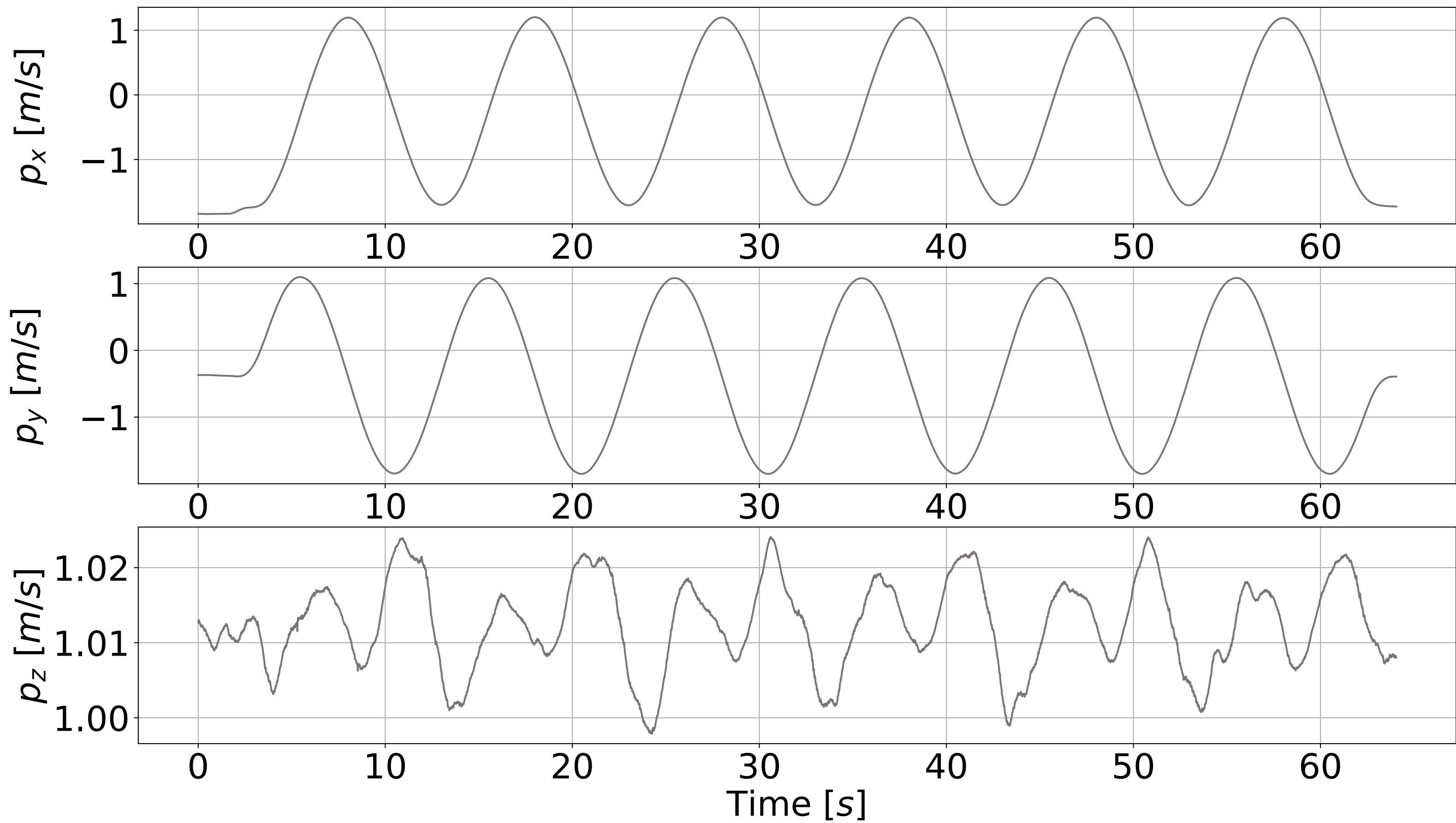
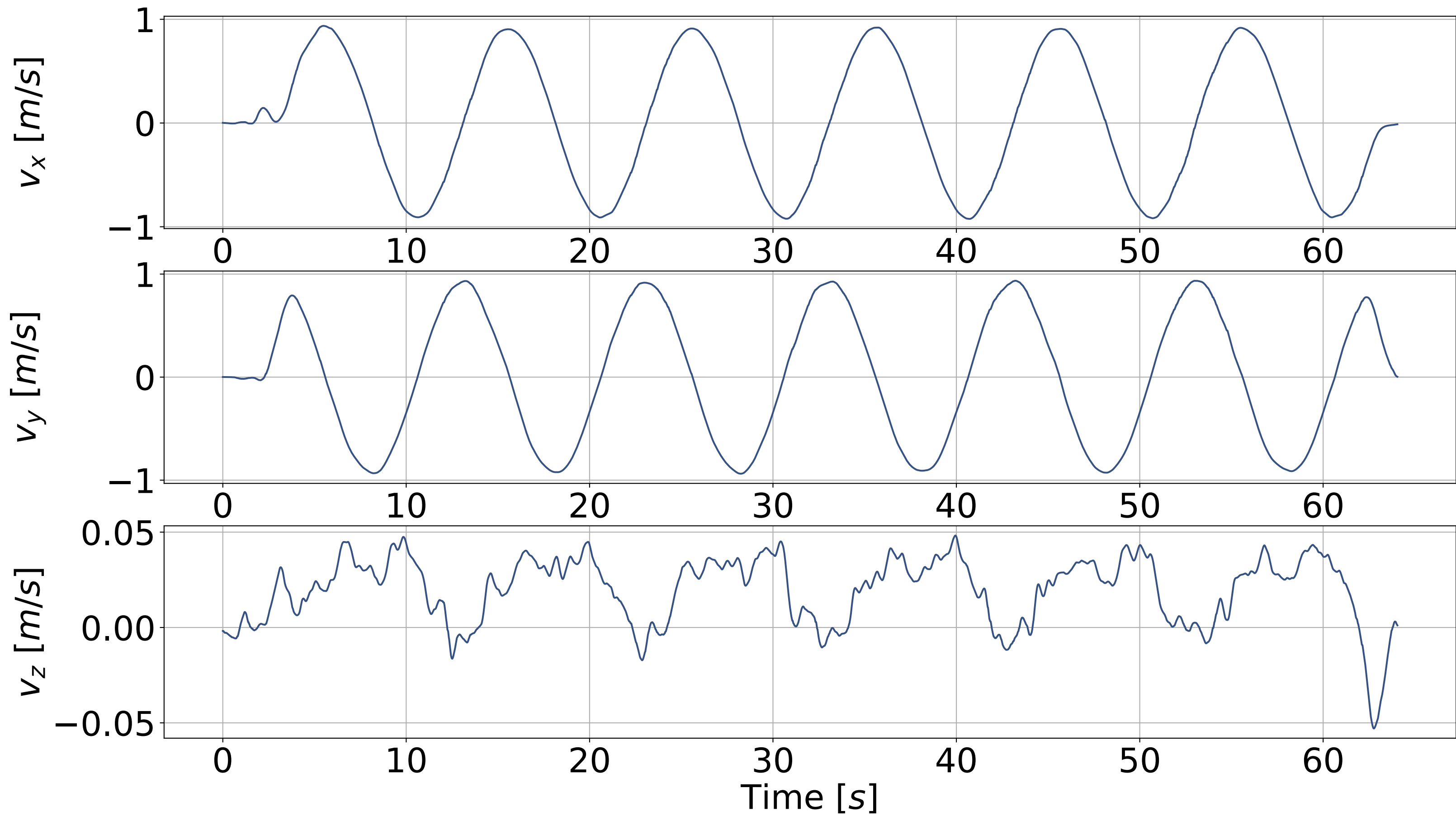


