

Recurrent **Neural Networks**

Holberton

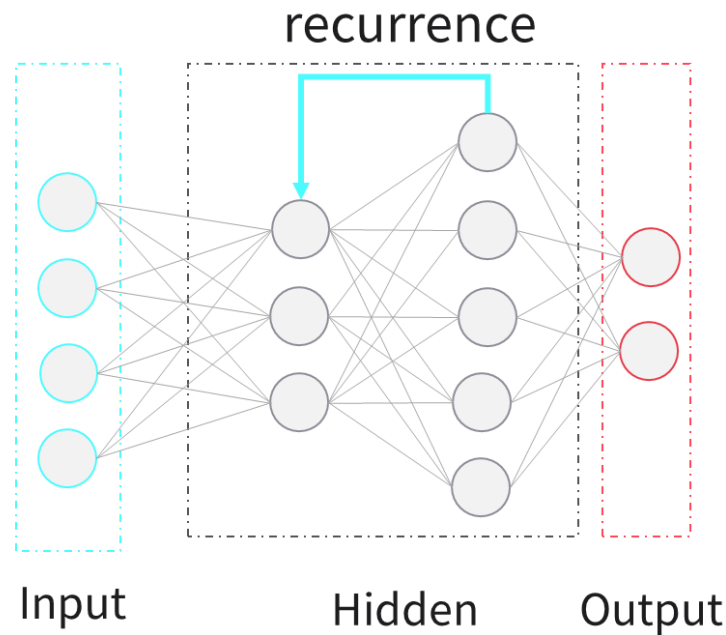




What are Recurrent Neural Networks?

Motivation

- What if patterns of data *change over time*?
- Internal *memory* as a distinctive feature
- A passage *through time*



| Applications

— Natural language processing



— Autonomous driving



— Time series



“Predict” the
near **future**
based on **past**
observations

Categories and applications

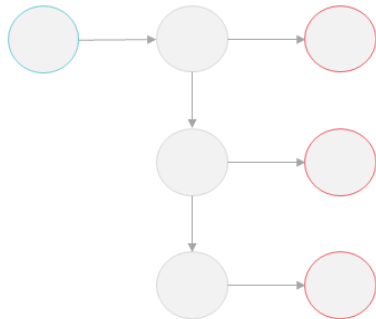
One to One



image
captioning



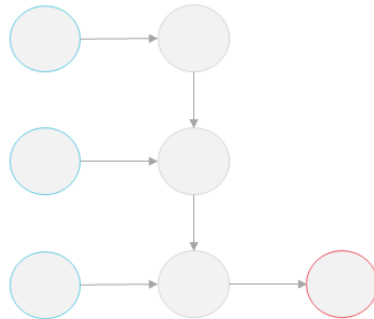
One to Many



music
generation



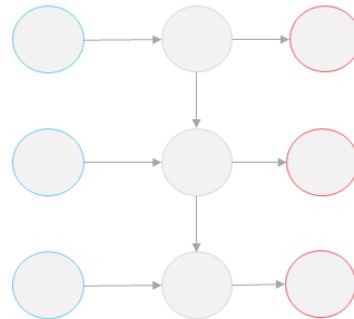
Many to One



text
classification



Many to Many



automatic
translation



| Applications

— Natural language processing



— Autonomous driving



— Time series

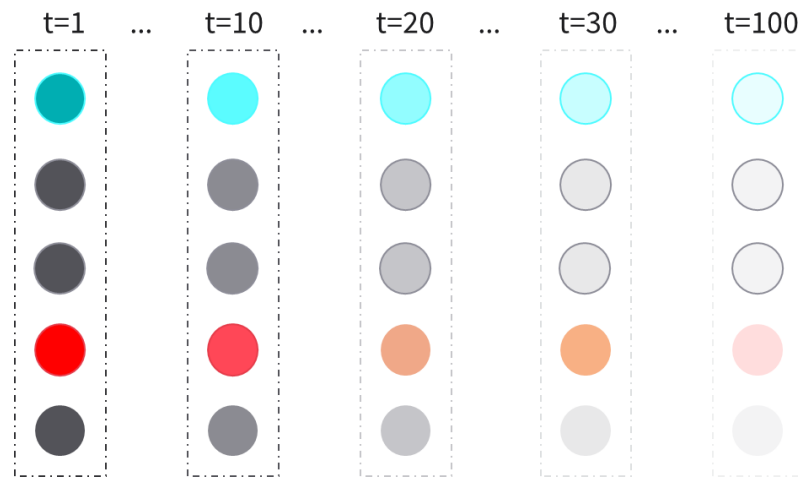


“Predict” the
near **future**
based on **past**
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Challenges of standard RNN

