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Sonar Modelbus Plugin Project Manual

Software project WiSe 2012 Modelbased Software Engineering Software entwicklung

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Introduction

1.1 Motivation

Sonar is an open source software quality platform that uses various static code analysis tools such as Checkstyle, PMD, FindBugs to extract software metrics, which then can be used to improve software quality. Usually Sonar is used in combination with programming languages like Java, C or C#, but Sonar indeed gives the functionality to display all kind of measures and handle more than just sourcecode. From model driven software developement we know, that all the object oriented ideas also can be mapped to models, which represent the original objects. So in fact, we also could analyse models instead of just sourcecode.

Modelbus is a model repository, which is used to achieve a seamless integration between tools and the work of the development team. In the Modelbus system information (models) can be stored and reused in a transparent way. Therefore it would be an important feature to analyse models located in such a Modelbus repository.

Since we cannot just use all of the metrics we know from object oriented code analysis, Sonar cant be run out of the box to analyse models. Our plugin should therefore use the Metrino service, which gives us the functionality to examine all of the metrics on models as well. So with our work we want to provide a Sonar plugin to analyse models located at a Modelbus repository using the Metrino Service.

1.2 Requirements

The product owner identified the following requirements:

1. Create a plugin for sonar (closed)

- 2. Comprehend and cooperate with ModelBus repository (closed)
- 3. Transfer as many as possible metrics from Metrino to Sonar (open)
- 4. Select the model (closed)
- 5. Traverse the directory tree (closed)
- 6. Analyse sourcecodes (cancelled)
- 7. Plugin must work as efficient as possible (closed)

Create a plugin for sonar

- Requirement Number: 1
- Description: Each sonar plugin has a specific architecture. The created sonar plugin must hold the specifications for a sonar plugin. Additionally, it must be run on a server and offers a WSDL interface.
- Type: functional
- Dependencies: -:- (should be done first)
- Priority: high
- State: closed
- Fit Criterion: The plugin can be build and runs on a chosen server. A client connects to the Modelbus server and understands the WSDL interface. The client receives a message from the WSDL interface of the Modelbus server.

Comprehend and cooperate with ModelBus repository

• Requirement Number: 2

• Description: ModelBus has an own repository, where it stores artefacts of the tools, which are connected to the ModelBus via adapters. It must be understood, how ModelBus connects to the repository and how an external tool (like a sonar plugin) can do this.

• Type: functional

• Dependencies: # 1

• Priority: high

• State: closed

• Fit Criterion: The sonar plugin is able to connect to the Model-Bus repository via a command. It can fetch the sourcecode for a random project to test, if the connection is established. The sonar plugin can terminate the connection to the respository for a given command.

Transfer as many as possible metrics from Metrino to Sonar

• Requirement Number: 3

• Description: The sonar plugin can already fetch model code from the repository. The models are read by Metrino and analyzed by Metrino with OO metrics. The results of the analysis are fetched from metrino by the sonar plugin and visualized on the web interface. Metrino offers a lot of metrics and it should be possible to offer as many metrics from metrino as possible.

• Type: functional, partly non-functional

• Dependencies: # 4

• Priority: high

• State: open

• Fit Criterion: The sonar plugin sends a model to Metrino with the information which OO metric shall be applied. Metrino returns the results. The results are vizualized. The plugin offers to select at least 10 OO metrics of Metrino to apply to the sent model code.

Select the model

- Requirement Number: 4
- Description: The sonar plugin can fetch model code from the repository and transform the model into a format which can be read by model metric analyzing tools, like Metrino.
- Type: functional
- Dependencies: # 3
- Priority: high
- State: closed
- Fit Criterion: The plugin fetched a model. It transforms the model into the format of Metrino. For a test case, the transformed model shall be saved in a file and read successfully by Metrino.

Traverse the directory tree

- Requirement Number: 5
- Description: In the directory tree of sonar plugin, a lot of source-code and model code projects are placed. The plugin should be able to analyze all codes from the repository.
- Type: functional
- Dependencies: -:-
- Priority: high
- State: closed

• Fit Criterion: The plugin fetched the whole project tree of the repository. It loads each project into its own directory tree. It traverses the whole directory tree. For each project in its directory tree, it analyzes the code and visualizes it on the web interface.

Analyse sourcecodes

- Requirement Number: 6
- Description: The sonar plugin can apply a set of metrics to the fetched sourcecode. The results are visualized with graphs or statistics and can be get via the web interface.
- Type: functional
- Dependencies: # 2
- Priority: high
- cancelled, because requirement is infeasible with current Sonar version (could be with future versions)
- Fit Criterion: The plugin fetches normale program source code from the repository. It applies a couple of metrics, which can be chosen from the application interface.

Plugin must work as efficient as possible

- Requirement Number: 7
- Description: Plugin must traverse the directory tree fastly. The connection to the ModelBus must provide security standards, but it should not be slow. The results of the analysis should be offerred via the web interface as fast as possible.
- Type: non-functional
- Dependencies: # 6

- Priority: middle
- closed
- Fit Criterion: Because of the difficulty of the decision, if it works properly fast, a usability test with the customer must be done, who can tell in a better way, if the product works fast or not.

1.3 Expectations

Our team consists of six computer science MSc students who are motivated to find a stable solution for the given task: Alexander Dümont, Arsenij Solovjev, Damla Durmaz, Ferhat Beyaz, Markus Rudolph, Sebastian Barthel. Our goal is to expand Sonar to cooperate with ModelBus. At the beginning of the course none of us had experience in working with neither Sonar nor Modelbus nor Metrino. So in fact our first expectation was to learn the usage of those software systems. We also had not much experience in the model driven software developement. Therefore it should be necessary to learn to work with models and to generate code from it (as later used with the SMM parser and other software components). Although we had no experience with those systems, their good programming interfaces are promising to work fluently together.

1.4 Model-Driven Engineering

With model-driven engineering we focus on domain models rather then on objects in the sense of object oriented programming. Those domain models are anbstract representations of the knowledge and activities that belong them). We can compare them with objects, but instead of describing them with sourcecode from programming languages like Java or C we simply use UML and generate the sourcecode from it.

With the usage of standardized models model-driven engineering wants to maximize the compatibility between systems and wants to increase the overall productivity. Models are developed in the communication process between the product owner, developers and other people (designers, etc).

As the model set approaches completion, developement process can be started.

