Physics Laboratory Report

Lab number and Title: Lab 106 - Static and

Kinetic Friction

Name: Arsh Bhamla Group ID: 3

Date of Experiment: 09/14/2023 Date of Report Submission: 09/21/2023

Course & Section Number: PHYS111A Instructor's Name: Professor Thuan

Nguyen

Partners' Names: Logan Chappel, Jose Tabuena, Connor Nguyen

1. INTRODUCTION

1.1 Objectives

This lab, Lab 106, is about understanding and using static and kinetic frictions, which are prevalent in our everyday lives. In our previous labs, we had ignored the use of friction in favor of simpler forces, but now we are subject to understanding how to put friction in as well. Our objective is to pull objects of different weight and determine how the coefficients of static and kinetic friction change. From this, we can reinforce the idea taught in class that the force of friction (which is in the x vector) is dependent on the normal force (which is in the y vector).

1.2 Theoretical background

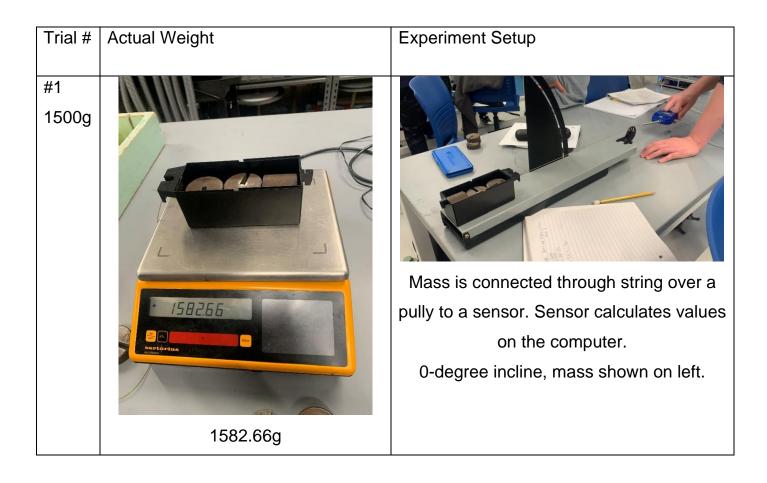
We are already familiar with F = ma for both the x and y components, having used it in our previous labs. However, this time for the x vector we will have to include the force of friction, which runs opposite of the applied force. Furthermore, in class we were taught that the force of friction is equal to mu(s/k) *Fn, where mu(s/k) represents the coefficient of static or kinetic friction, and Fn represents the normal force calculated through the y vector.

When at a horizontal plane (0 degrees incline), the Fn is simply equal to Fg (or mg), but in the later experiment we raised the platform to see changes in the force of friction.

2 EXPERIMENTAL PROCEDURE

Experiment One

Our group followed the directions in the lab manual. In summary, it involved us doing 5 experiments, one of each at a different weight, where we pulled the mass using a string to find the static and kinetic frictions. The platform was at 0 degrees.



#2 1200g



1283.28g



Mass is connected through string over a pully to a sensor. Sensor calculates values on the computer.

0-degree incline, mass shown on left.

#3 900g



983.65g



Mass is connected through string over a pully to a sensor. Sensor calculates values on the computer.

0-degree incline, mass shown on left.

#4 600g



683.90g



Mass is connected through string over a pully to a sensor. Sensor calculates values on the computer.

0-degree incline, mass shown on left.





384.26g



Mass is connected through string over a pully to a sensor. Sensor calculates values on the computer.

0-degree incline, mass shown on left.

Variables

- Mass of Weight (m)
- Gravity (g)
- Coefficient of static friction (Ms)
- Coefficient of kinetic friction (Mk)

Experiment Two

Experiment two was split into two parts. The first part had us test for the angle of theta where the mass begins sliding without having to be pushed. We did this three times and found an average. The second part gave us set variables for which we had to run similar trials as in experiment one (pull the string up the incline) and recognize the difference.

