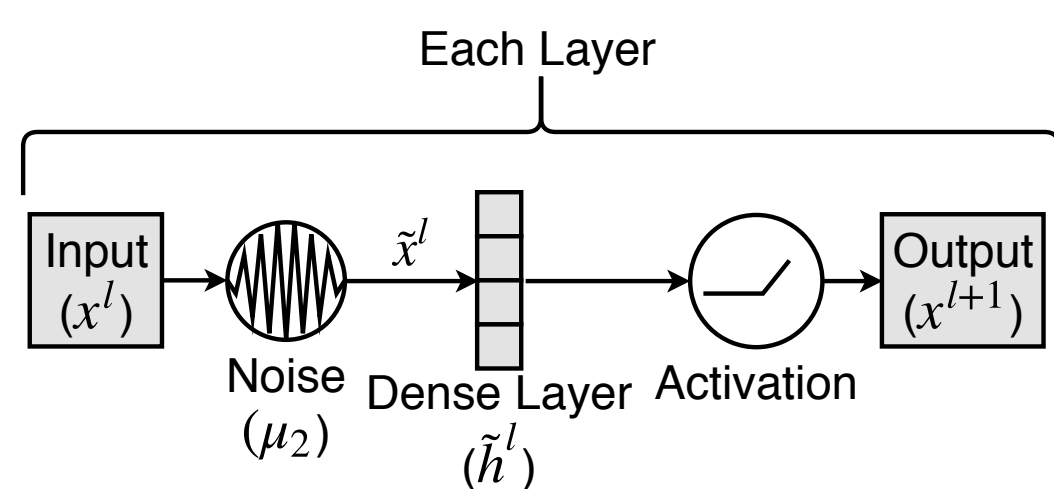


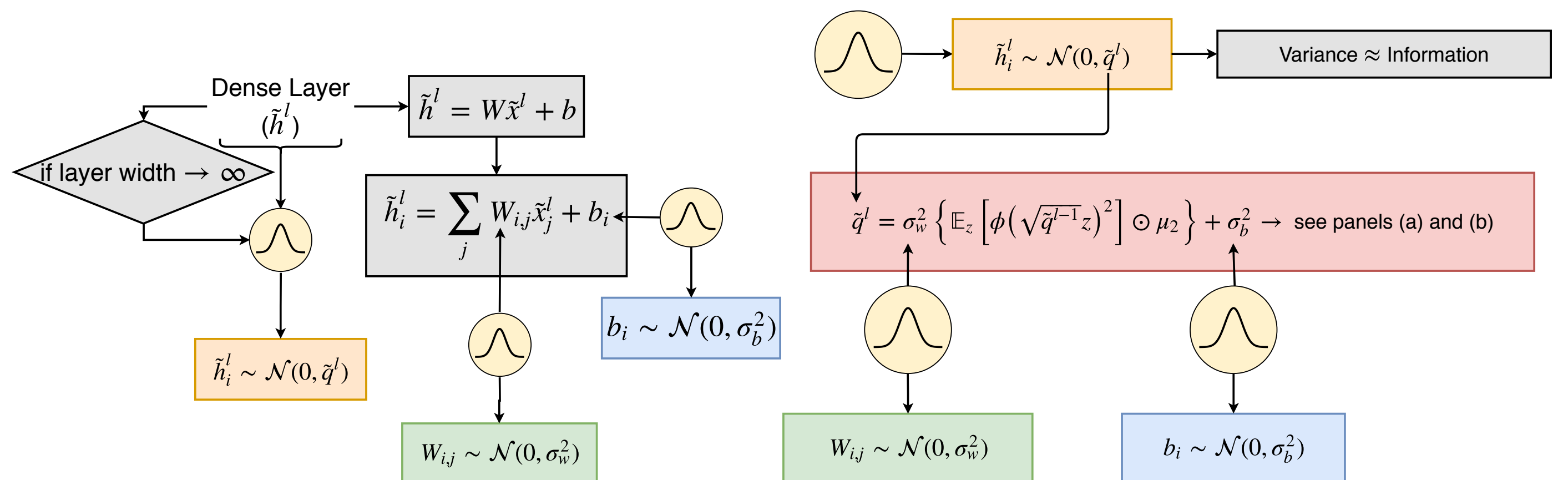
## Contributions

- We extend the mean field framework in [1], to describe noisy signal propagation in fully connected feed-forward neural networks.
- We derive variance critical weight initialisation strategies for noisy ReLU networks, suitable for a wide range of noise models.
- We describe the limitations to information flow as a result of noise by studying the signal correlation dynamics.