1.5 Responsibilities and Progress

Table 1.1: Exercises pt. 1

Exercise	Begin	End	Progress	Done by
Explore	Mo 05.11.12	Fr 09.11.12	100%	Team
Modelbus				
Explore Sonar	Mo 05.11.12	Fr 09.11.12	100%	Team
Explore plugin	Mo 05.11.12	Fr 09.11.12	100%	Ferhat
developement				
possibilities				
Explore Sonar	Mo 05.11.12	Fr 09.11.12	100%	Damla
features and				
developement				
possibilities				
First attempt to	Mo 05.11.12	Fr 09.11.12	100%	Markus
plugin				
developement				
Wiki	Mo 05.11.12	Fr 09.11.12	100%	Sebastian
Introduction	3.5 0	D	1000	
Modelbus	Mo 05.11.12	Fr 09.11.12	100%	Arsenij
connection	N.F. OF 11 10	F 00 11 10	1000	3.6.1
Sonar	Mo 05.11.12	Fr 09.11.12	100%	Markus
documentation	M 05 11 10	D 00 11 10	10007	A 1 1
Wiki Metrino	Mo 05.11.12	Fr 09.11.12	100%	Alexander
Sonar plugin	Mo 05.11.12	Fr 09.11.12	100%	Ferhat
documentation	M 05 11 10	E 00 11 10	10007	T) 1
Modelbus	Mo 05.11.12	Fr 09.11.12	100%	Damla
documentation	M- 05 11 10	E. 00 11 19	10007	D 1 - 0 -
Requirements	$M0 \ 05.11.12$	Fr 09.11.12	100%	Damla &
Dungantation	Ma 05 11 10	E ₂ 00 11 19	10007	Ferhat
Presentation	Mo 05.11.12	Fr 09.11.12	100%	Ferhat
Requirements Improve	M_{\odot} 19 11 19	Er 16 11 19	10007	Damla
requirements	Mo 12.11.12	Fr 16.11.12	100%	Daima
requirements				

Table 1.2: Exercises pt. 2

Exercise	Begin	End	Progress	Done by
Architecture	Mo 12.11.12	Fr 16.11.12	100%	Ferhat
conecept for				
sonar				
Architecture	Mo 12.11.12	Fr 16.11.12	100%	Alexander
conecept for				
metrino				
Introduction to	Mo 12.11.12	Mo 19.11.12	100%	Sebastian
wiki				
Presentation	Mo 12.11.12	Fr 19.11.12	100%	Damla
Template			0.4	
Software	Mo 12.11.12	Fr 23.11.12	100%	Sebastian
architecture –				
sequencedia-				
gram/activitydiag		M 00 11 10	10007	
Setup Modelbus	Mo 19.11.12	Mo 26.11.12	100%	Arsenij
Repository				
Server	D: 90 11 19	Ma 96 11 19	10007	Λ::
Explore howto	Di 20.11.12	Mo 26.11.12	100%	Arsenij
running sonar				
on a repository Installation of	Do 23.11.12	Do 23.11.12	100%	Team
software	D0 23.11.12	D0 23.11.12	10070	ream
components				
Example Sonar	Mo 19.11.12	Fr 23.11.12	100%	Unknown
plugin	WIO 10.11.12	11 29.11.12	10070	Ommown
Multilanguage	Fr 23.11.12	Do 29.11.12	100%	Markus &
(different	11 2011112	20 20 11 11 2	20070	Damla &
programming				Ferhat
languages)				-
support in sonar				
plugins				
P1481110				

Table 1.3: Exercises pt. 3

Exercise	Begin	End	Progress	Done by
Sequence diagram for the	So 25.11.12	So 25.11.12	100%	Damla & Sebastian
work of sonar				
with Metrino				
and ModelBus	Fr 23.11.12	Mo 26.11.12	100%	Markus
Setup modelbus server	F1 23.11.12	WIO 20.11.12	10070	Markus
Presentation	Fr 23.11.12	Mo 26.11.12	100%	Ferhat
first architecture	11 20.11.12	1,10 20.11.12	10070	
Activity	Fr 23.11.12	Mo 26.11.12	100%	Damla
diagram				
modelbus				
repository				
SOAP Client	Fr 23.11.12	Do 06.12.12	100%	Alexander
Metrino	M- 00 11 10	D- 20 11 10	10007	Daula a 4
Wiki Logo and header	Mo 26.11.12	Fr 30.11.12	100%	Ferhat
OCL &	Mo 26.11.12	Fr 30.11.12	100%	Damla &
Documentation	1110 20:11:12	11 00.11.12	10070	Ferhat
Milestone	Mo 26.11.12	Fr 30.11.12	100%	Sebastian
definitions and				
description				
Installation	Mo 03.12.12	Mo 10.12.12	100%	Sebastian
manual			2.4	
Include other	Mo 03.12.12	Mo 10.12.12	100%	Arsenij
language				
plugins with				
modules				

Table 1.4: Exercises pt. 4

Exercise	Begin	End	Progress	Done by
Client without	Mo 03.12.12	Mo 10.12.12	100%	Markus
using WSDL by				
hand				
Objectoriented	Mo 03.12.12	Mo 10.12.12	100%	Ferhat
Analysis to				
Models				
Understand	Mo 10.12.12	Fr 21.12.12	100%	Sebastian
Metrino metrcis				&
, ,	3.5 40.40.40	T 01 10 10	1000	Alexander
ownload	Mo 10.12.12	Fr 21.12.12	100%	Markus
modelbus files in				
a sonar plugin	M- 17 10 10	D. 01 10 10	10007	Daulas 4
Create latex	Mo 17.12.12	Fr 21.12.12	100%	Ferhat
documentation Meeting	Mo 17.12.12	Fr 21.12.12	100%	Damla
Protocols to	WIO 17.12.12	ΓΙ 21.12.12	10070	Daima
latex				
documentation				
Metrino	Mo 07.01.13	Mo 21.01.13	100%	Arsenij
CheckModel,	1,10 01.01.10	1110 21.01.10	10070	Tirsonij
download and				
parse SMM				
from Repo				
Sonar frontend	Mo 07.01.13	Mo 21.01.13	100%	Sebastian
Parser for SMM	Mo 14.01.13	So 20.01.13	100%	Damla &
				Ferhat
Using of EMF	Mo 21.01.13	Mo 28.01.13	100%	Damla &
to parse SMM				Ferhat
files				

Table 1.5: Exercises pt. 5

Exercise	Begin	End	Progress	Done by
Include parser into project workflow	Mo 21.01.13	Mo 28.01.13	100%	Damla & Ferhat
Merge all components into	Mo 21.01.13	Mo 28.01.13	100%	Arsenij
Project spezific measurements	Mo 21.01.13	Mo 28.01.13	100%	Markus
in sonar ceate ocl metrics Color Measurements	Mo 21.01.13 Mo 21.01.13	So 03.02.13 Mo 28.01.13	100% $100%$	Alexander Sebastian
Documentation in Latex	Mo 28.01.13	Mo 18.02.13	25%	Team
SMM Adapter Load dynamic	Mo 28.01.13 Mo 28.01.13	Mo 18.02.13 Mo 18.02.13	67% $36%$	Arsenij Sebastian
metrics in sonar Meeting Protocols	Mo 03.12.12	Mo 18.02.13	95%	Damla & Ferhat

