#### A self-contained, simplified analysis of span program algorithms

A.J. Cornelissen<sup>1</sup>, S. Jeffery<sup>2</sup>, M. Ozols<sup>1</sup>, A. Piedrafita<sup>2</sup>

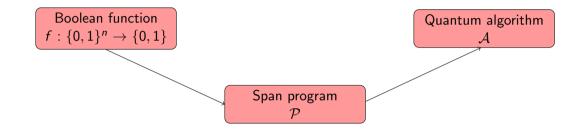
 $^{1}$ QuSoft - UvA

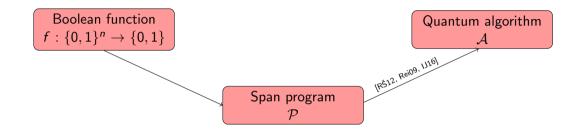
 $^2$ QuSoft – CWI

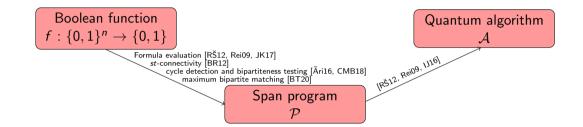
September 18th, 2020

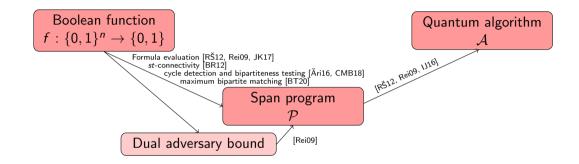
Boolean function  $f: \{0,1\}^n \to \{0,1\}$ 

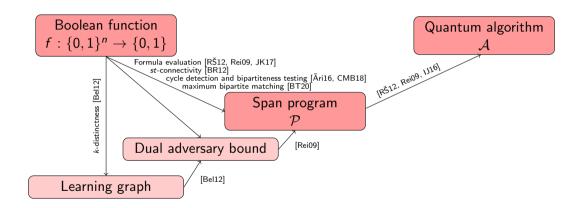
Quantum algorithm  ${\cal A}$ 

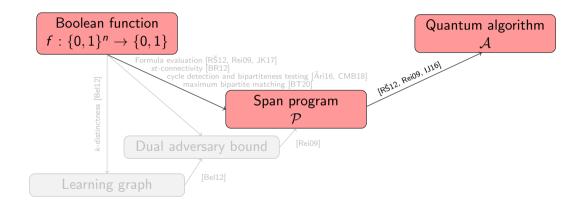


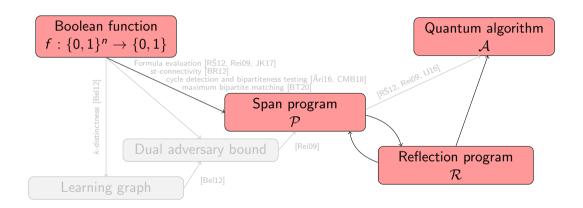




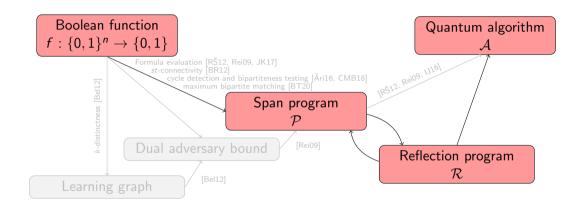
















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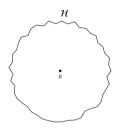


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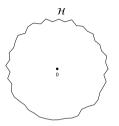


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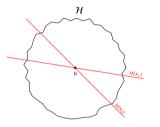




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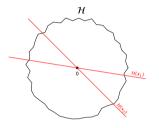




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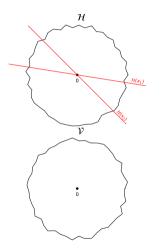




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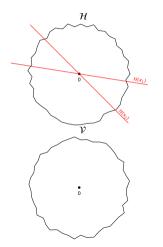




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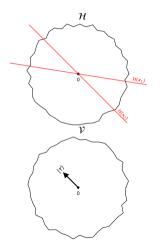




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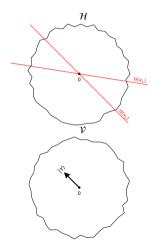




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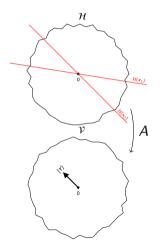




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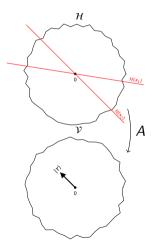


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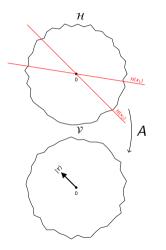
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Positive instances: 
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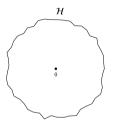
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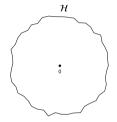




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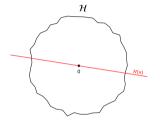




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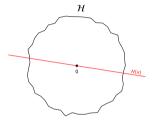




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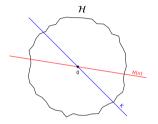




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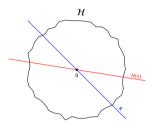


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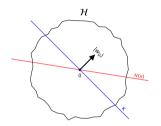


