

Boolean Quantifier Shifting as an Optimization Problem



Adrian Rebola-Pardo July 1, 2024 QUANTIFY 2024, Nancy (France)

JOHANNES KEPLER UNIVERSITY LINZ Altenberger Straße 69 4040 Linz, Austria

Some pictures by HashiCorp, Inc. and The Walt Disney Company.

The larger context

The work presented here is contained in:

Quantifier Shifting for Quantified Boolean Formulas Revisited
Simone Heisinger, Maximilian Heisinger, Adrian Rebola-Pardo, Martina Seidl

Today theoretical basis

Thursday 14:30 IJCAR talk by Simone Heisinger

Friday 17:10 IJCAR talk by Maximilian Heisinger





QBF solvers and prenex formulas

QBF solvers are decision procedures for the satisfiability problem on quantified Boolean formulas...

$$\exists a. (\forall x. a \lor \neg x) \land (\forall y. \exists b. y \lor (\neg a \land b))$$



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... on *prenex form*...

$$\exists a. \forall x. \forall y. \exists b. (a \lor \neg x) \land (y \lor (\neg a \land b))$$



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... on prenex form...

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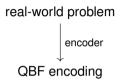
... and in many cases in prenex conjunctive normal form (PCNF)...

$$\exists a. \forall x. \forall y. \exists b. (a \lor \neg x) \land (y \lor \neg a) \land (y \lor b)$$



real-world problem







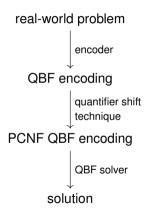
real-world problem

| encoder

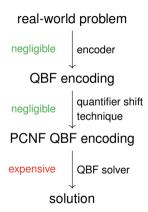
QBF encoding
| quantifier shift technique

PCNF QBF encoding

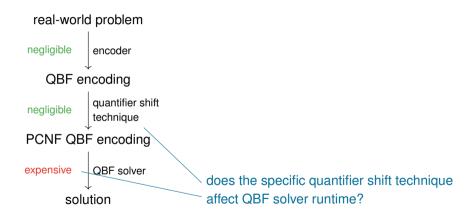




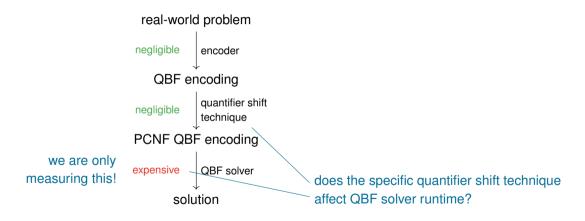




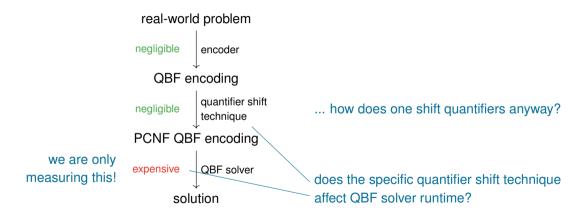














We can assume the target QBF:

- is in *negation normal form* (i.e. negation only occurs in front of variables)
- follows the Barendregt convention (i.e. variables are renamed apart)



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Quantifiers $Q \in \{\forall, \exists\}$ can then be "pulled" across Q and connectives $\circ \in \{\land, \lor\}$:

$$(Qx. \varphi) \circ \psi \equiv \varphi \circ (Qx. \psi) \equiv Qx. \varphi \circ \psi$$

$$Qx. Qy. \varphi \equiv Qy. Qx. \varphi$$



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- Lesson 1 Connective structure is irrelevant for quantifier shifting.
- Only choices in distinct, branched quantifiers matter: Lesson 2

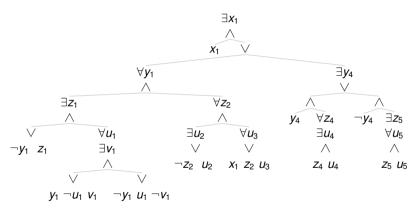
$$(Qx. \varphi) \circ (\overline{Q}y. \psi) \equiv Qx. \overline{Q}y. \varphi \circ \psi \equiv \overline{Q}y. Qx. \varphi \circ \psi$$



$$\exists x_{1}. \ x_{1} \land ((\forall y_{1}. (\exists z_{1}. (\neg y_{1} \lor z_{1}) \land \forall u_{1}. \exists v_{1}. (y_{1} \lor \neg u_{1} \lor v_{1}) \land (\neg y_{1} \lor u_{1} \lor \neg v_{1})) \land (\forall z_{2}. (\exists u_{2}. \neg z_{2} \lor u_{2}) \land (\forall u_{3}. x_{1} \lor z_{2} \lor u_{3}))) \lor (\exists y_{4}. (y_{4} \land \forall z_{4}. z_{4} \land u_{4}) \lor (\neg y_{4} \land \exists z_{5}. \forall u_{5}. z_{5} \land u_{5})))$$

