

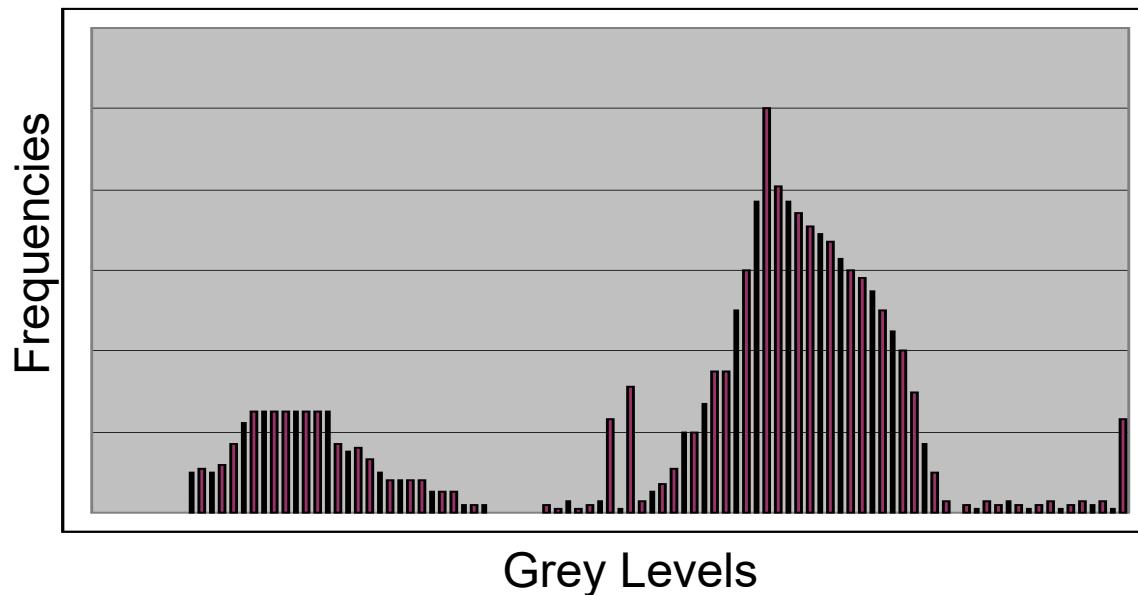
# Intensity Transformations

## Histogram Processing

# Image Histograms

The histogram of an image shows us the distribution of grey levels in the image

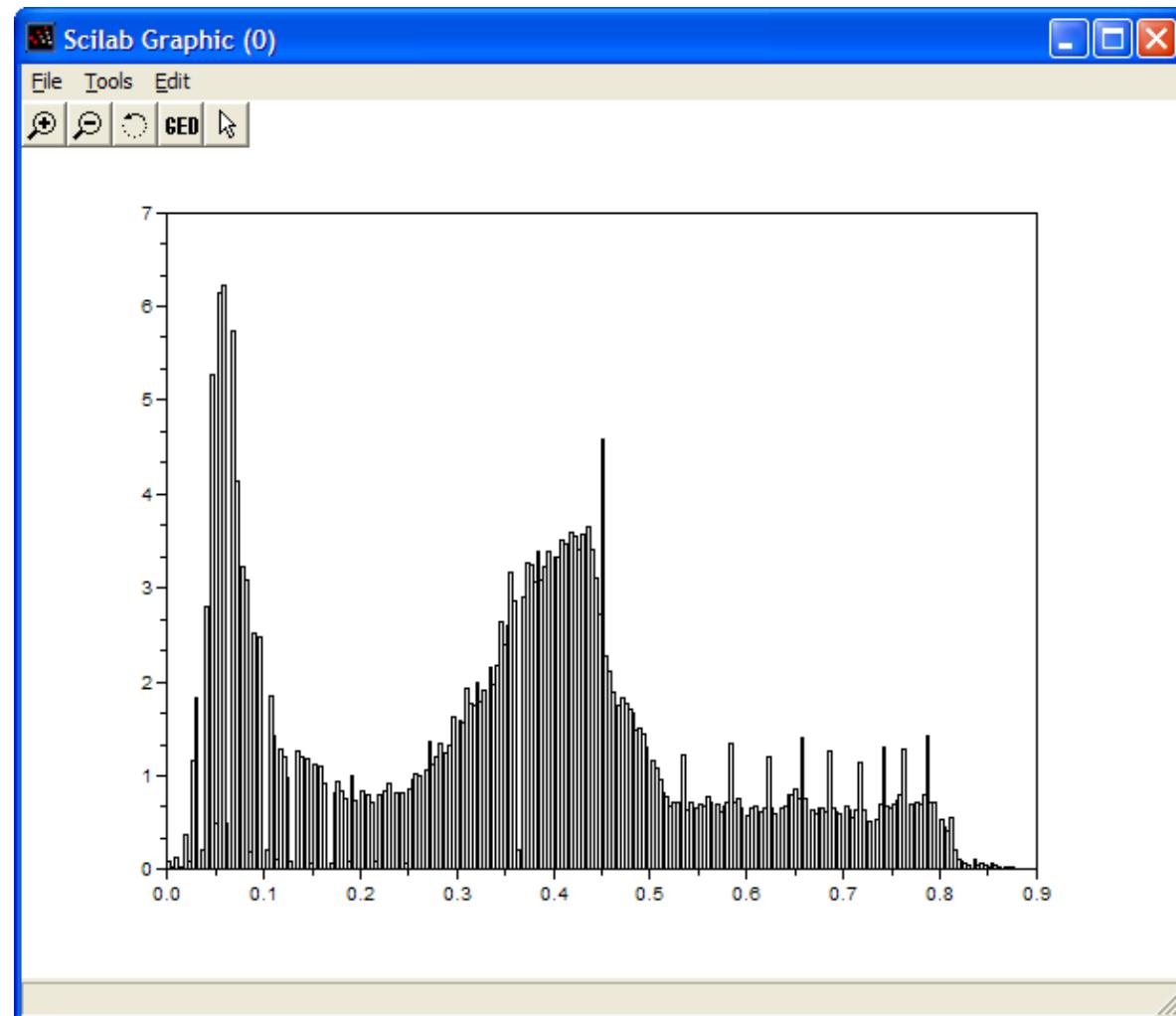
Massively useful in image processing,  
especially in segmentation



# Histogram Examples



# Histogram Examples (cont...)



# Histogram Processing

Histogram  $h(r_k) = n_k$

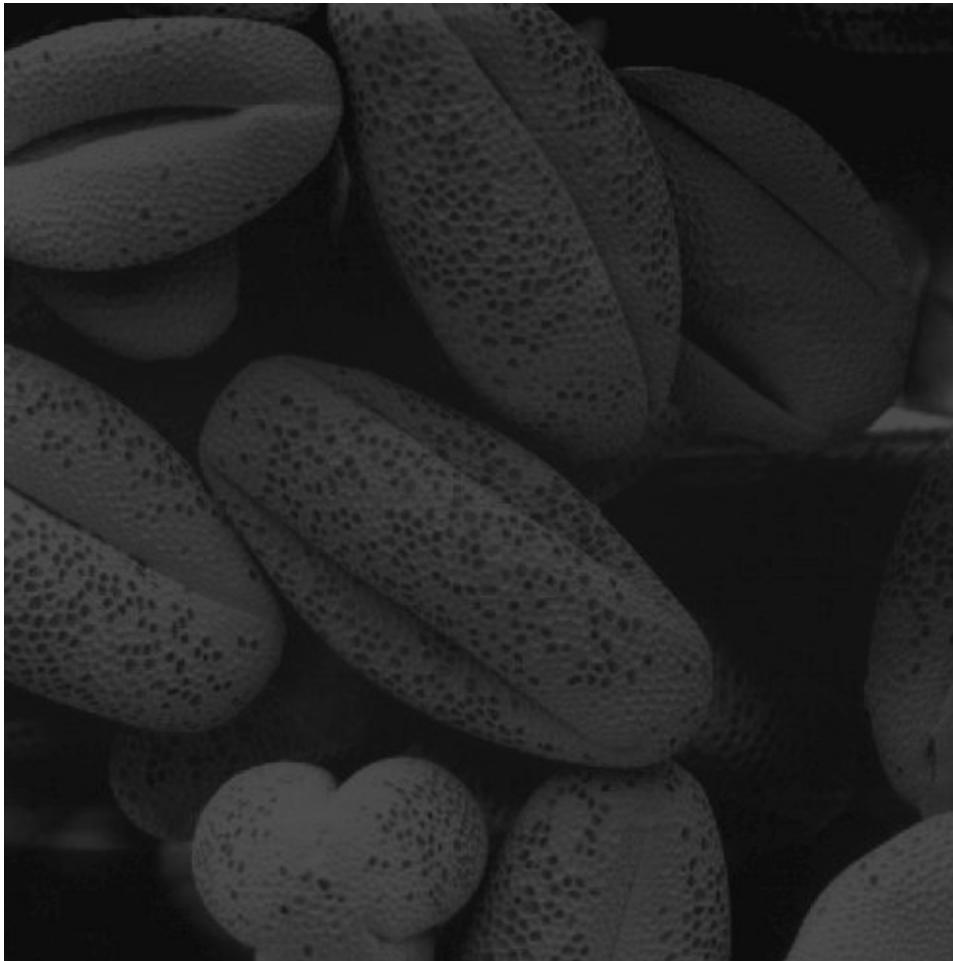
$r_k$  is the  $k^{th}$  intensity value