## Noisy signal propagation model



## Critical initialisation for noisy ReLU networks



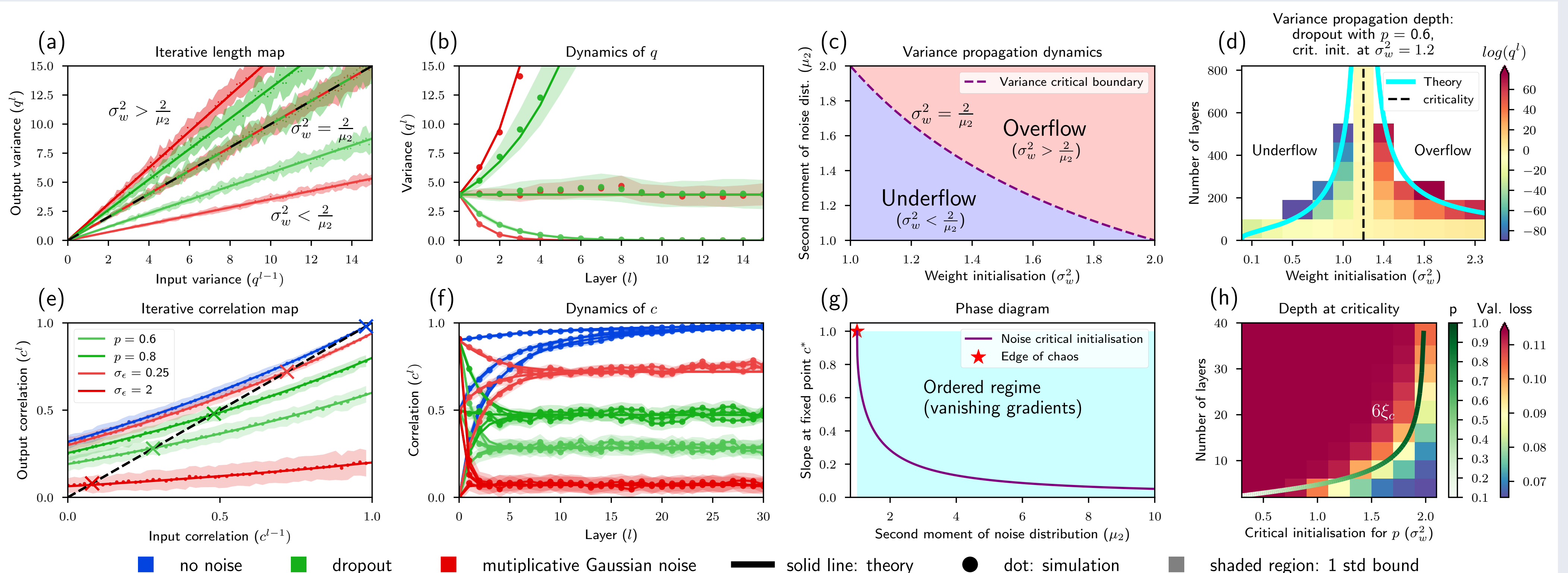
- **Critical initialisation:**  $\tilde{q}^* = \sigma_w^2 [\tilde{q}^* \mathbb{E}_z(z^2) \odot \mu_2] + \sigma_b^2 = \sigma_w^2 \left( \frac{1}{2} \tilde{q}^* \odot \mu_2 \right) + \sigma_b^2$ .

$$\text{Additive Noise} \Rightarrow (\sigma_w, \sigma_b, \mu_2) = (\sqrt{2}, 0, 0)$$

