

# MiniASM Specification

Version: 0.0.1

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# 1 Purpose

This document serves as a specification for a hypothetical instruction set, designed specifically for teaching low-level programming concepts.

## 2 Architecture

We assume a big-endian Von Neumann architecture wherein instructions are stored contiguously in memory starting at address 128. The word size of this hypothetical architecture is 16 bits. There are 32 1-word registers –  $R_0, R_1, \dots, R_{31}$  – of which the first 25 are general-purpose. Additionally, there is exactly 1024 bytes of contiguous, byte-addressable memory, starting from address zero (which will henceforth be referred to as “Mem” and treated as a 0-based array of bytes).

There is also an output device for displaying textual output (to which data written to the *output stream* is sent), in addition to an input device for reading textual input (from which data read from the *input stream* comes).

Finally, single instructions are always represented with single words. There are several different instruction formats, each pertaining to a specific instruction type.

### 2.1 Instruction Types

#### 2.1.1 Two-Register (R2) Type

6 bits	5 bits	5 bits
Opcode	$R_D$	$R_S$

An example R2-type instruction is `add R2 R3`, which adds the contents of  $R_2$  and  $R_3$ , then stores the result back into  $R_2$ . Another example is `mov R5 R4`, which copies the contents of  $R_4$  into  $R_5$ .

#### 2.1.2 One-Register (R1) Type

6 bits	5 bits	5 bits
Opcode	$R_D$	?

An example R1-type instruction is `not R6`, which performs a bitwise-NOT operation on the contents of  $R_6$ , then puts the result back into  $R_6$ .

#### 2.1.3 Zero-Register (R0) Type

6 bits	10 bits
Opcode	?

An example R0-type instruction is `halt`, which terminates program execution.

### 2.1.4 Immediate (I) Type

6 bits	5 bits	5 bits
Opcode	$R_D$	$I$

An example I-type instruction is `movi R7 42`, which places the decimal value 42 into  $R_7$ .

### 2.1.5 Jump (J) Type

6 bits	10 bits
Opcode	$J$

An example J-type instruction is `jmp -4`, which jumps backwards 3 instructions relative to the current instruction.

## 2.2 Special-Purpose Registers

Registers  $R_{26}, R_{37}, \dots, R_{32}$  are specific-purpose registers.

Register	Alt. Name	Purpose
$R_{26}$	$R_{PC}$	Program counter
$R_{27}$	$R_{SP}$	Stack pointer
$R_{28}$	$R_S$	Status register
$R_{29}$	-	Currently unused
$R_{30}$	-	Currently unused
$R_{31}$	-	Currently unused

It is important to note that although  $R_{29}$ ,  $R_{30}$  and  $R_{31}$  are currently unused, they could be assigned a meaning in future updates to this specification. Hence, programs still should not use these registers as general-purpose registers.

### 2.2.1 Program Counter

$R_{26}$  stores the program counter, which always points to the *next* instruction to be executed. The program counter is always incremented when an instruction is fetched. Jump instructions modify this register.

### 2.2.2 Stack Pointer

The stack grows downwards from the highest addressable memory location.  $R_{27}$  stores the stack pointer, which always points to the element after the top of the stack. “Element” in this context means “word”, because the stack uses words as its fundamental unit of transaction.

### 2.2.3 Status Register

$R_{28}$  is the status register, which has the following layout:

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
$U$	$U$	$U$	$U$	$U$	$U$	$U$	$U$	$U$	$U$	$U$	$U$	$U$	$U$	$S$	$Z$

where

- $Z$  is the *zero bit*, which is 1 if and only if the result of the last arithmetic instruction was zero.
- $S$  is the *sign bit*, which is 1 if and only if the result of the last arithmetic instruction was negative.
- $U$  indicates that the specified bit is currently unused.

## 3 Instruction Listing

Instruction	Opcode	Type	Effect
halt	000000	R0	Terminate program
break	111111	R0	Breakpoint
not	000001	R1	$R_D \leftarrow \sim R_D$
push	000010	R1	$\text{Mem}[R_{SP}] \leftarrow \text{Hi}(R_D),$ $\text{Mem}[R_{SP} + 1] \leftarrow \text{Lo}(R_D),$ $R_{SP} \leftarrow R_{SP} - 2$
pop	000011	R1	$R_{SP} \leftarrow R_{SP} + 2,$ $\text{Hi}(R_D) \leftarrow \text{Mem}[R_{SP}]$ $\text{Lo}(R_D) \leftarrow \text{Mem}[R_{SP} + 1]$
print	000100	R1	See below
read	000101	R1	See below
sl	000110	R2	$R_D \leftarrow R_D \ll R_S$
sru	000111	R2	$R_D \leftarrow R_D \gg R_S$
srs	001000	R2	$R_D \leftarrow R_D \ggg R_S$
mov	001001	R2	$R_D \leftarrow R_S$
add	001010	R2	$R_D \leftarrow R_D + R_S$
sub	001011	R2	$R_D \leftarrow R_D - R_S$
and	001100	R2	$R_D \leftarrow R_D \& R_S$
or	001101	R2	$R_D \leftarrow R_D \mid R_S$
xor	001110	R2	$R_D \leftarrow R_D \wedge R_S$
cmp	001111	R2	$Z \leftarrow R_D \stackrel{?}{=} R_S,$ $S \leftarrow R_D \stackrel{?}{<} R_S$
sw	010000	R2	$\text{Mem}[R_D] \leftarrow \text{Hi}(R_S)$