$n_k$  is the number of pixels in the image with intensity  $r_k$

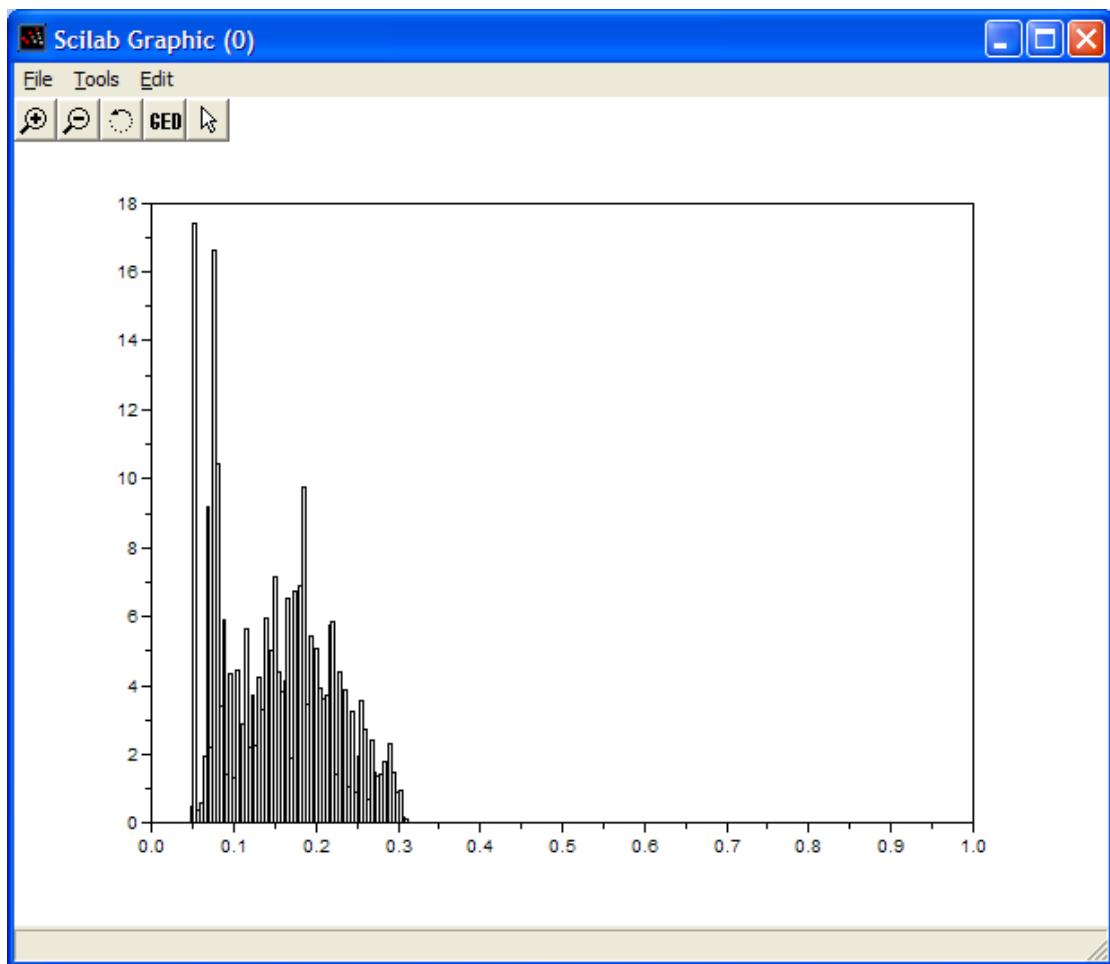
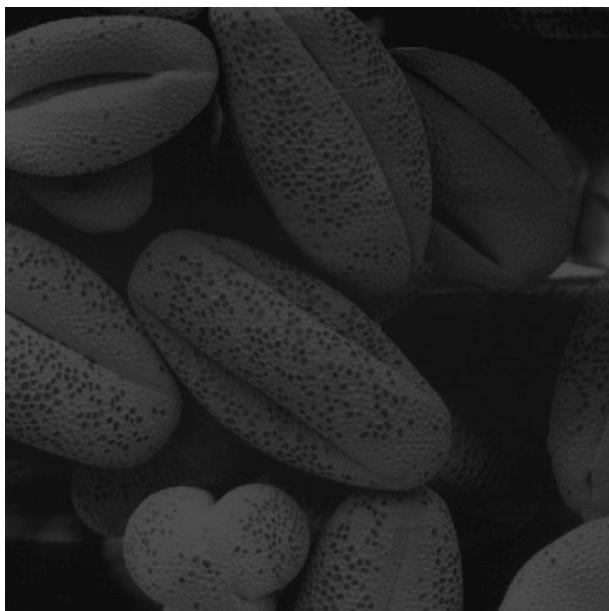
Normalized histogram  $p(r_k) = \frac{n_k}{MN}$

$n_k$ : the number of pixels in the image of size  $M \times N$  with intensity  $r_k$

# Histogram Examples (cont...)



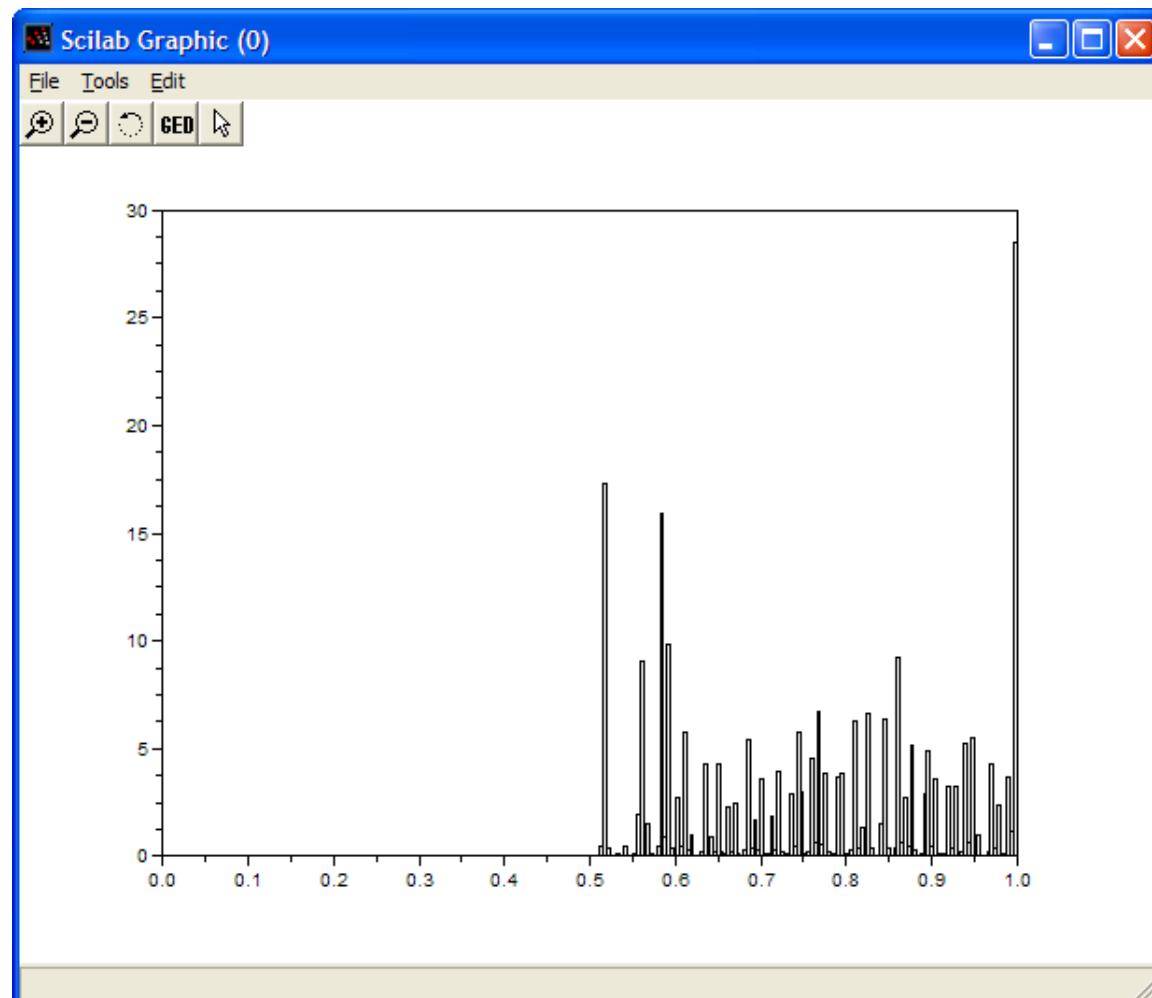
# Histogram Examples (cont...)



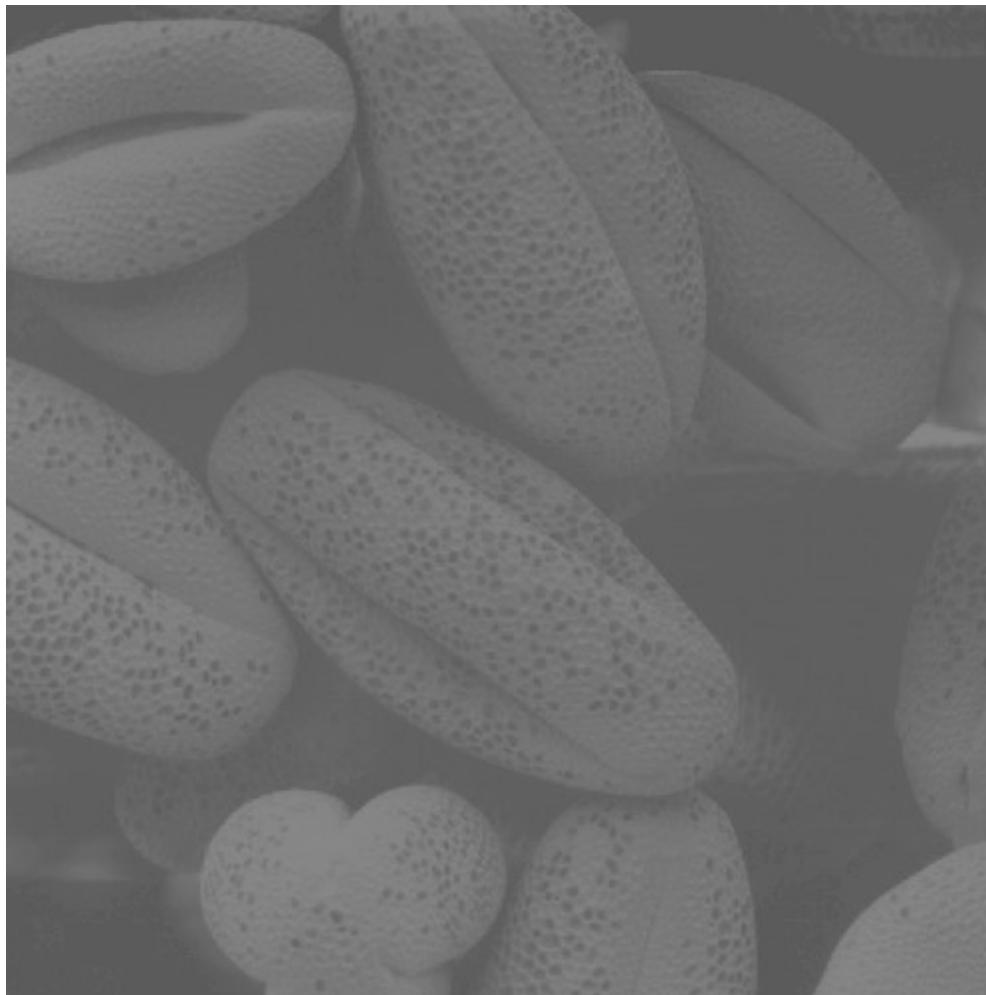
# Histogram Examples (cont...)