1.6 Paper Purposes

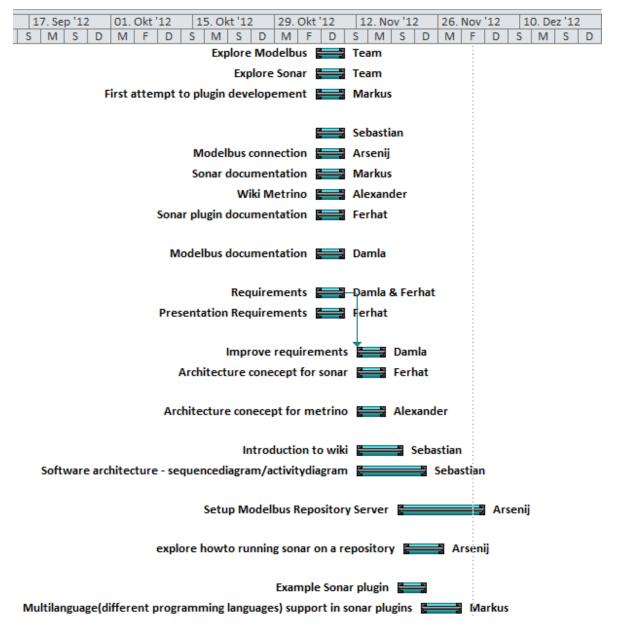


Figure 1.1: Exercises - MS Project screenshot 1

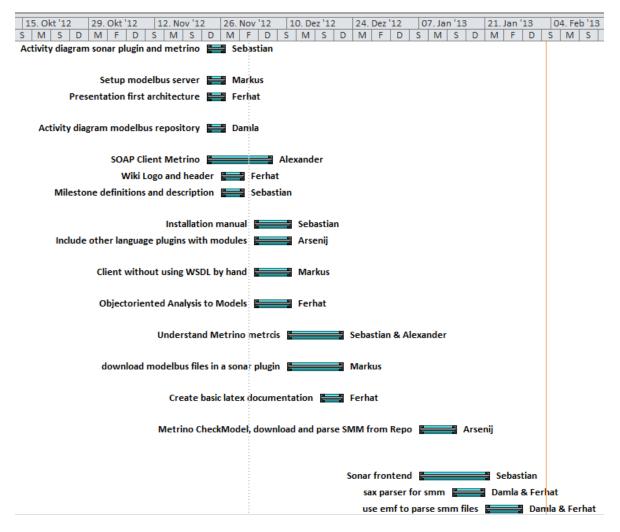


Figure 1.2: Exercises - MS Project screenshot 2

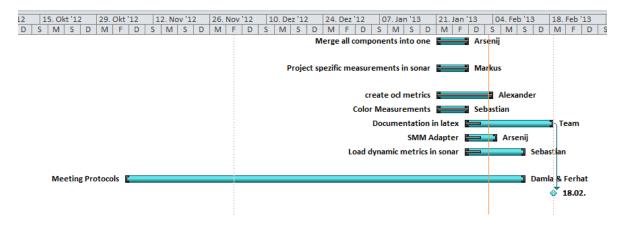


Figure 1.3: Exercises - MS Project screenshot 3

Chapter 2

Installation and Usage

2.1 Software Requirements

For development following software components are needed:

- Java (JDK) 1.6 or 1.7
- Maven
- Eclipse (Juno)
- Maven Plugin for Eclipse
- Git or Egit for Eclipse
- Modelbus Team Provider for Eclipse
- Modelbus 1.9.7
- Metrino for Modelbus with following plugins
 - Metrino rule evaluator plugin
 - Metrino measure plugin

Sonar will be downloaded and deployed via Maven at compile time.

2.2 Installation Manual

In the following sections we explain every detail. Just skip a section if you think you still have done that what the regarding section focuses.

Java

We tested the software with Java 1.6 and 1.7. You can get those from here. Select and download the current JDK to install it on your system. If Java is ready, make sure that the following system variables exist:

```
JAVA_HOME = C:\Program Files\Java\jdk1.7.0_09
(change the path to your JDK install path)
```

Also you must add your JAVA_HOME variable (add \bin\) to your path variable.

```
PATH = . . . ; %JAVA_HOME%\bin\;
```

Maven

Download the current Maven from here and follow the instructions from the README: Extract it somewhere and create following path variables:

```
M2_HOME = C:\Program Files\apache-maven-3.0.4 (change the path to your maven folder)
M2 = %M2_HOME%\bin\
PATH =...;%M2%;
```

Eclipse

Download Eclipse from here. We recommend a current Eclipse version. We use Eclipse Juno (4.2) for Java developer. Remember to select the correct version for your operating system.

Maven Plugin for Eclipse

Open Eclipse and open "Help — Install New Software...". Now select or add the repository of your eclipse version. In our example we will use

```
http://download.eclipse.org/releases/juno
```

Select "m2e-Maven Integration for Eclipse" and click through the progress to install the plugin. If everything works well, Eclipse will ask you for an Eclipse restart.

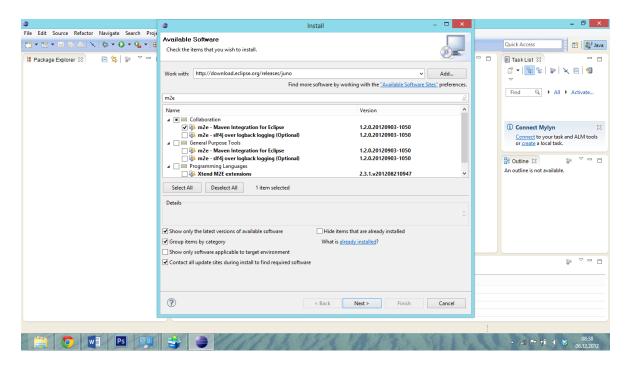


Figure 2.1: Maven Eclipse plugin installation

Git or Egit for Eclipse

If you have installed Juno, Egit is already integrated. If not so, you can download Egit from here. Or you get and install Git from here.

Modelbus Team Provider for Eclipse

The update site for the Modelbus Team Provider is here. Select only the Modelbus Team Provider for the installation.

Modelbus and Metrino

Request the Modelbus developers for a version of Modelbus with an integrated Metrino service. Make sure that the following Jars lie in the plugin folder of Modelbus:

- de.fraunhofer.fokus.metrino.ruleEvaluator
- de.fraunhofer.fokus.metrino.measure

Extract Modelbus to any location in your file system. Now you have to setup the configuration file of Modelbus. Open the "modelbus.config" in the "serverConfiguration" folder of your modelbus installation. Set the "repositoryLocation" to "http://localhost:8080/modelbusrepository" and the "svnRepositoryLocation" to "repository":

Then you will have to set some environment variables. Set

- MODELBUS_ROOT to the folder of your Modelbus installation
- MODELBUS_NOTIFICATION_LOCATION to "tcp://localhost:61616" like in the config file
- MODELBUS_REPOSITORY_LOCATION to "http://localhost:8080/modelbusrepository" like in the config file

2.3 Usage Manual

The typical workflow for plugin development is:

- 1. start Modelbus
- 2. open the plugin project with Eclipse
- 3. make some changes to the code
- 4. build the project with the Maven goal "install"

- 5. deploy Sonar including out plugin via Maven
- 6. analyse the project with the goal "sonar:sonar" to test the plugin on your installed Modelbus repository

The typical workflow for an user of our plugin is:

- 1. start ModelBus
- 2. start Sonar with our plugin via Maven
- 3. check in models into the Modelbus repository
- 4. analyse a Maven project with the goal "sonar:sonar" (this will also analyse your installed Modelbus repository)

The single steps are described below in detail.

Download the source of our Sonar-Modelbus-Plugin

Download the following copy of our repository:

https://github.com/arsenij-solovjev/sonar-modelbus-plugin/archive/master.zip

Extract the archive and if you like copy the folder sonar-modelbusplugin-master into a special folder. It is just important that you don't copy this folder in your Eclipse workspace.