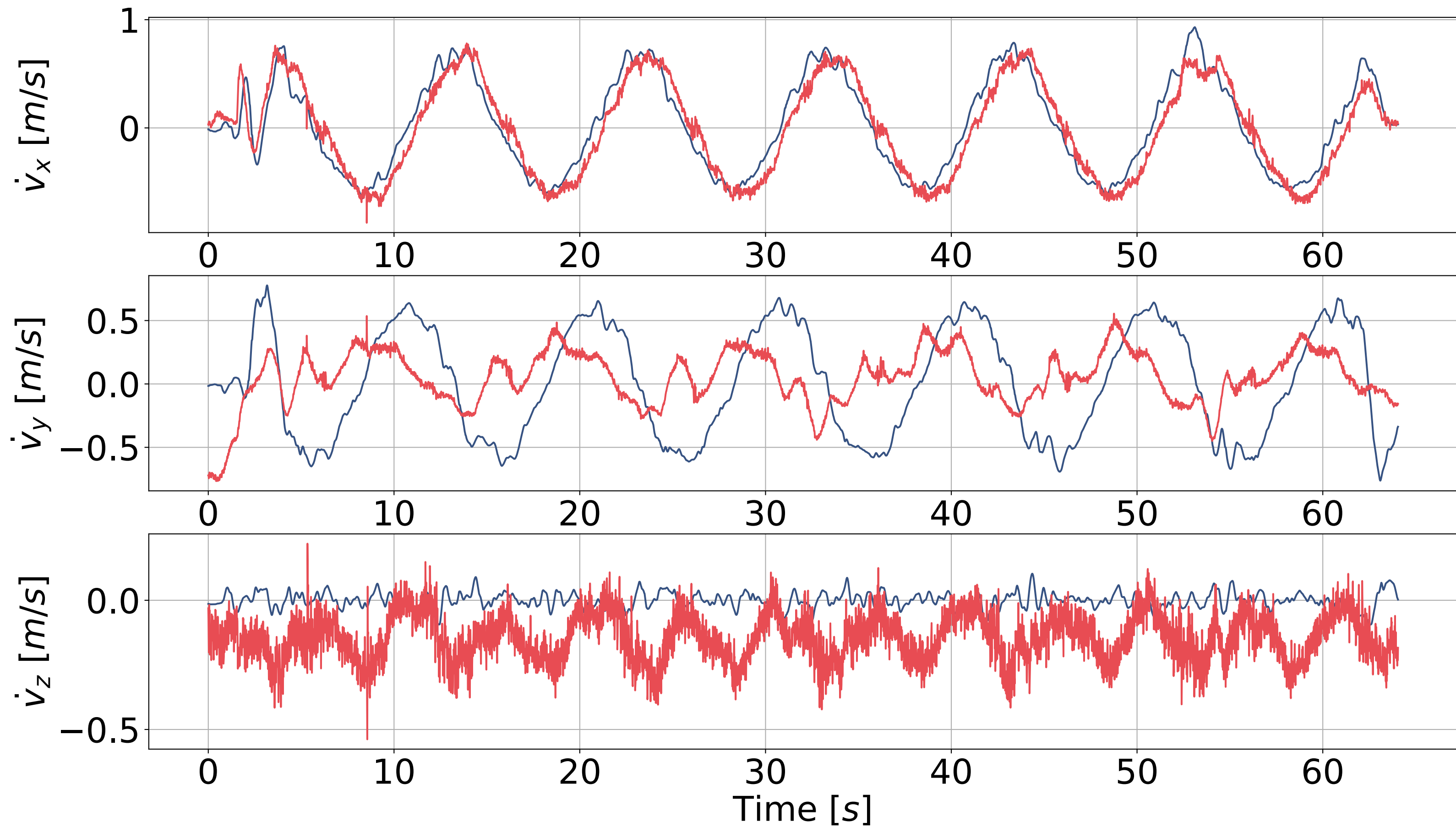
Position



