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# Alexander Robey

## Education

- 2018-present PhD, Electrical and Systems Engineering, University of Pennsylvania, Philadelphia, PA, USA.
  - 2014-2018 Bachelor of Science, Engineering, Swarthmore College, Swarthmore, PA, USA.
  - 2014-2018 Bachelor of Arts, Mathematics, Swarthmore College, Swarthmore, PA, USA.

## Journal Papers

2018 **Alexander Robey** and Vidya Ganapati. Optimal physical preprocessing for example-based super-resolution. *Optics Express*, volume 26, pages 31333–31350. Optical Society of America, 2018.

# Refereed Conference Papers

- 2021 **Alexander Robey**, George J Pappas, and Hamed Hassani. Model-based domain generalization. In *Advances in Neural Information Processing Systems*, 2021.
- 2021 **Alexander Robey**, Lars Lindemann, Stephen Tu, and Nikolai Matni. Learning robust hybrid control barrier functions for uncertain systems. *IFAC-PapersOnLine*. Elsevier, 2021.
- Alexander Robey, Luiz Chamon, George J. Pappas, Hamed Hassani, and Alejandro Ribeiro. Adversarial robustness with semi-infinite constrained learning. In *Advances in Neural Information Processing Systems*, 2021.
- 2021 Alexander Robey, Arman Adibi, Brent Schlotfeldt, George J Pappas, and Hamed Hassani. Optimal algorithms for submodular maximization with distributed constraints. In *Learning for Dynamics and Control*. PMLR, 2021.
- 2021 Lars Lindemann, Haimin Hu, Alexander Robey, Hanwen Zhang, Dimos V Dimarogonas, Stephen Tu, and Nikolai Matni. Learning hybrid control barrier functions from data. Conference on Robot Learning. PMLR, 2021.
- Alexander Robey, Haimin Hu, Lars Lindemann, Hanwen Zhang, Dimos V Dimarogonas, Stephen Tu, and Nikolai Matni. Learning control barrier functions from expert demonstrations. In 2020 59th IEEE Conference on Decision and Control (CDC), pages 3717–3724. IEEE, 2020.
- 2019 Mahyar Fazlyab, **Alexander Robey**, Hamed Hassani, Manfred Morari, and George Pappas. Efficient and accurate estimation of lipschitz constants for deep neural networks. In *Advances in Neural Information Processing Systems*, pages 11427–11438, 2019.

# **Preprints**

- 2021 Stephen Tu, **Alexander Robey**, Tingnan Zhang, and Nikolai Matni. On the sample complexity of stability constrained imitation learning. *arXiv preprint arXiv:2102.09161*, 2021.
- 2021 Lars Lindemann, Alexander Robey, Lejun Jiang, Stephen Tu, and Nikolai Matni. Learning robust output control barrier functions from safe expert demonstrations. arXiv preprint arXiv:2111.09971, 2021.
- 2020 **Alexander Robey**, Hamed Hassani, and George J Pappas. Model-based robust deep learning. *arXiv preprint arXiv:2005.10247*, 2020.

2020 Edgar Dobriban, Hamed Hassani, David Hong, and **Alexander Robey**. Provable tradeoffs in adversarially robust classification. *arXiv preprint arXiv:2006.05161*, 2020.

# **Patents**

2020 **Alexander Robey**, Hamed Hassani, and George J Pappas. Model-based robust deep learning, 2020. United States Provisional Patent 63/034,355.

## Fellowships & Awards

- 2021 Outstanding Reviewer Award, Neural Information Processing Systems (NeurIPS) 2021.
- 2021 Outstanding Reviewer Award, International Conference on Learning Representations (ICLR) 2021.
- 2020 Outstanding Reviewer Award, International Conference on Machine Learning (ICML) 2020.
- 2020 Teaching Assistant of the Year, Department of Electrical and Systems Engineering, University of Pennsylvania.
- 2018 Dean's Fellowship, Department of Electrical and Systems Engineering, University of Pennsylvania.
- 2016 Summer Undergraduate Research Fellowship, Department of Engineering, Swarthmore College.

## Professional Activities

## Organizing

2021 International Conference on Computer Vision (ICCV) workshop on *Adversarial Robustness in the Real World*.

#### Reviewing

ICCPS 2020, 2021; L4DC 2020, 2021; CDC 2020, 2021; NeurIPS 2020, 2021; ICML 2020, 2021; ICLR 2021, 2022; ACC 2021; JMLR 2021; PAMI 2021; ICCV 2021; TAC 2021; IEEE RA-L 2021

#### Technical Skills

*Programming languages:* Python, MATLAB, JavaScript, HTML, CSS, R, C/C++, SQL (Postgres), Verilog HDL, LaTeX

Frameworks: Pytorch, TensorFlow, Jax, Django, Slurm

# Teaching Experience

- Spring 2021 ESE 605: Modern Convex Optimization, University of Pennsylvania (Teaching Assistant).
- Spring 2020 ESE 290: Introduction to Research Methodologies, University of Pennsylvania (Mentor).
  - Fall 2020 ESE 530: Elements of Probability Theory, University of Pennsylvania (Teaching Assistant).
  - Fall 2019 ESE 530: Elements of Probability Theory, University of Pennsylvania (Teaching Assistant).
- Spring 2018 ENGR 019: Numerical Methods for Engineering Applications, Swarthmore College (Teaching Assistant).
  - Fall 2017 ENGR 011: Electrical Circuit Analysis, Swarthmore College (Teaching Assistant).
- Spring 2017 ENGR 012: Linear Physical Systems Analysis, Swarthmore College (Teaching Assistant).
  - Fall 2016 ENGR 011: Electrical Circuit Analysis, Swarthmore College (Teaching Assistant).
- Spring 2016 ENGR 006: Engineering Mechanics, Swarthmore College (Teaching Assistant).