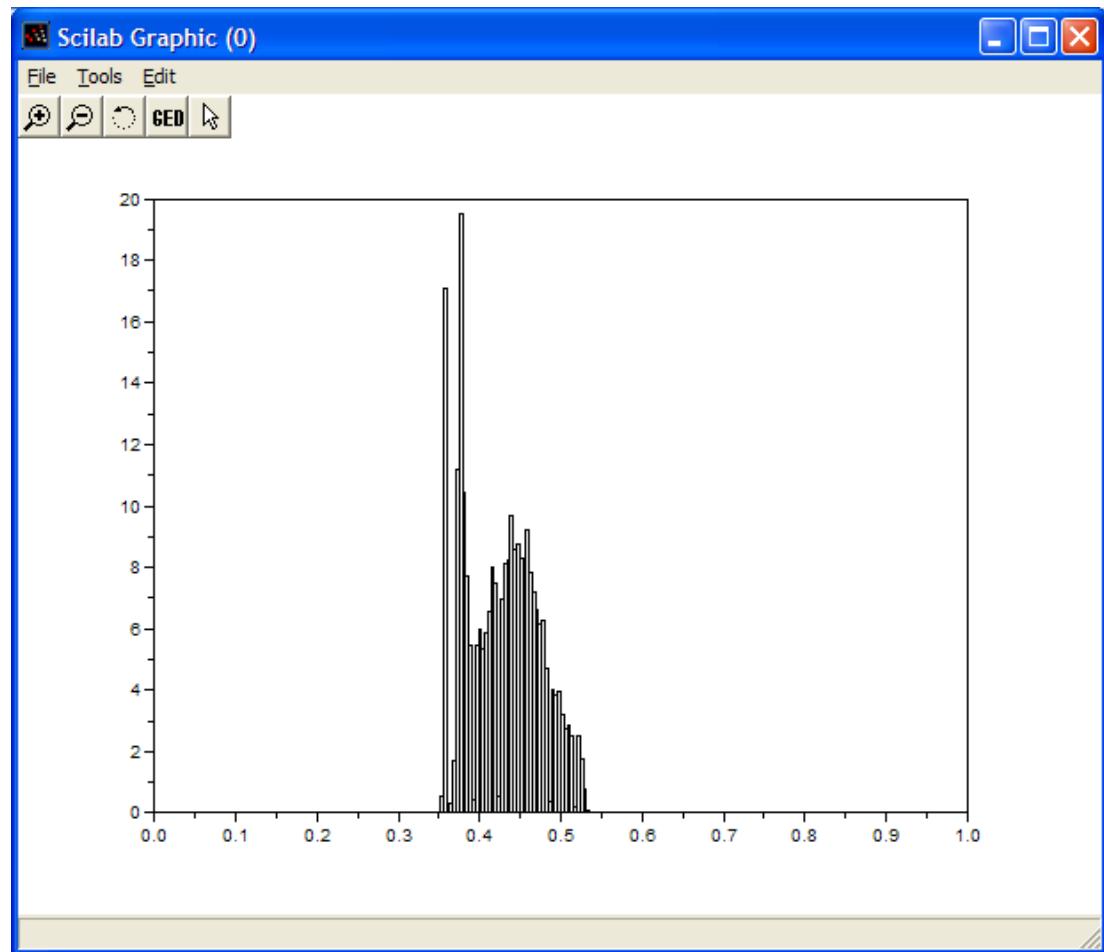
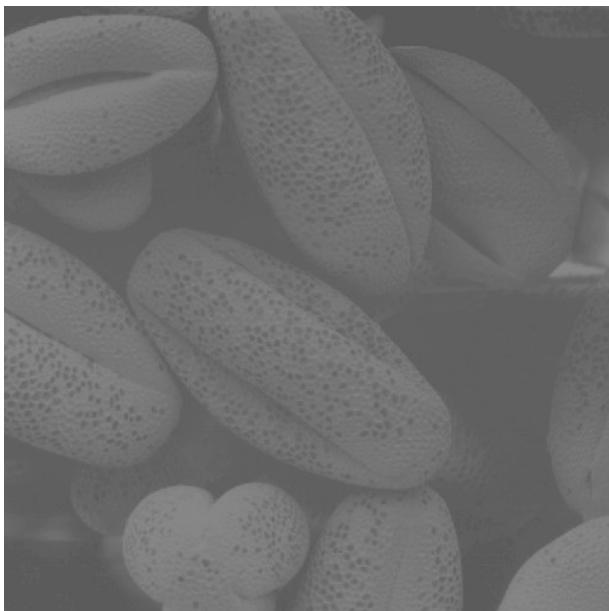
# Histogram Examples (cont...)



# Histogram Examples (cont...)



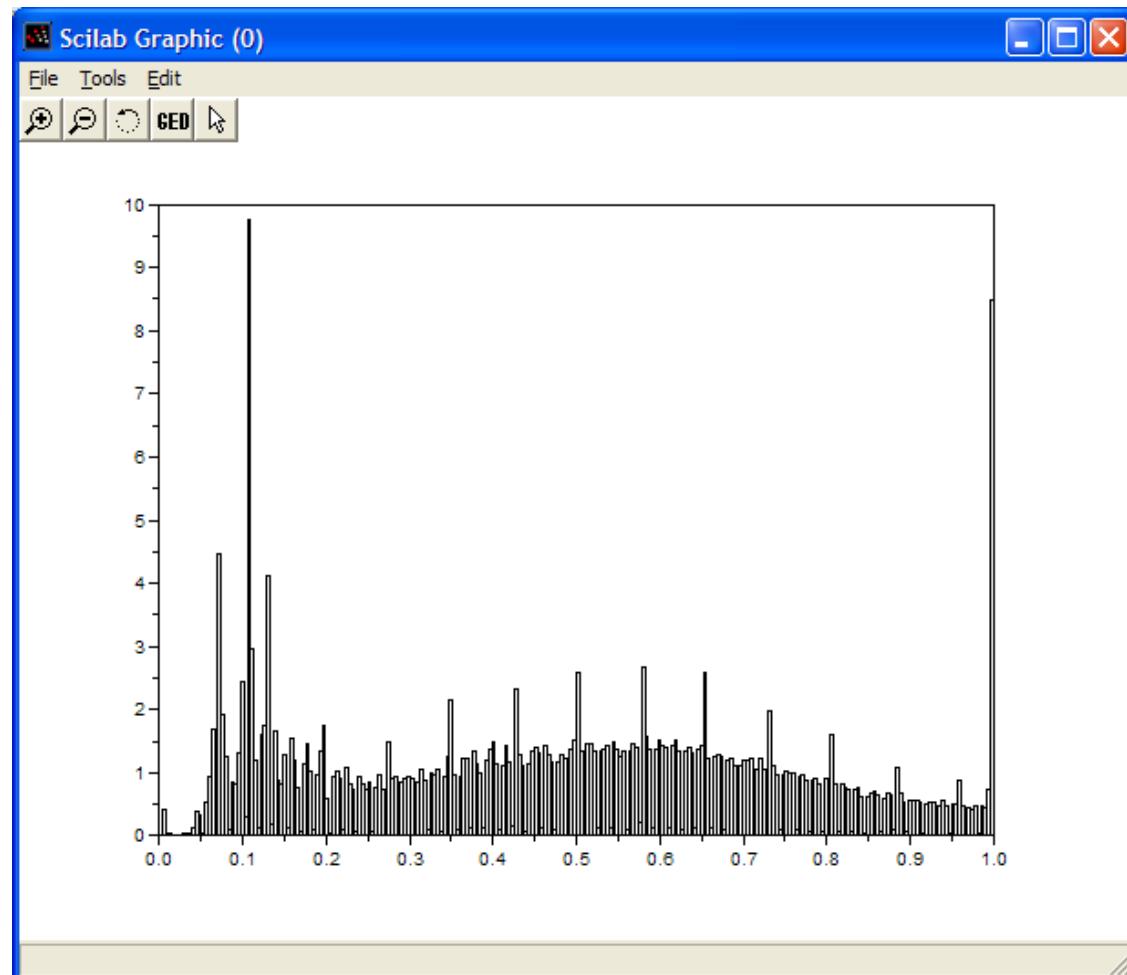
# Histogram Examples (cont...)



# Histogram Examples (cont...)

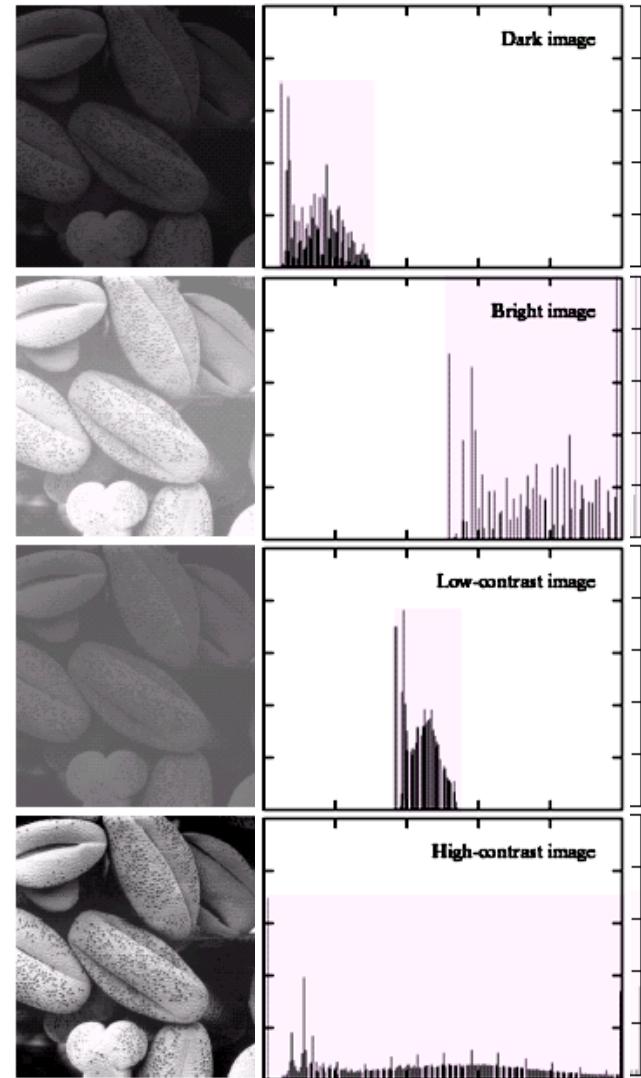


# Histogram Examples (cont...)



# Histogram Examples (cont...)

- A selection of images and their histograms
- Notice the relationships between the images and their histograms
- Note that the high contrast image has the most evenly spaced histogram



# Contrast Stretching

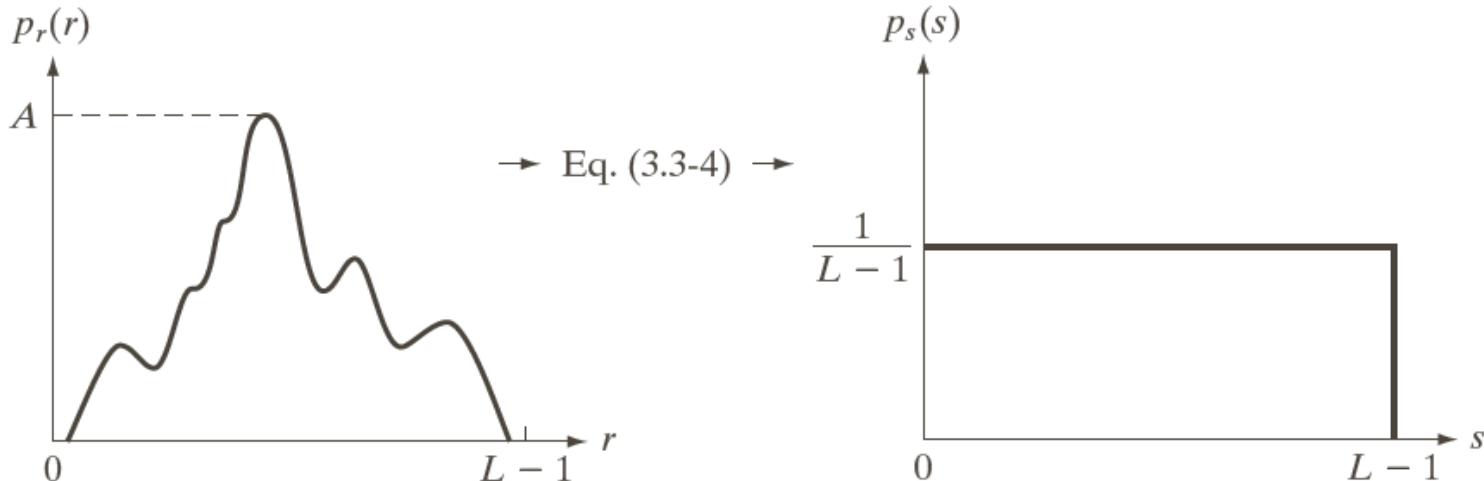
- We can fix images that have poor contrast by applying a pretty simple contrast specification
- The interesting part is how do we decide on this transformation function?



# Histogram Equalization

The intensity levels in an image may be viewed as random variables in the interval  $[0, L-1]$ .

