

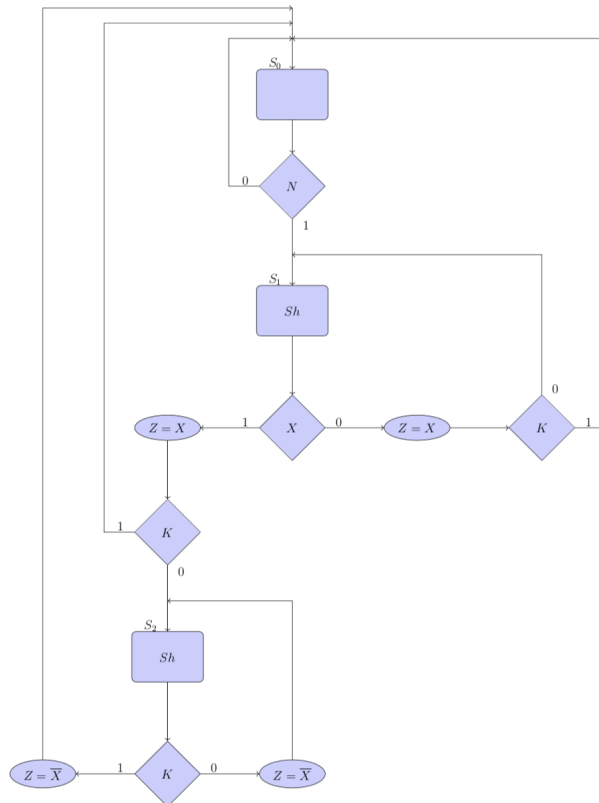
# Points to Remember

Aditya Arora

April 26, 2018

1. **For Asynchronous circuits:** The outputs are only to be written for the stable state condition while the other input conditions are all outputting don't cares i.e.  $X$  or  $-$
2. **Fundamental mode:** The state diagram assuming fundamental mode operation (output is shown as a Moore output but it only assumes that value if the state is stable)
3. **State Reduction Table:** All states except first vertically down, all states except last horizontally right
4. **POS and SOP:** SOP  $\rightarrow 1$  and POS  $\rightarrow 0$  (to remember when writing equation from K-Map)
5. **Asynchronous circuit analysis:** Question 13 from Assignment 10 is so smart, so many little tricks combined
6. **Writing DFF equation:** The DFF equations can be written directly since the property  $Q(t+1) = D$  is valid
7. **Mealy and Moore:** Mealy output on arrows, Moore output in state

