## Linear Algebra



Holberton

### **Machine Learning**

### Why

Social media features

Sentiment analysis

Face recognition







Product recommendations

Medical analysis

Stock market prediction







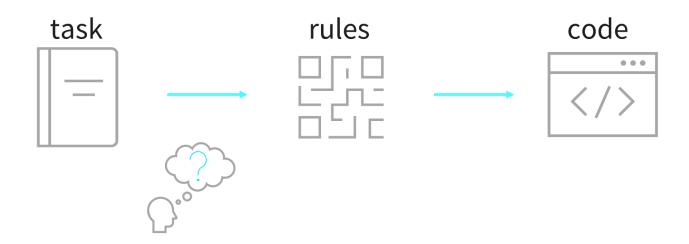
### What

"A computer program is said to **learn** from **experience** E with respect to some class of tasks T and **performance** measure P, if its performance at tasks in T, as measured by P, improves with experience E,

-- Tom Mitchel

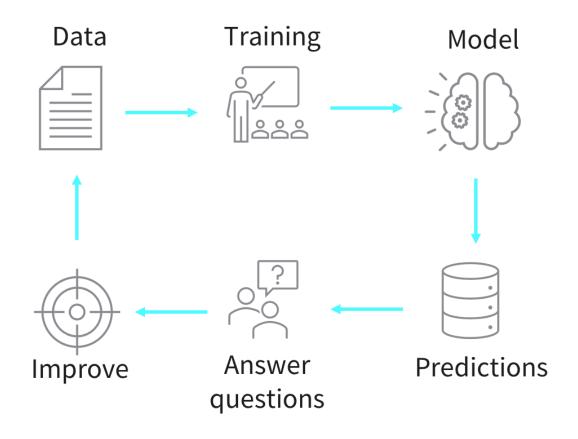
#### How

For some problems we cannot simply write down the rules

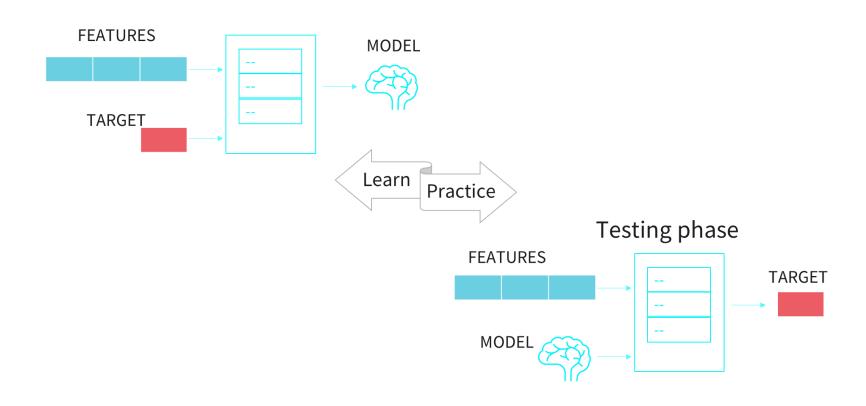


— What if computer systems could learn through trial and error?

### **Machine Learning Framework**



### **Machine Learning Framework**



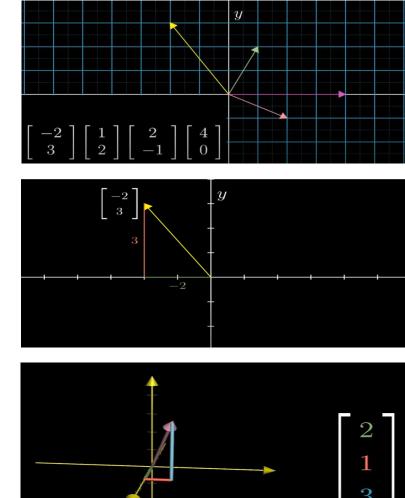
## Introduction to Vectors and Matrices

### **Vectors**

- Cornerstone of linear algebra
- Physics: arrows pointing in space
- CS: list of numbers
- Math: generalize both views