Let  $p_r(r)$  and  $p_s(s)$  denote the probability density function (PDF) of random variables  $r$  and  $s$ .



a b

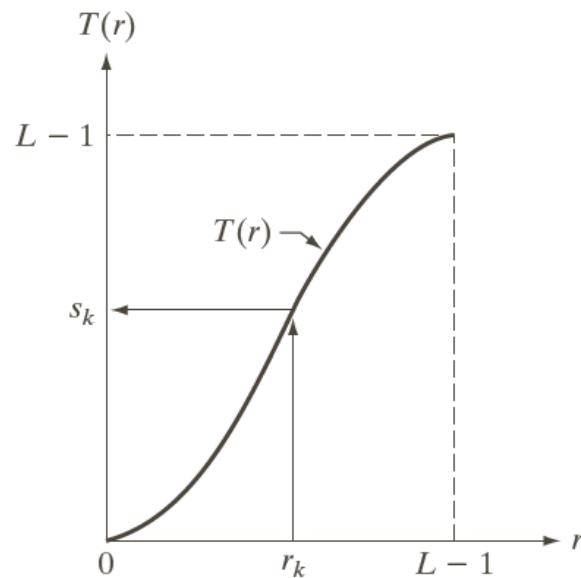
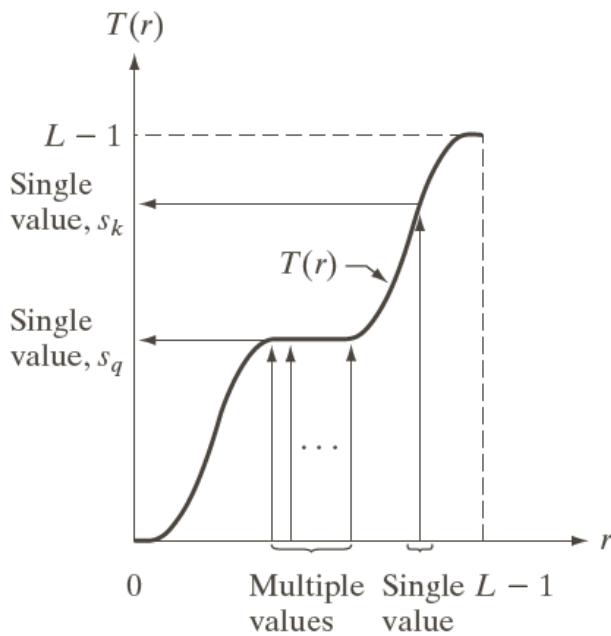
**FIGURE 3.18** (a) An arbitrary PDF. (b) Result of applying the transformation in Eq. (3.3-4) to all intensity levels,  $r$ . The resulting intensities,  $s$ , have a uniform PDF, independently of the form of the PDF of the  $r$ 's.

# Histogram Equalization

$$s = T(r) \quad 0 \leq r \leq L - 1$$

- a.  $T(r)$  is a strictly monotonically increasing function in the interval  $0 \leq r \leq L - 1$ ;
- b.  $0 \leq T(r) \leq L - 1$  for  $0 \leq r \leq L - 1$ .

a b



**FIGURE 3.17**

(a) Monotonically increasing function, showing how multiple values can map to a single value.

(b) Strictly monotonically increasing function. This is a one-to-one mapping, both ways.

# Histogram Equalization

$$s = T(r) \quad 0 \leq r \leq L - 1$$

- a.  $T(r)$  is a strictly monotonically increasing function in the interval  $0 \leq r \leq L - 1$ ;
- b.  $0 \leq T(r) \leq L - 1$  for  $0 \leq r \leq L - 1$ .

$T(r)$  is continuous and differentiable.

$$p_s(s)ds = p_r(r)dr$$

# Histogram Equalisation (cont...)

- We can view intensities  $r$  and  $s$  as random variables and their histograms as probability density functions (pdf)  $p_r(r)$  and  $p_s(s)$ .
- Fundamental result from probability theory:
  - If  $p_r(r)$  and  $T(r)$  are known and  $T(r)$  is continuous and differentiable, then

$$p_s(s) = p_r(r) \frac{1}{\left| \frac{ds}{dr} \right|} = p_r(r) \left| \frac{dr}{ds} \right|$$

# Histogram Equalisation (cont...)

- The pdf of the output is determined by the pdf of the input and the transformation.
- This means that we can determine the histogram of the output image.
- A transformation of particular importance in image processing is the cumulative distribution function (CDF) of a random variable:

$$s = T(r) = (L - 1) \int_0^r p_r(w) dw$$

# Histogram Equalisation (cont...)

- It satisfies the first condition as the area under the curve increases as  $r$  increases.
- It satisfies the second condition as for  $r=L-1$  we have  $s=L-1$ .
- To find  $p_s(s)$  we have to compute

$$\frac{ds}{dr} = \frac{dT(r)}{dr} = (L-1) \frac{d}{dr} \int_0^r p_r(w) dw = (L-1)p_r(r)$$

# Histogram Equalisation (cont...)

Substituting this result:

$$\frac{ds}{dr} = (L-1)p_r(r)$$

to

$$p_s(s) = p_r(r) \left| \frac{dr}{ds} \right|$$

Uniform pdf

yields

$$p_s(s) = p_r(r) \left| \frac{1}{(L-1)p_r(r)} \right| = \frac{1}{L-1}, \quad 0 \leq s \leq L-1$$

# Histogram Equalisation (cont...)

The formula for histogram equalisation in the discrete case is given

$$s_k = T(r_k) = (L-1) \sum_{j=0}^k p_r(r_j) = \frac{(L-1)}{MN} \sum_{j=0}^k n_j$$

where

- $r_k$ : input intensity
- $s_k$ : processed intensity
- $n_j$ : the frequency of intensity  $j$
- $MN$ : the number of image pixels.

# Histogram Equalisation (cont...)

## Example

A 3-bit 64x64 image has the following intensities:

$r_k$	$n_k$	$p_r(r_k) = n_k/MN$
$r_0 = 0$	790	0.19
$r_1 = 1$	1023	0.25
$r_2 = 2$	850	0.21
$r_3 = 3$	656	0.16
$r_4 = 4$	329	0.08
$r_5 = 5$	245	0.06
$r_6 = 6$	122	0.03
$r_7 = 7$	81	0.02

$$s_k = T(r_k) = (L-1) \sum_{j=0}^k p_r(r_j)$$

Applying histogram equalization:

$$s_0 = T(r_0) = 7 \sum_{j=0}^0 p_r(r_j) = 7 p_r(r_0) = 1.33$$

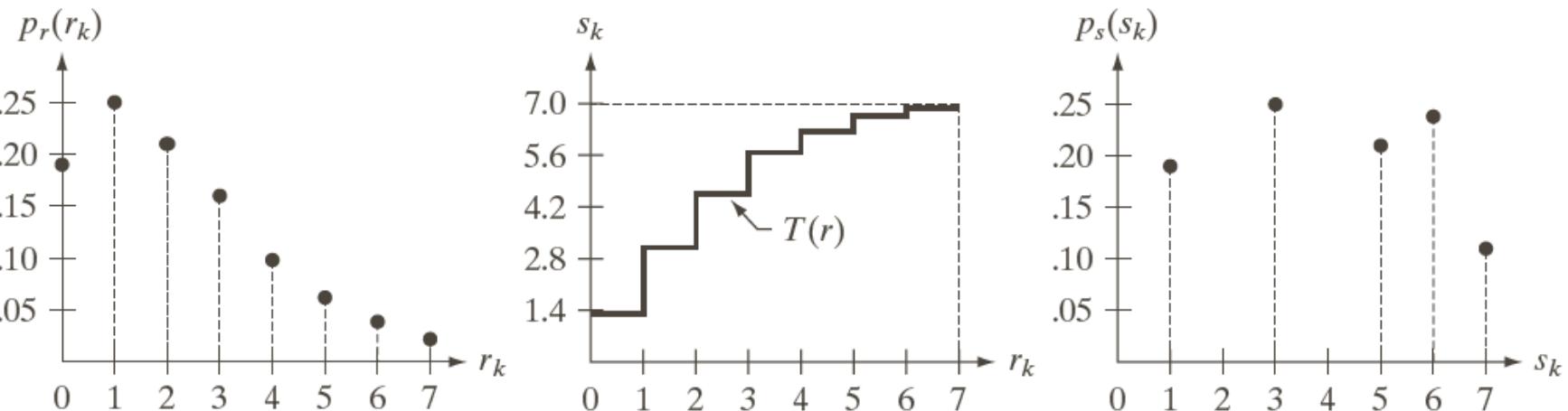
$$s_1 = T(r_1) = 7 \sum_{j=0}^1 p_r(r_j) = 7 p_r(r_0) + 7 p_r(r_1) = 3.08$$

# Histogram Equalisation (cont...)

## Example

Rounding to the nearest integer:

$$\begin{array}{llll} s_0 = 1.33 \rightarrow 1 & s_1 = 3.08 \rightarrow 3 & s_2 = 4.55 \rightarrow 5 & s_3 = 5.67 \rightarrow 6 \\ s_4 = 6.23 \rightarrow 6 & s_5 = 6.65 \rightarrow 7 & s_6 = 6.86 \rightarrow 7 & s_7 = 7.00 \rightarrow 7 \end{array}$$



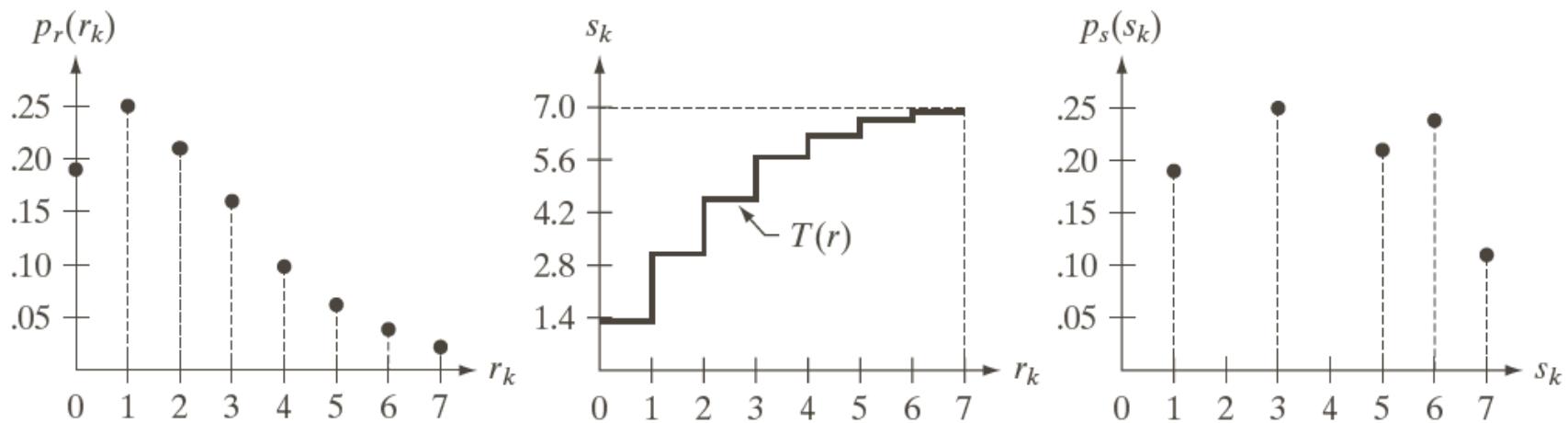
a | b | c

**FIGURE 3.19** Illustration of histogram equalization of a 3-bit (8 intensity levels) image. (a) Original histogram. (b) Transformation function. (c) Equalized histogram.

