

LU Algorithm

• Input an $m \times n$ matrix A

• Step 1: Row reduce A , if possible, to an echelon form matrix U , using only row replacement ops that add a multiple of a row to a row below

• Step 2: Place entries in L such that the same seq of row ops reduces $L \rightarrow I$

• Remark: a) the computational efficiency of the LU approach depends on the fact that L is obtained without doing any significant work.

b) Step 1 is not always possible. But if step 1 is possible, we will give the theoretical justification for why an LU factorization is easily obtained.

Eg:- $A = \begin{bmatrix} 1 & -1 & -2 \\ 1 & 0 & -3 \\ 2 & 3 & 12 \end{bmatrix}$ A $\xrightarrow{\text{Echelon}}$ U
e₁: R₁ $\rightarrow R_2 - R_1$
R₃ $\rightarrow R_3 - 2R_1$
R₃ $\rightarrow R_3 - 5R_1$

\rightarrow U (echelon form of A) = $\begin{bmatrix} 1 & -1 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

We record the elementary row ops e_i & their inverse f_i :

$$e_1 : R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 - 2R_1 \\ R_3 \rightarrow R_3 - 5R_1$$

$$f_1 : R_1 \rightarrow R_1 + R_2 \\ f_2 : R_3 \rightarrow R_3 + 2R_1 \\ f_3 : R_3 \rightarrow R_3 + 5R_1$$

The theory: the same steps which take A to U take L to I :-

$$I = (E_p \dots E_1) L \Rightarrow L = (E_p \dots E_1)^{-1} I$$

$$L = (E_1^{-1} \dots E_p^{-1}) I$$

To get L , apply f_3 , then f_2 , then f_1 to I

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\text{1) } f_3} \xrightarrow{\text{2) } f_2} \xrightarrow{\text{3) } f_1} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 2 & 5 & 1 \end{bmatrix} = L$$

lower triangular with 1's on diagonal.

$$\text{check: } LU = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 2 & 5 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 2 \\ 1 & 0 & -1 \\ 2 & 3 & 2 \end{bmatrix} = A$$

Note: If we have to solve for only one given RHS, say \bar{b}_1 , then, it is better to do directly by ~~RREF~~ augmented matrix. But if we have to solve for $\bar{b}_1, \bar{b}_2, \dots, \bar{b}_r$, you can use the same LU for all of them.

Solve $A\bar{x} = \bar{b}$ where $\bar{x} = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$

Now $-L\bar{y} = \bar{b}$ is:

$$y_1 = 2$$

$$y_1 + y_2 = -1$$

$$2y_1 + 5y_2 + y_3 = 1$$

Rather than row-redundant, we just do forward substitution

$$y_1 = 2$$

$$y_2 = -3$$

$$y_3 = 12$$

Now we solve $U\bar{x} = \bar{y} = \begin{bmatrix} 2 \\ -3 \\ 12 \end{bmatrix}$

$$U = \begin{bmatrix} 1 & 1 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$x_1 - x_2 - 2x_3 = 2$$

$$x_2 + x_3 = -3$$

$$x_3 = 12$$

To solve this, we use back-substitution

$$\Rightarrow x_3 = 12$$

$$x_2 = -15$$

$$x_1 = 1)$$