Start Modelbus

Under Windows start the "startModelBusServer.exe" of your Modelbus installation.

Under Linux run the "startup.sh" as root user. Make sure that the "startup.sh" and the "bin/service" files are executable.

If Modelbus is up, you can visit the Modelbus manager under http://localhost:8080/modelbus?startup=manager: You can login with the username "Admin" and the password "ModelBus". Here you can see all the checked in files and models. When uploading a new file, press the refresh button to see the changes.

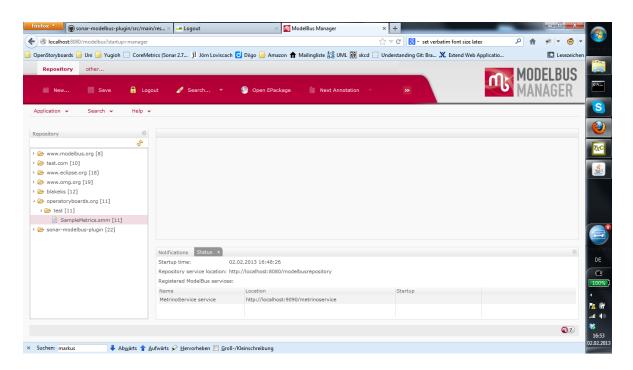


Figure 2.2: The Modelbus manager

Uploading models

We created a tool for checking in and out files from/to the ModelBus repository. It can be simply called via "make". First compile the tool: Go to the "modelbusclient/sonar-modelbus-client" folder and run:

make install

This will compile and package the tool. Next, checkin some models to the Modelbus repository using:

make checkin

URI=http://uri.de/location/in/repository/file.txt
FILENAME=location/to/local/file.txt

You can find some example models in the "/src/main/resources/metrinostuff" folder of our plugin.

Create a new Eclipse project

Now create a new Eclipse project:

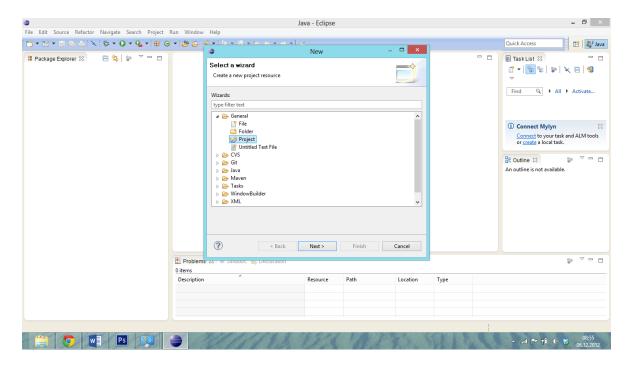


Figure 2.3: Creating a new Eclispe project

Unselect the "Use default location" box and select the sonar-modelbusplugin-master folder. Don't forget to set a project name.

Notice: If you finish the project creation process you may get "Git could not detect where GIT is installed" or "check HOME directory" warning but it doesn't matter in this case.

Convert your project to a Maven project

Right click on your project folder and choose "Configure — Convert to Maven Project".

Notice: If you get any errors (this is not unusual) just ignore them. If you can't do the next step just repeat the previous one.

Compilation

Next: right click on your project again and select "Run as — Maven install". If everything works well you see a "BUILD SUCCESS" reports like this:

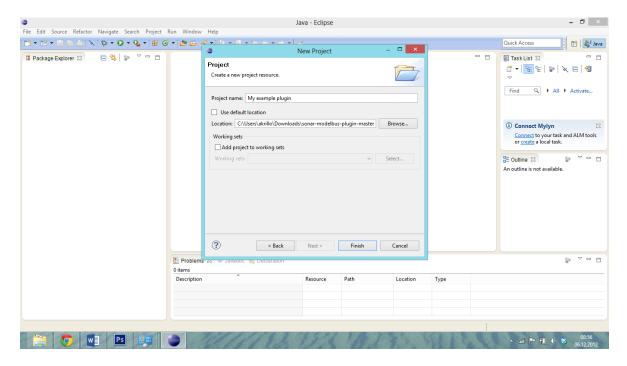


Figure 2.4: Selecting a location

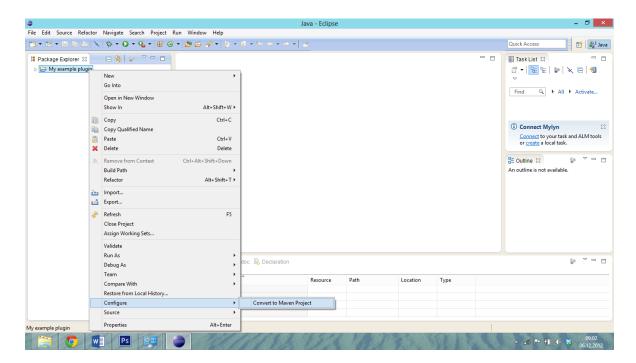


Figure 2.5: Converting to a Maven project

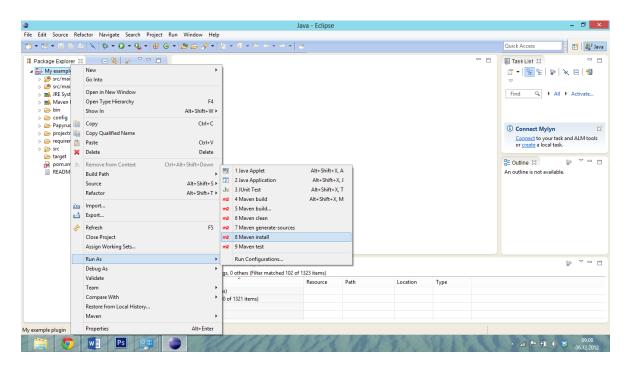


Figure 2.6: Maven install

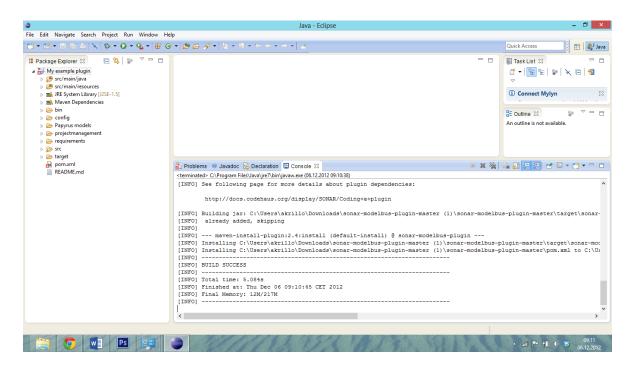


Figure 2.7: BUILD SUCCESS

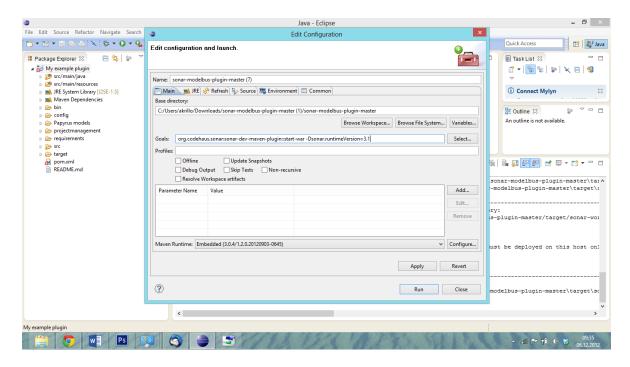


Figure 2.8: Deploying Sonar with Maven

Deploy the Sonar server

To run Sonar with our example plugin we need to run maven with an other goal. Right click on your Project and select "Run as — Maven Build". In "Goals" you must copy-paste

```
org.codehaus.sonar:sonar-dev-maven-plugin::start-war-Dsonar.runtimeVersion=3.3
```

Then press "Run" to start the build process that will deploy a Sonar server for you.