Part One



Setup of Experiment



Highest Point for Trial 1

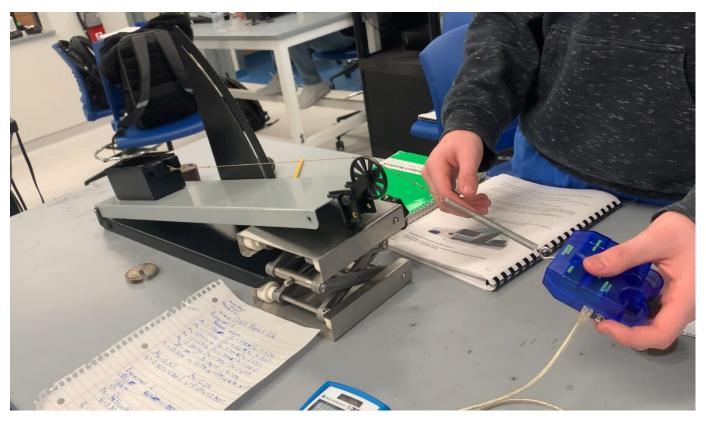
Variables

- Angle (Θ)
- Mass (m)
- Acceleration due to gravity (g)

Part Two



Theta = 10-degrees



Setup of Part Two

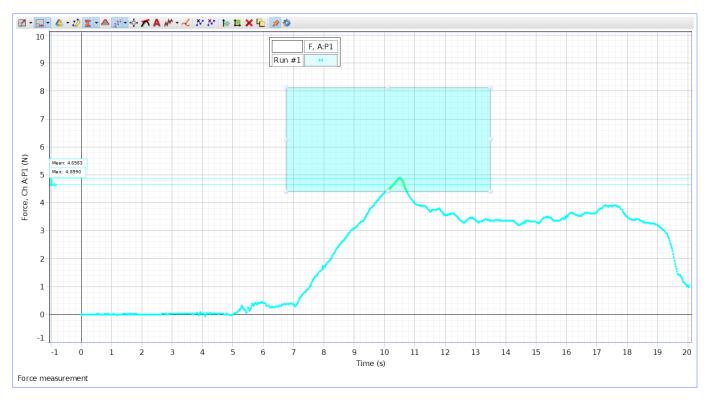
Variables

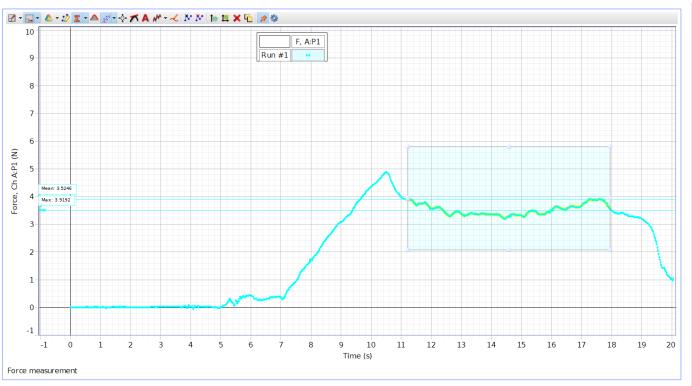
- Angle (Θ)
- Mass (m)
- Acceleration due to gravity (g)

