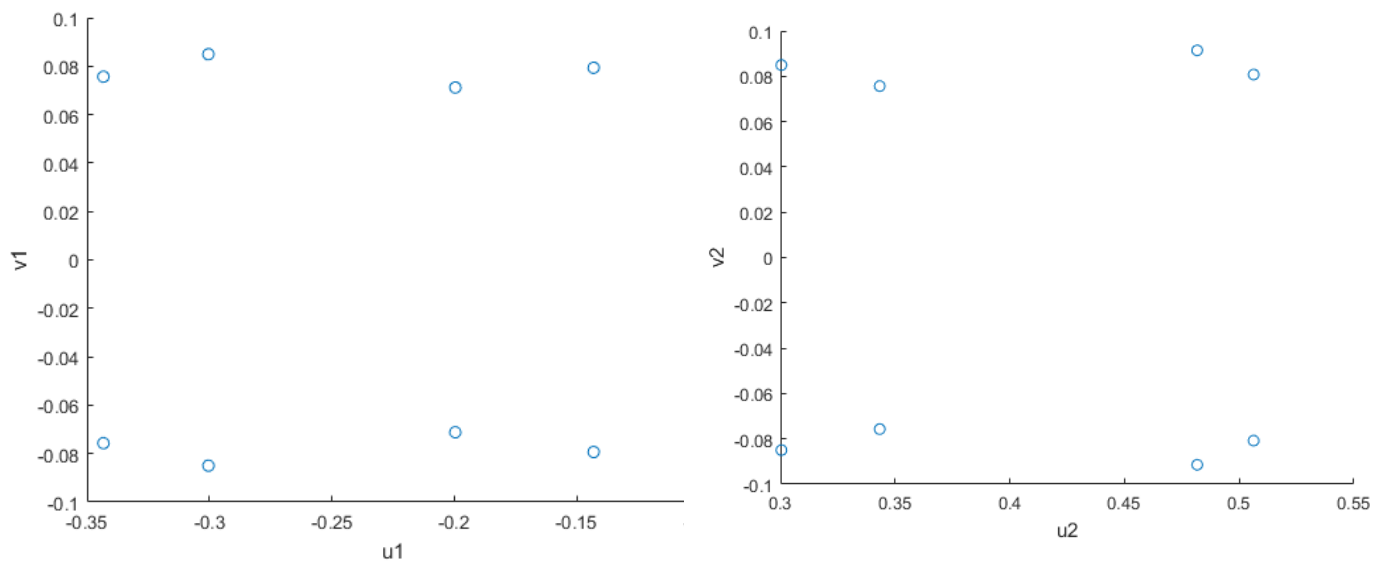


1- a) Camera Model



u1 =

-0.3433 -0.1996 -0.1996 -0.3433 -0.3004 -0.1431 -0.1431 -0.3004

v1 =

0.0757 0.0712 -0.0712 -0.0757 0.0850 0.0793 -0.0793 -0.0850

$$u_2 =$$

0.3433 0.5063 0.5063 0.3433 0.3004 0.4817 0.4817 0.3004

 $v_2 =$

0.0757 0.0808 -0.0808 -0.0757 0.0850 0.0914 -0.0914 -0.0850

b) Stereo Vision

 $XYZ =$ [illegible]

Homework 4

c) Pose Estimation

R =

$$\begin{bmatrix} 0.8660 & 0.0000 & 0.5000 \\ -0.0000 & -1.0000 & -0.0000 \\ 0.5000 & 0.0000 & -0.8660 \end{bmatrix}$$

T =

$$\begin{bmatrix} -2.2680 \\ 0.5000 \\ 7.9282 \end{bmatrix}$$

2- Neural network

a)

2 (a)

$$\Delta W_{qp} = W_{qp}^{k+1} - W_{qp}^k = -\alpha \frac{\partial E_p}{\partial W_{qp}}$$

where $\frac{\partial E_p}{\partial W_{qp}} = \frac{\partial E_p}{\partial I_q} \cdot \frac{\partial I_q}{\partial W_{qp}} \rightarrow (1)$