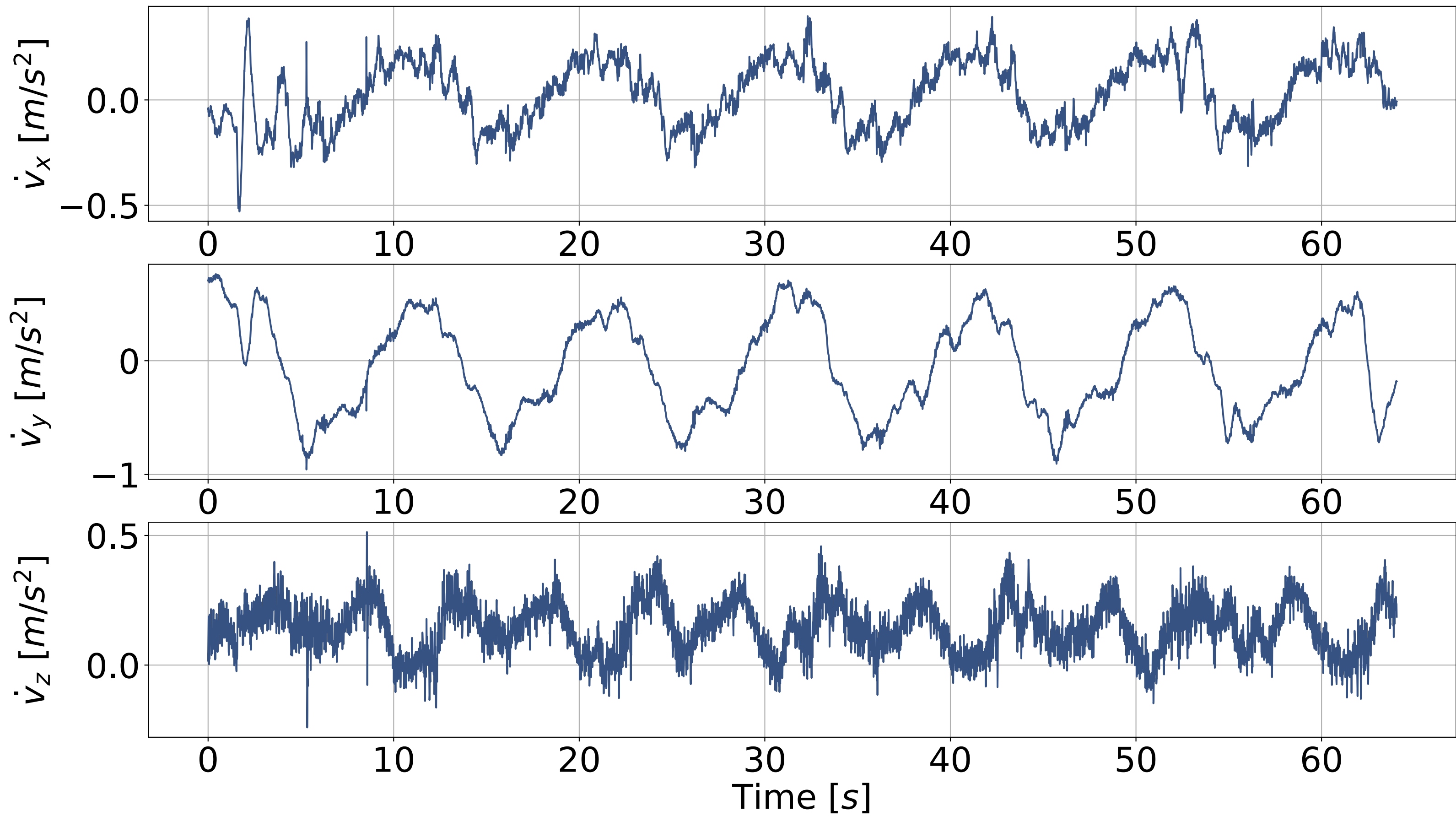
Linear Velocity



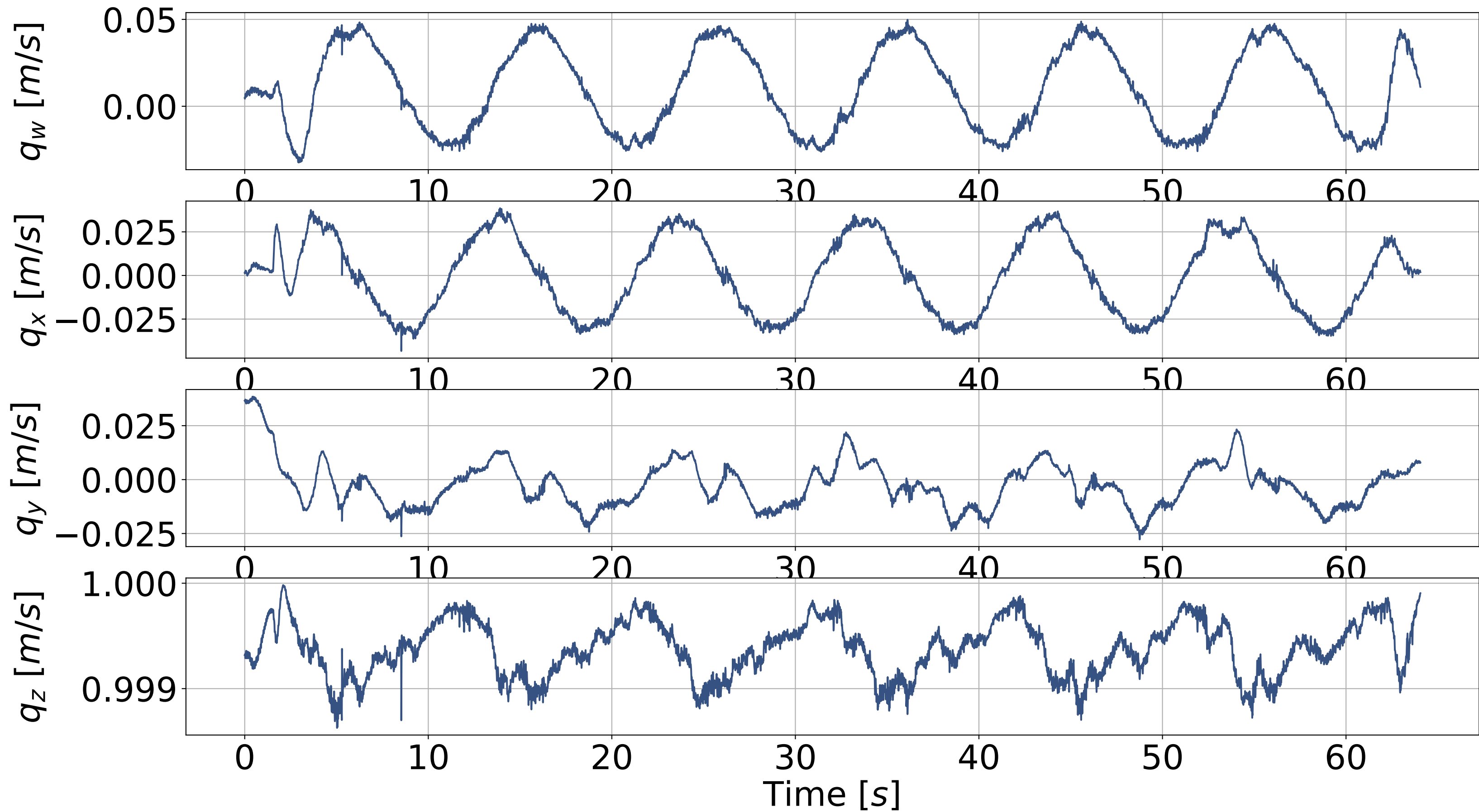