3 RESULTS

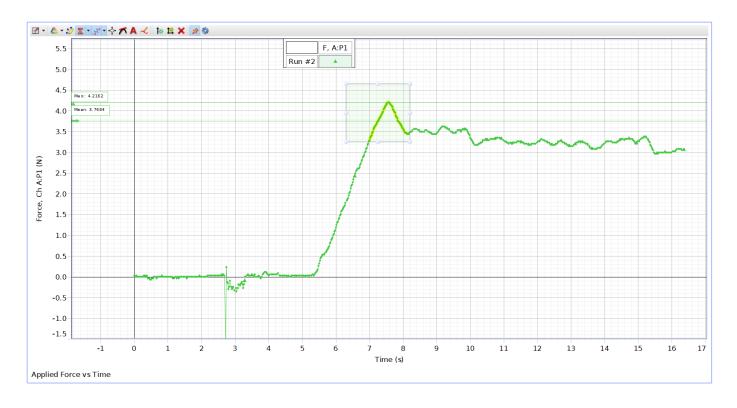
Experiment One

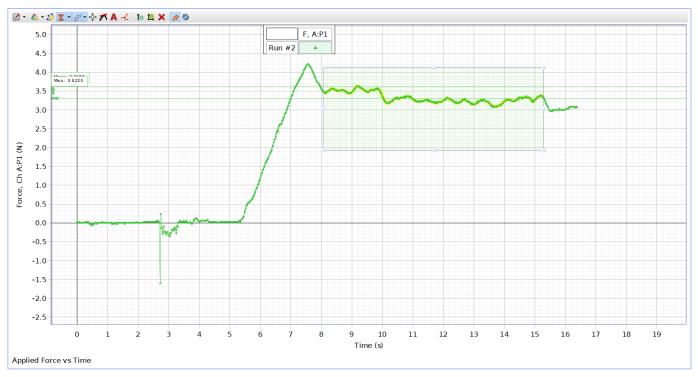
1500g Weight

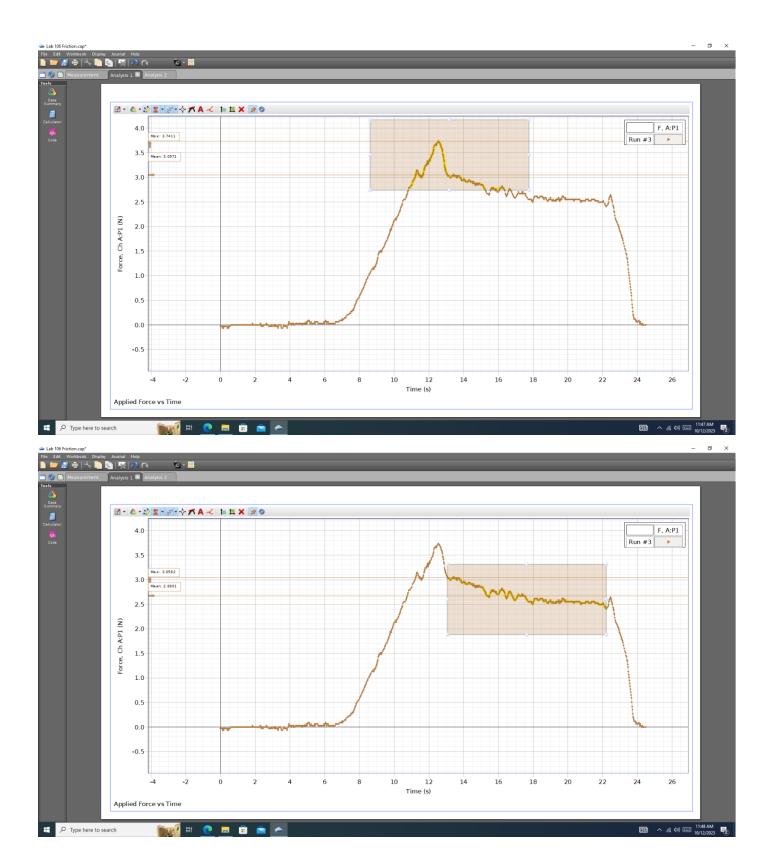




1200g

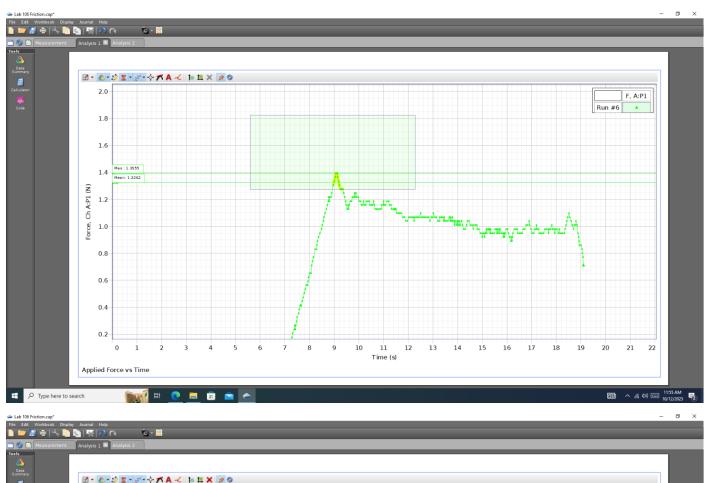






600g



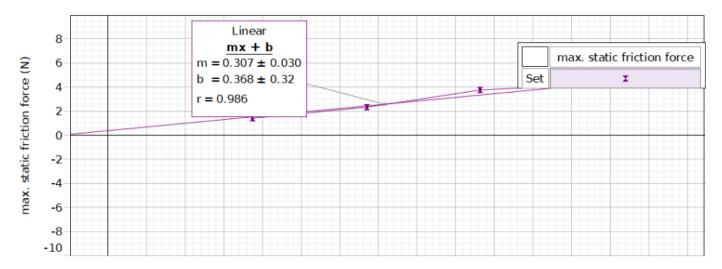




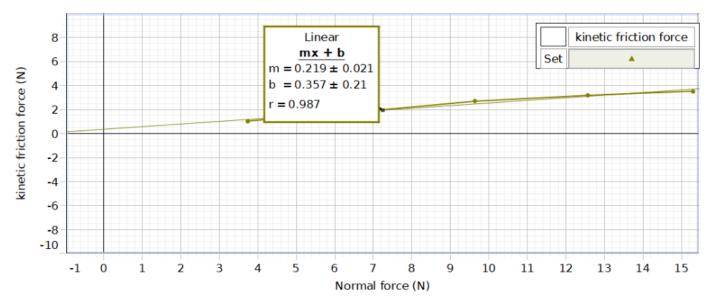
Mass	Static and Kinetic Friction	
1500g	S: 4.885N, K: 3.525N	
1200g	S: 4.216N, K: 3.180N	
900g	S: 3.741N, K: 2.689N	
600g	S: 2.316N, K:1.826N	

300g	S: 1.395N, K: 1.042N
