





Look Ma! No Interference!

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Resolution [Davis, Putnam '60]

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The real issue non-monotonicity and global dependence a.k.a. interference

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Dominance [Boggaerts, Gocht, McCreesh, Nordström '23]

C is dominance-redundant over K, R, O upon σ if:

- $\blacksquare K \cup R \cup \{\overline{C}\} \models K|_{\sigma}$
- $\blacksquare K(x) \cup R(x) \cup \{\overline{C(x)}\} \models O(x, \sigma(x)) \cup \overline{O(\sigma(x), x)}$

Dominance: interference with a vengeance

Dominance needs three accumulated formulas please stop...

K(x), R(x), O(x, x') are CNF formulas

$$O(x,x')$$
 encodes a preorder: $O(x,x') \equiv \sum_{i=0}^n 2^i x_i - \sum_{i=0}^n 2^i x_i' \leq 0$

$$F \curvearrowright \searrow K \curvearrowright K \hookrightarrow K \cup R \qquad K(x) \vDash O(x, \delta(x))$$

RUP and SR add clauses in R(x)

SR now requires proving $K(x) \models O(x, \sigma(x))$, and σ is added to δ

Dominance [Boggaerts, Gocht, McCreesh, Nordström '23]

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If is dominance-redundant over K, R, O upon σ , then C is redundant on $K \cup R$

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This process cannot continue forever because O is non-increasing on δ and strictly decreasing on σ .

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$$F \sim K \sim K \sim K \cup R \qquad K(x) \vDash x \ge \delta(x)$$

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$$F \sim K \qquad K \cup R(x) \cup \overline{C}(x) \vDash x > \sigma(x)$$

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$$K(x) \cup R(x) \cup \overline{C}(x) \vDash x > \sigma(x)$$

$$F \xrightarrow{\kappa} K \xrightarrow{\delta} K \cup R \qquad K(x) \vDash x \ge \delta(x)$$

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termination order

invariant
$$K(x) \cup R(x) \cup \overline{C}(x)$$
 $F \sim K \qquad K \cup R \qquad K(x) \models x \geq \delta(x)$

$$K(x) \cup R(x) \cup \overline{C}(x) \vDash x > \sigma(x)$$

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$$F \xrightarrow{\text{MODEL CHECKING BY ANY OTHER NAME}} K \cup R \qquad K(x) \vDash x \ge \delta(x)$$

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Why do we keep having global conditions on classical reasoning when we know classical logic is monotonic? [Martin Suda over lunch in 2017]

 $\nabla(T : -\sigma)(I)$ is $I \circ \sigma$ if $I \vDash T$, or I otherwise.

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if we want to make this work for dominance, we must be even more general:

- programs may be partial maps (to allow while loops)
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$$J \models C$$



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Dynamic constraints a static constraint must hold after executing a program

$$J \vDash C$$
 $I \otimes J \vDash \varepsilon$

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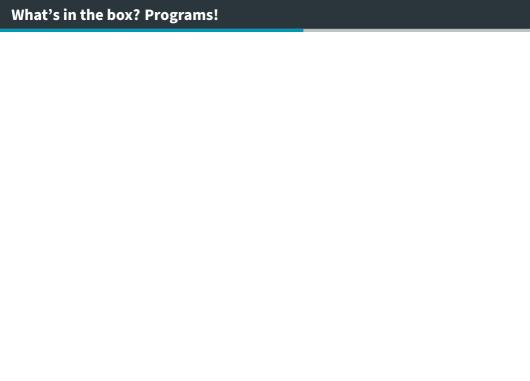
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 $I \models \varepsilon.C$ iff $J \models C$ for all J such that $I \otimes J \models \varepsilon$



Noop $I \otimes J \models 1$ iff I = J

Noop $I \otimes J \vDash 1$ iff I = JComposition $I \otimes J \vDash \varepsilon_1 \varepsilon_2$ iff $\exists K, \ I \otimes K \vDash \varepsilon_1 \ \text{and} \ K \otimes J \vDash \varepsilon_2$

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```
Noop I \otimes J \vDash 1 iff I = J