Linear Acceleration



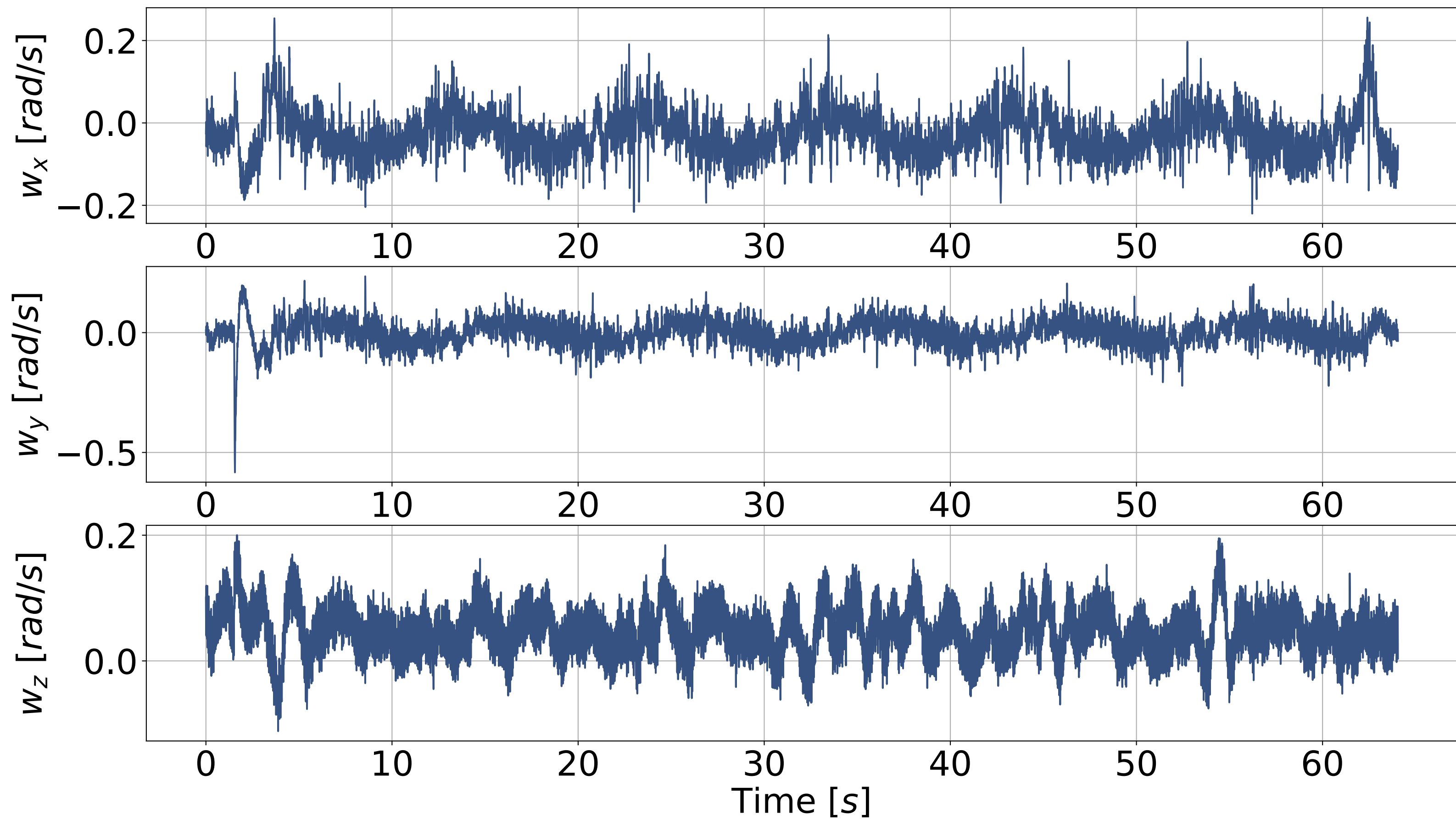
Residual Linear Acceleration



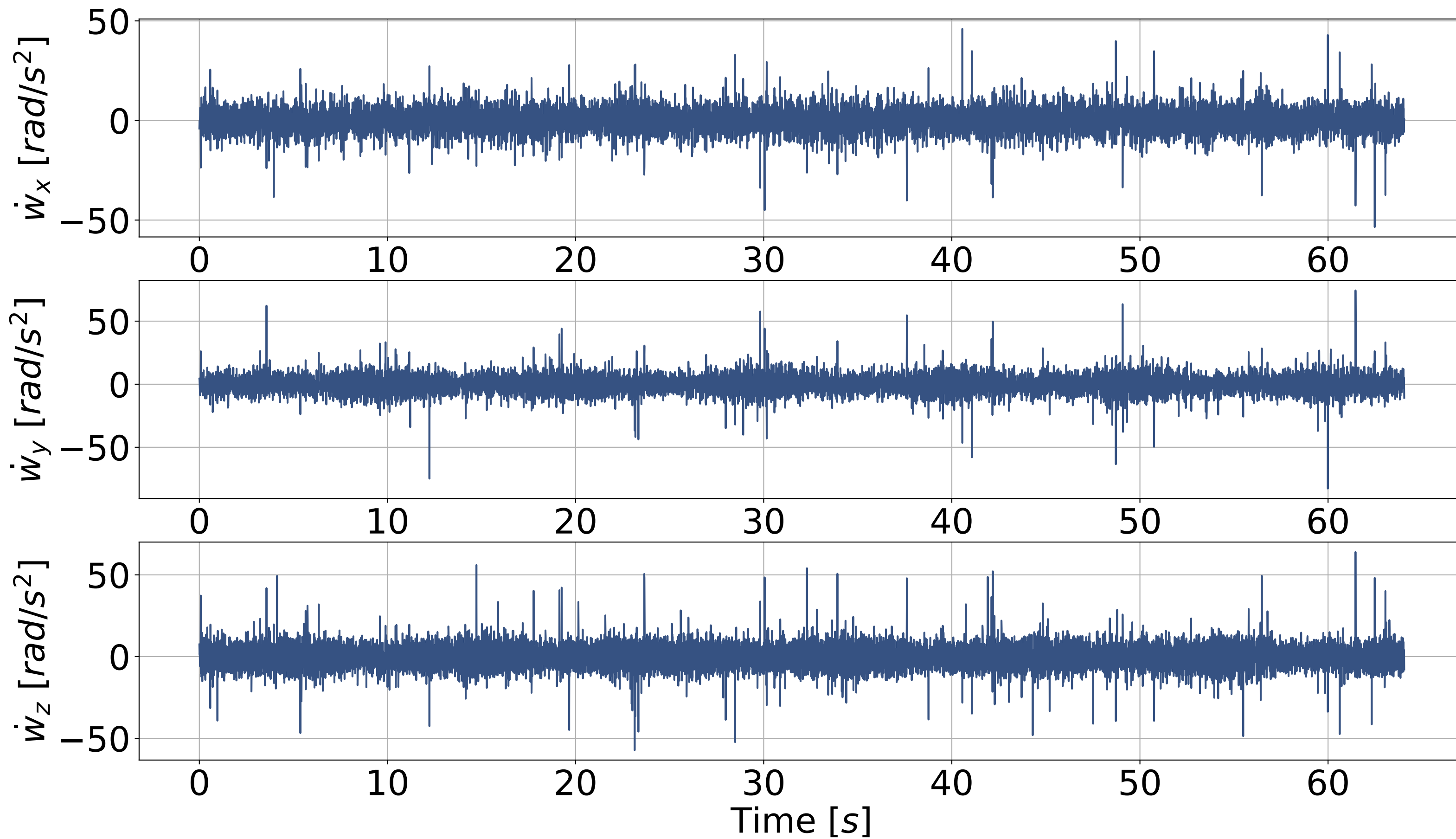
Quaternion



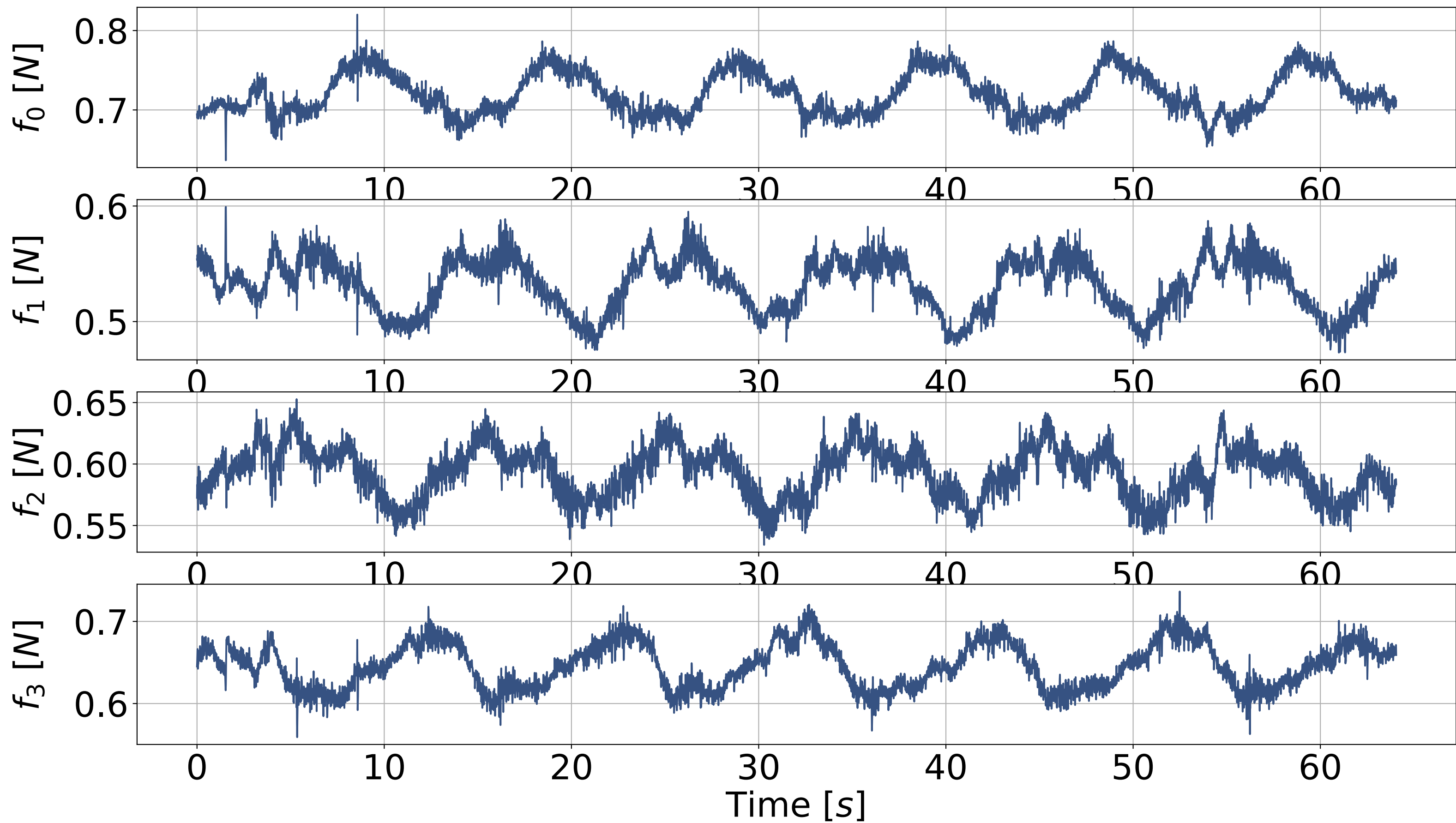
Angular Velocity



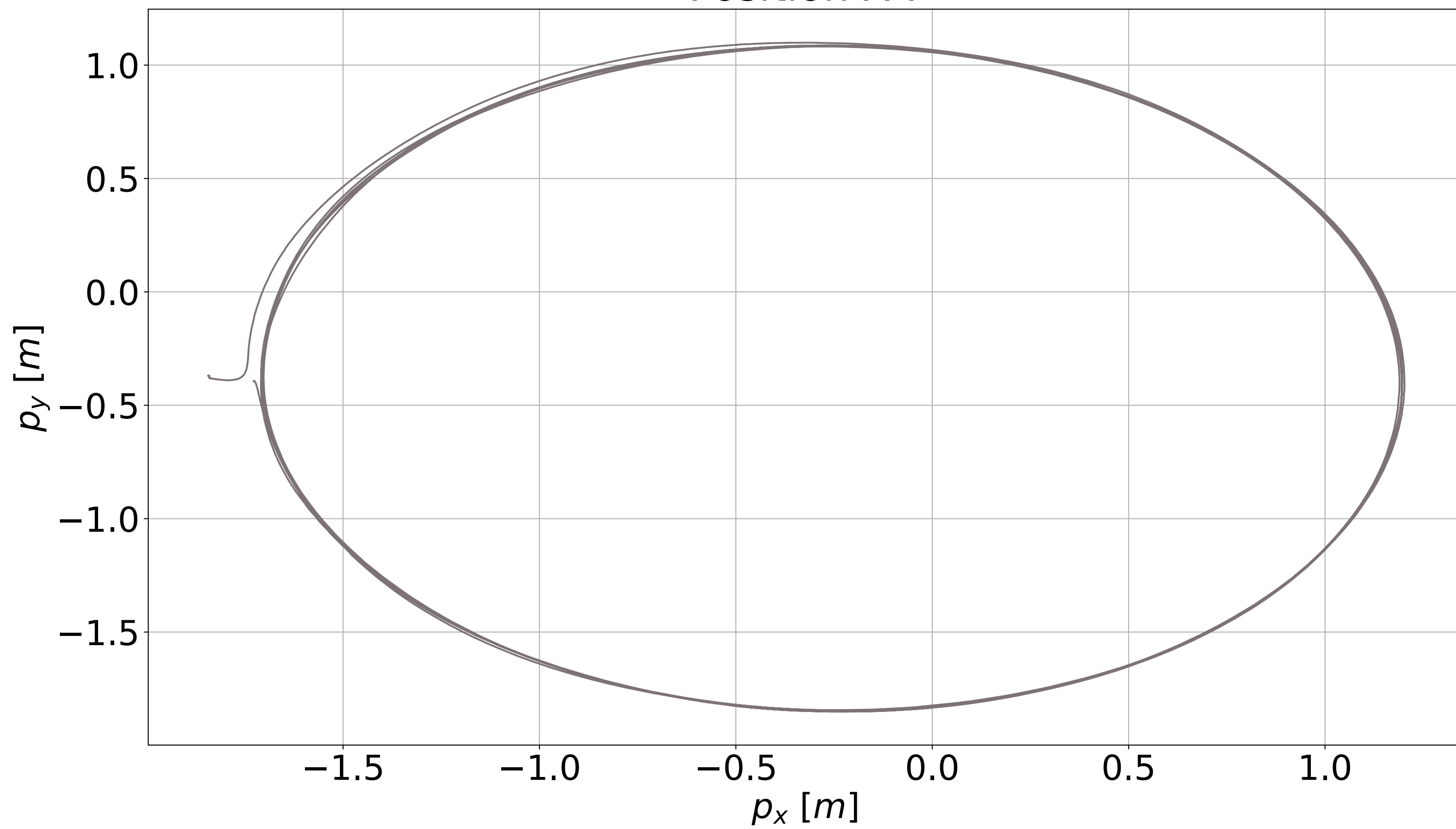
Angular Acceleration