# Histogram Equalization (cont...)

## Example

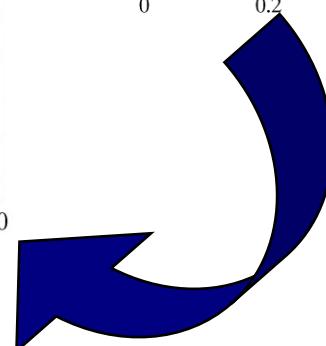
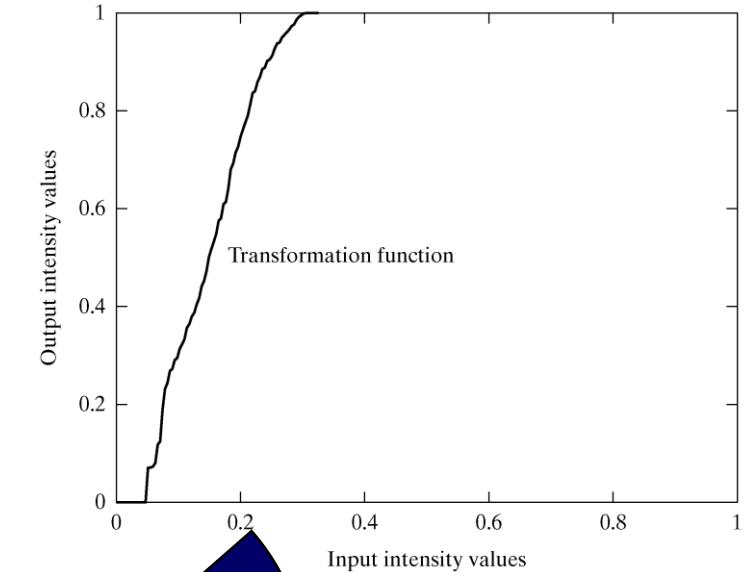
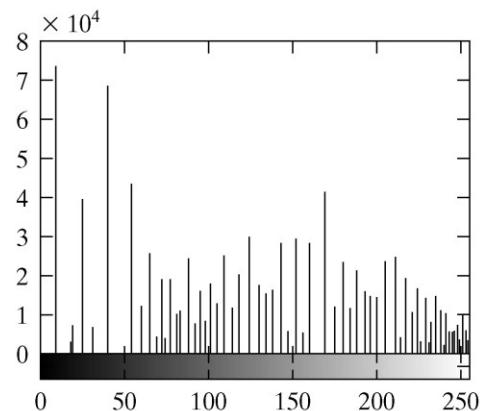
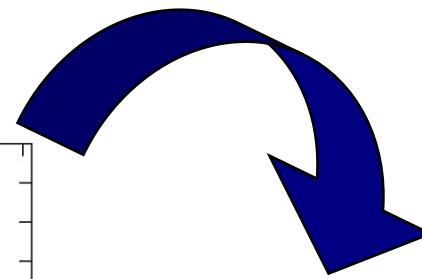
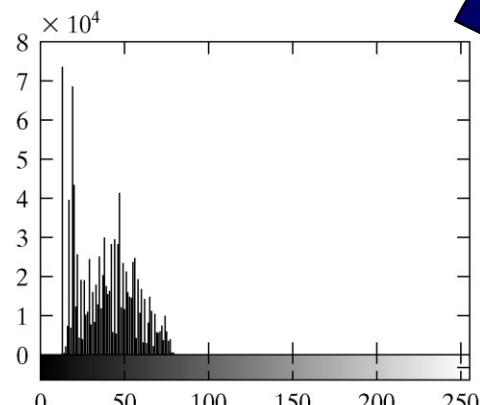
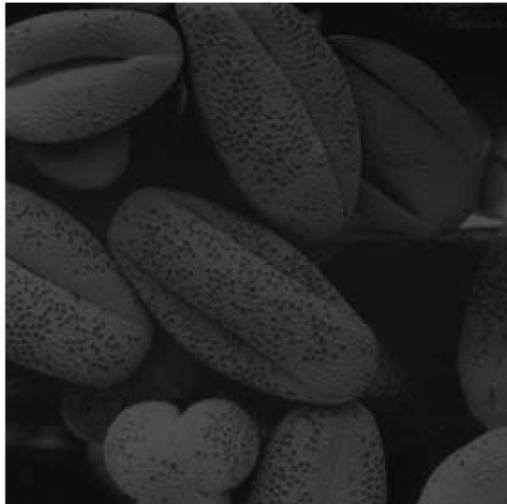
Notice that due to discretization, the resulting histogram will rarely be perfectly flat. However, it will be extended.



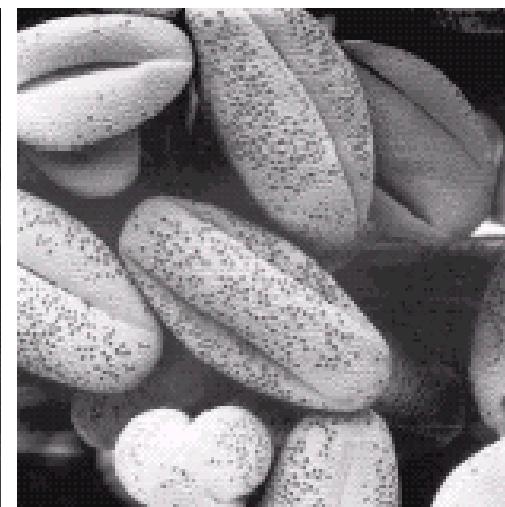
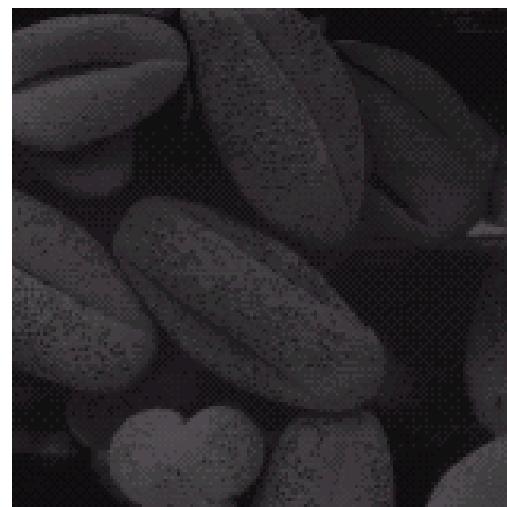
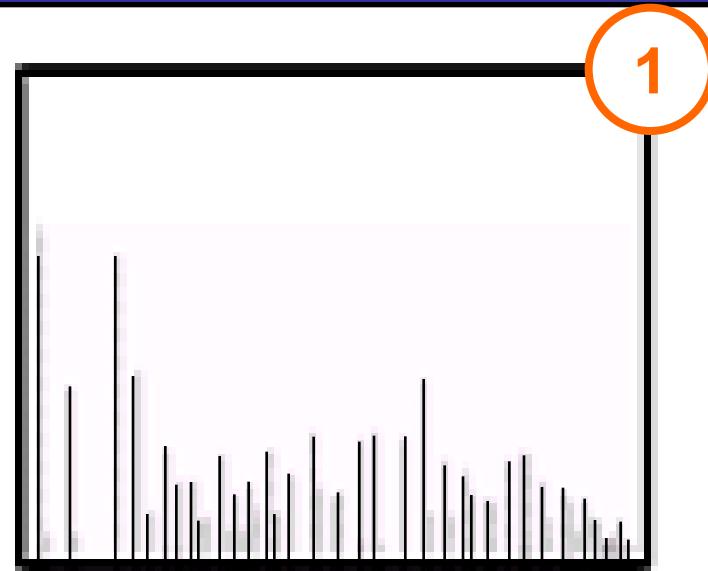
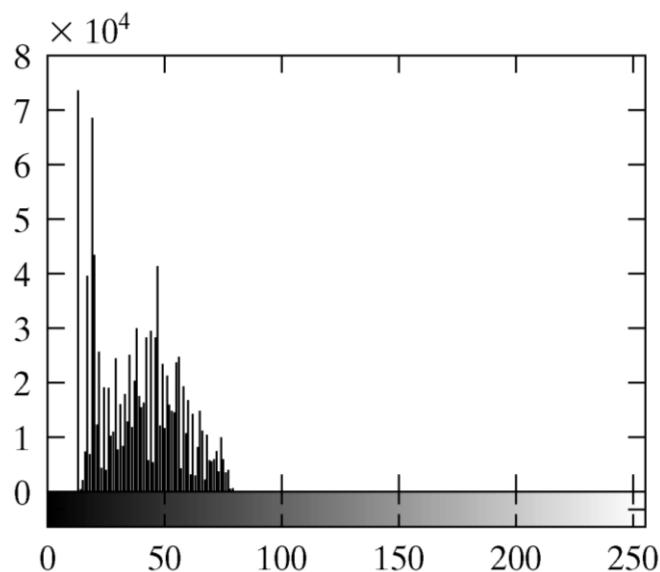
a | b | c

**FIGURE 3.19** Illustration of histogram equalization of a 3-bit (8 intensity levels) image. (a) Original histogram. (b) Transformation function. (c) Equalized histogram.