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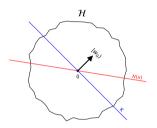
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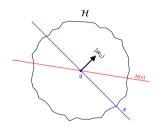
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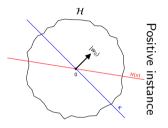
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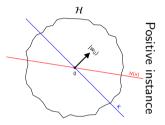
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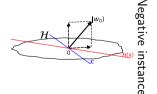
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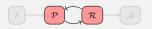
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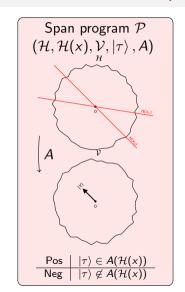
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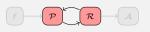


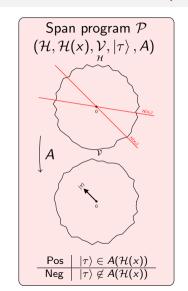


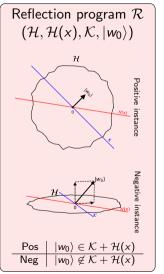


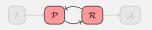


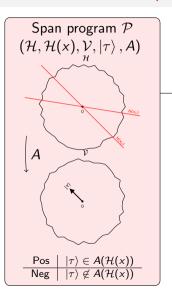




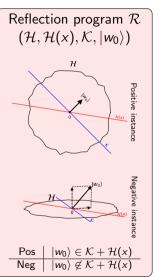


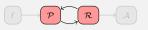


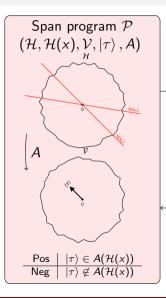




$$\mathcal{K} = \mathsf{Ker}(A) \ |w_0
angle = rac{A^+| au
angle}{\|A^+| au
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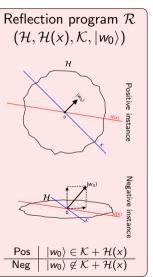


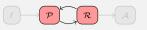


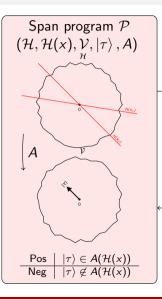


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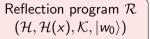


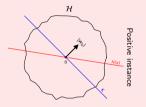


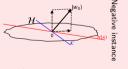
$$\mathcal{K} = \operatorname{\mathsf{Ker}}(A) \ |w_0\rangle = rac{A^+| au
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These conversions don't change positive and negative instances.

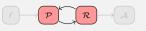
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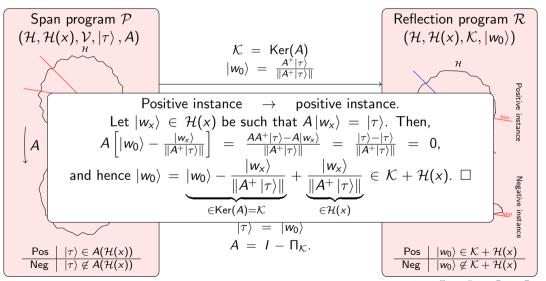






Pos	$ w_0\rangle \in \mathcal{K} + \mathcal{H}(x)$
Neg	$ w_0\rangle \not\in \mathcal{K} + \mathcal{H}(x)$









Reflection program:  $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle).$ 



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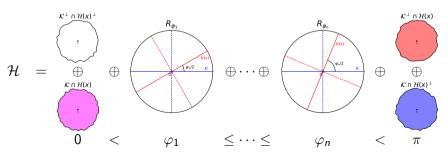
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  - **3** The remainder decomposes into 2-dimensional rotation spaces with angles  $\varphi_1, \ldots, \varphi_n$ .



Reflection program:  $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle).$ 

Reflection program operator:  $U(x) = (2\Pi_{\mathcal{H}(x)} - I)(2\Pi_{\mathcal{K}} - I)$ .

- Acts as I on  $(\mathcal{K} \cap \mathcal{H}(x)) \oplus (\mathcal{K}^{\perp} \cap \mathcal{H}(x)^{\perp})$ ,
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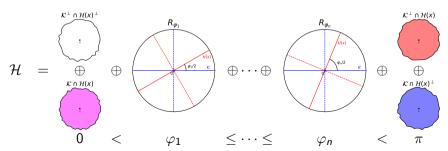




Reflection program:  $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle)$ .

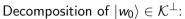
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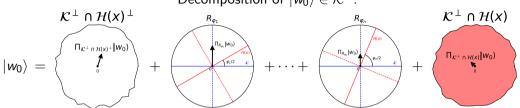
- Acts as I on  $(\mathcal{K} \cap \mathcal{H}(x)) \oplus (\mathcal{K}^{\perp} \cap \mathcal{H}(x)^{\perp})$ ,
- **2** Acts as -I on  $(\mathcal{K} \cap \mathcal{H}(x)^{\perp}) \oplus (\mathcal{K}^{\perp} \cap \mathcal{H}(x))$ .
- ullet The remainder decomposes into 2-dimensional rotation spaces with angles  $arphi_1,\dots,arphi_n$ .
- **1**  $\Pi_{\mathcal{K}}$  and  $\Pi_{\mathcal{H}(x)}$  commute with the projectors on all these spaces.