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For the calculated frictional force, I used the value of μ s and μ k to plug into the equation.



Coefficient of Static Friction: 0.307



Friction Force vs. Normal Force

Coefficient of Kinetic Friction: 0.219

No calculations are needed for part one since this was done just by the experiment and collecting data.

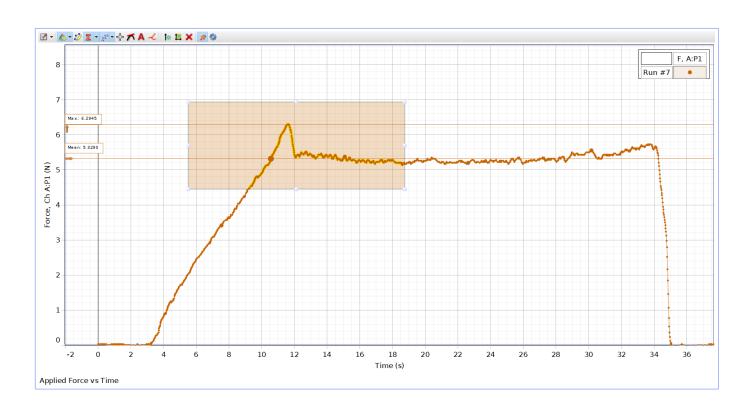
Experiment Two

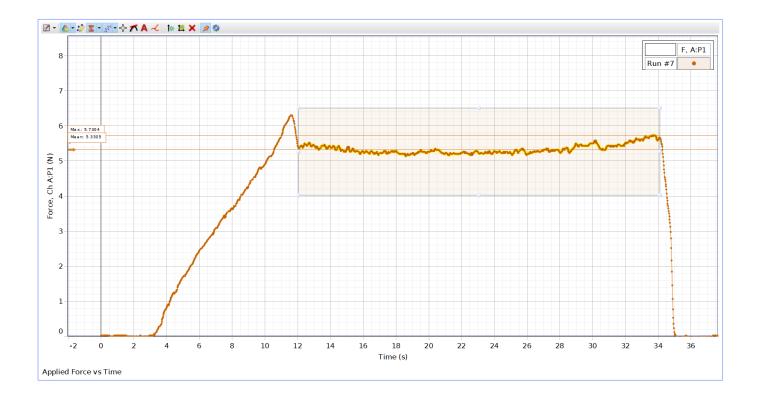
Part One

Trial	Angle	
#1	21°	
#2	22°	
#3	22.5°	
Average	21.8 OR 22 (in significant figures)	