#### Selected Talks

- Dec. 2021 *Model-Based Domain Generalization*, CDC 2021 Workshop on Robust Deep Learning-Based Control, Austin, TX, USA (virtual).
- Oct. 2021 Robustness against Natural Variation: Theory and Practice, GRASP SFI Seminar, University of Pennsylvania, Philadelphia, PA, USA.

- Sept. 2021 A Critique of "Generalization in Adversarially Robust Deep Learning", NSF-Simons Math of Deep Learning (MoDL) annual meeting, Simons Foundation, New York, NY, USA.
- Sept. 2021 Robustness against Natural Variation: Theory and Practice, NSF-Simons THEORINET seminar, Baltimore, MD, USA (virtual).
- July 2021 Learning Robust Hybrid Control Barrier Functions for Uncertain Systems, 7th IFAC Conference on Analysis and Design of Hybrid Systems (ADHS), Brussels, Belgium (virtual).
- Apr. 2021 *Model-Based Robust Deep Learning: Generalizing to Natural Out-of-Distribution Data*, Italian Conference on CyberSecurity (ITASEC), Al for Security and Security for Al Workshop (virtual).
- Mar. 2021 *Model-Based Domain Generalization*, NSF-Simons Math of Deep Learning (MoDL) seminar (virtual).
- Dec. 2020 Learning Control Barrier Functions from Expert Demonstrations, 59<sup>th</sup> IEEE Conference on Decision and Control (CDC 2020), Jeju Island, Korea (virtual).
- Nov. 2020 *Model-Based Robust Deep Learning: Generalizing to Natural Out-of-Distribution Data*, Intel, Santa Clara, CA, USA (virtual).
- Oct. 2020 *Generalizing to Natural Out-of-Distribution Data*, C3.ai Workshop on the Analytical Foundations of Deep Learning (virtual).
- Sept. 2020 *Model-Based Robust Deep Learning: Generalizing to Natural Out-of-Distribution Data*, Intel, Santa Clara, CA, USA (virtual).
- Sept. 2020 Model-Based Robust Deep Learning: Generalizing to Natural Out-of-Distribution Data, Data Augmentation and Equivariance Workshop, University of Pennsylvania, Philadelphia, PA, USA (virtual).
- Aug. 2020 Model-Based Robust Deep Learning: Generalizing to Natural Out-of-Distribution Data, European Conference on Computer Vision (ECCV) workshop on Adversarial Robustness in the Real World, Glasgow, Scotland (virtual).
- July 2020 Model-Based Robust Deep Learning, Stanford University, Stanford, CA, USA (virtual).
- Dec. 2019 Efficient and Accurate Estimation of Lipschitz Constants of Deep Neural Networks, Spotlight talk at Neural Information Processing Systems (NeurIPS), Vancouver, Canada.
- May 2018 Computationally Expediting Fourier Ptychographic Miscroscopy, Swarthmore Research Showcase, Swarthmore College, Swarthmore, PA, USA.

### Selected Poster Presentations

- Dec. 2021 Adversarial Robustness via Semi-Infinite Constrained Learning, Neural Information Processing Systems (NeurIPS) 2021.
- Dec. 2021 Model-Based Domain Generalization, Neural Information Processing Systems (NeurIPS) 2021.
- Sept. 2021 *Model-Based Domain Generalization*, NSF-Simons Mathematics of Deep Learning (MoDL) annual meeting, Simons Foundation, New York, NY, USA.
- July 2021 Model-Based Robust Deep Learning: Generalizing to Natural Out-of-Distribution Data, International Conference on Machine Learning (ICML) Workshop on Uncertainty and Robustness in Deep Learning (virtual).
- June 2021 Optimal Algorithms for Submodular Maximization with Distributed Constraints, Learning for Dynamics and Control (L4DC), Zurich, Switzerland (virtual).
- Nov. 2020 Learning Hybrid Control Barrier Functions from Data, Conference on Robot Learning (CoRL), Boston, MA, USA (virtual).
- Dec. 2019 Efficient and Accurate Estimation of Lipschitz Constants of Deep Neural Networks, Neural Information Processing Systems (NeurIPS) 2019, Vancouver, Canada.
- Aug. 2017 Quantifying the Impact of Factors Affecting Communication Performance, Lawrence Livermore National Laborary (LLNL), Livermore, CA, USA.

Sept. 2016 Bird-Window Collision Prevention, Sigma Xi Poster Session, Swarthmore College, Swarthmore, PA, USA.