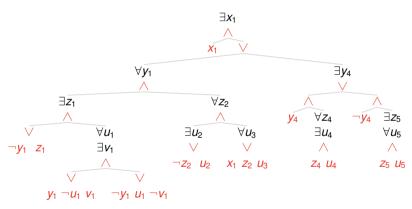
QBF formula φ





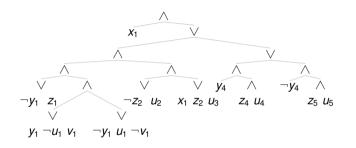
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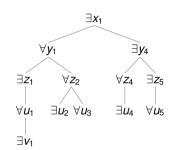




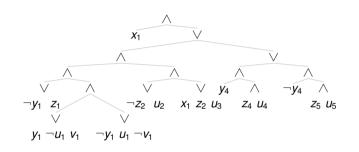
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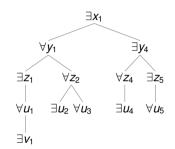




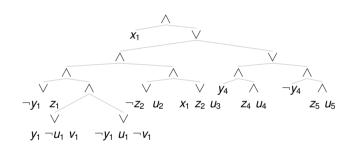




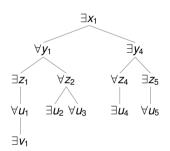




propositional skeleton φ^{psk}

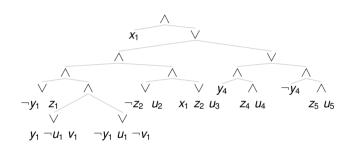


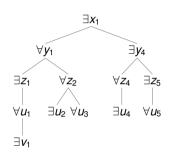
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quantifier tree





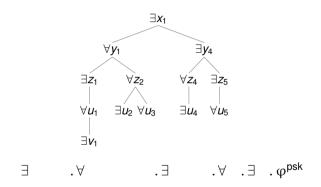


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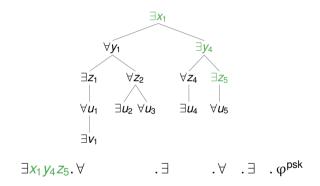
quantifier tree

goal:
$$\exists X_1. \forall X_2. \exists X_3. \forall X_4. \exists X_5. \varphi^{psk}$$

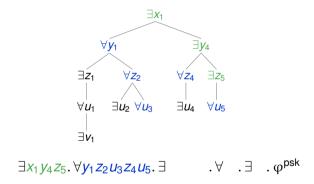




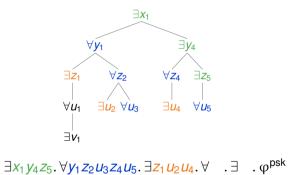




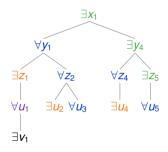






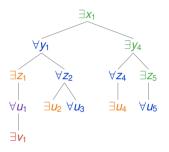






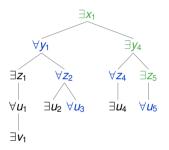
 $\exists x_1 y_4 z_5. \forall y_1 z_2 u_3 z_4 u_5. \exists z_1 u_2 u_4. \forall u_1. \exists . \varphi^{psk}$





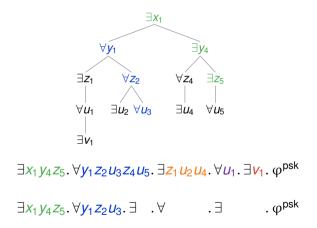
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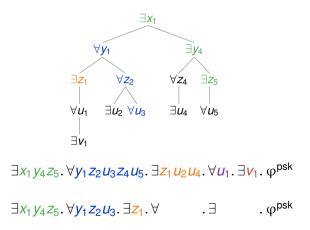


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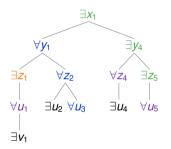








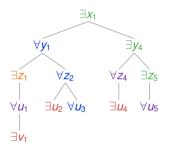




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Digression: Thoralf Skolem would like a word with us



In FOL we can eliminate existential quantifiers via Skolem functions:

$$\forall x. (\forall y. \exists a. \varphi(x, y, a)) \land (\forall z. \exists b. \psi(x, z, b))$$

$$\downarrow$$

$$\forall x. \forall y. \forall z. \varphi(x, y, a(x, y)) \land \psi(x, z, b(x, z))$$

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Reality: QBF ⊆ SOL

Skolemization over QBF operates on HOL

 Egly, Seidl, Tompits, Woltran, Zolda. Comparing different prenexing strategies for quantified Boolean formulas. SAT 2003.