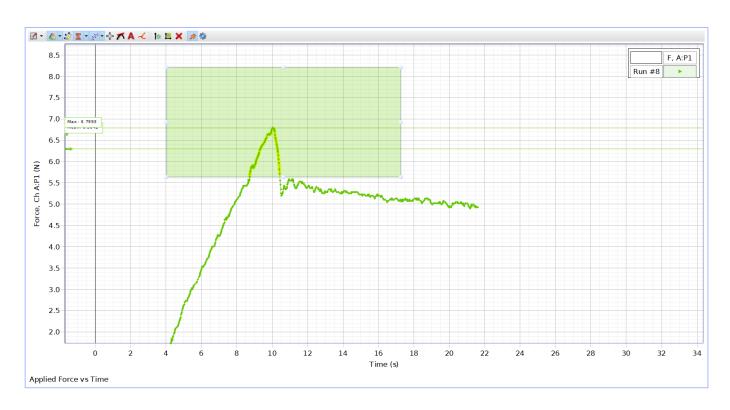
No calculations are needed for part one since this was done just by the experiment and collecting data.

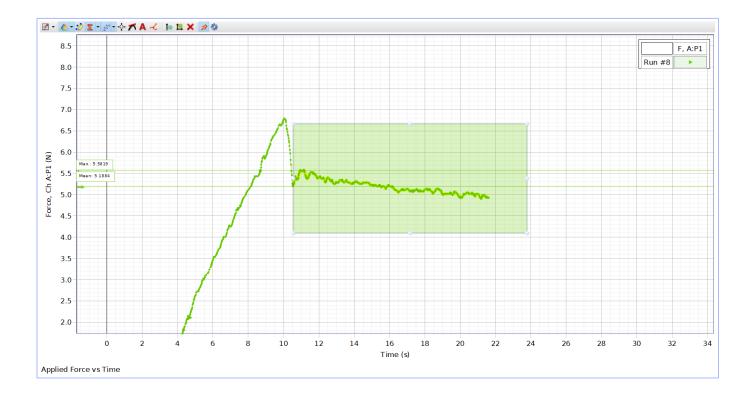
Part Two Trial One



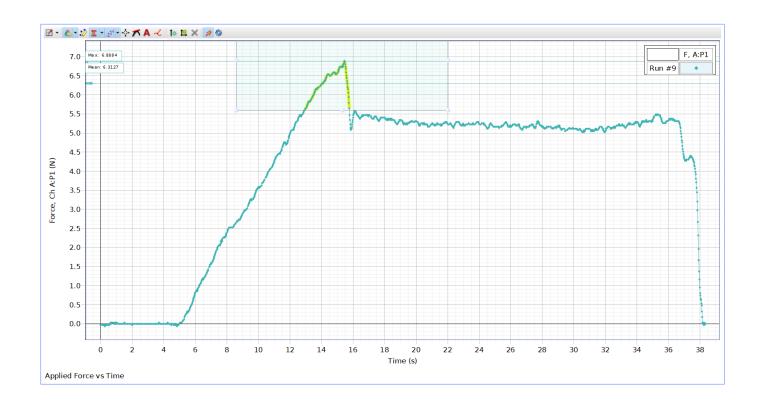


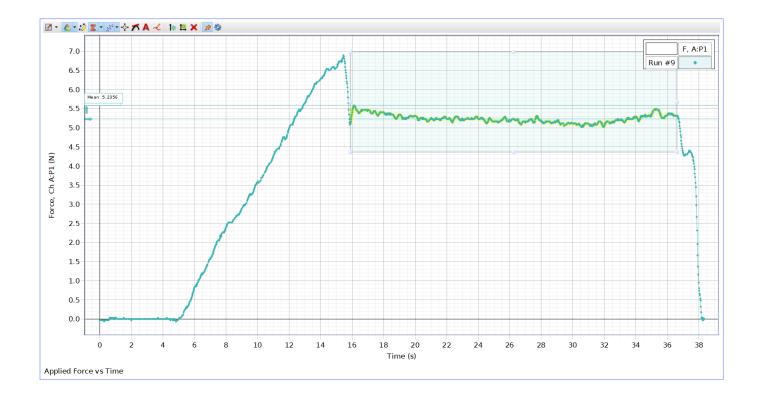
Trial Two





Trial Three





Lab 106

(alculations

$$M_s = 0.307$$
, $M_k = 0.219$ (taken from exp.1)

 $F_{sf} = M_{slcos}(\Theta)$ $F_{sf} = (0.307)(12.97N)(cos10')$
 $F_{sf} = 3.80N$
 $F_{kf} = M_k F_{ncos}(\Theta)$ $F_{kf} = (0.209)(12.97N)(cos10')$
 $F_{kf} = 2.71N$
 $\Sigma F_{sf} = 0 \rightarrow F_{n} - m_g = 0$ $F_{n} = m_g$
 $F_{n} = (1.283 \text{ kg})(9.87\%\text{ s}^2)$ $F_{n} = 12.57N$

	Theoretical	Measured
Static Friction	3.80N	6.6607N (EP: 75.3%)
Kinetic Friction	2.71N	5.2515N (EP: 94.5%)

Used the formula |(Measured – Theoretical / Theoretical| * 100

4 ANALYSIS and DISCUSSION

The two formulas that were used during the calculation of the theoretical values were the use of Newton's Second Law ($\Sigma F = ma$) and the definition of Force of Friction (Ff = $\mu(s/k)Fn$). Fn can be solved using Newton's Second Law in the y vector, and then substituted within the force of friction formula to get what we are looking for. There were no calculations for this part in order to find μs and μk because the values can not be solved. This is because the value of Force of Friction and μf (for both s and k) were unknown, which means we wouldn't be able to solve for the equation. However, when solving Ff after knowing μf , we were able to match that up and reach a near value to the value that the computer provided.

For experiment two, part one, we did not have calculations, and it was simply testing. We just ran the experiment three times and jotted down the values and evaluated. The result was that the force of friction decreases as the angle increases, and at some point, the value of friction becomes lower than the value of $\cos(\Theta)$ mg, or the force of gravity. For part two, we were given set values, and had to calculate for the answer. This experiment however had one major problem; the