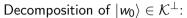


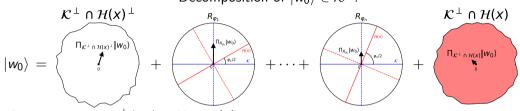










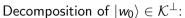


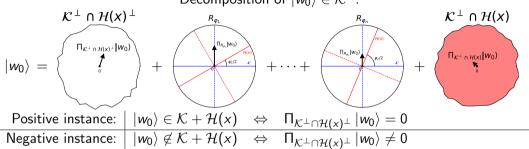
Positive instance: | |v

$$|w_0\rangle \in \mathcal{K} + \mathcal{H}(x)$$

Negative instance:  $|w_0\rangle \not\in \mathcal{K} + \mathcal{H}(x)$ 

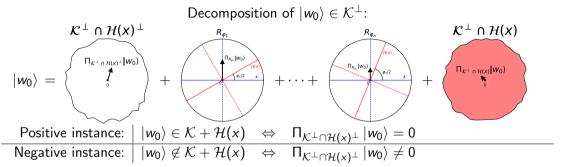






Negative instance:



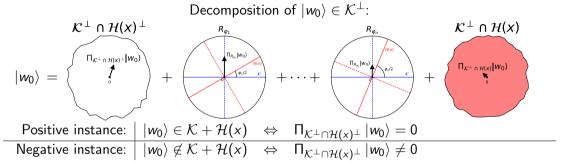


Thought experiment: run phase estimation

- With operator U(x),
- ② With initial state  $|w_0\rangle$ ,
- With infinite precision,

call the outcome  $\Phi$ .

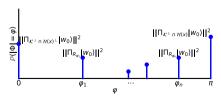




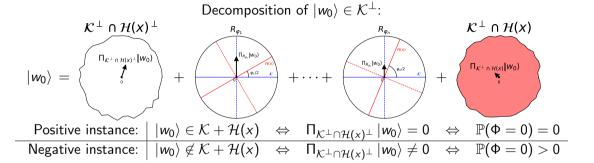
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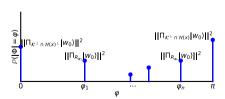




Thought experiment: run phase estimation

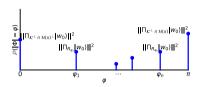
- With operator U(x),
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call the outcome  $\Phi$ .





Positive instance: 
$$\mathbb{P}(\Phi = 0) = 0$$
, Negative instance:  $\mathbb{P}(\Phi = 0) > 0$ .



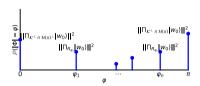
8 / 13



Positive instance: 
$$\mathbb{P}(\Phi = 0) = 0$$
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- Finite precision algorithm:
  - Run phase estimation
    - With operator U(x),
    - **②** With initial state  $|w_0\rangle$ ,
    - **3** With precision  $\delta > 0$ ,

call the outcome  $\Phi_{\delta}$ .

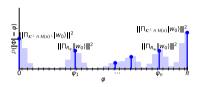




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8 / 13



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Finite precision algorithm:

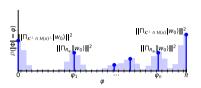
- Run phase estimation
  - With operator U(x),
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- ② Distinguish between

  - ②  $\mathbb{P}(\Phi_{\delta}=0)\geq \varepsilon$  (output f(x)=0),

by running amplitude estimation with precision  $\Theta(\sqrt{\varepsilon})$ .



8 / 13



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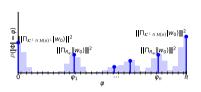
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Total cost:  $\Theta\left(\frac{1}{\delta\sqrt{\varepsilon}}\right)$  calls to U(x).





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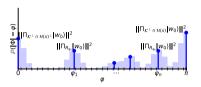
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Analysis of phase estimation:

$$\mathbb{P}(\Phi=0) \leq \mathbb{P}(\Phi_{\delta}=0) \leq \delta^2 \mathbb{E}\left[rac{1}{\sin^2\left(rac{\Phi}{2}
ight)}
ight]$$
 ,

8 / 13



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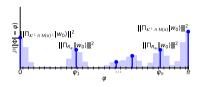
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- ② Distinguish between
  - $\mathbb{P}(\Phi_{\delta}=0) \leq \varepsilon/2$  (output f(x)=1),
  - ②  $\mathbb{P}(\Phi_{\delta}=0)\geq \varepsilon$  (output f(x)=0),

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Total cost:  $\Theta\left(\frac{1}{\delta\sqrt{\varepsilon}}\right)$  calls to U(x).



Analysis of phase estimation:

$$\mathbb{P}(\Phi=0) \leq \mathbb{P}(\Phi_{\delta}=0) \leq \delta^2 \mathbb{E}\left[rac{1}{\sin^2(rac{\Phi}{2})}
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 ,

We need to ensure that:

For positive instances:

$$\mathbb{E}\left[\frac{1}{\sin^2(\frac{\Phi}{2})}\right] \leq \frac{\varepsilon}{2\delta^2}.$$



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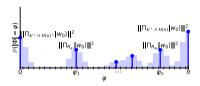
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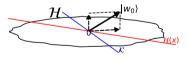
$$\mathbb{E}\left[\frac{1}{\sin^2\left(\frac{\Phi}{2}\right)}\right] \leq \frac{\varepsilon}{2\delta^2}.$$

② For negative instances:

$$\mathbb{P}(\Phi=0)\geq \varepsilon.$$



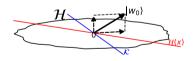
For all negative instances, we need to ensure that  $\mathbb{P}(\Phi = 0) \geq \varepsilon$ .