$\frac{\partial E_p}{\partial I_q} = -(r_q - o_q) \rightarrow (11)$

$\frac{\partial I_q}{\partial W_{qp}} = o_q(1 - o_q) \rightarrow (12)$

$\frac{\partial I_q}{\partial W_{qp}} = o_p \rightarrow (6)$

$o_q = h(I_q) \rightarrow (7)$

$I_q = \sum W_{qp} o_p \rightarrow (8)$

$I_p = \sum W_{pj} o_j \rightarrow (9)$

$o_j = \frac{\partial I_p}{\partial W_{pj}} \rightarrow (10)$

where $\frac{\partial E_p}{\partial o_q} = \frac{\partial E_p}{\partial I_q} \cdot \frac{\partial I_q}{\partial o_q} \rightarrow (3)$

where $\frac{\partial E_p}{\partial o_q} = [(r_1 - o_1)^2 + (r_2 - o_2)^2 + \dots + (r_{n_q} - o_{n_q})^2] \rightarrow (4) \frac{1}{2} \frac{\partial}{\partial o_q} [\sum_{i=1}^{n_q} (r_i - o_i)^2]$

where $\frac{\partial o_q}{\partial I_q} = \frac{\partial [h(I_q)]}{\partial I_q} = h'(I_q) = y' = \frac{d}{ds} \left(\frac{1}{1 + e^{-s}} \right) = o_q(1 - o_q) \rightarrow (5)$

$\Rightarrow \delta_q = (r_q - o_q) h'_q(I_q) = -\frac{\partial E_p}{\partial o_q} \frac{\partial o_q}{\partial I_q}$

Using the above equations

$$\Delta W_{qp} = \alpha (r_q - o_q) h'(I_q) o_p = \alpha (r_q - o_q) h(I_q) h(1 - I_q) o_p$$

$$W_{qp}^{new} = W_{qp}^{old} + \Delta W_{qp}$$

Similarly,

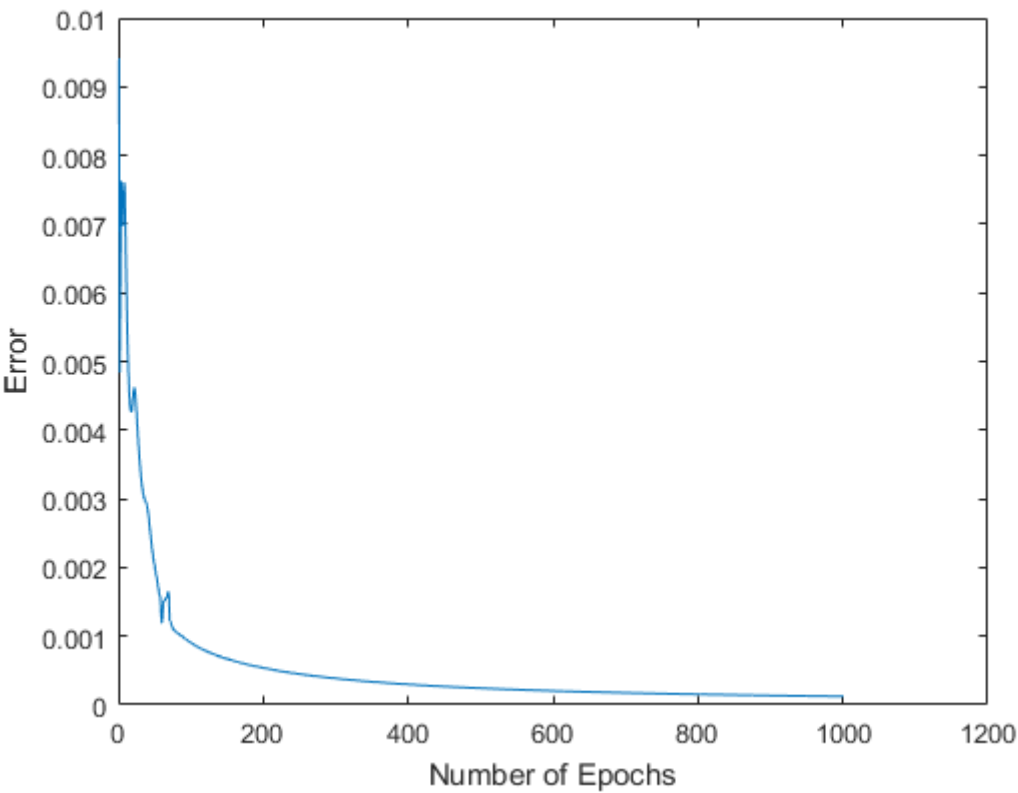
$$\Delta W_{pj} = -\alpha \frac{\partial E}{\partial W_{pj}} = -\alpha \frac{\partial E}{\partial o_p} \frac{\partial o_p}{\partial I_p} \frac{\partial I_p}{\partial W_{pj}}$$