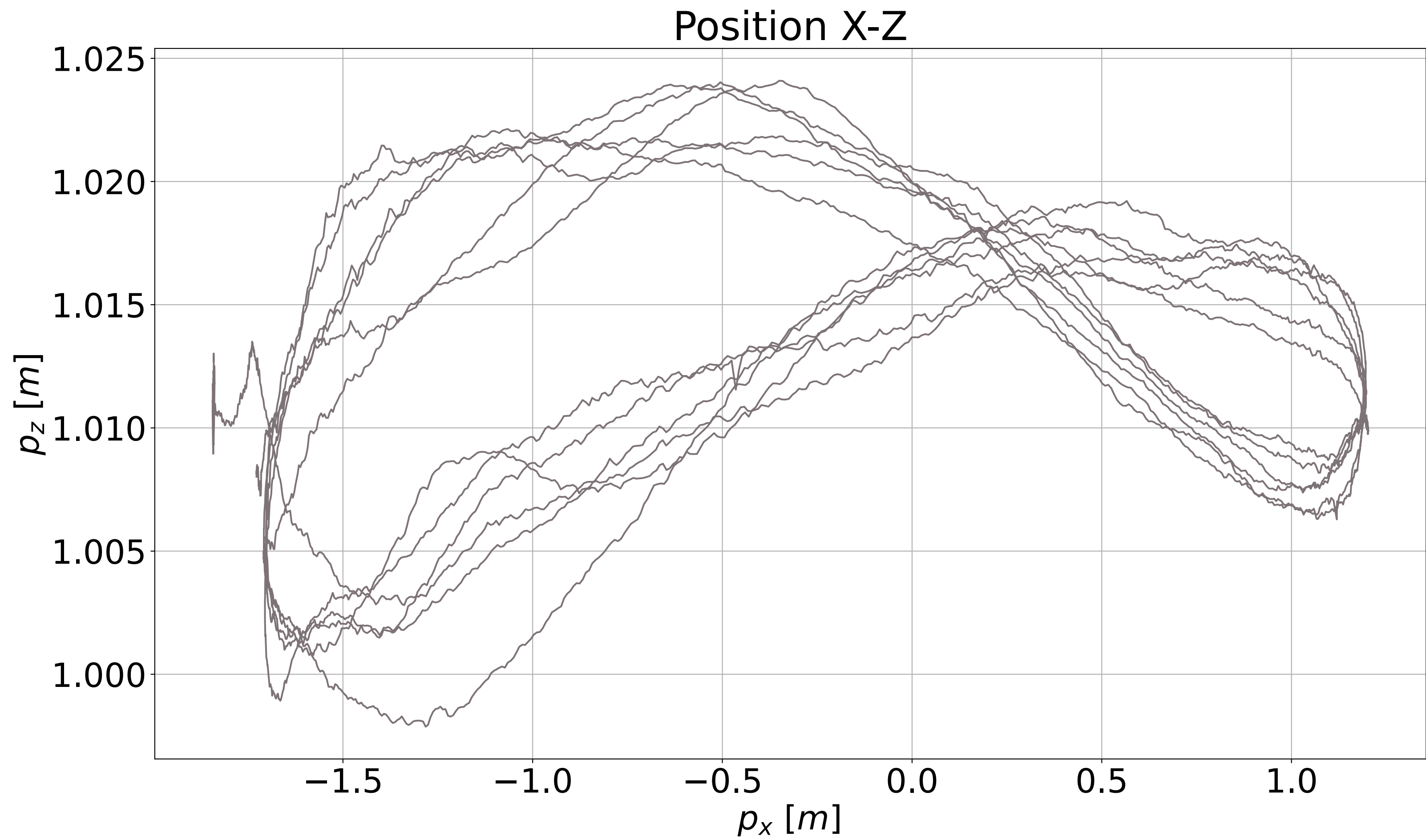


Motor Thrust



Position X-Y





Position Y-Z