Composition I \otimes J \vDash \varepsilon_1 \varepsilon_2 iff \exists K, \ I \otimes K \vDash \varepsilon_1 \text{ and } K \otimes J \vDash \varepsilon_2

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Test I \otimes J \vDash T? iff I = J \text{ and } I \vDash T
```

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Branch I \otimes J \vDash \nabla (T : \varepsilon_1 \parallel \varepsilon_0) iff I \otimes J \vDash (T ? \varepsilon_1) \sqcup (\overline{T} ? \varepsilon_0)
```

```
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Repeat I \otimes J \vDash \varepsilon^* iff \exists I_i, \ I_0 = I, \ I_n = J, \ I_{i-1} \otimes I_i \vDash \varepsilon
```

```
Noop I \otimes J \models 1 iff I = J

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Assignment I \otimes J \models \langle \sigma \rangle iff J = I \circ \sigma

Choice I \otimes J \models \varepsilon_1 \sqcup \varepsilon_2 iff I \otimes J \models \varepsilon_1 \ \text{or} \ I \otimes J \models \varepsilon_2

Test I \otimes J \models T? iff I = J \ \text{and} \ I \models T

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Repeat I \otimes J \models \varepsilon^* iff \exists I_i, \ I_0 = I, \ I_n = J, \ I_{i-1} \otimes I_i \models \varepsilon

Loop I \otimes J \models \Box (T : \varepsilon) iff I \otimes J \models (\overline{T} ? \varepsilon)^* T?
```

```
Noop I \otimes J \models 1 iff I = J
Composition I \otimes J \models \varepsilon_1 \varepsilon_2 iff \exists K, I \otimes K \models \varepsilon_1 and K \otimes J \models \varepsilon_2
Assignment I \otimes J \models \langle \sigma \rangle iff J = I \circ \sigma
Choice I \otimes J \models \varepsilon_1 \sqcup \varepsilon_2 iff I \otimes J \models \varepsilon_1 or I \otimes J \models \varepsilon_2
Test I \otimes J \models T? iff I = J and I \models T
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Loop I \otimes J \models \Box (T : \varepsilon) iff I \otimes J \models (\overline{T}?\varepsilon)^* T?
Rendezvous I \otimes J \models \Diamond(V : \varepsilon_1 \parallel \varepsilon_0) iff \exists J_1, J_0, I \otimes J_i \models \varepsilon_i and J = J_1 +_V J_0
```

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Choice I \otimes J \models \varepsilon_1 \sqcup \varepsilon_2 iff I \otimes J \models \varepsilon_1 or I \otimes J \models \varepsilon_2
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Branch I \otimes J \models \nabla (T : \varepsilon_1 \parallel \varepsilon_0) iff I \otimes J \models (T : \varepsilon_1) \sqcup (T : \varepsilon_0)
Repeat I \otimes J \models \varepsilon^* iff \exists I_i, I_0 = I, I_n = J, I_{i-1} \otimes I_i \models \varepsilon
Loop I \otimes J \models \Box (T : \varepsilon) iff I \otimes J \models (\overline{T}?\varepsilon)^* T?
Rendezvous I \otimes J \models \Diamond(V : \varepsilon_1 \parallel \varepsilon_0) iff \exists J_1, J_0, I \otimes J_i \models \varepsilon_i and J = J_1 +_V J_0
Solve I \otimes J \models [R] iff I \otimes J \models R
```

```
Noop I \otimes J \models 1 iff I = J
Composition I \otimes J \models \varepsilon_1 \varepsilon_2 iff \exists K, I \otimes K \models \varepsilon_1 and K \otimes J \models \varepsilon_2
Assignment I \otimes J \models \langle \sigma \rangle iff J = I \circ \sigma
Choice I \otimes J \models \varepsilon_1 \sqcup \varepsilon_2 iff I \otimes J \models \varepsilon_1 or I \otimes J \models \varepsilon_2
Test I \otimes J \models T? iff I = J and I \models T
Branch I \otimes J \models \nabla (T : \varepsilon_1 \parallel \varepsilon_0) iff I \otimes J \models (T : \varepsilon_1) \sqcup (T : \varepsilon_0)
Repeat I \otimes J \models \varepsilon^* iff \exists I_i, I_0 = I, I_n = J, I_{i-1} \otimes I_i \models \varepsilon
Loop I \otimes J \models \Box (T : \varepsilon) iff I \otimes J \models (\overline{T}?\varepsilon)^* T?
Rendezvous I \otimes J \models \Diamond(V : \varepsilon_1 \parallel \varepsilon_0) iff \exists J_1, J_0, I \otimes J_i \models \varepsilon_i and J = J_1 +_V J_0
Solve I \otimes J \models [R] iff I \otimes J \models R
Havoc I \otimes J \models \forall V iff I \otimes J \models \Diamond (V : [T] \parallel 1)
```