error percentage was very high. The values for these are close to 100%, which would mean that one of the two values is highly inaccurate. Alternatively, I believe that the reason the error percentage is so high is due to rounding error and perhaps the unforeseen factors that may affect the experiment. Also having used the muk and mus from the first experiment was possibly not correct, as the values dramatically shifted between experiments one and two. However, this still satisfies the objective of the experiment.

There were three questions within the lab manual. Question one, referring to the graph in the manual, asks about the motion at the different points. At A, the acceleration is increasing. At B, acceleration has reached its maximum but has stopped increasing. At this point the acceleration is constant but not for long. At point C, the acceleration begins decreasing, thus making the force value decreasing. Lastly at point D, the force is constant, so the acceleration is constantly being applied. The next question asks if the

normal force affects the coefficient of friction, and the answer is no. The coefficient is dependant on the type of materials that are interacting with one another, and Fn is calculated separately to get force of Friction. Last question asks about trends between the coefficient of kinetic and static friction. Simply put, static is always higher than kinetic coefficients.

5 CONCLUSIONS

We learned how to solve problems using Newton's second law and the definition of the force of friction to solve for the problems displayed in the labs. We were able to go back and force between the x and y vector (during experiment two) to calculate for these values and get a better understanding of how friction works. This experiment had me questioning how this would change if we used a different surface with a higher coefficient of friction, because our lab cut short the different materials and how they affect the situation. A change I would propose to the experiment is that we use different values of. Overall, it was an enjoyable lab with many learned experiences.