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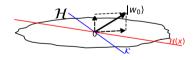
$$\mathbb{P}(\Phi=0) = \left\| \Pi_{\mathcal{K}^{\perp} \cap \mathcal{H}(x)^{\perp}} \left| w_0 \right\rangle \right\|^2$$





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$$\mathbb{P}(\Phi = 0) = \left\| \Pi_{\mathcal{K}^{\perp} \cap \mathcal{H}(x)^{\perp}} | w_0 \rangle \right\|^2$$
$$= \min\{ \| |\omega_x \rangle \|^2 : |\omega_x \rangle \in \mathcal{K}^{\perp} \cap \mathcal{H}(x)^{\perp}, \langle \omega_x | w_0 \rangle = 1 \}^{-1}$$

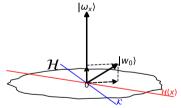




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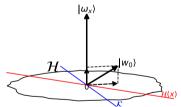




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Negative witnesses





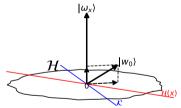
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Negative witnesses

$$\geq \frac{1}{\left\|\left|\omega_{\mathsf{x}}\right\rangle\right\|^{2}}$$

for any negative witness  $|\omega_x\rangle$ .





For all negative instances, we need to ensure that  $\mathbb{P}(\Phi = 0) \geq \varepsilon$ .

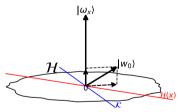
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$$W_{-} := \max_{\mathbf{x} \in f^{(-1)}(\mathbf{0})} \left\| |\omega_{\mathbf{x}}\rangle \right\|^{2}$$





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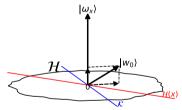
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$$W_- := \max_{x \in f^{(-1)}(0)} \left\| \ket{\omega_x} 
ight\|^2 \quad \Rightarrow \quad \mathbb{P}(\Phi = 0) \geq rac{1}{W_-} =: arepsilon.$$





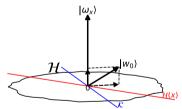
For all negative instances, we need to ensure that  $\mathbb{P}(\Phi = 0) \geq \varepsilon$ .

$$\begin{split} \mathbb{P}(\Phi = 0) &= \left\| \Pi_{\mathcal{K}^{\perp} \cap \mathcal{H}(x)^{\perp}} \left| w_{0} \right\rangle \right\|^{2} \\ &= \min\{ \left\| \left| \omega_{x} \right\rangle \right\|^{2} : \underbrace{\left| \omega_{x} \right\rangle \in \mathcal{K}^{\perp} \cap \mathcal{H}(x)^{\perp}, \left\langle \omega_{x} \right| w_{0} \right\rangle = 1}_{\textit{Negative witnesses}} \}^{-1} \\ &\geq \frac{1}{\left\| \left| \omega_{x} \right\rangle \right\|^{2}} \end{split}$$

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Shorter negative witnesses give better bounds.







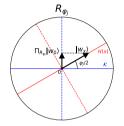
For all positive instances, we need to ensure that  $\mathbb{E}\left[\frac{1}{\sin^2(\frac{\Phi}{2})}\right] \leq \frac{\varepsilon}{\delta^2}$ .

$$\mathbb{E}\left[\frac{1}{\sin^2\left(\frac{\Phi}{2}\right)}\right] = \sum_{j=1}^n \frac{\left\|\Pi_{R_{\varphi_j}} \left|w_0\right\rangle\right\|^2}{\sin^2\left(\frac{\varphi_j}{2}\right)}$$



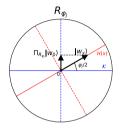
For all positive instances, we need to ensure that  $\mathbb{E}\left[\frac{1}{\sin^2(\frac{\theta}{2})}\right] \leq \frac{\varepsilon}{\delta^2}$ .

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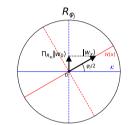


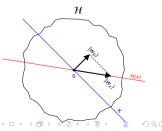
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$$\begin{split} \mathbb{E}\left[\frac{1}{\sin^2\left(\frac{\Phi}{2}\right)}\right] &= \sum_{j=1}^n \frac{\left\|\Pi_{R_{\varphi_j}} \left|w_0\right\rangle\right\|^2}{\sin^2\left(\frac{\varphi_j}{2}\right)} \\ &= \sum_{j=1}^n \min\{\left\|\left|w_x\right\rangle\right\|^2 : \left|w_x\right\rangle \in \mathcal{H}(x) \cap R_{\varphi_j}, \Pi_{\mathcal{K}^{\perp}} \left|w_x\right\rangle = \Pi_{R_{\varphi_j}} \left|w_0\right\rangle\} \end{split}$$



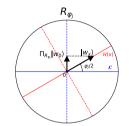


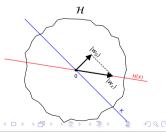


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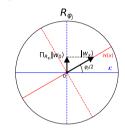
For all positive instances, we need to ensure that  $\mathbb{E}\left[\frac{1}{\sin^2(\frac{\theta}{2})}\right] \leq \frac{\varepsilon}{\delta^2}$ .

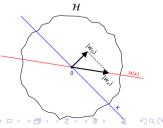
$$\mathbb{E}\left[\frac{1}{\sin^2\left(\frac{\Phi}{2}\right)}\right] = \sum_{j=1}^n \frac{\left\|\Pi_{R_{\varphi_j}} \left|w_0\right\rangle\right\|^2}{\sin^2\left(\frac{\varphi_j}{2}\right)}$$

$$= \sum_{j=1}^n \min\{\left\|\left|w_x\right\rangle\right\|^2 : \left|w_x\right\rangle \in \mathcal{H}(x) \cap R_{\varphi_j}, \Pi_{\mathcal{K}^{\perp}} \left|w_x\right\rangle = \Pi_{R_{\varphi_j}} \left|w_0\right\rangle\}$$