Quantifiers are shifted following strategies $\exists^{\dagger}\forall^{\ddagger}$ with $\dagger, \ddagger \in \{\uparrow, \downarrow\}$.

- ↑ means "push this quantifier rootwards"
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A systematic study of the effect of quantifier shifting on solver performance requires well-defined quantifier shifting algorithms



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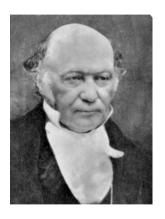
Hamilton would like a word with us











Newtonian mechanics describe the configuration of a system depending on previous configuration

• ... if the system is simple enough and you can solve it!



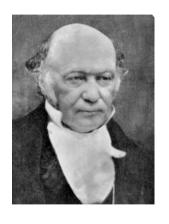
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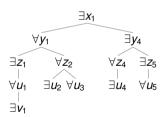
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Newton rules modify a configuration until halt **Hamilton** rules describe configuration preference

We can regard quantifier trees as partially ordered sets

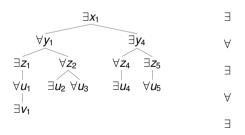
x < y iff y is a descendent of x





We can regard quantifier trees as partially ordered sets x < y iff y is a descendent of x

The QBF prefix is also a tree (in this case, linear)

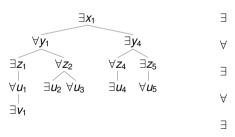




We can regard quantifier trees as partially ordered sets

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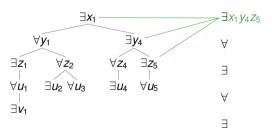




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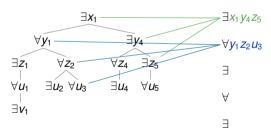




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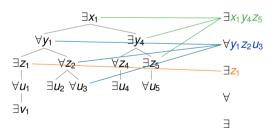




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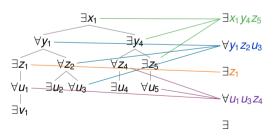




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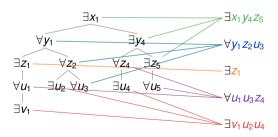




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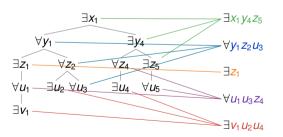


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Linearizations: quantifier tree maps that preserve (non-strict) order and quantifiers



linearizations induce semantically equivalent quantifier shifts



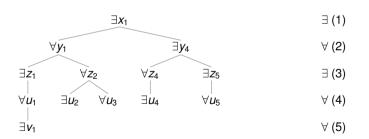
The plan



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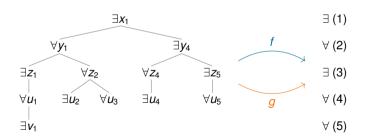


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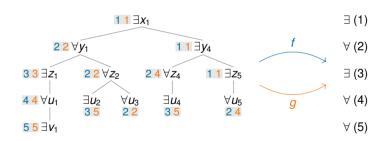


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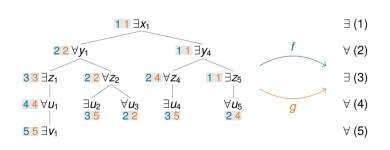
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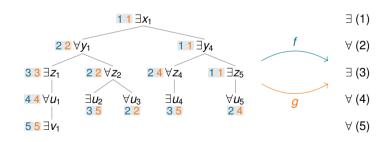
• Define a partial order over linearizations (preferences)

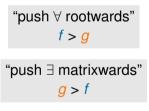


"push \forall rootwards" f > g



The plan

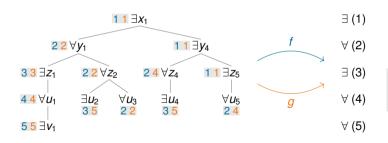


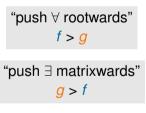




The plan

- Define a partial order over linearizations (preferences)
- Show that the maximal linearization is unique

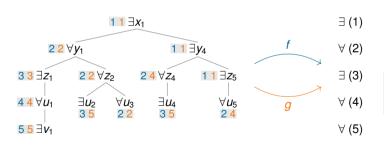




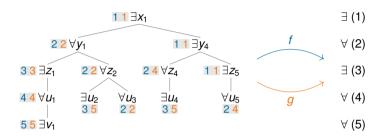


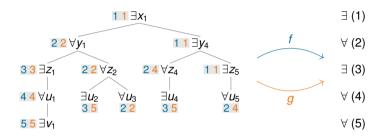
The plan

- Define a partial order over linearizations (preferences)
- Show that the maximal linearization is unique (and pray that it is easy to compute)

