Radar and Remote Sensing

Formulas

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Constants 1

Constant which appear in the equations and useful quantities to help in computations.

$$c \simeq 3 \times 10^8 \,\mathrm{m/s}^1$$

$$\tau_c = 6.67 \, \text{ns/m}^2$$

$$c \simeq 3 \times 10^8 \, \mathrm{m/s^1} \qquad \qquad \tau_c = 6.67 \, \mathrm{ns/m^2} \qquad \quad k_B = 1.38 \times 10^{-23} \, \mathrm{m^2 kg/s^2 K^3}$$

- 1. Speed of light
- 2. Time needed for light to travel for 1 m considering the full roundtrip. This is helpful for quick computations like "what's the range of an object if the time of flight is 120 ns?"
- 3. Boltzmann's constant

2 Generic Radar

2.1 Geometry

$$A_e = \frac{G\lambda^2}{4\pi} = \rho A^4 \qquad \qquad \sigma = \frac{P_R \frac{4\pi}{\Omega}}{\frac{P_c}{A_{\text{target}}}} = G_{\text{target}} A_{\text{target}} ^6 \qquad \qquad \sigma_{\text{plate}} = \frac{4\pi A^2}{\lambda^2} ^8$$

$$G = 4\pi \frac{A_e}{\lambda^2} ^5 \qquad \qquad \sigma_{\text{sphere}} = \pi r^2 ^7 \qquad \qquad \sigma_{\text{corner}} = \frac{4\pi A_{\text{eff}}^2}{\lambda^2} ^9$$

2.2 Power

$$P_{D} = \frac{P_{t}}{4\pi R^{2}} G^{10} \qquad P_{r} = P_{t} \frac{G_{0}^{2} \lambda^{2} \sigma}{(4\pi)^{3} h^{4}} \qquad \text{SNR}_{s} = \frac{P_{\text{avg}} G \lambda^{2} \sigma T_{\text{scan}}}{(4\pi)^{2} R^{4} \ k T_{e} \ F \ L \ \Omega}^{14}$$

$$P_{r} = P_{t} \frac{G^{2} \lambda^{2} \sigma}{(4\pi)^{3} R^{4}} \qquad \text{SNR} = \frac{P_{t} G^{2} \lambda^{2} \sigma n_{p}}{(4\pi)^{3} R^{4} \ k_{B} T_{e} B \ F \ L}^{13}$$

- 4. Effective area of the antenna
- 5. Gain
- 6. Radar Cross Section
- 7. RCS of a sphere; r is the radius
- 8. RCS of a plate
- 9. RCS of a corner reflector
- 10. Transmitted power density over the surface of a sphere with radius R
- 11. Radar equation
- 12. Radar equation for $cosec^2$ pattern
- 13. Signal to Noise Ratio in the radar equation. n_p is the number of transmitted pulses
- 14. Signal to Noise Ratio in a surveillance Radar

3 Pulsed Radar

3.1 Characteristics

$$f_r = \frac{1}{T}^{15} \qquad \qquad \tau = \frac{1}{B}^{16}$$

3.2 Range

$$R = \frac{c}{2t}^{17} \qquad \qquad R_{\min} = \delta R = \frac{c}{2\tau}^{19} \qquad \qquad \theta_B = R \frac{\lambda}{d}^{20} \qquad \qquad M = \frac{R_{\max} - R_{\min}}{\delta R}^{21}$$

$$R_{\max} = \frac{c}{2T}^{18}$$

3.3 Power

$$d_t = \frac{\tau}{T}^{22} \qquad \qquad P_{\text{avg}} = P_t \cdot d_t^{23}$$

- 15. Pulse Repetition Interval (PRF) versus Pulse Repetition Interval (PRI)
- 16. Bandwidth
- 17. Range
- 18. Max. unambiguous range
- 19. Min. range or range resolution
- 20. Azimuth resolution; d is the length of the antenna
- 21. Number of space bins
- 22. Duty Cycle
- 23. Average power

4 Doppler

$$f_d = \frac{2v_{\text{target}}}{\lambda} \cos \theta_e \cos \theta_a \, ^{24} \qquad \qquad \delta f_d = \frac{1}{NT} \, ^{25} \qquad \qquad \gamma = 1 + \frac{2v_{\text{target}}}{c} \, ^{27}$$
$$f_r \geq 2f_{d,\text{max}} ^{26}$$

- 24. Doppler frequency. Normally the cosines are not needed
- 25. Resolution of the doppler frequency
- 26. PRF must follow the Nyquist rule to sample the Doppler frequency
- 27. Time dilation

5 Linear FM Radar

5.1 Characteristics

$$B\tau = B\Delta t^{28}$$

5.2 Range

$$f_{bd} = \frac{2R}{c} \frac{B}{\Delta t} + f_d$$

$$f_{bu} = \frac{2R}{c} \frac{B}{\Delta t} - f_d$$

$$\frac{f_{bd} - f_{bu}}{2} = f_d$$

$$\delta R = \frac{c}{2B} \frac{B}{\Delta t}$$

$$R_{\text{max}} = \frac{c \Delta t}{2} \frac{f_s}{2\Delta f}$$

$$\delta R = \frac{c}{2B}$$

- 28. Time-Bandwidth product. Δt is the duration of the chirp.
- 29. Range resolution
- 30. Max. range

6 Scattering Matrix

$$\vec{b} = S\vec{a}^{31}$$

6.1 Useful matrices

$$S_{c, cw} = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} 32$$

$$S_{ins} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} 34$$

$$S_{c, cw} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} 33$$

$$S_{dc} = \begin{pmatrix} 0 & \sqrt{1 - k^2} & ke^{j\theta} & 0 \\ \sqrt{1 - k^2} & 0 & 0 & ke^{j\theta} \\ ke^{j\theta} & 0 & 0 & \sqrt{1 - k^2} \\ 0 & ke^{j\theta} & \sqrt{1 - k^2} & 0 \end{pmatrix} 35$$

6.2 Other quantities

$$C = 10\log_{10}\frac{P_1}{P_3} = 20\log_{10}\frac{1}{S_{3.1}} = -20\log_{10}|k|^{36}$$

- 31. Definition of the scattering matrix
- 32. Clockwise circulator
- 33. Counter-clockwise circulator
- 34. Insulator
- 35. Directional coupler
- 36. Coupling factor for a directional coupler

7 Microstrps

7.1 Characteristics

$$\epsilon_{\text{eff}} = \frac{\epsilon_r + 1}{2} + \frac{\epsilon_r - 1}{2} \frac{1}{\sqrt{1 + 12h/W}} \, ^{37} \qquad \lambda_g = \frac{\lambda_0}{\sqrt{\epsilon_{\text{eff}}}} \, ^{38}$$

- 37. Effective dielectric constant
- 38. Guided wavelength