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Positive witnesses







For all positive instances, we need to ensure that  $\mathbb{E}\left[\frac{1}{\sin^2(\frac{\theta}{\alpha})}\right] \leq \frac{\varepsilon}{\delta^2}$ .

$$\mathbb{E}\left[\frac{1}{\sin^2\left(\frac{\Phi}{2}\right)}\right] = \sum_{j=1}^n \frac{\left\|\Pi_{R_{\varphi_j}} |w_0\rangle\right\|^2}{\sin^2\left(\frac{\varphi_j}{2}\right)}$$

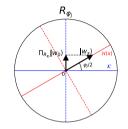
$$= \sum_{j=1}^n \min\{\||w_x\rangle\|^2 : |w_x\rangle \in \mathcal{H}(x) \cap R_{\varphi_j}, \Pi_{\mathcal{K}^{\perp}} |w_x\rangle = \Pi_{R_{\varphi_j}} |w_0\rangle\}$$

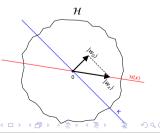
$$= \min\{\||w_x\rangle\|^2 : |w_x\rangle \in \mathcal{H}(x), \Pi_{\mathcal{K}^{\perp}} |w_x\rangle = |w_0\rangle\}$$

Positive witnesses

$$\leq \||w_{x}\rangle\|^{2}$$
,

for any positive witness  $|w_x\rangle$ .







For all positive instances, we need to ensure that  $\mathbb{E}\left[\frac{1}{\sin^2(\frac{\theta}{\alpha})}\right] \leq \frac{\varepsilon}{\delta^2}$ .

$$\mathbb{E}\left[\frac{1}{\sin^2\left(\frac{\Phi}{2}\right)}\right] = \sum_{j=1}^n \frac{\left\|\Pi_{R_{\varphi_j}} |w_0\rangle\right\|^2}{\sin^2\left(\frac{\varphi_j}{2}\right)}$$

$$= \sum_{j=1}^n \min\{\||w_x\rangle\|^2 : |w_x\rangle \in \mathcal{H}(x) \cap R_{\varphi_j}, \Pi_{\mathcal{K}^{\perp}} |w_x\rangle = \Pi_{R_{\varphi_j}} |w_0\rangle\}$$

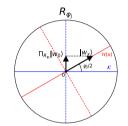
$$= \min\{\||w_x\rangle\|^2 : \underline{|w_x\rangle} \in \mathcal{H}(x), \Pi_{\mathcal{K}^{\perp}} |w_x\rangle = |w_0\rangle\}$$

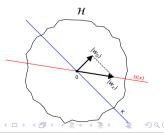
Positive witnesses

$$\leq \||w_{\mathsf{x}}\rangle\|^2$$
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$$W_{+} := \max_{x \in f^{(-1)}(1)} \||w_{x}\rangle\|^{2}$$







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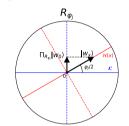
$$\begin{split} \mathbb{E}\left[\frac{1}{\sin^2\left(\frac{\Phi}{2}\right)}\right] &= \sum_{j=1}^n \frac{\left\|\Pi_{R_{\varphi_j}} \left|w_0\right\rangle\right\|^2}{\sin^2\left(\frac{\varphi_j}{2}\right)} \\ &= \sum_{j=1}^n \min\{\left\|\left|w_x\right\rangle\right\|^2 : \left|w_x\right\rangle \in \mathcal{H}(x) \cap R_{\varphi_j}, \Pi_{\mathcal{K}^{\perp}} \left|w_x\right\rangle = \Pi_{R_{\varphi_j}} \left|w_0\right\rangle\} \\ &= \min\{\left\|\left|w_x\right\rangle\right\|^2 : \left|w_x\right\rangle \in \mathcal{H}(x), \Pi_{\mathcal{K}^{\perp}} \left|w_x\right\rangle = \left|w_0\right\rangle\} \end{split}$$

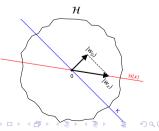
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$$W_+ := \max_{x \in f^{(-1)}(1)} \||w_x\rangle\|^2 \quad \Rightarrow \quad \mathbb{E}\left[\frac{1}{\sin^2\left(\frac{\Phi}{2}\right)}\right] \leq W_+ =: \frac{\varepsilon}{2\delta^2}.$$









Reflection program:  $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle)$ .

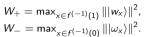


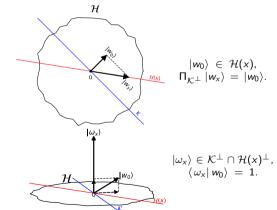
- Reflection program:  $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle).$ 
  - For all  $x \in f^{(-1)}(1)$ , find a positive witness  $|w_x\rangle$ ,
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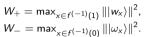


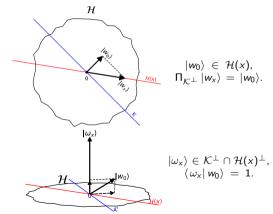
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#### Choose the finite precision parameters:

- $② W_+ = \frac{\varepsilon}{2\delta^2} \quad \Rightarrow \quad \delta := 1/\sqrt{2W_-W_+},$







Reflection program:  $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle).$ 

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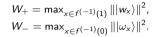
Choose the finite precision parameters:

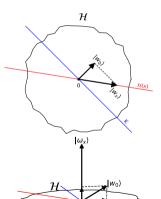
- $\bullet$   $\varepsilon := 1/W_-$ ,

Run the algorithm:

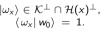
- Run phase estimation
  - ① with operator  $U(x) = (2\Pi_{\mathcal{H}(x)} I)(2\Pi_{\mathcal{K}} I)$ ,
  - ② with initial state  $|w_0\rangle$ ,
  - $\odot$  with precision  $\delta$ ,

call the outcome  $\Phi_{\delta}$ .





$$|w_0
angle \in \mathcal{H}(x), \ \Pi_{\mathcal{K}^{\perp}} |w_x
angle = |w_0
angle$$





- Reflection program:  $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle).$ 
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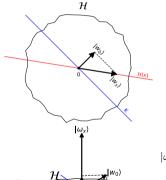
call the outcome  $\Phi_{\delta}$ .

