

view_frames Result

Recorded at time: 2363.140

map

Broadcaster: /map_odom_broadcaster
Average rate: 10.204 Hz
Most recent transform: 2363.220 (-0.080 sec old)
Buffer length: 4.900 sec

odom

Broadcaster: /ekf_localization
Average rate: 50.201 Hz
Most recent transform: 2363.120 (0.020 sec old)
Buffer length: 4.980 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.130 (0.010 sec old)
Buffer length: 4.980 sec

front_left_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.130 (0.010 sec old)
Buffer length: 4.980 sec

front_right_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.130 (0.010 sec old)
Buffer length: 4.980 sec

rear_left_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.130 (0.010 sec old)
Buffer length: 4.980 sec

rear_right_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.130 (0.010 sec old)
Buffer length: 4.980 sec

base_footprint

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.640 (-0.500 sec old)
Buffer length: 4.980 sec

top_plate_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.640 (-0.500 sec old)
Buffer length: 4.980 sec

base_laser_mount

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.640 (-0.500 sec old)
Buffer length: 4.980 sec

base_laser

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.640 (-0.500 sec old)
Buffer length: 4.980 sec

front_bumper_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.640 (-0.500 sec old)
Buffer length: 4.980 sec

imu_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.640 (-0.500 sec old)
Buffer length: 4.980 sec

inertial_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.640 (-0.500 sec old)
Buffer length: 4.980 sec

rear_bumper_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.640 (-0.500 sec old)
Buffer length: 4.980 sec

top_chassis_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.640 (-0.500 sec old)
Buffer length: 4.980 sec

user_rail_link

Broadcaster: /robot_state_publisher
Average rate: 50.201 Hz
Most recent transform: 2363.640 (-0.500 sec old)
Buffer length: 4.980 sec