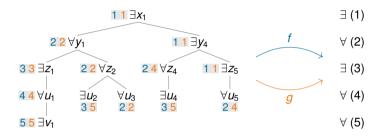


"push \forall rootwards" $f > g$	
"push \exists matrixwards" $g > f$	



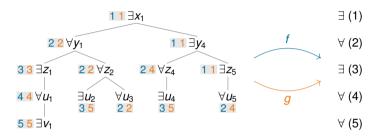


• $\forall \uparrow$: $f \leq^{\forall \uparrow} g$ iff $f(a) \geq g(a)$ for all \forall -quantified nodes a



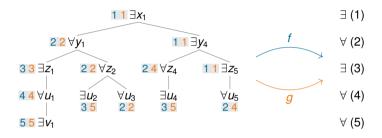
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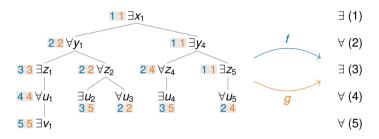


- $\forall \uparrow$: $f \leq^{\forall \uparrow} g$ iff $f(a) \geq g(a)$ for all \forall -quantified nodes a $g \leq^{\forall \uparrow} f$
- $\forall \downarrow$: $f \leq^{\forall \downarrow} g$ iff $f(a) \leq g(a)$ for all \forall -quantified nodes a





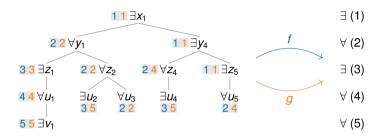
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- $g \leq^{\forall\uparrow} f$
- $\forall \downarrow$: $f \leq^{\forall \downarrow} g$ iff $f(a) \leq g(a)$ for all \forall -quantified nodes a
- $f \leq^{\forall\downarrow} g$



- $\forall \uparrow$: $f \leq^{\forall \uparrow} g$ iff $f(a) \geq g(a)$ for all \forall -quantified nodes a
- $\forall \downarrow$: $f \leq^{\forall \downarrow} g$ iff $f(a) \leq g(a)$ for all \forall -quantified nodes a $f \leq^{\forall \downarrow} g$
- Similarly for $\exists\uparrow$ and $\exists\downarrow$ $g\leq^{\exists\uparrow} f$ and $f\leq^{\exists\downarrow} g$

 $g \leq^{\forall \uparrow} f$

Semipreferences



- $\forall \uparrow$: $f \leq^{\forall \uparrow} g$ iff $f(a) \geq g(a)$ for all \forall -quantified nodes a $g \leq^{\forall \uparrow} f$
- $\forall \downarrow$: $f \leq^{\forall \downarrow} g$ iff $f(a) \leq g(a)$ for all \forall -quantified nodes a $f \leq^{\forall \downarrow} g$
- Similarly for $\exists\uparrow$ and $\exists\downarrow$ $g\leq^{\exists\uparrow}f$ and $f\leq^{\exists\downarrow}g$

these are not partial orders, though...



We can now express the strategies from [Egly et al, 2003] as preference relations:

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This is a partial order and its maximal linearization is unique



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Proof of maximal linearization uniqueness:



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No.



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 No. We give a single-pass recursive algorithm that computes the maximum with negligible overhead



The algorithm

Theoretical results. Let us consider a quantree (T, \leq, q) and a strategy $\mathbb{Q}\uparrow \ddagger$. We define the mapping $\Gamma_{\uparrow}: T \to \{1, \dots, \operatorname{aht}(T)\}$ given by

$$\Gamma_{\dagger}(x) = \left\lfloor \left| \max^{\dagger} \left\{ 1, \dots, \operatorname{aht}(T) \right\} - \operatorname{aht}(T_x^{\dagger}) \right| + 1 \right\rfloor_{q^*(x)}^{\dagger}. \tag{1}$$

Furthermore, we define the mapping $[f]^{\sf Q\ddagger}:T\to\{1,\dots,{\rm aht}(T)\}$ for $f\in{\rm Lin}(T)$ given by

$$[f]^{\mathsf{Q}^{\ddag}}(x) = \left\lfloor \min^{\ddag} \{f(y) \mid y \in T_x^{\ddag} \text{ and } q(y) = \mathsf{Q} \} \right\rfloor_{q^{\star}(x)}^{\ddag}. \tag{2}$$

Example 7 suggests that $[f]^{Q_4^2}$ can be computed recursively. Indeed, the rank of a node can be computed based on the ranks of its children or parent.

Corollary 1. Let $x \in T$ such that $q(x) \neq Q$. Then,

$$[f]^{\mathbb{Q}^{\ddag}}(x) = \left\lfloor \min^{\ddag} \{ [f]^{\mathbb{Q}^{\ddag}}(y) \mid x \text{ is covered by } y \in T \text{ w.r.t. } \leq^{\ddag} \}. \right\rfloor_{q^{*}(x)}^{\ddag}$$



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Is there a tool? Yes. Go to Maximilian Heisinger's talk on Friday at 17:10.







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