

NIRMAL A J L A

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Mechanical Engineer | Robotics and Automation | Expertise in Haptics, IOT Systems, Sensor Modeling and Product Design

EDUCATION

Cornell University Ithaca | Aug 2024 ~ May 2025

M.Eng in Mechanical and Aerospace Engineering (MAE) | GPA : 3.721

Coursework: Robotics, Automation, Sensor Modelling and simulations,Advanced Product Design and Haptics, IOT Systems

College of Engineering Guindy (CEG) Chennai | Aug 2019 – May 2023

B.E Mechanical Engineering | GPA : 3.903

Patent for String Drive Wheelchair

SKILLS

Technical : SolidWorks, CATIA, AutoCAD, Fusion 360, Inventor, Ansys, Aveva E3D, BricsCAD, Rapid Prototyping, 3D Printing, Design for Manufacturing, Blender (Renders), GD&T, CFD, NX, Onshape, Microcontroller Programming

Programming : C++, Python, Matlab, C#, Kotlin, Front-End(HTML, CSS, JS), Android Dev, Flutter, SQL

Interpersonal: Communication, collaboration, leadership & initiative, problem-solving & critical thinking, adaptability & resilience, work ethic & accountability.

PROFESSIONAL EXPERIENCE

AMTDC, IIT Madras Feb 2022 – June 2022

Research and Design Intern

- Developed an automated pallet changer for the FANUC Robodrill, reducing workpiece changeover time by 40% and increasing throughput.
- Contributed to mechanical design and CAD modeling of the changer mechanism, focusing on modularity and ease of integration with existing CNC systems.
- Performed feasibility and kinematic analysis to validate system efficiency, reliability, and manufacturability under industrial constraints.

Technip Energies Aug 2023 – Aug 2024

Piping Design Engineer

- Designed optimized layouts for hydrocarbon refineries and chemical plants, modeling 300+ pipelines in AutoCAD and ensuring full compliance with ASME and other industry codes.
- Routed process piping systems with a focus on safety, accessibility, thermal stress management, and efficient material usage.
- Oversaw on-site construction for 3 months at the Indian Oil Corporation plant in Paradip, Odisha, delivering 100% spool installations on time under strict deadlines

TECHNICAL PROJECTS

SAVIpress: Acupressure-Inspired Footrest Massage Device Sep 2024 ~ May 2025

- Engineered a haptic footrest with pressure nodes for relaxation and improved circulation.
- Conducted finite element analysis (FEA) for stress and deformation testing under various loads.
- Led branding, mechanical design, and prototype development for usability testing.

Smart Wheelchair with String Drive Mechanism Mar 2022 – Sep 2022

- Redesigned the drive mechanism using a string-based system for improved mobility.
- Conducted ergonomic and force analysis to optimize effort reduction for users.
- Developed a mechanical prototype with enhanced maneuverability.

Agricultural Smart Bot (Capstone Project) Dec 2022 ~ May 2023

- Designed and fabricated an autonomous robot capable of plowing, seeding, and irrigation.
- Integrated sensor-based automation for precision farming tasks.
- Conducted mechanical design validation and field testing.

Autonomous Mobile Robot – Sensor Fusion, Mapping & Control

Jan 2025 ~ May 2025

- Programmed and tested real-time localization, mapping, and motion planning algorithms on the iRobot Create platform, using MATLAB.
- Developed lab solutions for sensor integration, SLAM, and autonomous navigation; final competition project demonstrated obstacle avoidance and path execution in a dynamic environment.

Haptic Device for Fishing Arcade Game

Sep 2024 – Dec 2024

- Designed a dual Hapkit-based force feedback system to simulate realistic fishing sensations.
- Implemented bilateral control with position and force scaling for an immersive arcade experience.

LiDAR-Based Sensor Modeling and Navigation

Sep 2024 – Dec 2024

- Designed a sensor model for autonomous navigation, detecting obstacles and mapping environments.
- Implemented real-time filtering and noise reduction for accurate target identification.
- Achieved 82% scanning coverage with optimized movement planning for rapid response applications.

Autonomous Selfie Drone Controller

Sep 2024 – Dec 2024

- Developed a PySMT and Z3-based autonomous controller for takeoff, hover, and landing.
- Designed real-time trajectory optimization to handle wind disturbances and user proximity constraints.
- Integrated dynamic force calculations and stability adjustments for precision control.

High-Precision Bluetooth Scroll Wheel

Jan 2025 ~ May 2025

- Designed a compact, ergonomic scroll wheel using a hollow-shaft BLDC motor, AS5600 magnetic encoder, and nRF52840 microcontroller for high-resolution wireless HID input.
- Integrated a circular capacitive touchpad and Li-Po battery in a modular, 3D-printed form factor; project is heading toward a provisional patent for its innovative design and seamless user experience.

Modular 3D-Printed Camera Cage for Nikon Z50II

Jan 2025 ~ May 2025

- Engineered a fully 3D-printed camera cage with integrated Arca-Swiss base, side vertical shooting plate, cold shoe mounts, and top handle, enabling enhanced ergonomics, modularity, and accessory mounting.
- Achieved full screen articulation and unobstructed access to battery and SD card doors; designed for strength, minimal weight, and printability, demonstrating strong CAD and product development skills.

Motorized Camera Slider with Closed-Loop Control

Jan 2025 ~ May 2025

- Designed and prototyped a belt-driven camera slider using a NEMA 17 stepper motor, magnetic encoder, and ESP32 microcontroller for closed-loop motion control.
- Built on 2020 V-slot extrusions with a custom carriage, the system supports Bluetooth control for remote operation and precise positioning.

Aerodynamic Analysis of a Three-Wheeler

Sep 2021 – Jan 2022

- Conducted CFD simulations to optimize vehicle aerodynamics. Proposed design modifications to reduce drag and improve efficiency.

STEM IoT Education Training Platform

Jan 2025 ~ May 2025

- Designed scalable IoT training modules and coding tutorials for high school educators in rural Geneva, NY.
- Developed user-friendly sensor demos and Arduino/TTN content to support long-term classroom integration.

CREATIVE & LEADERSHIP EXPERIENCE

Freelance Graphic Designer & Filmmaker

2018 – 2023

- Delivered branding and promotional content for clients; specialized in motion graphics, video editing, and storytelling.
- Portfolio: [Website](#) | [YouTube](#)

Student Video Producer – Cornell Student & Campus Life

Sep 2023 ~ May 2025

- Produces videos for Cornell's official platforms; involved in scripting, shooting, and editing campus life stories.
- Featured Work: [Food of the Original People](#)

Student Director – CEG Tech Forum

Aug 2021 – Aug 2023

Design Head – NSS Unit 7

Aug 2020 – Aug 2022