# Equalisation Transformation Function



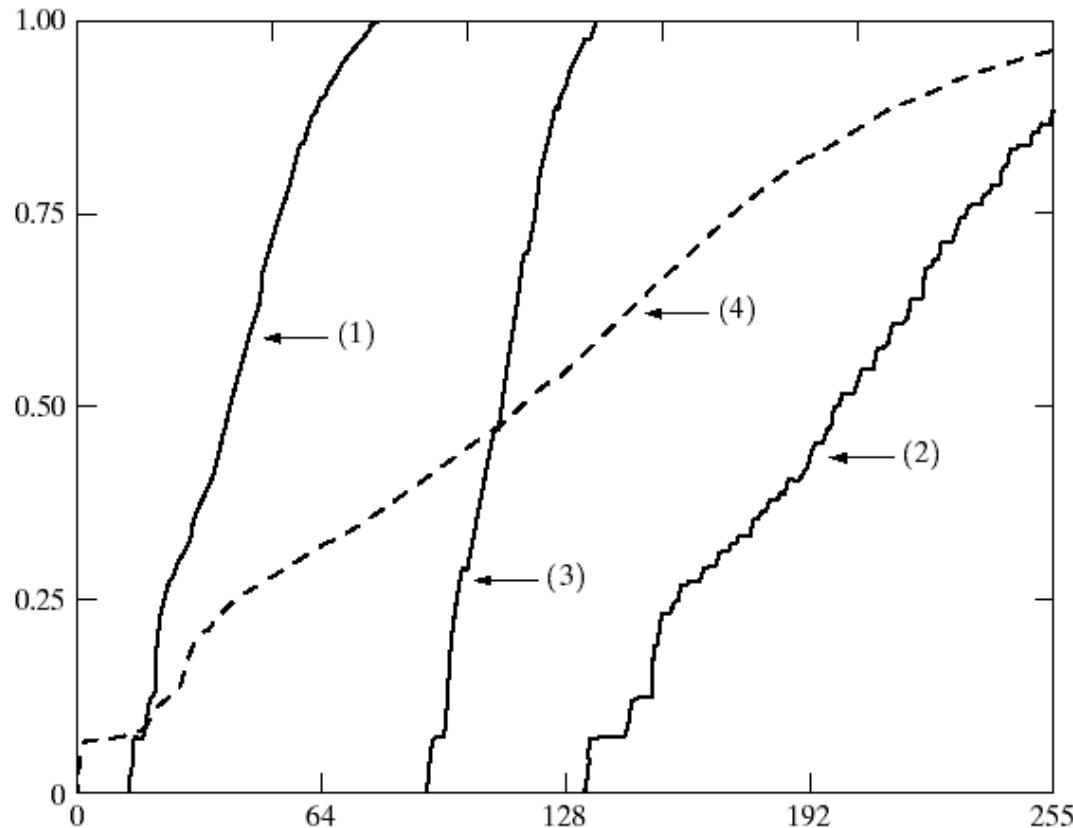
# Equalisation Examples



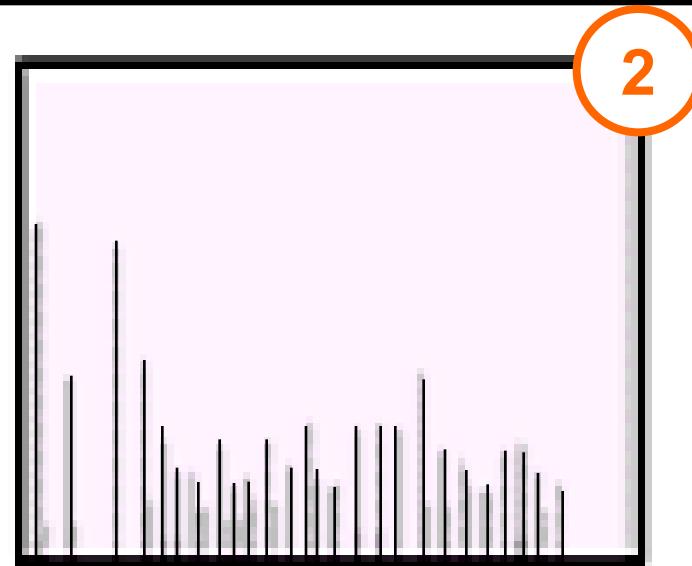
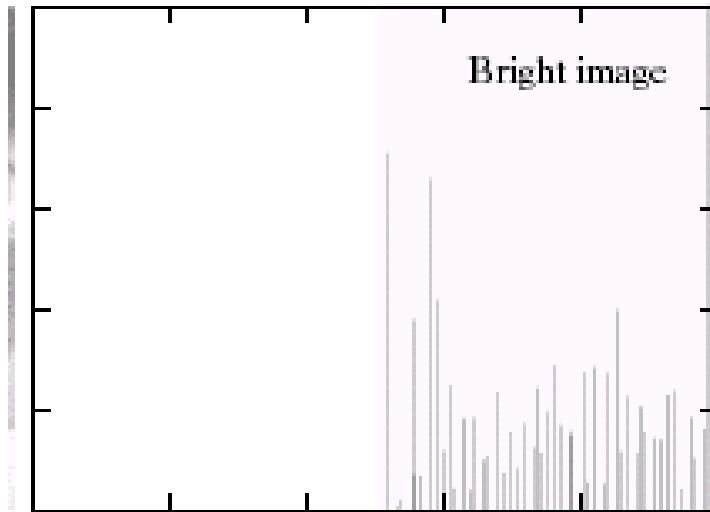
1

# Equalisation Transformation Functions

The functions used to equalise the images in the previous example

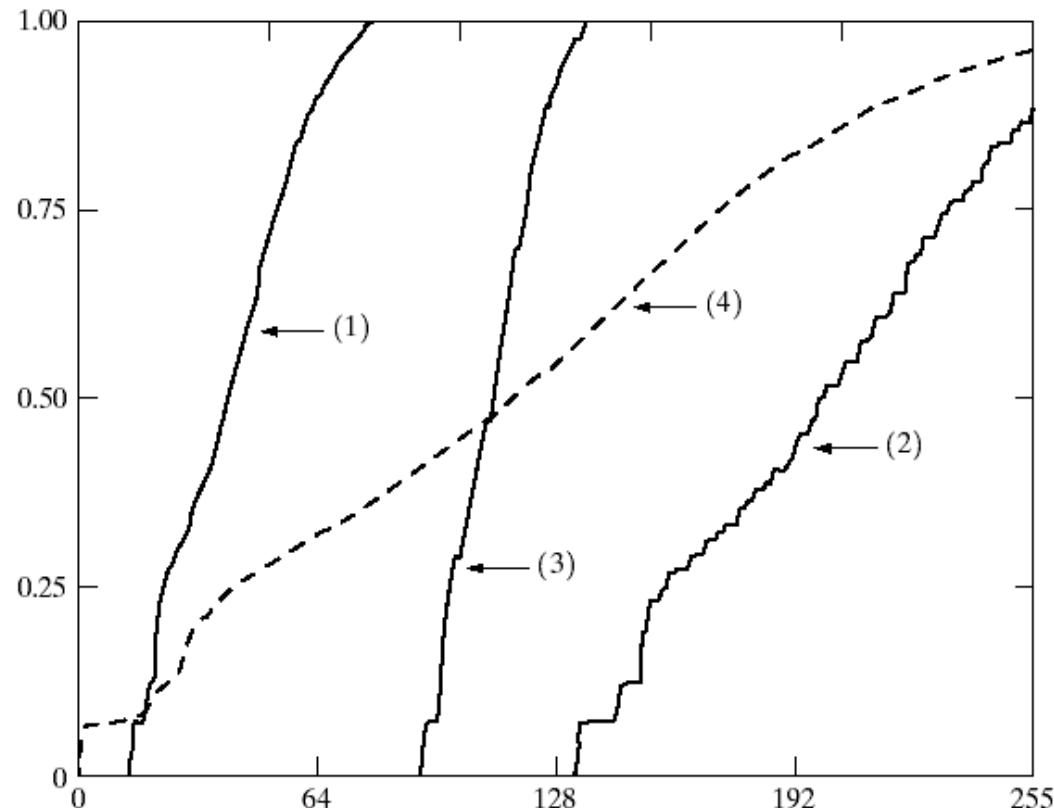


# Equalisation Examples

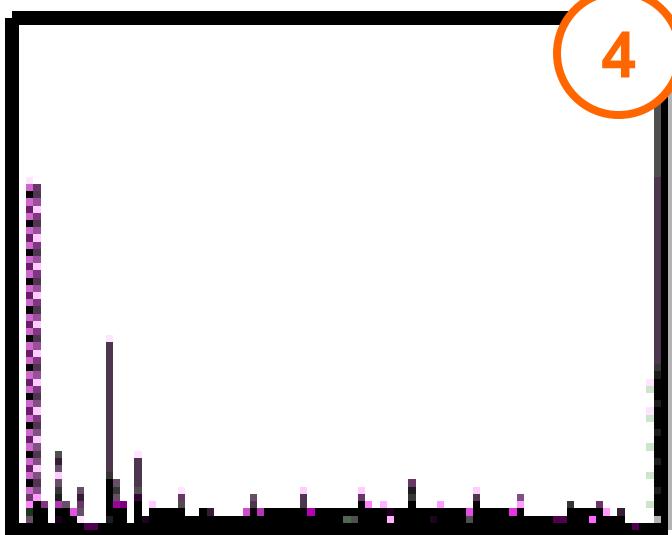
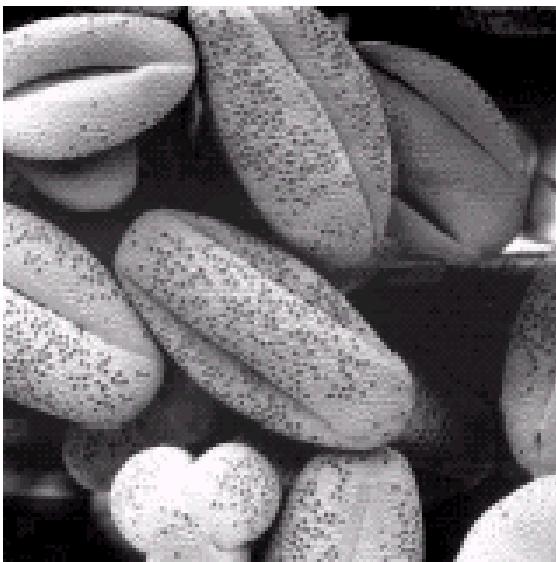
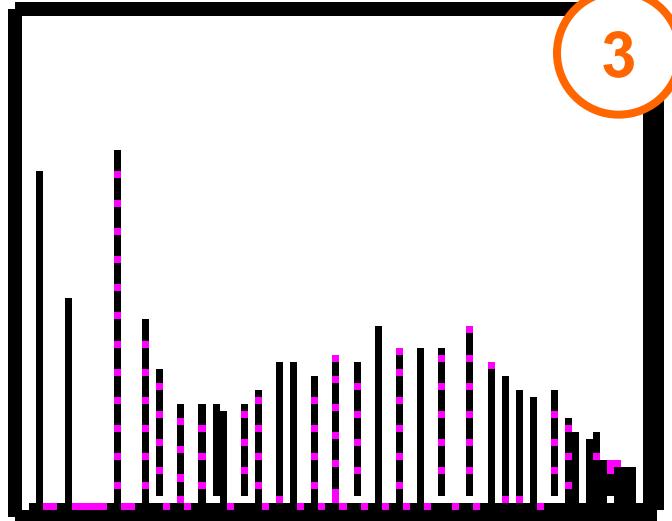
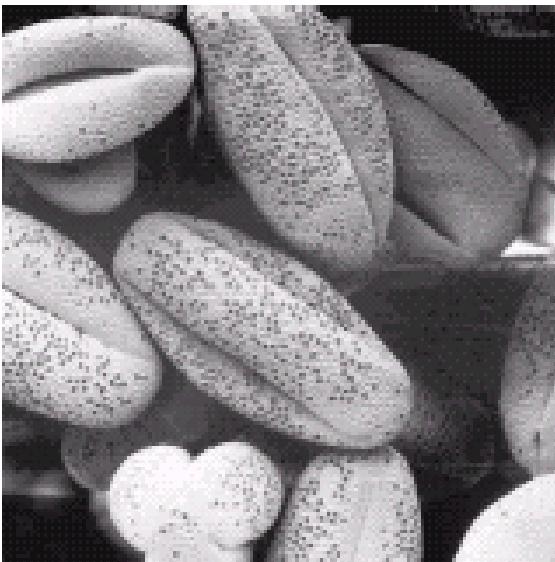