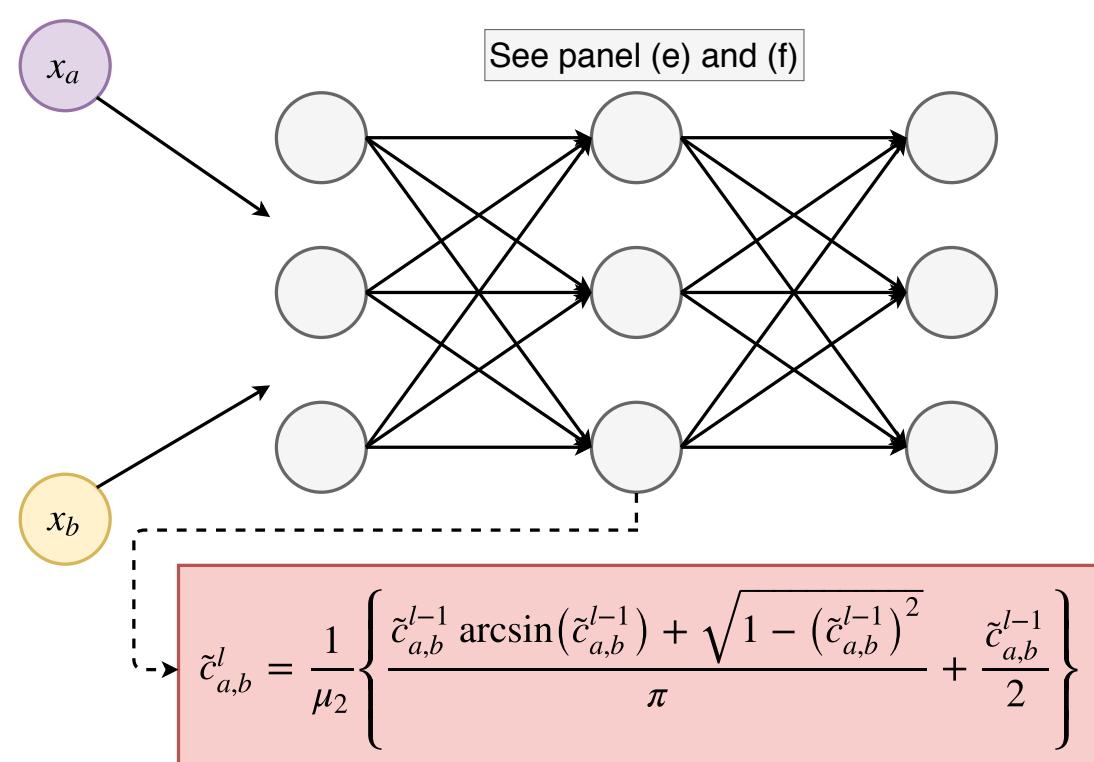
$$\text{Multiplicative Noise} \Rightarrow (\sigma_w, \sigma_b, \mu_2) = \left( \sqrt{2/\mu_2}, 0, \mu_2 \right)$$

- **Examples:** Mult Gauss noise:  $\mu_2 = \sigma_\epsilon^2 + 1 \Rightarrow (\sigma_w, \sigma_b) = \left( \sqrt{2/(\sigma^2 + 1)}, 0 \right)$ .  
Dropout:  $\mu_2 = 1/p \Rightarrow (\sigma_w, \sigma_b) = (\sqrt{2p}, 0)$  (see panel (c) and (d)).

## Experiments



## Limits to information flow



- **Training regime:** At the fixed point correlation  $c^*$  the slope of the correlation map is

$$\chi(c^*) = \frac{1}{\mu_2} \left( \frac{\arcsin(c^*)}{\pi} + \frac{1}{2} \right)$$

If  $\chi(c^*) < 1$ , the network is in the *ordered* regime of signal propagation where gradients tend to vanish during the backward pass [2]. Any amount of noise induced regularisation pushes the network into this ordered regime (see panel (g)).

- **Depth scales:**  $\xi_c = -1/\log[\chi(c^*)]$ . The value  $6\xi_c$  seems to be able to predict feasible depths for trainability [2] and generalisation (see panel (h)).

Training regime  
panel (g)

Trainable depth  
panel (h)

## Takeaways

- When using multiplicative stochastic regularisation techniques (such as dropout) with ReLU networks, critically initialising the weights and biases ensures that information from the input can reliably flow through the network.
- However, even at critically, noise causes the correlation between signals to decay with increasing depth and as a result gradients may vanish during backpropagation. This limits the depth at which noisy ReLU networks are able to perform well.

## References

- [1] B. Poole, S. Lahiri, M. Raghu, J. Sohl-Dickstein, and S. Ganguli. Exponential expressivity in deep neural networks through transient chaos. NIPS, 2016.
- [2] S. S. Schoenholz, J. Gilmer, S. Ganguli, and J. Sohl-Dickstein. Deep Information Propagation. ICLR, 2017.