An old problem: backpropagation is used to train RNNs

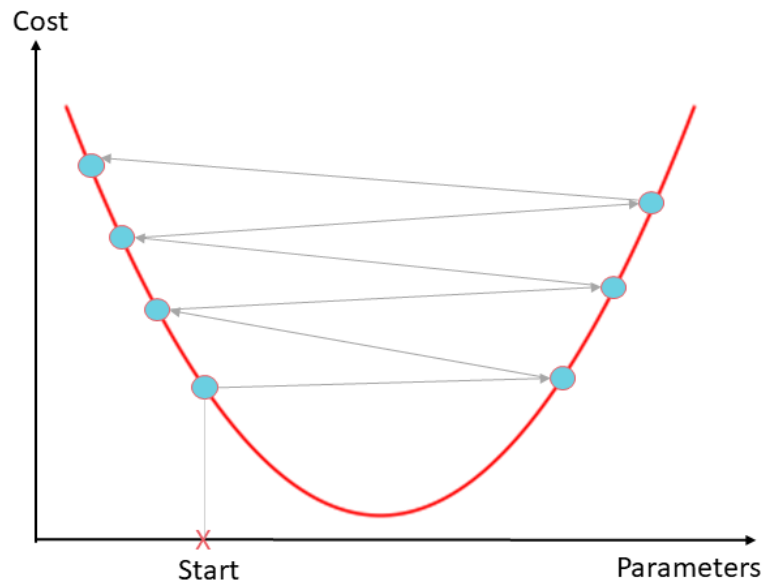
- It *suffers* from gradient issues
- *Decay of information* through time
- *Signal gets lost* as it travels in time
- Difficult for network to learn



Challenges of standard RNN

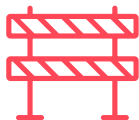
Another old problem: exploding gradients

- Unreasonably high weights
- Large gradient *errors accumulate*
- Network gets *unstable*

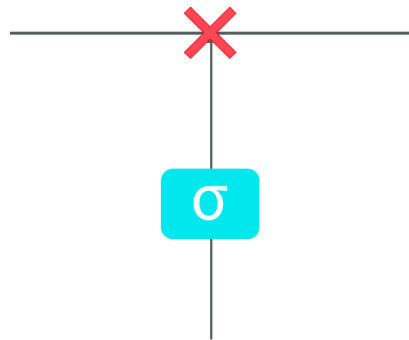


Addressing the challenges

Solution: **gated** units



- Long Short-Term Memory Unit (LSTM)
- Gated Recurrent Unit (GRU)
- Capable of handling long-term dependencies
- Carry information across time-steps

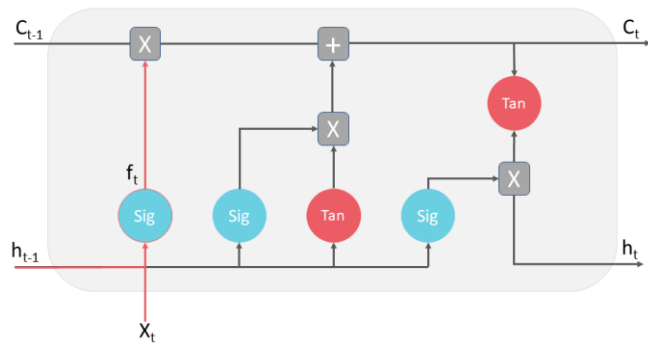


Information is **added** or **removed** through structures called gates

The role of gates in LSTM

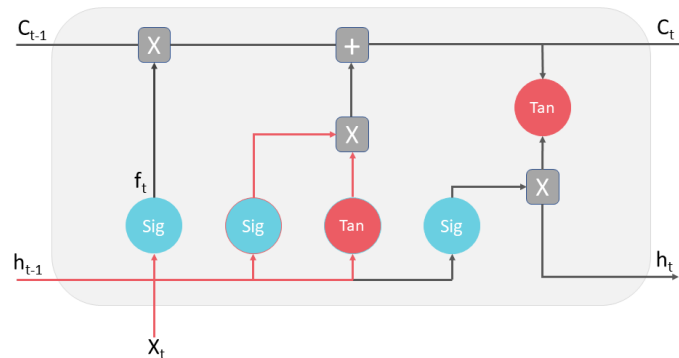
The **forget gate**

- decide what to keep to keep from prior cell state
- consider current input and previous hidden state



The **input gate**

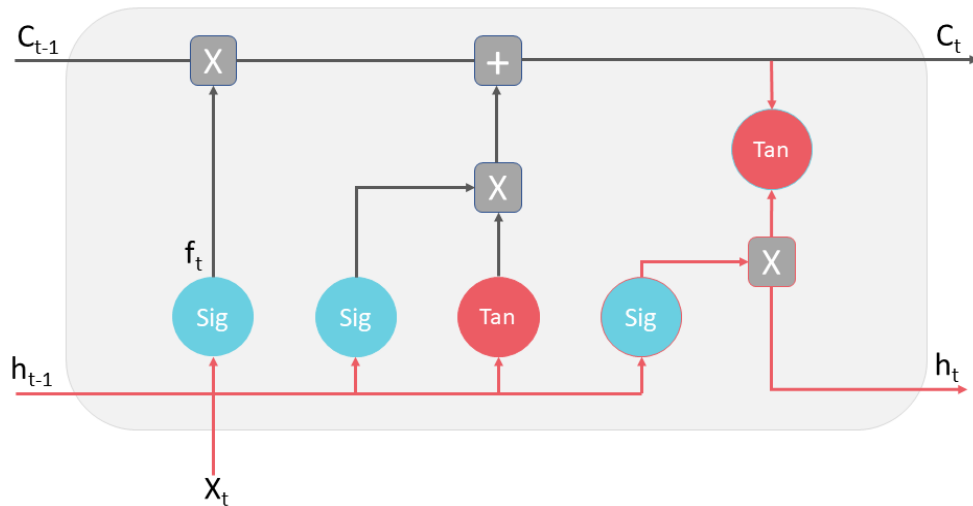
- decide what is relevant to update in current cell
- network calculates cell state