Notice: this can take some minutes and if it seems to be frozen just restart the build process. If some errors occur just restart. If everything went fine you will see following status messages:

Now you can see Sonar running at "localhost:9000" in your browser.

Analysing with Sonar

If you like to analyse your project with Sonar (or any other Maven project) you can start the build process with the goal "sonar:sonar".

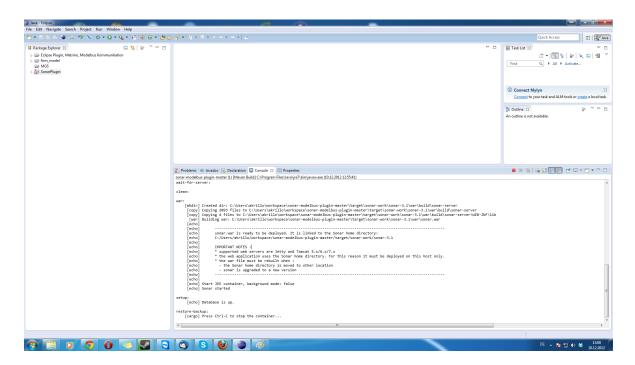


Figure 2.9: Sonar is ready





Figure 2.10: Sonar in the browser

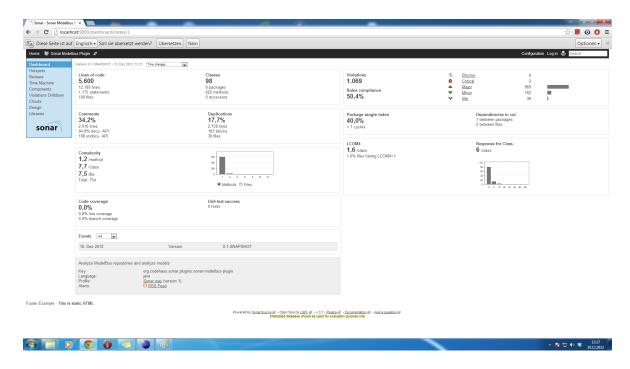


Figure 2.11: Sonar in action

After processing you can refresh your browser at "localhost:9000" and can see the results of the analysis.

Chapter 3

Sonar Modelbus Plugin

3.1 Modelbus

Scenario

Imagine, you are in a software development process. You and your team partners use different development tools and a lot of artefacts are produced by different team members. In such a case, the artefacts may be inconsitent and a developer needs to make updates and changes by hand to keep them consistent. A tool which would automate this process and do more, is ModelBus.

What is ModelBus?

It is a model-driven open source framework for the integration of development tools during a MDE process. It keeps the artefacts of the development process consistent. It offers a communication between tools with the help of adapters: the tools are connected to the bus via adapters and can offer their services to other tools connected to the bus.

Goals

- Data Integration: Tools can share (data) models
- Control Integration: Tools connected to the bus can use the service of other
- connected tools

- Process Integration: Several tools are used together in the development and are highly supported
- Support: Support of distributed MDE development
- Architecture: Based on SOA
- Architecture
- based on SOA
- central bus-like communication structure number of core services
- a copule of model management tools
- different tools can be added to the bus via adapters
- if a tool is connected, it is handled as a service for other tools orchestration: a lot of tools (with their service) and automation are connected
- together to a complex system

Features

Automation of development tasks

- define tasks as modeling services
- orchestrate defined tasks with other modelling services
- orchestrations can be run automatically (by user or other orchestrations)

33

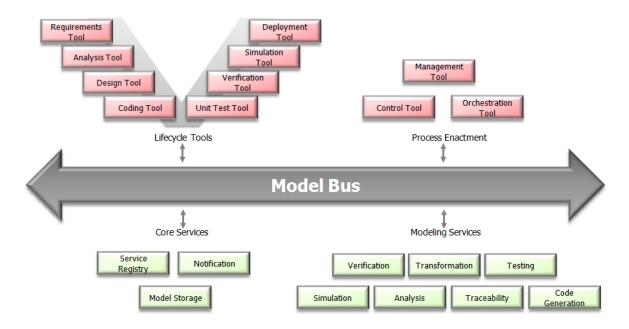


Figure 3.1: Modelbus tools and services

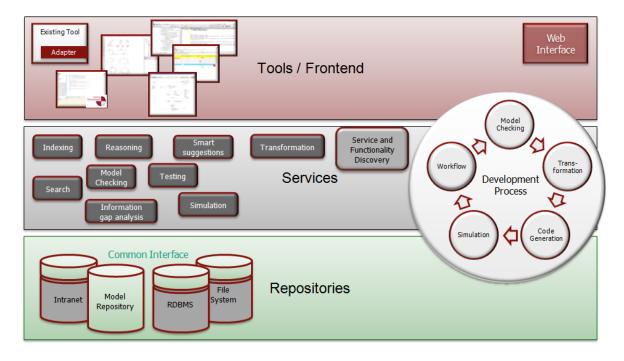


Figure 3.2: Developement process and layers

Inbuilt and transparent model management

- problem: development produces artefacts and developer don't want to care about where they came from and how they have to be imported
- artefacts are acceessed to the rigth model by each connected tool on the ModelBus bus

Support of large and complex models

- models often have complex structure
- model A imports parts if model B and B references package C and ...
- thus, a lof ot developers work on the models concurrently
- solution: versioning of (complex) models and model fragments in the model repository
- core service notification: notification system, which informs about changes to a model

Distributed and heterogeneous

- normally, if a tool is updated, different artefacts may be non-compatible together
- this may happen frequently in larger development teams
- but this would be crucial, espepcially for model operations tools (for example tools, which transform models)
- solution: via the adapters, models from the tools are translated into a ModelBus known format
- distribution of models is therefore realized
- data models stay consistent, even when tools are updated

3.2. METRINO 35

Built on industry standards

• Transportation: HTTP, HTTPS, XMPP, CXF, JMS, SOAP

• Core services: Distributed OSGi, SVN, EMF

• ...

