The "Ls" estimator as a solution to a Maximum Entropy

miles to the state of the control

Consider the linear model y=b+b1x+E. We make the following & assumptions:

- (1) IE [6] = 0 Errors have zero mean
- (2) IE[e2]= 0-2 Errors have constant variance
- (3) FLxe] = 0 orthogonality

We define the entropy of a probability distribution p(E)

where the integration is over the support of E Cusually R)

we seek a p(E) that maximize H. Using the method of

Lagrange multipliers:

(where we have added the constraint that the probability distribution integrate to 1).

Taking derivative of of w.r.t. p(E):

In p (e) +
$$\lambda_0$$
 + λ_1 e + λ_2 e² + λ_3 x e

In p (e) = λ_0 - 1 + λ_1 e + λ_2 e² + λ_3 x e

Taking derivatives with λ_1 and λ_2 and λ_3 and λ_4 and

polysby
$$P(t) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[\frac{(y-b_0-b_1x)^2}{2\sigma^2}\right]$$

We can now find the values of bo and by that maximize ther entropy