The role of gates in LSTM

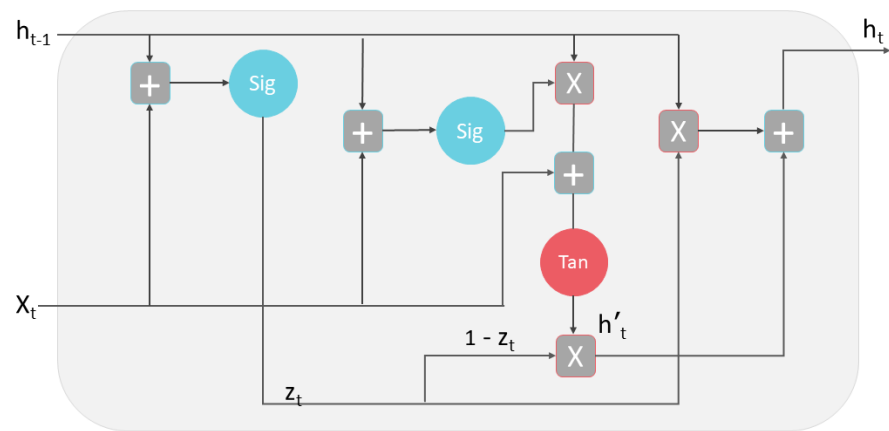
The **output** gate

- decide what to output from memory cell
- Current state becomes input for next unit



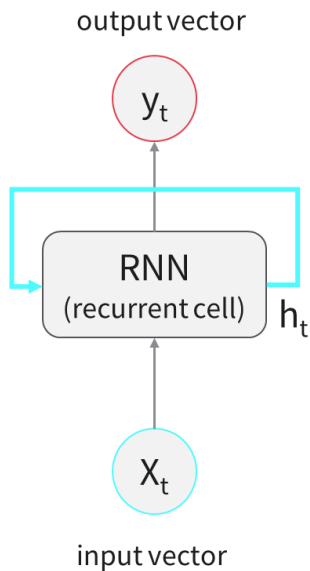
Gated recurrent units

- decide what to output from memory cell
- Current state becomes input for next unit
- **Update** gate decides what information to pass
- **Reset** gate decides how much to forget



Training RNNs

- Apply **recurrence** to each timestep

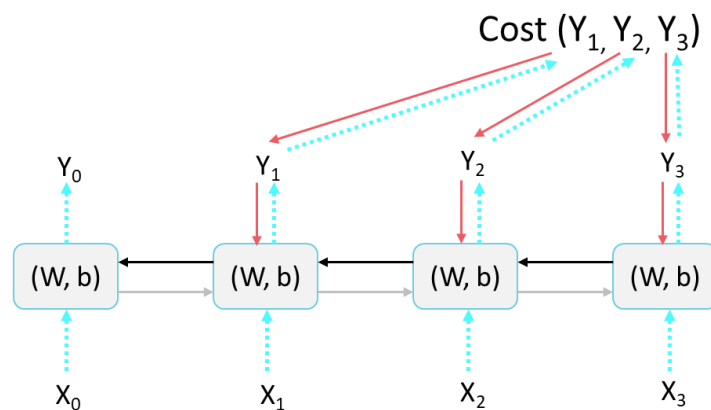
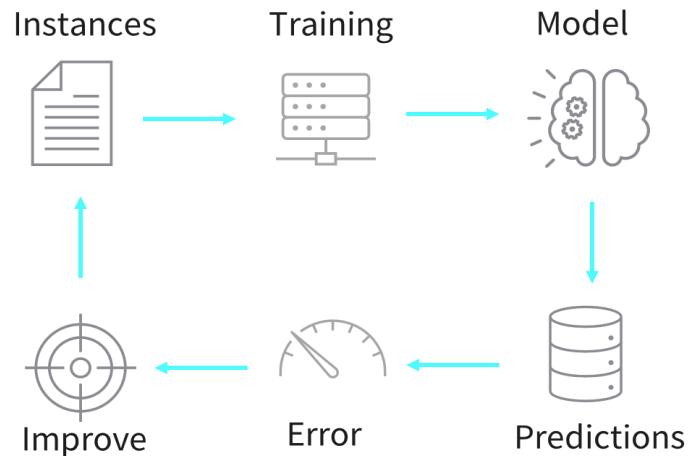


$$h_t = f_W (h_{t-1}, x_t)$$

cell state function parametrized by W previous state input vector

Training RNNs

- Backpropagation **through time**
- Forward pass: process information & generate input for next timestep
- Backward pass: compute gradient of classification loss & adjust





Any questions?