			$\text{Mem}[R_D + 1] \leftarrow \text{Lo}(R_S)$
lw	010001	R2	$\text{Hi}(R_D) \leftarrow \text{Mem}[R_S]$
			$\text{Lo}(R_D) \leftarrow \text{Mem}[R_S + 1]$
sb	010010	R2	$\text{Mem}[R_D] \leftarrow \text{Lo}(R_S)$
lb	010011	R2	$R_D \leftarrow \text{Mem}[R_S]$
movi	010100	I	$R_D \leftarrow I$
addi	010101	I	$R_D \leftarrow R_D + I$
subi	010110	I	$R_D \leftarrow R_D - I$
andi	010111	I	$R_D \leftarrow R_D \& I$
ori	011000	I	$R_D \leftarrow R_D   I$
xori	011001	I	$R_D \leftarrow R_D \wedge I$
jmp	011010	J	$R_{PC} \leftarrow R_{PC} + J$
jmpeq	011011	J	if $Z = 1$ then: $R_{PC} \leftarrow R_{PC} + J$
jmpne	011100	J	if $Z = 0$ then: $R_{PC} \leftarrow R_{PC} + J$
jmpgt	011101	J	if $S = 1$ and $Z = 0$ then: $R_{PC} \leftarrow R_{PC} + J$
jmplt	011110	J	if $S = 1$ then: $R_{PC} \leftarrow R_{PC} + J$
jmpge	011111	J	if $S = 0$ then: $R_{PC} \leftarrow R_{PC} + J$
jmple	100000	J	if $S = 1$ or $Z = 0$ then: $R_{PC} \leftarrow R_{PC} + J$

The **print** instruction prints the ASCII character located at  $\text{Mem}[R_d]$ .

The **read** instruction performs a non-blocking 1-byte read from the input stream and places the result into  $\text{Mem}[R_d]$ . If there is nothing to be read, a 0-byte is placed in  $\text{Mem}[R_d]$ .

Note that overflow in addition or subtraction is defined behavior, and simply results in a wrap-around.

## 4 Program Execution

After the program code is loaded at memory address 128, program execution commences as follows:

1.  $R_{PC} \leftarrow 128$
2. Fetch instruction  $I = \text{Mem}[R_{PC}]$ .
3.  $R_{PC} \leftarrow R_{PC} + 2$

4. Execute *I*.
5. Return to step 2, unless program terminated from execution of `halt` or from error.

## 4.1 Program Termination

Program termination is always accompanied by a *status*, which is either “success” or “failure”. A “success” status is obtained upon the execution of a `halt` instruction, and a “failure” status is obtained when an error condition is encountered.

## 4.2 Error Conditions

Encountering an error condition results in immediate program termination with a “failure” status. The following error conditions exist:

- Attempting to execute an unknown opcode.
- Attempting to access a nonexistent memory location. This includes jumping to a nonexistent address.
- Attempting to execute a `sw` or `lw` instruction with a memory address that is not word-aligned (i.e. divisible by 2).

# 5 Sample Programs

## 5.1 Factorial

The following program finds the factorial of the value in register  $R_1$  and places the result back into  $R_1$ .

```

1 # Factorial program
2 # Compiled: 500050275061244350803
   c406c06288358416bf624443c616c0454616bea24220000
3
4 MOVI  R0 0 # constant 0
5 MOVI  R1 7 # number to factorial-ize
6
7 MOVI  R3 1 # counter to target
8 MOV   R2 R3 # holds running factorial
9
10 fact:
11 MOVI  R4 0 # result of this multiplication
12
13 mul:  # mul R2 R3; destroy R2
14 CMP   R2 R0
15 JMPEQ out_mul
16 ADD   R4 R3
17 SUBI  R2 1

```

```

18 JMP    mul
19 out_mul:
20 MOV     R2 R4
21
22 CMP     R3 R1
23 JMPEQ   out_fact
24 ADDI    R3 1
25 JMP     fact
26
27 out_fact:
28 mov     R1 R2
29
30 HALT

```

## 5.2 String reversal

The following program reads the standard input and prints the reverse to the standard output. For example, “hello world” would become “dlrow olleh”.

```

1 # String reversal program
2 # Compiled: 5000502014204
   c413c406c0454216bf410203c206c0458216bf60000
3
4 MOVI    R0 0    # constant 0
5 MOVI    R1 0    # pointer into memory
6
7 # read stdin
8 loop1:
9 READ    R1
10 LB     R2 R1
11 CMP    R2 R0
12 JMPEQ  out1
13 ADDI   R1 1
14 JMP    loop1
15 out1:
16
17 # write reverse to stdout
18 loop2:
19 PRINT  R1
20 CMP    R1 R0
21 JMPEQ  out2
22 SUBI   R1 1
23 JMP    loop2
24 out2:
25
26 HALT

```

## 6 Acknowledgements

This concept is based on work done by Christopher Woodall. See <https://github.com/cwoodall/sx86-emulator>.