- ② Distinguish between

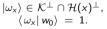
with amplitude estimation with precision  $\Theta(\sqrt{\varepsilon})$ .

$$W_{+} = \max_{x \in f^{(-1)}(1)} |||w_{x}\rangle||^{2},$$
  

$$W_{-} = \max_{x \in f^{(-1)}(0)} |||\omega_{x}\rangle||^{2}.$$



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angle \in \mathcal{H}(x), \ \Pi_{\mathcal{K}^{\perp}} |w_x
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Reflection program:  $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle).$ 

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Choose the finite precision parameters:

Run the algorithm:

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call the outcome  $\Phi_{\delta}$ .

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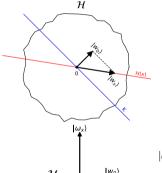
  - ②  $\mathbb{P}(\Phi_{\delta} = 0) \geq \varepsilon$  (output f(x) = 0),

with amplitude estimation with precision  $\Theta(\sqrt{\varepsilon})$ .

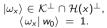
Total calls to U(x):  $\mathcal{O}\left(\frac{1}{\delta\sqrt{\varepsilon}}\right) = \mathcal{O}(W_-\sqrt{W_+})$ ,

$$W_{+} = \max_{x \in f^{(-1)}(1)} |||w_{x}\rangle||^{2},$$
  

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angle \in \mathcal{H}(x),$$
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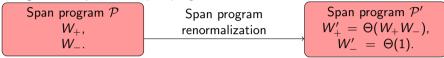


• The complexity can be improved from  $\mathcal{O}(W_-\sqrt{W_+})$  to  $\mathcal{O}(\sqrt{W_-W_+})$ :

- **1** The complexity can be improved from  $\mathcal{O}(W_-\sqrt{W_+})$  to  $\mathcal{O}(\sqrt{W_-W_+})$ :
  - Using a technique called *span program renormalization*.

Span program $\mathcal{P}$ $W_+$ ,	Span program renormalization	Span program $\mathcal{P}'$ $W'_{+} = \Theta(W_{+}W_{-}),$
$W_{-}$ .		$W'_{-} = \Theta(1).$

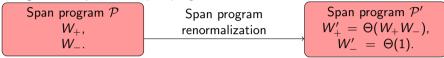
- **1** The complexity can be improved from  $\mathcal{O}(W_-\sqrt{W_+})$  to  $\mathcal{O}(\sqrt{W_-W_+})$ :
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Mow does this technique look in the reflection program case?



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When the domain is the effection of t

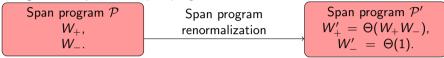


② Other relations seem to play a non-trivial role:

$$\chi(y) := \mathbb{E}\left[\frac{1}{y - \sin^2\left(\frac{\Phi}{2}\right)}\right] = \langle w_0 | \left(\Pi_{\mathcal{K}^{\perp}} \Pi_{\mathcal{H}(x)^{\perp}} \Pi_{\mathcal{K}^{\perp}} - (1 - y)I\right)^{-1} | w_0 \rangle.$$



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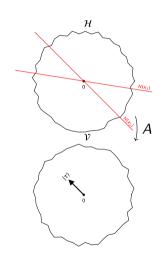
To be continued...



Thanks for your attention! arjan@cwi.nl

# Span programs – example

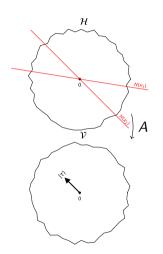




# Span programs – example

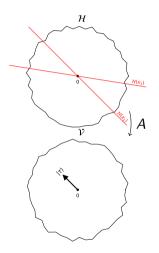


Search function:  $f(x_1, ..., x_n) = x_1 \vee \cdots \vee x_n$ .





Search function:  $f(x_1, ..., x_n) = x_1 \lor \cdots \lor x_n$ .

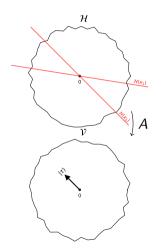


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Search function:  $f(x_1, ..., x_n) = x_1 \vee ... \vee x_n$ .

- $2 \mathcal{H}(x) = \mathsf{Span}\{|j\rangle : x_j = 1\}.$

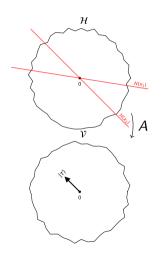


13 / 13



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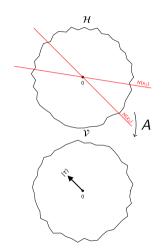
- $\mathcal{V} = \mathbb{C}$ .





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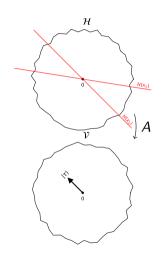
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- $\bullet A = \sum_{j=1}^{n} \langle j |.$

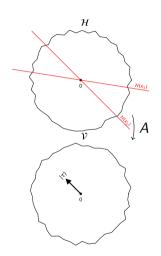




Search function:  $f(x_1, \ldots, x_n) = x_1 \vee \cdots \vee x_n$ .