### **Key elements**

Length and direction of vectors



### The Matrix

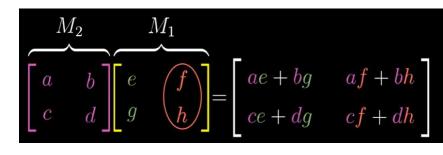
- A m by n matrix is a function of two variables with domains {1, 2, ... m} and {1, 2, ... n}
- Matrices can be used to store data

$$\begin{bmatrix} a & \mathbf{b} \\ c & \mathbf{d} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x \begin{bmatrix} a \\ c \end{bmatrix} + y \begin{bmatrix} \mathbf{b} \\ \mathbf{d} \end{bmatrix} = \begin{bmatrix} ax + \mathbf{b}y \\ cx + \mathbf{d}y \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \left( \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right) = \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$
Shear Rotation Composition

### **Linear transformations**

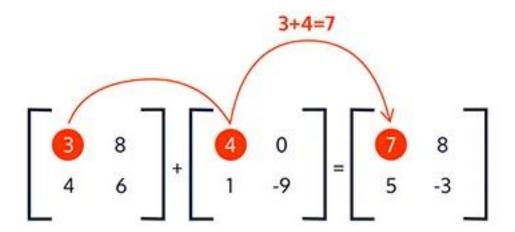
- A linear transform can be represented by an array of coefficients
- The composition of linear transforms yields the product of their matrices



## **Key Operations**

### **Matrix addition**

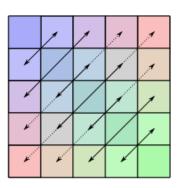
 In matrix addition, corresponding matrix entries are added together



### **Matrix transpose**

- Flip a matrix over its diagonal
- Switch the row and column indices
- A square matrix whose transpose is equal to itself is called a symmetric matrix  $A = A^T$





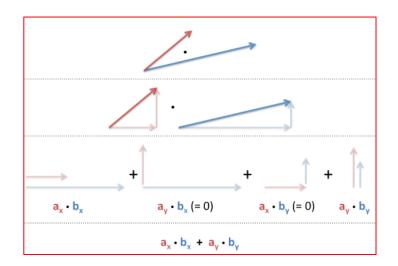
### Matrix dot product: directional multiplication

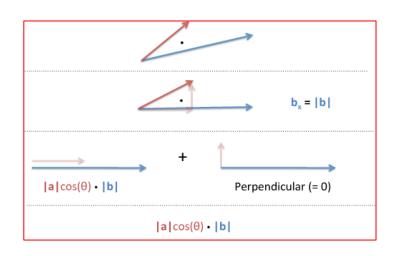
- Add vectors: accumulate the growth contained in several vectors
- Multiply by a constant: make an existing vector stronger
- Dot product: Apply the directional growth of one vector to another

### **Dot product**

- Rectangular Coordinates:
   Component-by-component overlap
- $\bullet \quad A \cdot B = \sum (A[i,j] \cdot B[i,j])$

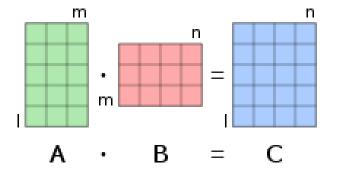
- Polar coordinates: Projection
- How much energy is actually going in our original direction?





### **Matrix multiplication**

- A binary operation that produces a matrix from two matrices
- The number of columns in the first matrix must be equal to the number of rows in the second matrix
- The resulting matrix has the number of rows of the first and the number of columns of the second matrix



$$C_{ij} = \Sigma_1^n (A_{ik} \cdot B_{kj})$$

### **Matrix multiplication**

$$\begin{bmatrix} 2 & 4 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 3 & 1 & 5 \\ -2 & 1 & 3 \end{bmatrix} = \begin{bmatrix} \\ (2 \times 2) \\ (2 \times 3) \end{bmatrix}$$

$$(2 \times 3)$$

$$(2 \times 3)$$

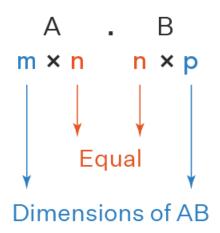
### Matrix multiplication vs dot product

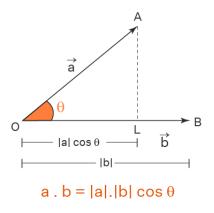
#### Matrix multiplication

- Combining two matrices to produce a new matrix.
- The number of columns in the first matrix must match the number of rows in the second matrix.
- The product of matrix multiplication is a new matrix

#### Dot product

- An operation between two vectors to produce a scalar
- The vectors must have the same number of elements





# Any questions?