Adapters for tools

- Doors
- Eclipse Papyrus
- Enterprise Architect
- Eclipse TeamProvider
- Office
- Rational Software Architect
- Rhapsody
- Simulink

3.2 Metrino

Short facts

- Validating models by information quantity and quality
- Uses OCL (Object Constraint Language) and SMM (Software Metrics Metamodel)
- Can be used as stand-alone tool or as ModelBus add-on with additional service features
- Works as a set of support tools in four conceptual phases

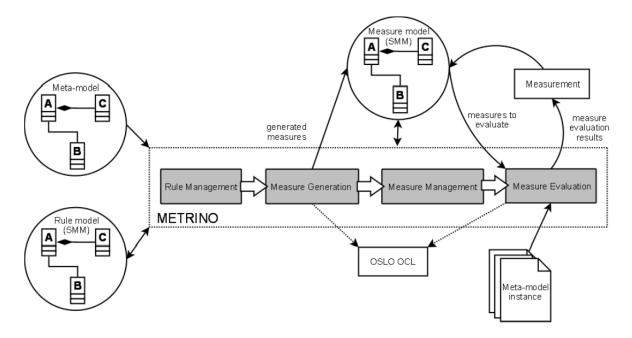


Figure 3.3: Developement process and layers

- Check of these selectable guidelines result in validation, warnings and/or errors
- Handles UML models, any Domain Specific Modeling Language (DSL) based on MOF
- Manage and compute generated or user-defined, domain specific measures
- Already includes a set of metrics in the current version
- Supports customizable report generation to different formats
- Supports visualization of computational results, e.g. graphs
- Installation by Eclipse update-site through ModelBus website: http://www.model

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Four phases

More

• Slides of the presentation given at the OCL Workshop in Denver: Generation of Formal Model Metrics for MOF based Domain Specific Models (Marcus Engelhardt, Christian Hein, Tom Ritter, Michael Wagner)

 Christian Hein, Marcus Engelhardt, Tom Ritter and Michael Wagner: Generation of Formal Model Metrics for MOF based Domain Specific Languages, OCL 2009 Workshop at ACM/IEEE Models 09 Conference, USA, September 5th 2009

Screencasts

Worth seeing, brief presentations about usability and features of Metrino:

- Short screencast showing the usage of Metrino for UML Models -The screen cast shows the evaluation of "hand coded" measures on a UML Model representing the results as tables and KIVIAT graphs
- Screencast of a Metrino Validation The screen cast shows the generation and evaluation measures on for a DSL based model and the integration into validation framework.

Problems

The installation of the current version of Metrino is not possible due to malformed dependencies. Unfortunately a recursively installing of the required dependencies does not help, since they need other dependencies by themselves, resulting in an infeasible search-and-install marathon. Screenshot

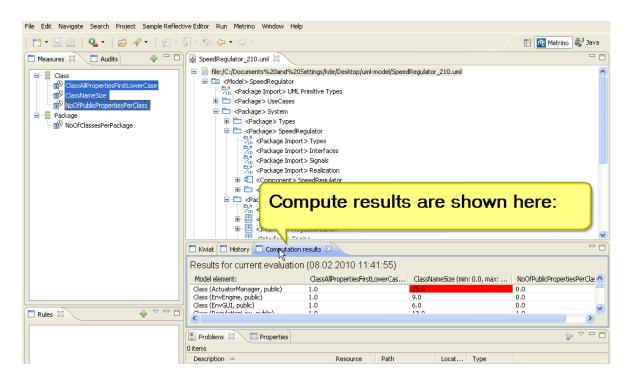


Figure 3.4: Development process and layers

Screenshots

These are only a subset of interesting screenshots taken from the screencasts above:

```
(generic validation by selected measures)
(graphical representation of a selected measurement)
(rules, measures, problems and validation)
```

Declaration of OCL rules

With the models, we got from the Modelbus service we can start an analysis. Therefore we want to use Metrino, which expects OCL (Object Constraint Language) as a description of the requests. OCL generally spoken is a declarative language for describing rules which apply on UML-Models.

In OCL there are 7 constraints to distinguish: 1. Invariants have to apply on either an instance or an association. 2. Pre- and postconditions have to apply every time, when the according operation begins or ends.

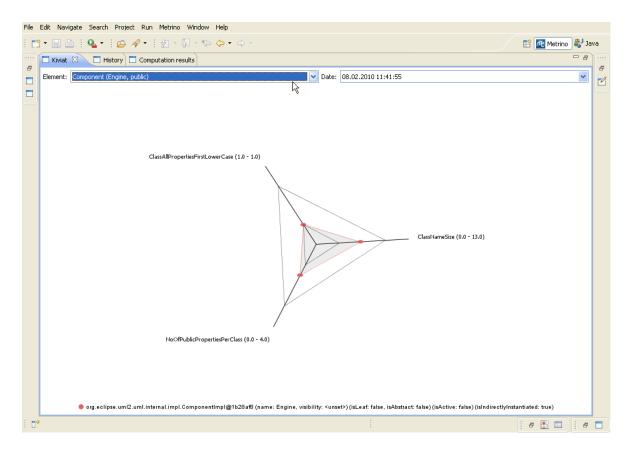


Figure 3.5: Developement process and layers

- 3. Initial and derived values are the constraints for other derived values.
- 4. You can define new attributes and operations, that are not defined in the model. 5. If there is a state transition, guards have to apply.

With this set of rules, we can define metrics on the models.

OCL

3.3 Sonar

Sonar is an open platform to manage code quality. It offers reports on duplicated code, coding standards, unit tests, code coverage, complex code, potential bugs, comments and design and architecture.

Sonar consists of 3 components:

• A database that stores the configuration and results of quality anal-

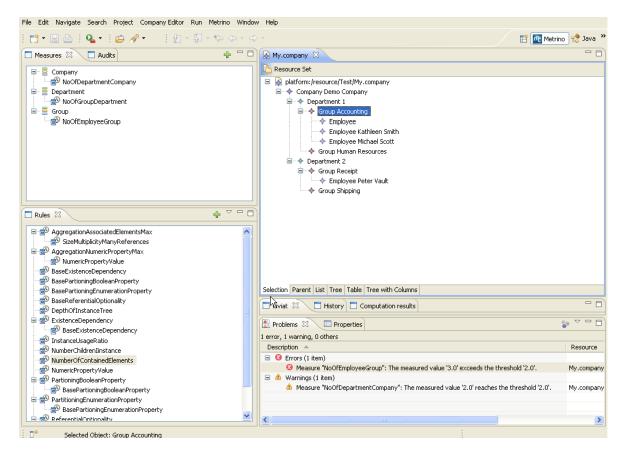


Figure 3.6: Developement process and layers

ysis

- A web server that is used to navigate the results of the analyzes and make configuration
- A client that will run source code analyzers to compute data on projects Covering new languages, adding rules engines, computing advanced metrics can be done through a powerful extension mechanism. More than 50 plugins are already available.

Primary supported language is Java. Other languages are supported with extensions. Several open source and commercial extensions can cover the following languages: C, C#, PHP, Flex, Groovy, JavaScript, Python, PL/SQL, COBOL and Visual Basic 6.

It integrates with Maven, Ant and continuous integration tools (Atlassian Bamboo, Jenkins, Hudson).

3.4 Developing Sonar Plugins

Building and Packaging

To create a plugin for Sonar, at least Java 5 is needed. Maven is also required to compile and package the plugin. The documentation of Sonar says, that a recommanded way is to duplicate one of the example plugins, which can be found in the /plugins directory of the github repository: https://github.com/SonarSource/sonar-examples

It is recommanded to use /plugins/sonar-reference-plugin. The example plugin can be copied by cloning the repository. Github provides the possibility to download the repository directly.