- **2**  $\mathcal{H}(x) = \text{Span}\{|j\rangle : x_j = 1\}.$
- $\mathcal{V} = \mathbb{C}$ .
- $| au\rangle=1.$
- $A = \sum_{j=1}^{n} \langle j |.$

 $\mathcal{P}=\left(\mathcal{H},x\mapsto\mathcal{H}(x),\mathcal{V},\left| au
ight>,A
ight)$  evaluates f, as:



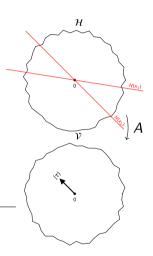


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$$\mathcal{P} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{V}, \ket{\tau}, A)$$
 evaluates  $f$ , as:

Positive instance:	$x \neq 0^n$	$\Rightarrow$
Negative instance:	$x = 0^n$	$\Rightarrow$



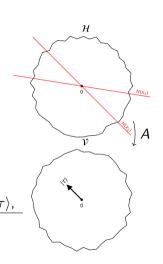


Search function:  $f(x_1, \ldots, x_n) = x_1 \vee \cdots \vee x_n$ .

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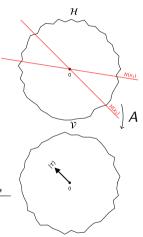


Search function:  $f(x_1, ..., x_n) = x_1 \vee \cdots \vee x_n$ .

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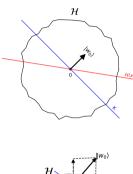
Positive instance: 
$$|x \neq 0^n| \Rightarrow \text{Let } x_j = 1, \ A|j\rangle = 1 = |\tau\rangle$$
, Negative instance:  $|x = 0^n| \Rightarrow A(\mathcal{H}(x)) = \{0\} \not\ni |\tau\rangle$ .

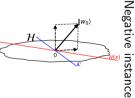




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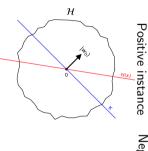


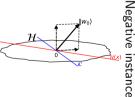


Positive instance



Search function:  $f(x_1, ..., x_n) = x_1 \lor \cdots \lor x_n$ .

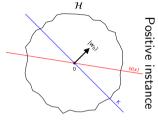


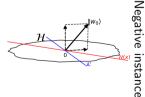


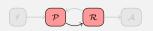


Search function:  $f(x_1, ..., x_n) = x_1 \lor \cdots \lor x_n$ .

- $2 \mathcal{H}(x) = \mathsf{Span}\{|j\rangle : x_i = 1\}.$
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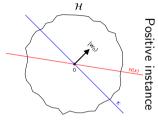


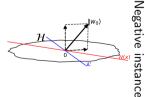




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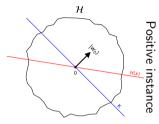


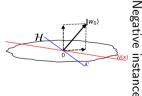


Search function:  $f(x_1, \ldots, x_n) = x_1 \vee \cdots \vee x_n$ .

 $\mathfrak{O}$   $\mathcal{H}=\mathbb{C}^n$ .

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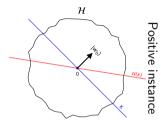


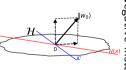


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- $\mathfrak{O}$   $\mathcal{H}=\mathbb{C}^n$ .
- $② \ \mathcal{H}(x) = \mathsf{Span}\{|j\rangle : x_j = 1\}. \qquad \textcircled{2} \ \mathcal{H}(x) = \mathsf{Span}\{|j\rangle : x_j = 1\}.$



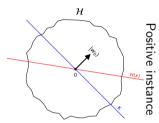


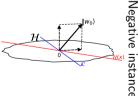


Search function:  $f(x_1, ..., x_n) = x_1 \lor \cdots \lor x_n$ .

- $\mathcal{H}(x) = \mathsf{Span}\{|j\rangle : x_i = 1\}.$
- $\mathcal{V} = \mathbb{C}.$
- $| au \rangle = 1.$
- **6**  $A = \sum_{j=1}^{n} \langle j | .$

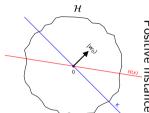
- $2 \mathcal{H}(x) = \mathsf{Span}\{|j\rangle : x_i = 1\}.$ 
  - **3**  $|w_0\rangle = \frac{A^+|\tau\rangle}{\|A^+|\tau\rangle\|} = \frac{1}{\sqrt{n}} \sum_{j=1}^n |j\rangle.$
  - $\mathcal{K} = \operatorname{Ker}(A) \stackrel{\sim}{=} \operatorname{Ker}(\langle w_0 |) = \operatorname{Span}\{|w_0\rangle\}^{\perp}.$

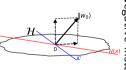




- $\mathfrak{A} \mathcal{H} = \mathbb{C}^n$ .
- $2 \mathcal{H}(x) = \operatorname{Span}\{|j\rangle : x_i = 1\}. 2 \mathcal{H}(x) = \operatorname{Span}\{|j\rangle : x_i = 1\}.$
- $\mathcal{V} = \mathbb{C}$
- $| \tau \rangle = 1.$
- $\bullet A = \sum_{i=1}^{n} \langle j|.$
- $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle)$  evaluates f, as:

- $\mathfrak{O}$   $\mathcal{H}=\mathbb{C}^n$ .
- **3**  $|w_0\rangle = \frac{A^+|\tau\rangle}{\|A^+|\tau\rangle\|} = \frac{1}{\sqrt{n}} \sum_{j=1}^n |j\rangle.$
- $\mathcal{K} = \text{Ker}(A) = \text{Ker}(\langle w_0 |) =$  $\operatorname{\mathsf{Span}}\{|w_0\rangle\}^{\perp}$ .