```
Noop I \otimes J \models 1 iff I = J
Composition I \otimes J \models \varepsilon_1 \varepsilon_2 iff \exists K, I \otimes K \models \varepsilon_1 and K \otimes J \models \varepsilon_2
Assignment I \otimes J \models \langle \sigma \rangle iff J = I \circ \sigma
Choice I \otimes J \models \varepsilon_1 \sqcup \varepsilon_2 iff I \otimes J \models \varepsilon_1 or I \otimes J \models \varepsilon_2
Test I \otimes J \models T? iff I = J and I \models T
Branch I \otimes J \models \nabla (T : \varepsilon_1 \parallel \varepsilon_0) iff I \otimes J \models (T : \varepsilon_1) \sqcup (T : \varepsilon_0)
Repeat I \otimes J \models \varepsilon^* iff \exists I_i, I_0 = I, I_n = J, I_{i-1} \otimes I_i \models \varepsilon
Loop I \otimes J \models \Box (T : \varepsilon) iff I \otimes J \models (\overline{T}?\varepsilon)^* T?
Rendezvous I \otimes J \models \Diamond(V : \varepsilon_1 \parallel \varepsilon_0) iff \exists J_1, J_0, I \otimes J_i \models \varepsilon_i and J = J_1 +_V J_0
Solve I \otimes J \models [R] iff I \otimes J \models R
Havoc I \otimes J \models \forall V iff I \otimes J \models \Diamond (V : [T] \parallel 1)
Not even a new thing! [Fischer, Ladner '79] [Balbiani, Herzig, Troquard '13]
     Propositional dynamic logic (PDL) defines modalities for each program
```

What's in the box? Programs!

```
Noop I \otimes J \models 1 iff I = J
Composition I \otimes J \models \varepsilon_1 \varepsilon_2 iff \exists K, I \otimes K \models \varepsilon_1 and K \otimes J \models \varepsilon_2
Assignment I \otimes J \models \langle \sigma \rangle iff J = I \circ \sigma
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Repeat I \otimes J \models \varepsilon^* iff \exists I_i, I_0 = I, I_n = J, I_{i-1} \otimes I_i \models \varepsilon
Loop I \otimes J \models \Box (T : \varepsilon) iff I \otimes J \models (\overline{T}?\varepsilon)^* T?
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```

Not even a new thing! [Fischer, Ladner '79] [Balbiani, Herzig, Troquard '13]
Propositional dynamic logic (PDL) defines modalities for each program

Necessitation law (a.k.a. I can apply programs to a proof) If $F \models G$ holds, then $\varepsilon . F \models \varepsilon . G$ holds too

Proving unsatisfiability F is unsatisfiable if $F \vdash \varepsilon . \bot$ and $\varepsilon . \bot \vdash \bot$

Proving unsatisfiability F is unsatisfiable if $F \vdash \varepsilon$. \bot and ε . $\bot \vdash \bot$

Proving satisfiability F is satisfiable if $T \vdash \varepsilon . F$ and $\varepsilon . \bot \vdash \bot$

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Parametric proofs If I have proven $F \vdash G$, then I can prove $F|_{\sigma} \vdash G|_{\sigma}$ as $\langle \sigma \rangle . F \vdash \langle \sigma \rangle . G$

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Refinements ε refines δ if $\varepsilon \vdash [R_{\varepsilon}]$ and $[R_{\delta}] \models \delta$ and $R_{\varepsilon} \vdash R_{\delta}$

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Refinements ε refines δ if $\varepsilon \vdash [R_{\varepsilon}]$ and $[R_{\delta}] \vDash \delta$ and $R_{\varepsilon} \vdash R_{\delta}$

I think this could be a good foundation for a general, versatile, unified certificate system for propositional reasoning beyond SAT

Proving unsatisfiability F is unsatisfiable if $F \vdash \varepsilon . \bot$ and $\varepsilon . \bot \vdash \bot$

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I think this could be a good foundation for a general, versatile, unified certificate system for propositional reasoning beyond SAT

An appetizer: [Rebola-Pardo '25, SYNASC]

all unsat, over the same variables

 F_1

 F_2

 F_3

$$u_1 \vee F_1$$

$$u_2 \vee F_2$$

$$u_3 \vee F_3$$

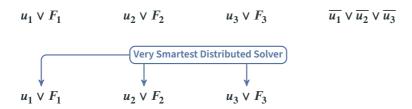
still unsat!

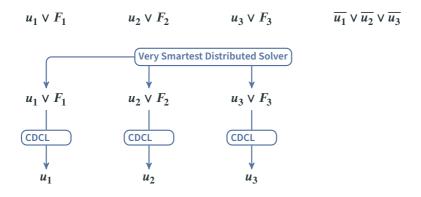
$$u_1 \vee F_1$$

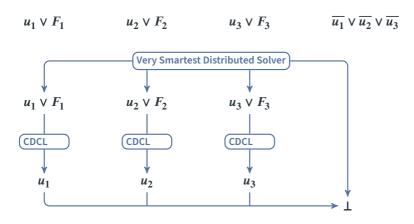
$$u_2 \vee F_2$$

$$u_3 \vee F_3$$

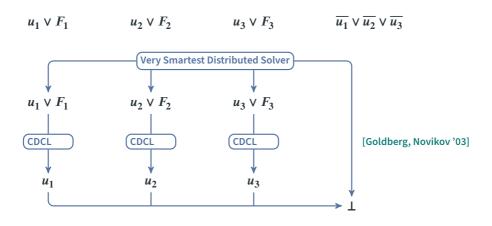
$$\overline{u_1} \vee \overline{u_2} \vee \overline{u_3}$$





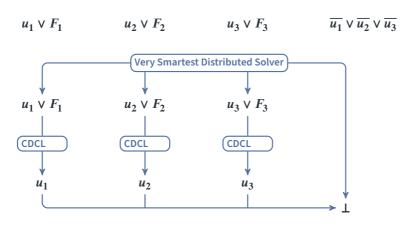


 $\pi_1 : u_1 \lor F_1 \vdash u_1$ $\pi_2 : u_2 \lor F_2 \vdash u_2$ $\pi_3 : u_3 \lor F_3 \vdash u_3$

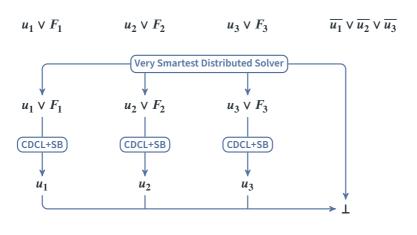


 $\pi_1: u_1 \vee F_1 \vdash u_1$

 $\pi_3: u_3 \vee F_3 \vdash u_3$



$$\begin{array}{lll} \pi_2: u_2 \vee F_2 \vdash u_2 & \pi: u_1 \wedge u_2 \wedge u_3 \wedge (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3}) \vdash \bot \\ \pi_3: u_3 \vee F_3 \vdash u_3 & \end{array}$$



$$\begin{array}{lll} \pi_1: u_1 \vee F_1 \vdash u_1 \\ \pi_2: u_2 \vee F_2 \vdash u_2 & \pi: u_1 \wedge u_2 \wedge u_3 \wedge (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3}) \vdash \bot \\ \pi_3: u_3 \vee F_3 \vdash u_3 & \end{array}$$

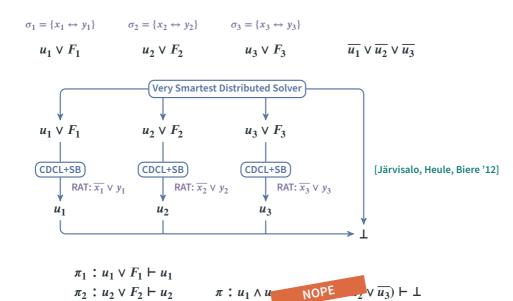
$$\begin{array}{lll} \pi_1: u_1 \vee F_1 \vdash u_1 \\ \pi_2: u_2 \vee F_2 \vdash u_2 & \pi: u_1 \wedge u_2 \wedge u_3 \wedge (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3}) \vdash \bot \\ \pi_3: u_3 \vee F_3 \vdash u_3 & \end{array}$$

 $\pi_1:u_1\vee F_1\vdash u_1$

 $\pi_3:u_3\vee F_3\vdash u_3$

 $\pi_2: u_2 \vee F_2 \vdash u_2 \qquad \pi: u_1 \wedge u_2 \wedge u_3 \wedge (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3}) \vdash \bot$

 $\pi_3:u_3\vee F_3\vdash u_3$



What are DRAT proofs really doing?

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\pi: F \vdash G proves that for each I \models F we have mut(I) \models G
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$$\pi_1: u_1 \vee F_1 \vdash (u_1 \vee F_1) \wedge (\overline{x_1} \vee y_1) \vdash u_1$$

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$$\begin{array}{c} \pi_1: u_1 \vee F_1 \vdash (u_1 \vee F_1) \wedge (\overline{x_1} \vee y_1) \vdash u_1 & I \vDash u_1 \vee F_1 \Rightarrow \operatorname{mut}_1(I) \vDash u_1 \\ & \operatorname{mut}_1 \operatorname{is} \text{ ``if } I \vDash x_1 \wedge \overline{y_1} \operatorname{then } I \coloneqq I \circ \{x_1 \leftrightarrow y_1\} \text{''} \end{array}$$

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$$\pi_3: u_3 \vee F_3 \vdash (u_3 \vee F_3) \wedge (\overline{x_3} \vee y_3) \vdash u_3 \qquad \qquad I \vDash u_3 \vee F_3 \Rightarrow \operatorname{mut}_3(I) \vDash u_3$$

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what we need is this!

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Interference-based proof systems force a single concurrent mut prefix...

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Interference-based proof systems force a single concurrent mut prefix...

... because of the accumulated formula

Unit propagation (BCP) a blazingly fast sound but incomplete algorithm for inconsistency in CNF formulas [Zhang, Madigan, Moskewicz, Malik '01]

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$$F \wedge \overline{C} \models \bot$$
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Can we have this for dynamic formulas? yes, but not built on consistency.

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 $F \wedge \overline{\varepsilon \cdot C} \models \bot$ iff $F \models \varepsilon \cdot C$ I don't have diamonds!

RUP-like inferences in dynamic logic

Unit propagation (BCP) a blazingly fast sound but incomplete algorithm for inconsistency in CNF formulas [Zhang, Madigan, Moskewicz, Malik '01]

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Can we have this for dynamic formulas? yes, but not built on consistency.

Instead we reduce a dynamic implication check to (several) RUP checks

 $F \wedge \overline{\varepsilon \cdot C} \models \bot$ iff $F \models \varepsilon \cdot C$ I don't have diamonds!

$$F = (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

$$F \quad = \quad (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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Step 1 introduce the symmetry breaker $B_1 = \overline{x_1} \vee y_1$ in $u_1 \vee F_1$

symmetry:
$$\sigma_1 = \{x_1 \leftrightarrow y_1\}$$

$$F = (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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$$F \vdash \nabla(B_1 : 1 \parallel \langle \sigma_1 \rangle). B_1$$

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$$F \vdash \nabla(B_1: 1 \parallel \langle \sigma_1 \rangle). B_1$$

$$F \land B_1 \vdash 1. B_1 \qquad F \land \overline{B_1} \vdash \langle \sigma_1 \rangle. B_1$$

$$F \quad = \quad (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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$$F = (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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$$F \quad = \quad (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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$$F \vdash \nabla(B_1 : 1 \parallel \langle \sigma_1 \rangle). B_1$$

$$F \vdash \nabla(B_1 : 1 \parallel \langle \sigma_1 \rangle). C \text{ for } C \in u_1 \lor F_1$$

$$F \quad = \quad (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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$$\sigma_1 = \{x_1 \leftrightarrow y_1\}$$
 program: $\nabla(B_1 : 1 \parallel \langle \sigma_1 \rangle)$

$$F \vdash \nabla(B_1 : 1 \parallel \langle \sigma_1 \rangle). B_1$$

$$F \vdash \nabla(B_1 : 1 \parallel \langle \sigma_1 \rangle). C \text{ for } C \in u_1 \lor F_1$$

$$F \land B_1 \vdash 1. C \qquad F \land \overline{B_1} \vdash \langle \sigma_1 \rangle. C$$

$$F \quad = \quad (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

Step 1 introduce the symmetry breaker $B_1 = \overline{x_1} \vee y_1$ in $u_1 \vee F_1$

symmetry:
$$\sigma_1 = \{x_1 \leftrightarrow y_1\}$$
 program: $\nabla(B_1: 1 \parallel \langle \sigma_1 \rangle)$ $F \vdash \nabla(B_1: 1 \parallel \langle \sigma_1 \rangle)$. B_1
$$F \vdash \nabla(B_1: 1 \parallel \langle \sigma_1 \rangle)$$
. $C \quad \text{for } C \in u_1 \lor F_1$
$$F \land B_1 \vdash 1$$
. $C \quad F \land \overline{B_1} \vdash \langle \sigma_1 \rangle$. C
$$F \land B_1 \vdash C$$
 trivial by inclusion

$$F \quad = \quad (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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$$F \land B_1 \vdash C \qquad F \land \overline{B_1} \vdash C|_{\sigma_1}$$
trivial by inclusion holds by RUP (because of symmetry)

$$F = (u_1 \vee F_1) \quad \land \quad (u_2 \vee F_2) \quad \land \quad (u_3 \vee F_3) \quad \land \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$
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 symmetry: $\sigma_1 = \{x_1 \leftrightarrow y_1\}$ program: $\nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle)$
$$F \vdash \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle).B_1$$

$$F \vdash \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle).C \quad \text{for } C \in u_1 \vee F_1$$

$$F \land B_1 \vdash 1.C \qquad F \land \overline{B_1} \vdash \langle \sigma_1 \rangle.C$$

$$F \land \overline{B_1} \vdash C \mid_{\sigma_1}$$
 trivial by inclusion holds by RUP (because of symmetry)

$$F \quad = \quad (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

- Step 1 introduce the symmetry breaker $B_1 = \overline{x_1} \lor y_1$ in $u_1 \lor F_1$ $F \vdash \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle) \cdot (u_1 \lor F_1) \land B_1$
- Step 2 derive u_1 from $(u_1 \vee F_1) \wedge B_1$

$$F = (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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 $(u_1 \lor F_1) \land B_1 \vdash u_1$ by a bunch of RUP steps

$$F \quad = \quad (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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 $(u_1 \lor F_1) \land B_1 \vdash u_1$ by a bunch of RUP steps

we haven't derived $(u_1 \vee F_1) \wedge B_1$ though...

$$F = (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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$$(u_1 \lor F_1) \land B_1 \vdash u_1$$
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$$(u_1 \lor F_1) \land B_1 \vdash u_1$$
 by a bunch of RUP steps

we haven't derived $(u_1 \vee F_1) \wedge B_1$ though... but we have necessitation!