where $\frac{\partial E}{\partial o_p} = \frac{\partial}{\partial o_p} \left[\frac{1}{2} (r_q - o_q)^2 \right] = -(r_q - o_q) \frac{\partial o_q}{\partial I_q} \frac{\partial I_q}{\partial o_p} = \frac{1}{2} (r_q - o_q) (1 - o_q^2) W_{qp} = -\delta_q W_{qp}$

$\frac{\partial o_p}{\partial I_p} = o_p(1 - o_p) ; I_p = \sum W_{pj} o_j ; \frac{\partial E_p}{\partial W_{pj}} = o_j$

$$\Delta W_{pj} = -\alpha \frac{\partial E}{\partial o_p} \cdot \frac{\partial o_p}{\partial I_p} \cdot \frac{\partial I_p}{\partial W_{pj}}$$

b) and c)



| | | | |
|--------|--------|--------|--------|
| Oq1 = | Oq2 = | Oq3 = | Oq4 = |
| 0.9964 | 0.0020 | 0.0004 | 0.0044 |
| 0.0069 | 0.9803 | 0.0118 | 0.0003 |
| 0.0003 | 0.0083 | 0.9778 | 0.0078 |
| 0.0012 | 0.0006 | 0.0250 | 0.9973 |

Homework 4

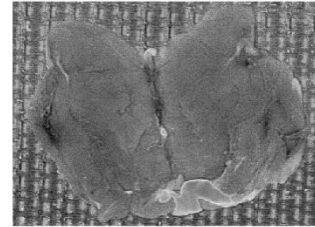
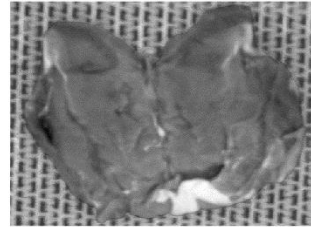
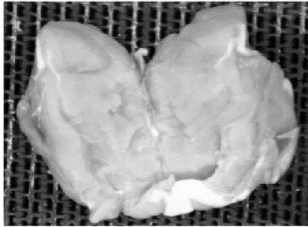
3- a) ACC