# Equalisation Transformation Functions

The functions used to equalise the images in the previous example

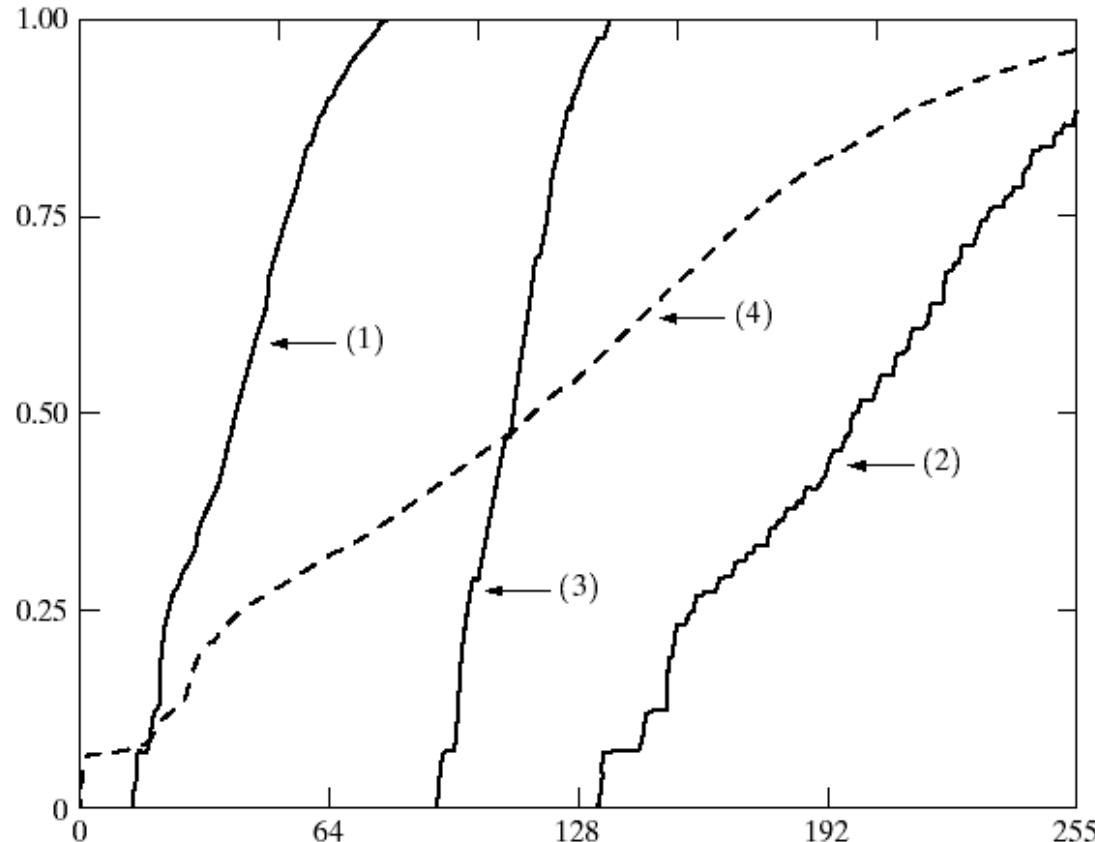


# Equalisation Examples (cont...)



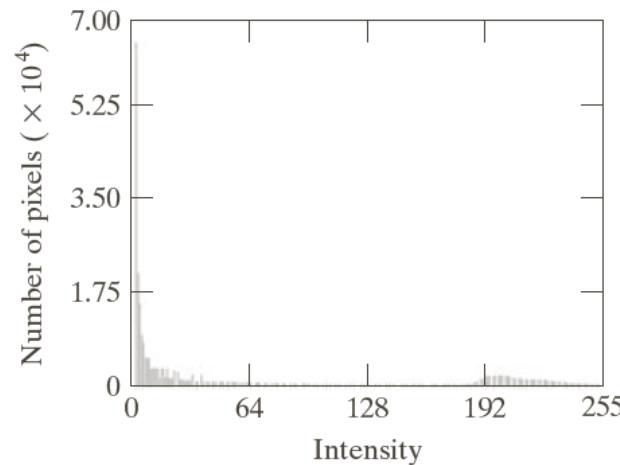
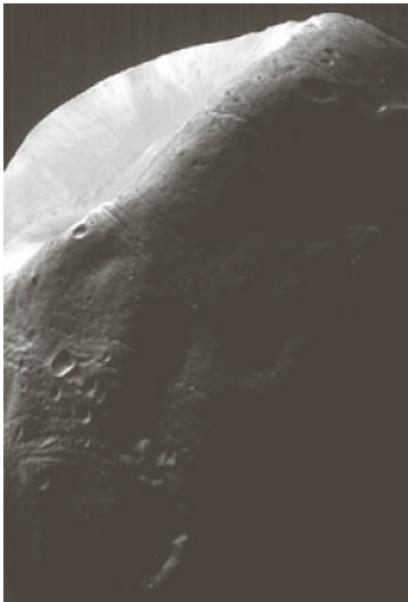
# Equalisation Transformation Functions

The functions used to equalise the images in the previous examples



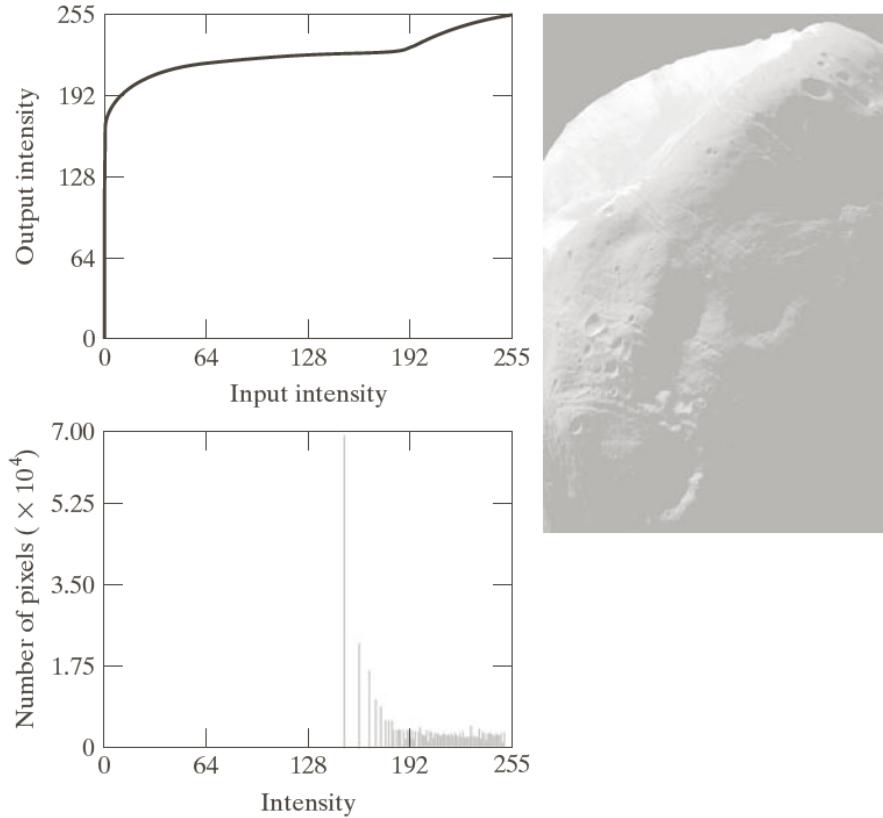
# Histogram Specification

- Histogram equalization does not always provide the desirable results.



- Image of Phobos (Mars moon) and its histogram.
- Many values near zero in the initial histogram

# Histogram Specification (cont...)



Histogram equalization

# Histogram specification (cont.)

- In these cases, it is more useful to specify the final histogram.
- Problem statement:
  - Given  $p_r(r)$  from the image and the target histogram  $p_z(z)$ , estimate the transformation  $z=T(r)$ .
- The solution exploits histogram equalization.

# Histogram specification (cont...)

- Equalize the initial histogram of the image:

$$s = T(r) = (L-1) \int_0^r p_r(w) dw \quad \xrightarrow{\hspace{1cm}} \quad G(z) = T(r)$$

- Equalize the target histogram:

$$s = G(z) = (L-1) \int_0^r p_z(w) dw \quad \xrightarrow{\hspace{1cm}}$$

- Obtain the inverse transform:  $z = G^{-1}(s) = G^{-1}(T(r))$

In practice, for every value of  $r$  in the image:

- get its equalized transformation  $s=T(r)$ .
- perform the inverse mapping  $z=G^{-1}(s)$ , where  $s=G(z)$  is the equalized target histogram.

# Histogram specification (cont...)

The discrete case:

- Equalize the initial histogram of the image:

$$s_k = T(r_k) = (L-1) \sum_{j=0}^k p_r(r_j) = \frac{(L-1)}{MN} \sum_{j=0}^k n_j \quad \xrightarrow{\text{G}} \quad G(z) = T(r)$$

- Equalize the target histogram:

$$s_k = G(z_q) = (L-1) \sum_{i=0}^q p_z(r_i)$$

- Obtain the inverse transform:  $z_q = G^{-1}(s_k) = G^{-1}(T(r_k))$

# Histogram Specification (cont...)

## Example

Consider again the 3-bit 64x64 image:

$r_k$	$n_k$	$p_r(r_k) = n_k/MN$
$r_0 = 0$	790	0.19
$r_1 = 1$	1023	0.25
$r_2 = 2$	850	0.21
$r_3 = 3$	656	0.16
$r_4 = 4$	329	0.08
$r_5 = 5$	245	0.06
$r_6 = 6$	122	0.03
$r_7 = 7$	81	0.02

It is desired to transform this histogram to:

$$p_z(z_0) = 0.00 \quad p_z(z_1) = 0.00 \quad p_z(z_2) = 0.00 \quad p_z(z_3) = 0.15$$

$$p_z(z_4) = 0.20 \quad p_z(z_5) = 0.30 \quad p_z(z_6) = 0.20 \quad p_z(z_7) = 0.15$$

with  $z_0 = 0, z_1 = 1, z_2 = 2, z_3 = 3, z_4 = 4, z_5 = 5, z_6 = 6, z_7 = 7$ .

# Histogram Specification (cont...)

## Example

The first step is to equalize the input (as before):

$$s_0 = 1, s_1 = 3, s_2 = 5, s_3 = 6, s_4 = 6, s_5 = 7, s_6 = 7, s_7 = 7$$

The next step is to equalize the output:

$$G(z_0) = 0 \quad G(z_1) = 0 \quad G(z_2) = 0 \quad G(z_3) = 1$$

$$G(z_4) = 2 \quad G(z_5) = 5 \quad G(z_6) = 6 \quad G(z_7) = 7$$

Notice that  $G(z)$  is not strictly monotonic. We must resolve this ambiguity by choosing, e.g. the smallest value for the inverse mapping.

# Histogram Specification (cont...)

## Example

Perform inverse mapping: find the smallest value of  $z_q$  that is closest to  $s_k$ :

$$s_k = T(r_i) \quad G(z_q)$$

$$s_0 = 1 \quad G(z_0) = 0$$

$$s_1 = 3 \quad G(z_1) = 0$$

$$s_2 = 5 \quad G(z_2) = 0$$

$$s_3 = 6 \quad G(z_3) = 1$$

$$s_4 = 6 \quad G(z_4) = 2$$

$$s_5 = 7 \quad G(z_5) = 5$$

$$s_6 = 7 \quad G(z_6) = 6$$

$$s_7 = 7 \quad G(z_7) = 7$$

$$s_k \rightarrow z_q$$

$$1 \rightarrow 3$$

$$3 \rightarrow 4$$

$$5 \rightarrow 5$$

$$6 \rightarrow 6$$

$$7 \rightarrow 7$$

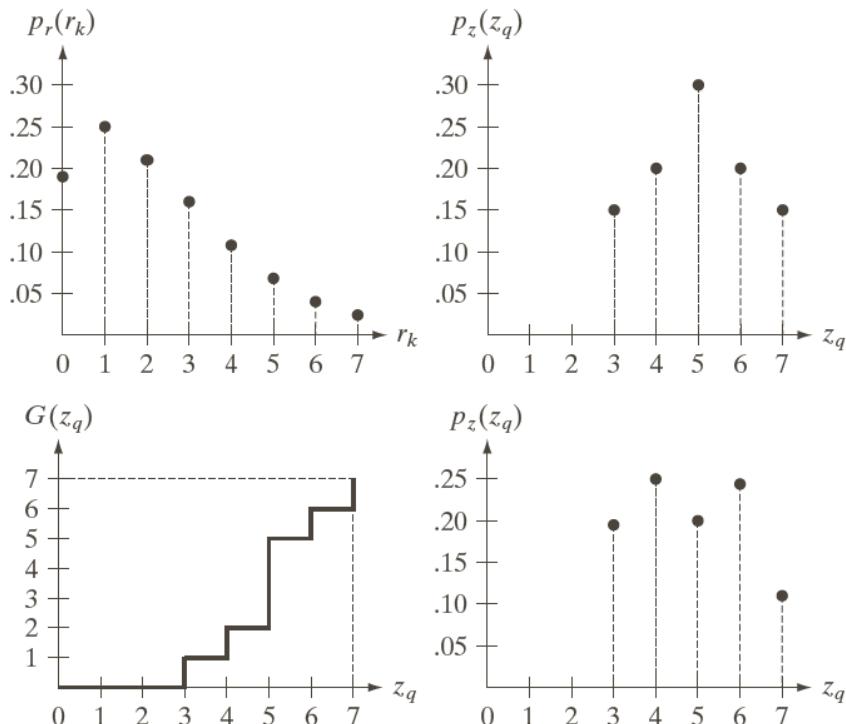


e.g. every pixel with value  $s_0=1$  in the histogram-equalized image would have a value of 3 ( $z_3$ ) in the histogram-specified image.

