0.6)$$

Substitute the initial conditions  $y(0) = 1$ ,  $y'(0) = -1$ , and  $y''(0) = 1$ :

$$(s^3Y(s) - s^2 \cdot 1 - s \cdot (-1) - 1) + 2(s^2Y(s) - s \cdot 1 - (-1)) + (sY(s) - 1) = 0 \quad (0.7)$$

$$s^3Y(s) - s^2 + s - 1 + 2s^2Y(s) - 2s + 2 + sY(s) - 1 = 0 \quad (0.8)$$

Simplify the equation:

$$(s^3 + 2s^2 + s)Y(s) - (s^2 - s + 1) - (2s - 2) - 1 = 0 \quad (0.9)$$

$$(s^3 + 2s^2 + s)Y(s) - s^2 - s + 1 - 2s + 2 - 1 = 0 \quad (0.10)$$

$$(s^3 + 2s^2 + s)Y(s) - (s^2 + s) = 0 \quad (0.11)$$

Now, solve for  $Y(s)$ :

$$(s^3 + 2s^2 + s)Y(s) = s^2 + s \quad (0.12)$$

$$Y(s) = \frac{s^2 + s}{s(s+1)^2} \quad (0.13)$$

$$\Rightarrow Y(s) = \frac{1}{s+1} \quad (0.14)$$

Now, take the inverse Laplace transform:

$$\mathcal{L}^{-1}\left(\frac{1}{s+1}\right) = e^{-t} \quad (0.15)$$

Thus, the solution to the differential equation is:

$$y(t) = e^{-t} \quad (0.16)$$

Computational Solution:

Consider the given linear differential equation

$$a_n y_n + a_{n-1} y_{n-1} + \cdots + a_1 y_1 + a_0 y_0 + c = 0 \quad (0.17)$$

Where  $y_i$  is the  $i$ th derivative of the function then

$$\begin{pmatrix} y'_0 \\ y'_1 \\ y'_2 \\ \vdots \\ y'_{n-1} \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ \frac{-(\sum_{i=0}^{n-1} a_i y_i) - c}{a_n} \end{pmatrix} \quad (0.18)$$

$$\Rightarrow \begin{pmatrix} 1 \\ y'_0 \\ y'_1 \\ y'_2 \\ \vdots \\ y'_{n-1} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & \cdots & \cdots & \cdots & \cdots \\ 0 & 0 & 1 & 0 & \cdots & \cdots & \cdots \\ 0 & 0 & 0 & 1 & 0 & \cdots & \cdots \\ 0 & 0 & 0 & 0 & 1 & 0 & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \\ \frac{-c}{a_n} & \frac{-a_0}{a_n} & \frac{-a_1}{a_n} & \frac{-a_2}{a_n} & \cdots & \cdots & \frac{-a_{n-1}}{a_n} \end{pmatrix} \begin{pmatrix} 1 \\ y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_{n-1} \end{pmatrix} \quad (0.19)$$

$$\Rightarrow \mathbf{V}'(t) = \mathbf{A}\mathbf{V}(t) \quad (0.20)$$

Where  $\mathbf{V}(t)$  is the vector  $\begin{pmatrix} 1 \\ y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_{n-1} \end{pmatrix}$  at a  $t$ . At any  $N$ , by defining derivative:

$$y'_N(t) = \lim_{h \rightarrow 0} \frac{y_N(t+h) - y_N(t)}{h} \quad (0.21)$$

$$y_N(t+h) = y_N(t) + hy'_N(t) \quad (0.22)$$

$$\implies y_0(t+h) = y_0(t) + hy'_0(t) \quad (0.23)$$

$$\implies y_1(t+h) = y_1(t) + hy'_1(t) \quad (0.24)$$

$$\implies y_2(t+h) = y_2(t) + hy'_2(t) \quad (0.25)$$

$$\vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad (0.26)$$

$$\implies y_{n-1}(t+h) = y_{n-1}(t) + hy'_{n-1}(t) \quad (0.27)$$

$$\implies \mathbf{V}(t+h) = \mathbf{V}(t) + h(A\mathbf{V}(t)) \quad (0.28)$$

When  $t$  ranges from  $t_o$  to  $t_f$  in increments of  $h$ , discretizing the steps gives us all  $\mathbf{V}(x)$  from  $t_o$  to  $t_f$  in increments of  $h$ . Record the  $y_0$  for each  $\mathbf{V}(x)$  we got and then plot the graph. The result will be as given below.

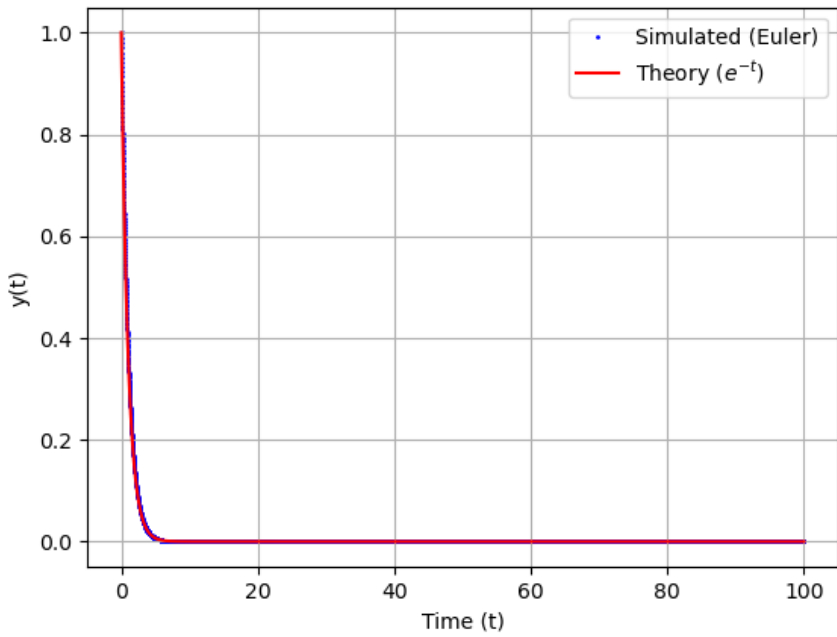


Fig. 0.1: Comparison between the Theoretical solution and Computational solution