The plugin can be built and deployed by executing in the plugin root directory, so for example /path/to/sonar-reference-plugin:

mvn clean install

Thereafter a JAR file is generated in the /target directory. After copying this JAR to the /extensions/plugin directory of Sonar, the server has to be restarded. There you go, you packaged your own Sonar plugin.

Creating an own plugin

A Sonar plugin is a set of Java objects, which implement extension points, which are interfaces or abstract classes to model an aspect of the system and define contracts of what needs to be implemented. Such extensions could be pages in the web application or sensors generating measures.

This plugin extensions must be declared in a Java class, that extends org.sonar.api.Plugin. This class must then be declared in the pom with the property:

<artifactId>sonar-foo-plugin</artifactId>
<packaging>sonar-plugin</packaging>

There are also more advanced parameters like Maven descriptors, etc. possible. The full list of advanced parameters can be found here.

There is a list of all known sub-interfaces and implementing classes of org.sonar.api.Extension. The most important and well known extension points are listed here.

Sensors and Decorators

Two extension enable methods to save measures: sensors and decorators. In plugin development it is often a problem to decide which one to use.

Sensor

A sensor is invoked once during the analysis of the project. The sensor then can invoke a maven plugin, parse flat files or connect to web servers. The generated XML file is parsed and used to save the first-level of measures on resources (project, package or class). The sensor can access and save measures on the whole tree of resources. They generally are used to add measures at the lowest level of the resource tree.

Decorator

Decorators are used when all sensors have completed their work. The decorate method is called on every resource of a certain level bottom up. Decorators load (SELECT) and save (INSERT) measures. Because of contextual calls it is only possible to access the resource and its children. So decorators are generally used to consolidate measured at higher levels that have been added by sensors at lower levels.

Modify the front-end of Sonar and working with sensors and decorators

Our plugin front-end consists of the following structure:

Package edu.swp.modelbus.reference

ModelbusMetrics.java

Our class ModelsbusMetrics implements the Metrics Interface of Sonar. In this file we define all Metrics that we'll create in other files. The obligatory metric definitions consist of the name, key and the return type. Optionally you can add more parameters with the description, direction, setQualitativ, and setDomain methods. At least we have to define the method getMetrics() because of the interface Metrics. In this method we add all metrics to an array list and set this as return value of the getMetrics() method.

ModelbusPlugin.java

This file is the main entry point for Sonar. With annotations we can define some Plugin meta data like the description and the name. The class ModelbusPlugin extends the class SonarPlugin and has the method getExtensions(). We add in this method all Sonar extensions that we want to use like definition classes. batch classes or ui classes.

 $Package\ edu.swp.modelbus.batch$

ExampleSensor.java

We created an exampleSensor to demonstrate how it must be defined. In this file it's possible to do all things you like to do. An example would be to connect to a server. In our case we don't need a sensor.

RandomDecorator.java

Our first decorator is a real random decorator. It will give a random value to all files.

Package edu.swp.modelbus.ui

ExampleFooter.java

It's possible to change the layout with plugins. This file implements the interface Footer. We just add the method getHtml() and return an example text to change the front-end layout of sonar.

ExampleRubyWidget.java

We can also add Widgets. The administrator can add widgets to the users layout. If our sensors get some values, the can be written from our widget and presented with plain text or with visual objects.

3.5 Software Architecture

The main architecture is described as the following. Our main soft-ware product is called the Sonar ModelBus Plugin which of course is a Sonar Plugin. This plugin, the project is dedicated to, implements a Metrino Adapter as well as a ModelBus Adapter. These sub programs are intended to communicate with the WebServices from Metrino and ModelBus.

(These diagrams are currently in work and not considered final.)

Simple Architecture / Package Diagram

Ecore-Diagramm

3.6 Metrics Input File SMM

SMM distinguishes between measures as the evaluation process of particular quality aspects of software artifacts and measurements which can be interpreted as the results of those processes. SMM specifies several types of measures and measurements for different outcome values:

- Dimensional Measure
- DirectMeasure

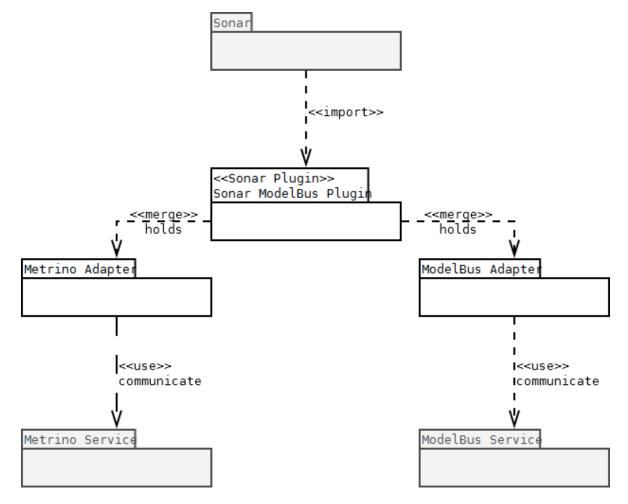


Figure 3.7: Sonar plugin package diagram

- BinaryMeasure
- CollectiveMeasure

The measures are calculated in a given scope, which has to be specified with scope="x", where x is the id of a scope element, specified with xsi:type="SoftwareMetricsMetamodel2:Scope". Every measure also is part of a category, therefore it has to define its category with category="x", where x is the id of a category element, specified with xsi:type="SoftwareMetrics". This way measures can be categorized, so that one can measure different metrics in the same SMM file. Every category has an attribute measureElement, which simply holds the ids of the measures in the category. The results of the measures are saved in a measurement with

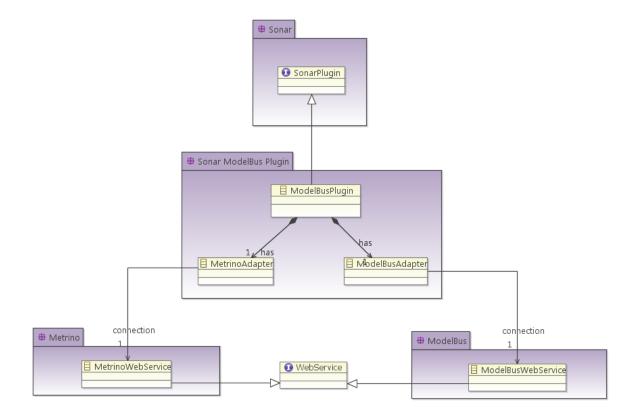


Figure 3.8: Sonar plugin ecore diagram

xsi:type="SoftwareMetricsMetamodel2:DirectMeasurement". The id of this element has to be saved in the measurement attribut in the measure.

For more information, see Software Metrics Metamodel (SMM) on Wikipedia.