 $\mathcal{H}$ 

Search function:  $f(x_1, \ldots, x_n) = x_1 \vee \cdots \vee x_n$ .

$$\mathfrak{O}$$
  $\mathcal{H} = \mathbb{C}^n$ .

$$\mathcal{H}(x) = \mathsf{Span}\{|j\rangle : x_i = 1\}.$$

$$\mathcal{V} = \mathbb{C}$$
.

$$|w_0\rangle = \frac{A^+|\tau\rangle}{\|A^+|\tau\rangle\|} = \frac{1}{\sqrt{n}} \sum_{j=1}^n |j\rangle.$$

$$| au\rangle = 1.$$

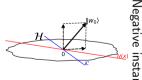
• 
$$\mathcal{K} = \text{Ker}(A) = \text{Ker}(\langle w_0 |) = \text{Span}\{|w_0\rangle\}^{\perp}$$
.

$$\bullet \ \ A = \sum_{j=1}^{n} \langle j |.$$

$$\mathcal{R} =$$

 $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle)$  evaluates f, as:

Positive instance:  $|x \neq 0^n| \Rightarrow$ 



Negative instance:  $x = 0^{n}$ 





 $\mathcal{H}$ 

Search function:  $f(x_1, \ldots, x_n) = x_1 \vee \cdots \vee x_n$ .

$$\mathfrak{O}$$
  $\mathcal{H}=\mathbb{C}^n$ .

$$\mathcal{H}(x) = \mathsf{Sp}$$

$$\mathcal{H}(x) = \operatorname{Span}\{|j\rangle : x_j = 1\}. \qquad \mathcal{H}(x) = \operatorname{Span}\{|j\rangle : x_j = 1\}.$$

$$\mathcal{V} = \mathbb{C}$$

• 
$$h(x) = \text{Span}\{|j\rangle : x_j = 1\}.$$
  
•  $|w_0\rangle = \frac{A^+|\tau\rangle}{\|A^+|\tau\rangle\|} = \frac{1}{\sqrt{n}} \sum_{j=1}^n |j\rangle.$ 

$$| au\rangle=1.$$

• 
$$\mathcal{K} = \text{Ker}(A) = \text{Ker}(\langle w_0 |) = \text{Span}\{|w_0\rangle\}^{\perp}$$
.

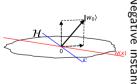
$$\bullet A = \sum_{i=1}^{n} \langle j |.$$

$$\mathcal{R} =$$

 $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle)$  evaluates f, as:



Positive instance: 
$$|x \neq 0^n| \Rightarrow \text{Let } x_j = 1,$$
  $|w_0\rangle = \underbrace{\sqrt{n}|j\rangle}_{\in \mathcal{H}(x)} + \underbrace{\frac{1}{\sqrt{n}}\sum_{k=1}^n|k\rangle - \sqrt{n}|j\rangle}_{k=1} \in \mathcal{K} + \mathcal{H}(x)$ 



 $x = 0^{n}$ Negative instance:



 $\mathcal{H}$ 

Search function:  $f(x_1, \ldots, x_n) = x_1 \vee \cdots \vee x_n$ .

$$\mathfrak{O}$$
  $\mathcal{H} = \mathbb{C}^n$ .

$$\mathcal{H}(x) = \mathsf{Span}$$

② 
$$\mathcal{H}(x) = \operatorname{Span}\{|j\rangle : x_j = 1\}.$$
 ②  $\mathcal{H}(x) = \operatorname{Span}\{|j\rangle : x_j = 1\}.$ 

$$\circ$$
  $\mathcal{V} = \mathbb{C}$ 

$$\mathcal{V} = \mathbb{C}$$
.

$$|w_0\rangle = \frac{A^+|\tau\rangle}{\|A^+|\tau\rangle\|} = \frac{1}{\sqrt{n}} \sum_{j=1}^n |j\rangle.$$

$$| au
angle=1.$$

$$\mathcal{K} = \operatorname{Ker}(A) = \operatorname{Ker}(\langle w_0 |) = \operatorname{Span}\{|w_0\rangle\}^{\perp}.$$

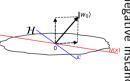
$$\bullet A = \sum_{j=1}^{n} \langle j |.$$



 $\mathcal{R} = (\mathcal{H}, x \mapsto \mathcal{H}(x), \mathcal{K}, |w_0\rangle)$  evaluates f, as:

Positive instance:  $| x \neq 0^n \Rightarrow \text{Let } x_i = 1$ ,

$$x \neq 0^n \Rightarrow \text{Let } x_j = 1,$$
 $|w_0\rangle = \underbrace{\sqrt{n}|j\rangle}_{\in \mathcal{H}(x)} + \underbrace{\frac{1}{\sqrt{n}}\sum_{k=1}^n|k\rangle - \sqrt{n}|j\rangle}_{\in \mathcal{K}} \in \mathcal{K} + \mathcal{H}(x)$ 



 $x = 0^n \Rightarrow \mathcal{K} + \mathcal{H}(x) = \overline{\mathcal{K}} = \operatorname{Span}\{|w_0\rangle\}^{\perp} \not\ni |w_0\rangle.$ Negative instance: