

# Find Chebyshev Center of a Polyhedron Using Linear Programming

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# Problem

Given a polyhedron. Find the largest Euclidean ball that lies inside a (convex) polyhedron.

Many equivalent ways of framing this problem. e.g. Find a point that maximizes the minimum distance ( $l_2$  norm) to a set of (hyper)planes; Find Chebyshev center; etc.

## ELI5 (3D Scenario)

Given any (weirdly shaped) cage with flat surfaces, what's the radius of the largest sphere that could fit inside the cage?

# Examples in 2D and 3D

# A polyhedron is a system of linear inequalities

Any polyhedron can be described in the following way.

$$\mathcal{P} = \{x \in \mathbb{R}^n \mid a_i^T x \leq b_i, i = 1, \dots, m\}$$

In other words, a polyhedron is the set of points that satisfy a system of linear inequalities.

# Euclidean ball

Any Euclidean ball can be described as

$$\mathcal{B} = \{x_c + u \mid \|u\|_2 \leq r\}$$

$x_c \in \mathbb{R}^n$  is the center.  $r$  is the radius.

Intuitively: the center + a vector whose length shorter than  $r$ .

# Rephrasing the problem

$$\mathcal{P} = \{x \in \mathbb{R}^n \mid a_i^T x \leq b_i, \ i = 1, \dots, m\} \text{ (given)}$$

$$\mathcal{B} = \{x_c + u \mid \|u\|_2 \leq r\}$$

Adjust variables  $x_c$  and  $r$  to maximize  $r$  subject to the constraint  $\mathcal{B} \subseteq \mathcal{P}$ .

Getting closer to a LP! Now the question is how to formulate  $\mathcal{B} \subseteq \mathcal{P}$  as *linear* constraints.

# One inequality at a time

$\mathcal{B} \subseteq \mathcal{P} \iff$  every point in  $\mathcal{B}$  satisfies every inequality required by  $\mathcal{P}$ .



# Math

For the  $i$ th inequality:  $a_i^T(x_c + u) \leq b_i$  for all  $\|u\|_2 \leq r$ .

$a_i^T u$  attains its maximum when  $\|u\|_2 = r$  and  $u$  is in the same direction as  $a_i$ , specifically  $u = \frac{a_i}{\|a_i\|_2} r$ .

Intuitively, we're looking for the vector that points straight to the hyperplane (perpendicular) with length  $r$ . If that vector satisfies then all vectors in the ball satisfies.

So the  $i$ th inequality is equivalent to

$$a_i^T(x_c + \frac{a_i}{\|a_i\|_2} r) = a_i^T x_c + r\|a_i\|_2 \leq b_i$$

# Formulation as a linear program

$$\begin{array}{ll}\text{maximize} & r \\ \text{subject to} & a_i^T x_c + r \|a_i\|_2 \leq b_i, \quad i = 1, \dots, m\end{array}$$