The following code is an examplary SMM file:

```
<sMMElement xsi:type="SoftwareMetricsMetamodel2:Observation" xmi:id=</pre>
        <whenObserved xmi:id="_Ckmb0kg8EeKe9JB-jPya7w" value="1355743348</pre>
    </sMMElement>
    <sMMElement xsi:type="SoftwareMetricsMetamodel2:DirectMeasurement" ;</pre>
        <measurand href="model/MetrinoSampleModel.uml#_QYmMoEg7EeKe9JB-;</pre>
    </sMMElement>
    <sMMElement xsi:type="SoftwareMetricsMetamodel2:Observation" xmi:id=</pre>
        <whenObserved xmi:id="_Cksickg8EeKe9JB-jPya7w" value="1355743348</pre>
    </sMMElement>
    <sMMElement xsi:type="SoftwareMetricsMetamodel2:DirectMeasurement" ;</pre>
        <measurand href="model/MetrinoSampleModel.uml#_QYmMoEg7EeKe9JB-</pre>
    </sMMElement>
    <sMMElement xsi:type="SoftwareMetricsMetamodel2:Observation" xmi:id=</pre>
        <whenObserved xmi:id="_NDgqskg8EeKe9JB-jPya7w" value="1355743418</pre>
    </sMMElement>
    <sMMElement xsi:type="SoftwareMetricsMetamodel2:DirectMeasurement" ;</pre>
        <measurand href="model/MetrinoSampleModel.uml#_QYmMoEg7EeKe9JB-;</pre>
    </sMMElement>
    <sMMElement xsi:type="SoftwareMetricsMetamodel2:Observation" xmi:id=</pre>
        <whenObserved xmi:id="_NDmxUkg8EeKe9JB-jPya7w" value="1355743418</pre>
    </sMMElement>
</SoftwareMetricsMetamodel2:SMMModel>
```

3.7 ModelBus Client Tool

We created a tool for checking in and out files from/to the ModelBus repository. It can be simply called via "make":

Use

make checkin URI=http://uri.de/location/in/repository/file.txt FILENAM to checkin a file located at FILENAME into the repository at a position

Use

make checkout URI=http://uri.de/location/in/repository/file.txt FILENA

to checkout a file from the repository located at URI to a local position defined by the FILENAME. Changes can be made at the Client.java file. You can compile it by calling "make install". This will compile and assemble the client with its ModelBus dependencies.

3.8 ClassLoader Problem

The problem was that we could not connect to the ModelBus repository through the sonar plugin. Using the same code in a standalone Java application instead worked fine: The ModelBus repository was successfully checked out.

The reason was that the ModelBus part could not resolve some bindings in its configuration. That was caused by the missing of a resource. This resource lied in the META-INF folder of the "org.modelbus.cxf.dosgi" jar bundle. The loading of this resource was done over the current context class loader in a ModelBus class:

```
ClassLoader cl = Thread.currentThread().getContextClassLoader();
Enumeration<URL> urls = cl.getResources("META-INF/cxf/bus/bus-extensions//loading each url...
```

The problem is that the context classloader of the current thread is not the plugin classloader.

Each Sonar plugin runs in an isolated classloader to avoid conflicts with other plugins. Third-party libraries can be loaded by using a mechanism specific to Sonar. It only requires to build the plugin with the sonar-packaging-maven-plugin, which copies the libs into META-INF/lib. This mechanism relies on its own classloader implementation.

By temporarly replacing the context class loader with the plugin class loader (the class loader of the extension), this issue can be solved:

```
ClassLoader initialClassLoader = Thread.currentThread().getContextClassI
try {
   Thread.currentThread().setContextClassLoader(getClass().getClassLoader
   //access ModelBus...
} finally {
```

```
Thread.currentThread().setContextClassLoader(initialClassLoader);
}
```

Chapter 4

Conclusion

4.1 Review

Eigene Meinung. Was kann man besser machen im Kurs?

4.2 Closing Words

Dankeschön an alle Betreuer, wir haben viel gelernt.

Exercise	Begin	End	Progress	Done by
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Include parser into project workflow	Mo 21.01.13	Mo 28.01.13	100%	Damla & Ferhat
Merge all components into one	Mo 21.01.13	Mo 28.01.13	100%	Arsenij
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Latex SMM Adapter	Mo 28.01.13	Mo 18.02.13	67%	Arsenij
Load dynamic metrics in sonar	Mo 28.01.13	Mo 18.02.13	36%	Sebastian
Meeting Protocols	Mo 03.12.12	Mo 18.02.13	95%	Damla & Ferhat

test

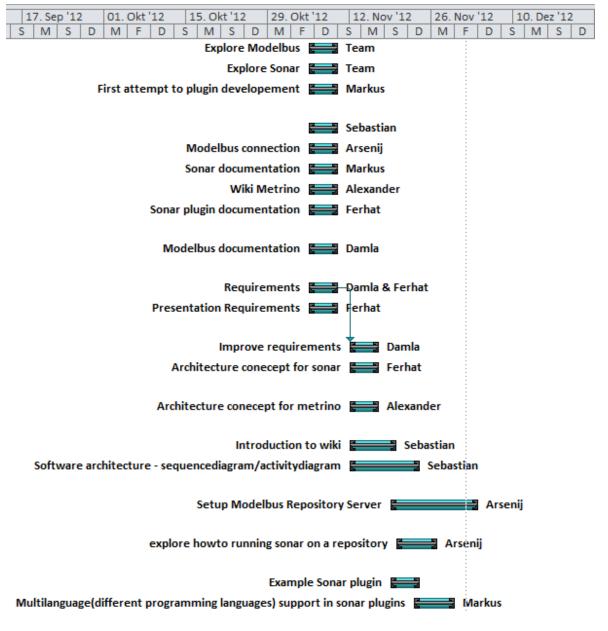


Figure 4.1: Exercises - MS Project screenshot 1

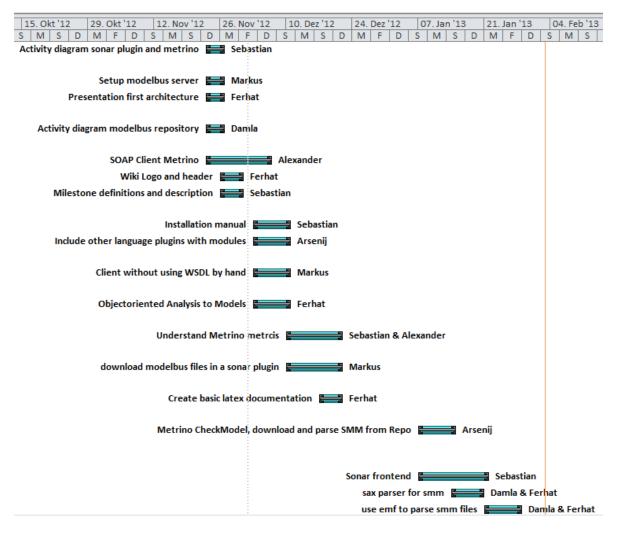


Figure 4.2: Exercises - MS Project screenshot 2

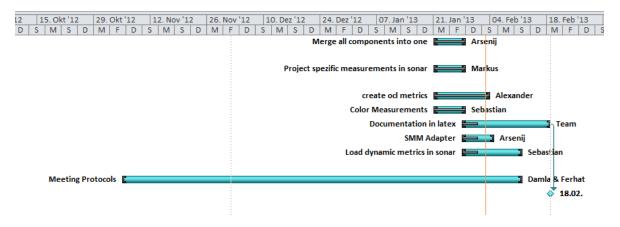


Figure 4.3: Exercises - MS Project screenshot 3