$$\nabla (B_1 \ : \ 1 \parallel \langle \sigma_1 \rangle).(u_1 \vee F_1) \wedge B_1 \vdash \nabla (B_1 \ : \ 1 \parallel \langle \sigma_1 \rangle).u_1$$

$$F = (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

- Step 1 introduce the symmetry breaker $B_1 = \overline{x_1} \vee y_1$ in $u_1 \vee F_1$ $F \vdash \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle) \cdot (u_1 \vee F_1) \wedge B_1$
- $\begin{array}{ll} \text{Step 2} & \text{derive } u_1 \text{ from } (u_1 \vee F_1) \wedge B_1 \\ & \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle). (u_1 \vee F_1) \wedge B_1 \vdash \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle). u_1 \end{array}$
- Step 3 derive u_1 from $u_1 \vee F_1$

$$F = (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

- Step 1 introduce the symmetry breaker $B_1 = \overline{x_1} \vee y_1$ in $u_1 \vee F_1$ $F \vdash \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle) \cdot (u_1 \vee F_1) \wedge B_1$
- Step 2 derive u_1 from $(u_1 \vee F_1) \wedge B_1$ $\nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle). (u_1 \vee F_1) \wedge B_1 \vdash \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle). u_1$
- Step 3 derive u_1 from $u_1 \vee F_1$

$$\nabla(B_1: 1 \parallel \langle \sigma_1 \rangle).u_1 \vdash u_1$$

$$F \quad = \quad (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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- Step 2 derive u_1 from $(u_1 \vee F_1) \wedge B_1$ $\nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle) \cdot (u_1 \vee F_1) \wedge B_1 \vdash \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle) \cdot u_1$
- Step 3 derive u_1 from $u_1 \vee F_1$

$$\begin{array}{c} \nabla(B_1:\ 1\parallel\langle\sigma_1\rangle).u_1\vdash u_1\\\\ B_1\wedge(1.u_1)\vdash u_1 & \overline{B_1}\wedge(\langle\sigma_1\rangle.u_1)\vdash u_1 \end{array}$$

$$F = (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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- Step 2 derive u_1 from $(u_1 \vee F_1) \wedge B_1$ $\nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle) \cdot (u_1 \vee F_1) \wedge B_1 \vdash \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle) \cdot u_1$
- Step 3 derive u_1 from $u_1 \vee F_1$

$$\nabla(B_1:\ 1\parallel\langle\sigma_1\rangle).u_1\vdash u_1$$

$$B_1\wedge(1.u_1)\vdash u_1$$

$$\overline{B_1}\wedge(\langle\sigma_1\rangle.u_1)\vdash u_1$$

$$trivial by inclusion$$

$$F = (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

Step 1 introduce the symmetry breaker
$$B_1 = \overline{x_1} \vee y_1$$
 in $u_1 \vee F_1$ $F \vdash \nabla(B_1 : 1 \parallel \langle \sigma_1 \rangle) \cdot (u_1 \vee F_1) \wedge B_1$

Step 2 derive
$$u_1$$
 from $(u_1 \vee F_1) \wedge B_1$

$$\nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle).(u_1 \vee F_1) \wedge B_1 \vdash \nabla (B_1 : 1 \parallel \langle \sigma_1 \rangle).u_1$$

Step 3 derive u_1 from $u_1 \vee F_1$

$$\nabla(B_1:\ 1\parallel\langle\sigma_1\rangle).u_1\vdash u_1$$

$$B_1\wedge(1.u_1)\vdash u_1 \qquad \qquad \overline{B_1}\wedge(\langle\sigma_1\rangle.u_1)\vdash u_1$$

$$B_1\wedge u_1\vdash u_1 \qquad \qquad B_1\wedge u_1\vdash u_1\big|_{\sigma_1}$$
 trivial by inclusion
$$\text{holds by RUP (because of cleanliness)}$$
 [Fazekas, Biere, Scholl '19]

$$F = (u_1 \vee F_1) \quad \wedge \quad (u_2 \vee F_2) \quad \wedge \quad (u_3 \vee F_3) \quad \wedge \quad (\overline{u_1} \vee \overline{u_2} \vee \overline{u_3})$$

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- Step 3 derive u_1 from $u_1 \vee F_1$ $\nabla (B_1: 1 \parallel \langle \sigma_1 \rangle).u_1 \vdash u_1$
- Step 4 repeat for u_2 and u_3 , then resolve

Conclusion

You don't need interference for RAT (or PR, or SR, or WSR)

You don't even need an accumulated formula

You can get new reasoning tools if you stop thinking in terms of redundancy notions

Proof logging and checking is not necessarily more complex