

Assignment 5 — Traps and Interrupts

Due: Wednesday, May 11th

In a real computer, there are typically far more running processes than there are physical CPU cores. In such situations, rather than having a process waste resources by polling while it waits for user input, another process can be allowed to run during that time¹.

Deliverables:

GitHub Classroom: <https://classroom.github.com/a/prRDtFJH>

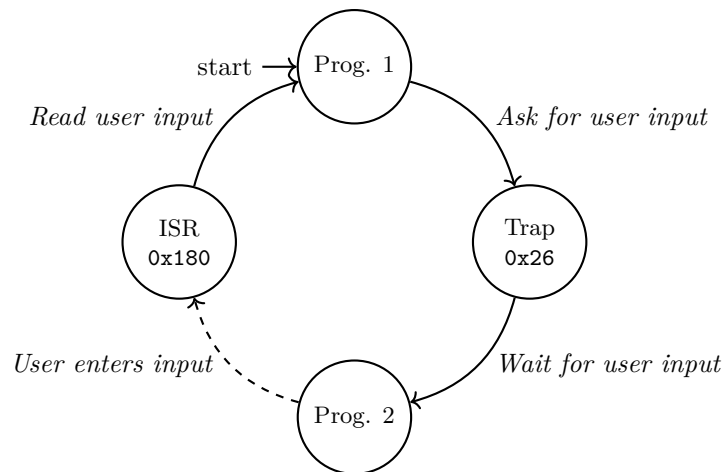
Required Files: trap26.asm

Optional Files: none

Part 1: Time-Sharing

Implementing interrupt-driven I/O requires a few extra steps. Notably, recall that in order to enable keyboard interrupts, bit 14 must be set to a ‘1’ in the KBSR. However, the KBSR is memory-mapped to 0xFE00, which is only accessible in privileged mode.

In order to properly use interrupts, you will need to implement *both* a trap service routine and an interrupt service routine, which will need to work together to transition to and from the calling program:



1. Execution begins with Program 1, which reads a single character. Rather than using `GETC`, Program 1 instead calls Trap 0x26.
2. The trap service routine sets up keyboard interrupts, but it does *not* return to Program 1 (which was its caller). Instead, it “returns” to Program 2.
3. Program 2 is allowed to execute while Program 1 is waiting for input.

Once the user types a character, an interrupt is triggered; ISR 0x180 responds.

4. The interrupt service routine reads the typed character, but it does *not* return to Program 2 (which was interrupted). Instead, it “returns” to Program 1.

From the perspective of Program 1, Trap 0x26 and ISR 0x180 behave as two halves of a single service routine.

¹Certainly, the mechanism implemented here is a gross oversimplification of how a real operating system implements *time-sharing*. However, within the confines of the LC-3, it will illustrate the fundamentals.

Part 2: Trap 0x26

Complete the service routine labeled **TRAP26** in **trap26.asm**. This service routine is responsible for setting up keyboard interrupts and switching to execution of Program 2:

- Your implementation must place the address of **ISR180** (which you will implement shortly) into the keyboard's entry in the Interrupt Vector Table.
- It must enable keyboard interrupts by setting bit 14 of the KBSR to '1'.
- It must "return" to Program 2. When **TRAP26** is called, the supervisor stack will contain (left):



...the service routine must swap Program 1's PC and PSR with those of Program 2 (right), which will cause an RTI to return to the latter. Moreover, **TRAP26** must store all of Program 1's state:

- | | | | | |
|-------|------|------|------|--------------|
| • PC | • R1 | • R3 | • R5 | • Keyboard's |
| • PSR | • R2 | • R4 | • R7 | IVT entry |

...the state of Program 2 must then be loaded²:

- | | | | | |
|-------|------|------|------|------|
| • PC | • R0 | • R2 | • R4 | • R7 |
| • PSR | • R1 | • R3 | • R5 | |

Note that Program 1's R0 need not be saved; it will eventually be used to return a typed character. You may also assume that R6 is used exclusively for the supervisor stack, and should not be touched.

Part 3: ISR 0x180

Complete the service routine labeled **ISR180** in **trap26.asm**. This service routine is responsible for responding to keyboard interrupts and switching back to execution of Program 1:

- Your implementation must read the typed character into R0. It may *not* call **GETC** or use polling.
- It must disable keyboard interrupts by setting bit 14 of the KBSR to '0'.
- It must "return" to Program 1. When **ISR180** is called, the supervisor stack will contain (left):



...the service routine must swap Program 2's PC and PSR with those of Program 1 (right), which will cause an RTI to return to the latter. Moreover, **ISR180** must store all of Program 2's state:

- | | | | | |
|-------|------|------|------|------|
| • PC | • R0 | • R2 | • R4 | • R7 |
| • PSR | • R1 | • R3 | • R5 | |

...the state of Program 1 must then be loaded:

- | | | | | |
|-------|------|------|------|--------------|
| • PC | • R1 | • R3 | • R5 | • Keyboard's |
| • PSR | • R2 | • R4 | • R7 | IVT entry |

That is to say, **ISR180** must restore all of Program 1's state that was saved by **TRAP26**, and it must save all of Program 2's state that will be restored if **TRAP26** is ever called again.

²The initial state of Program 2 has been defined in **trap26.asm**, so that the first call to **TRAP26** will begin Program 2.

Part 4: Testing

Consider the code in `program1a.asm` and `program2.asm`. Here, Program 1 uses `TRAP x26` to read a single character using interrupt-driven I/O. Program 2 simply infinitely, periodically increments the contents of `R1`.

Not only must `program1a`, `program2`, and `trap26` be assembled and loaded into the LC-3, but memory location `0x0026` must be manually set to `0x1000` to enable `TRAP x26`.

- Throughout this assignment, you may *not* alter any of the code for Programs 1 or 2.
- Depending on when characters are typed, the state of Program 2 as saved by `ISR180` and restored by `TRAP26` will vary. It need *not* be possible to rerun Program 1 by manually resetting the PC to `0x3000`.

You may assume that Program 2 will neither alter the keyboard's entry in the Interrupt Vector Table nor itself use `TRAP x26`. You may further assume that the user will wait long enough to type a character that a keyboard interrupt will not be triggered while `TRAP26` is running.

For example:

```
[Program 1] Reading...
[Program 2] R1: 0...
[Program 2] R1: 1...
[Program 2] R1: 2...
[Program 1] Read 'a'.
```

...where the number of lines printed will naturally depend on how long the user waits before typing a character.

Your implementation will be tested with other variations of Program 1 and Program 2. For example, consider `program1b.asm`, which invokes `TRAP x26` within an infinite loop:

```
[Program 1] Reading...
[Program 2] R1: 0...
[Program 2] R1: 1...
[Program 1] Read 'f'.
[Program 1] Reading...
[Program 2] R1: 2...
[Program 1] Read 'o'.
[Program 1] Reading...
[Program 2] R1: 3...
[Program 2] R1: 4...
[Program 2] R1: 5...
[Program 1] Read 'o'.
[Program 1] Reading...
[Program 2] R1: 6...
      ⋮
```

Part 5: Submission

The following files are required and must be pushed to your GitHub Classroom repository by the deadline:

- `trap26.asm` — A working assembly trap and ISR for interrupt-driven keyboard input, as specified.

The following files are optional:

- *none*

Any files other than these will be ignored.