# Histogram Specification (cont...)

## Example

Notice that due to discretization, the resulting histogram will rarely be exactly the same as the desired histogram.

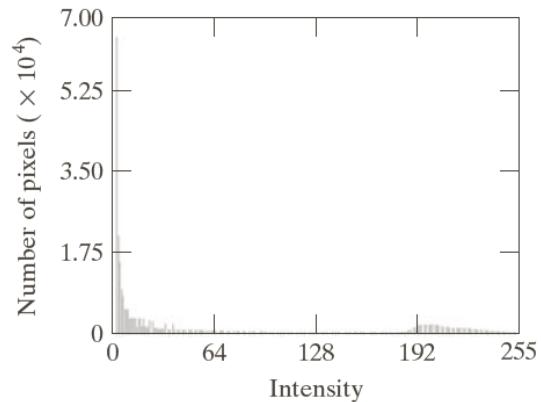
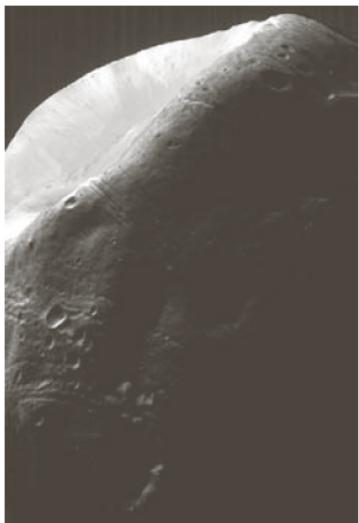


a	b
c	d

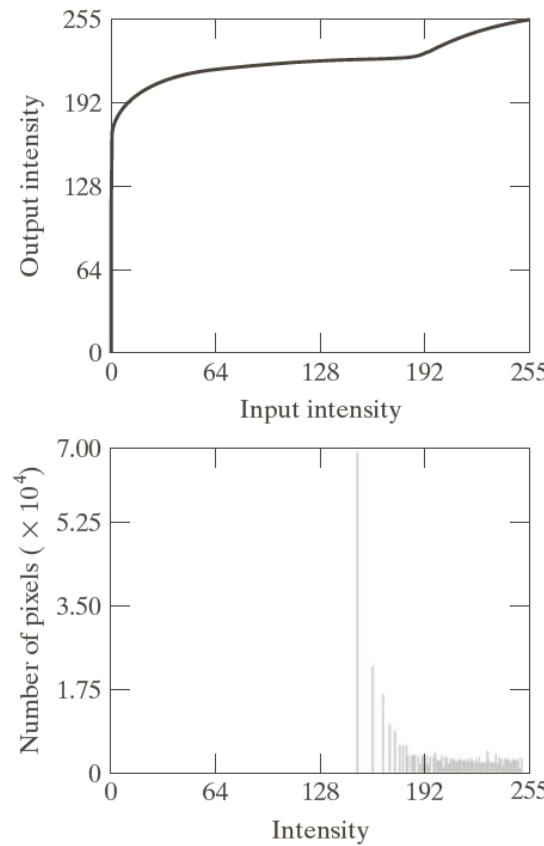
**FIGURE 3.22**

- (a) Histogram of a 3-bit image.
- (b) Specified histogram.
- (c) Transformation function obtained from the specified histogram.
- (d) Result of performing histogram specification. Compare (b) and (d).

# Histogram Specification (cont...)



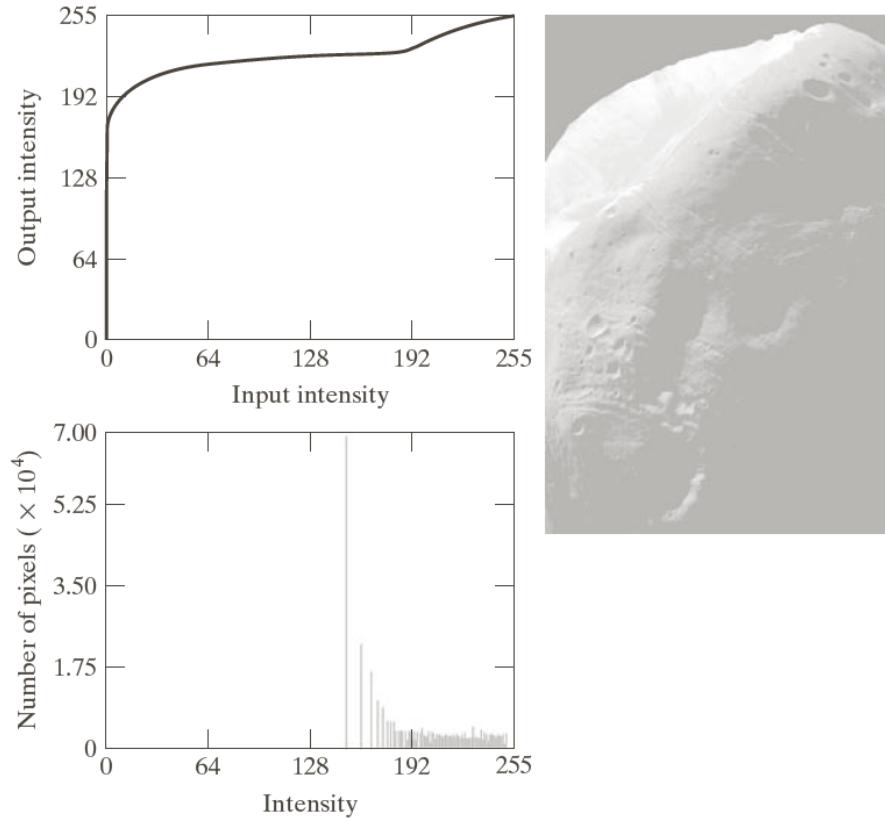
Original image



Histogram equalization



# Histogram Specification (cont...)



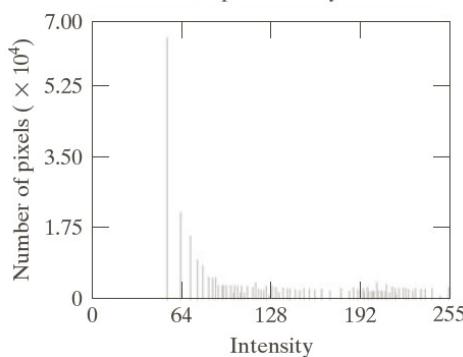
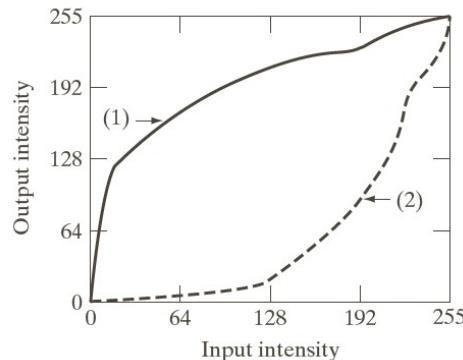
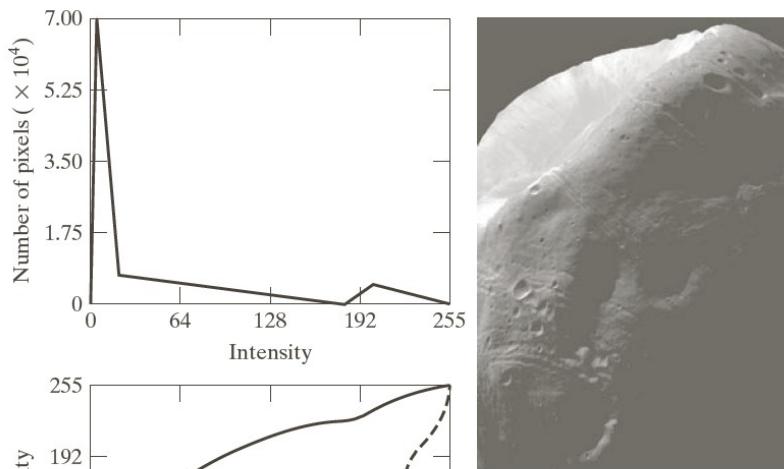
Histogram equalization

# Histogram Specification (cont...)

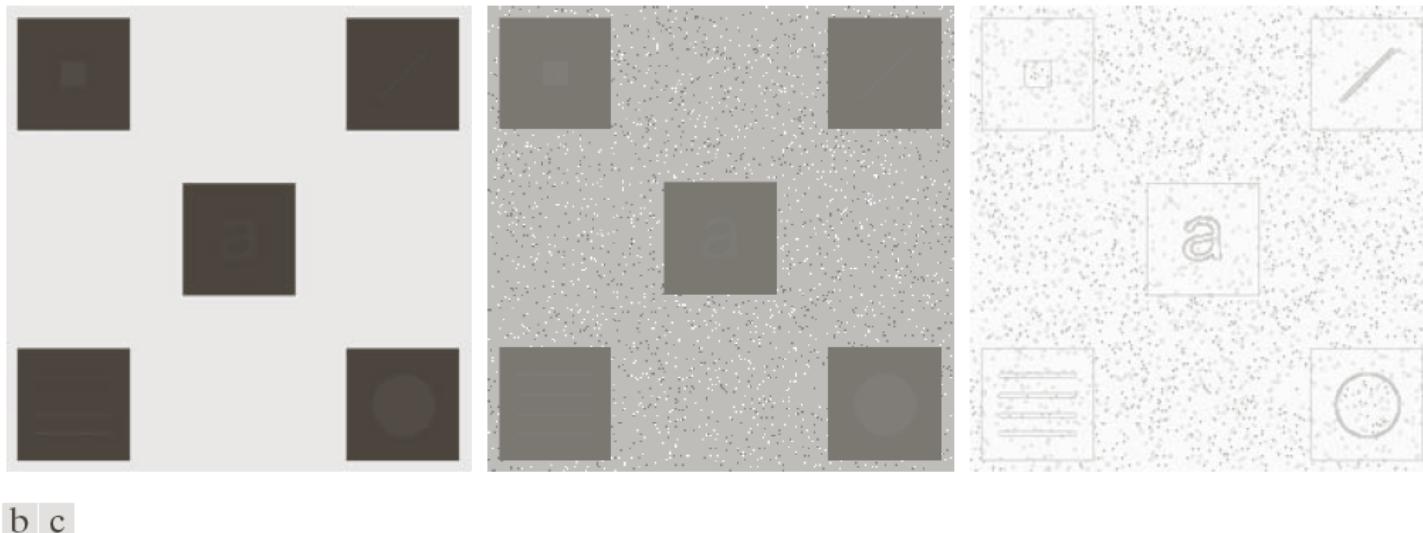
Specified histogram

Transformation function  
and its inverse

Resulting histogram



# Local Histogram Processing



**FIGURE 3.26** (a) Original image. (b) Result of global histogram equalization. (c) Result of local histogram equalization applied to (a), using a neighborhood of size  $3 \times 3$ .

- Image in (a) is slightly noisy but the noise is imperceptible.
- HE enhances the noise in smooth regions (b).
- Local HE reveals structures having values close to the values of the squares and small sizes to influence HE (c).

We have looked at:

- Different kinds of image enhancement
- Histograms
- Histogram equalisation
- Histogram specification

Next time we will start to look at spatial filtering and neighbourhood operations