## 8. ASM:

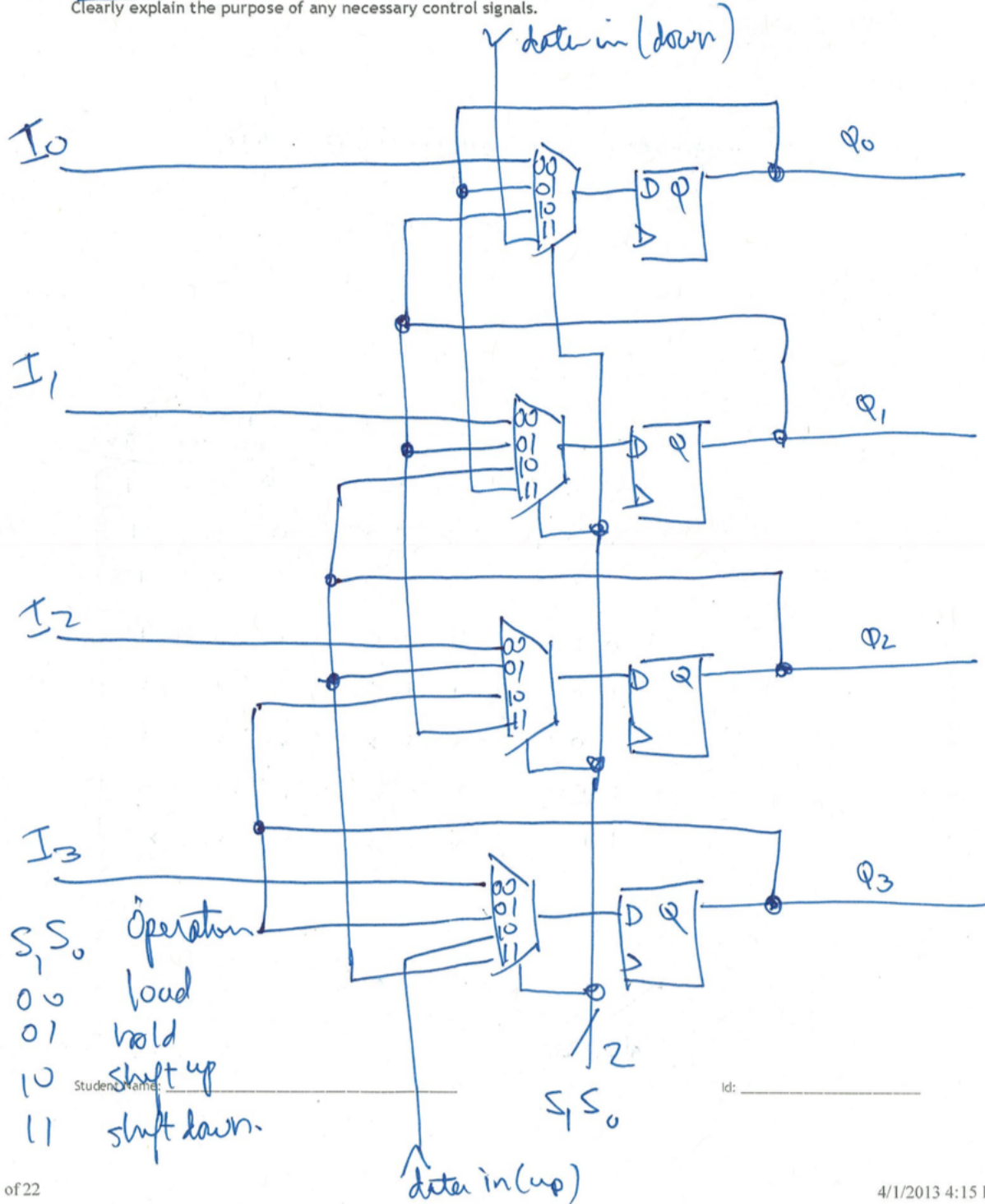


See the “Sh” shift signal for state dependent outputs

# 9. 4 Bit Bi-Directional shift register using D Flip Flops:

Part D) [4 MARKS]

Design and draw the circuit diagram for a 4-bit bi-directional shift register with parallel load and hold using D-type flip-flops. Use can use any other necessary circuit blocks (e.g., multiplexers, logic gates, etc.) required. Clearly explain the purpose of any necessary control signals.



10. **ASM:** ASM State changes are clocked by the edge

11. **f:**  $T_{clock} + T_{setup} + T_{data} = T \Rightarrow f_{max} = \frac{1}{T}$

12. **State Machine Diagram to Timing Diagram:** Output follows in Mealy diagram

### 13. DFF Equations:

One hot encoding implies  $A$  is 0001,  $B$  is 0010,  $C$  is 0100 and  $D$  is 1000. This leads to the state table given by

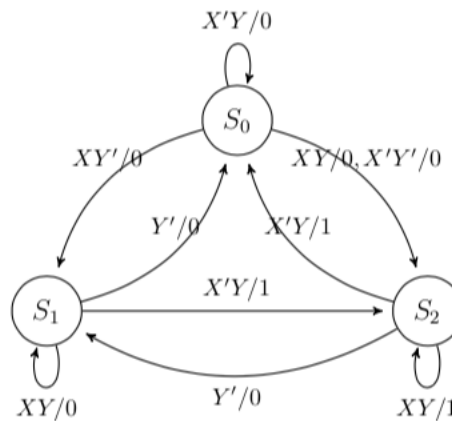
Current state $q_3q_2q_1q_0$	Next state		Outputs	
	$x = 0$ $q_3q_2q_1q_0$	$x = 1$ $q_3q_2q_1q_0$	$x = 0$ $z$	$x = 1$ $z$
0001	0100	1000	0	0
0010	0010	0001	0	0
0100	1000	0001	0	0
1000	0100	0010	1	1

The *DFF* equations can be written down directly.

$$\begin{aligned}
 d_3 &= \bar{x}q_2 + xq_0 \\
 d_2 &= \bar{x}q_3 + \bar{x}q_0 \\
 d_1 &= \bar{x}q_1 + xq_3 \\
 d_0 &= xq_2 + xq_1
 \end{aligned}$$

The circuit output is given as

$$z = q_3$$



### Solution:

Simply look at incoming edges for each state to get the flip flop input equations:

$$\begin{aligned}
 d_2 &= XY S_2 + X'Y S_1 + X'Y' S_0 \\
 d_1 &= XY S_1 + Y' S_2 + XY' S_0 \\
 d_0 &= X'Y S_0 + Y' S_1 + X'Y S_2
 \end{aligned}$$

The circuit output is a Mealy output given by

$$z = XY S_2 + X'Y S_2 + X'Y S_1$$

Note that I've written the flip flop inputs in terms of the symbolic state. You'd get the same thing if you did a state assignment; e.g.,  $S_0$  is 001,  $S_1$  is 010, and  $S_2$  is 100 and then called the flip flop outputs  $q_2q_1q_0$  — the  $S_i$  would simply get replaced by  $q_i$ .