$$h = G_{\sigma_c} * R + G_{\sigma_s} * (R - G)$$

$$h = G_{\sigma_c} * R + G_{\sigma_s} * (R - G) + G_{\sigma_s}(R - R)$$

$$h = [G_{\sigma_c} - G_{\sigma_s}] * R + G_{\sigma_s} * (2R - G)$$

$$h = DoG * R + G_{\sigma_s} * (2R - G)$$

b) PCA

C =

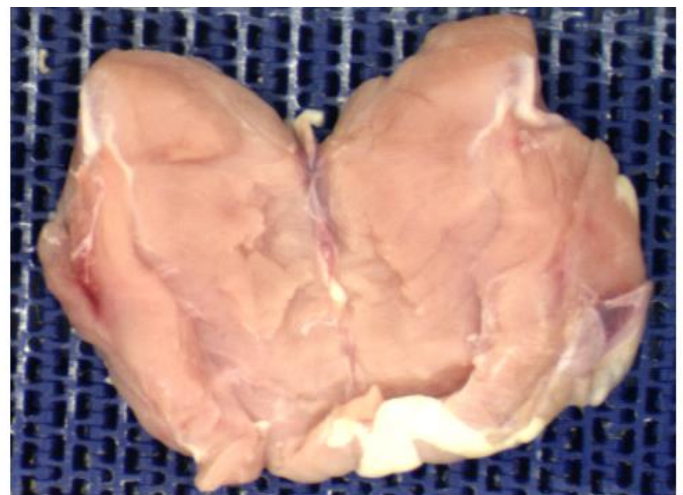
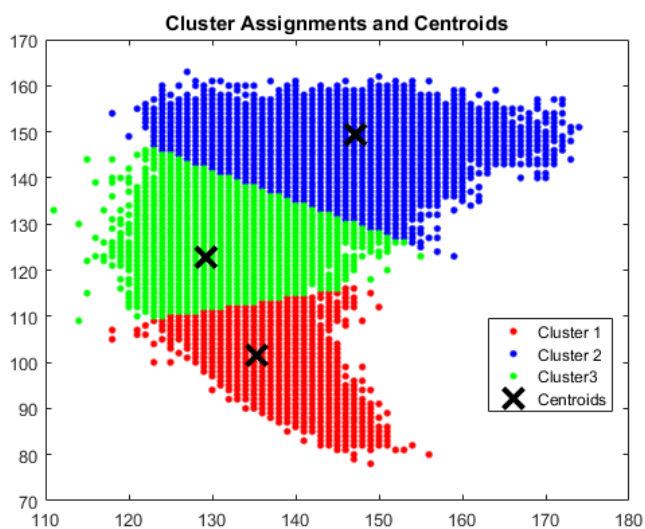
| | | |
|--------|--------|--------|
| 0.1246 | 0.0861 | 0.0487 |
| 0.0861 | 0.0634 | 0.0384 |
| 0.0487 | 0.0384 | 0.0270 |

D =

| |
|--------|
| 0.2067 |
| 0.0076 |
| 0.0007 |

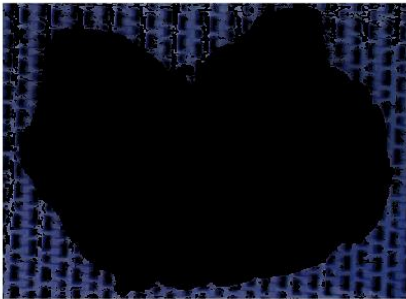
V =

| | | |
|---------|--------|---------|
| 0.7693 | 0.5495 | 0.3260 |
| -0.5338 | 0.2724 | 0.8005 |
| -0.3511 | 0.7898 | -0.5029 |

c) Image Segment

Homework 4

Cluster 1



Cluster 2



Cluster 3



4- a)

4(a)

$$\text{LHS} = (A \circ B)^c = ((A \oplus B) \ominus B)^c \rightarrow (1) \Rightarrow \text{from the definition of } \ominus \text{ using } (A \ominus B) = (A \oplus B) \ominus B.$$

Using $(X \ominus Y)^c = X^c \oplus \hat{Y} \rightarrow (2)$

$$\Rightarrow (A \circ B)^c = (A \oplus B)^c \oplus \hat{B} \quad [\text{Using (1) \& (2), where } X = (A \oplus B), Y = B] \rightarrow (4)$$

where

$$(A \oplus B)^c = ((A^c \oplus \hat{B}))^c$$

Using (2), where $X = A^c, Y = \hat{B}$

$$(A \oplus B)^c = ((A^c \ominus \hat{B})^c)^c = A^c \ominus \hat{B} \rightarrow (5)$$

substituting (5) in (4)

$$\begin{aligned} (A \circ B)^c &= (A^c \ominus \hat{B}) \oplus \hat{B} \\ &= A^c \circ \hat{B} \\ &= \text{RHS} \end{aligned}$$

Hence Proved.

Homework 4

b) Morphology

