```
Algorithm NextValue(k)
123456789
    //x[1], \ldots, x[k-1] have been assigned integer values in
    // the range [1, m] such that adjacent vertices have distinct
    // integers. A value for x[k] is determined in the range
    //[0,m]. x[k] is assigned the next highest numbered color
    // while maintaining distinctness from the adjacent vertices
    // of vertex k. If no such color exists, then x[k] is 0.
         repeat
10
             x[k] := (x[k] + 1) \mod (m+1); // Next highest color.
11
             if (x[k] = 0) then return; // All colors have been used.
12
13
             for i := 1 to n do
             { // Check if this color is
14
15
                  // distinct from adjacent colors.
                  if ((G[k,j] \neq 0) \text{ and } (x[k] = x[j]))
16
17
                  // If (k,j) is and edge and if adj.
                  // vertices have the same color.
18
19
                      then break;
20
             if (j = n + 1) then return; // New color found
21
         } until (false); // Otherwise try to find another color.
^{22}
23
```

```
Algorithm mColoring(k)
123456789
    // This algorithm was formed using the recursive backtracking
   // schema. The graph is represented by its boolean adjacency
    // matrix G[1:n,1:n]. All assignments of 1,2,\ldots,m to the
    // vertices of the graph such that adjacent vertices are
    // assigned distinct integers are printed. k is the index
    // of the next vertex to color.
         repeat
         \{//\text{ Generate all legal assignments for } x[k].
10
             NextValue(k); // Assign to x[k] a legal color.
11
             if (x[k] = 0) then return; // No new color possible
12
             if (k = n) then // At most m colors have been
13
                                 // used to color the n vertices.
14
15
                 write (x[1:n]);
             else mColoring(k+1);
16
         } until (false);
18
```

```
Algorithm HeapSort(a, n)
    // a[1:n] contains n elements to be sorted. HeapSort
       rearranges them inplace into nondecreasing order.
        Heapify(a, n); // Transform the array into a heap.
        // Interchange the new maximum with the element
        // at the end of the array.
        for i := n to 2 step -1 do
            t := a[i]; a[i] := a[1]; a[1] := t;
            Adjust(a, 1, i - 1);
12
```

```
Algorithm Heapify(a, n)
// Readjust the elements in a[1:n] to form a heap.
    for i := \lfloor n/2 \rfloor to 1 step -1 do Adjust(a, i, n);
```

```
Algorithm Adjust(a, i, n)

    \begin{array}{r}
      2 \\
      3 \\
      4 \\
      5 \\
      6 \\
      7 \\
      8 \\
      9
    \end{array}

          The complete binary trees with roots 2i and 2i + 1 are
          combined with node i to form a heap rooted at i. No
         node has an address greater than n or less than 1.
           j := 2i; item := a[i];
           while (j \le n) do
                 if ((j < n) \text{ and } (a[j] < a[j+1])) then j := j+1;
10
                      // Compare left and right child
11
                      // and let j be the larger child.
12
                 if (item \ge a[j]) then break;
                      // A position for item is found.
13
                a[|j/2|] := a[j]; j := 2j;
14
15
           a[|j/2|] := item;
16
17
      Algorithm DelMax(a, n, x)
\frac{2}{3} \frac{4}{4} \frac{5}{6} \frac{6}{7} \frac{7}{8}
      // Delete the maximum from the heap a[1:n] and store it in x.
           if (n=0) then
                 write ("heap is empty"); return false;
           x := a[1]; a[1] := a[n];
9
           Adjust(a, 1, n - 1); return true;
10
```

```
Algorithm Insert(a, n)
    // Inserts a[n] into the heap which is stored in a[1:n-1].
    i := n; item := a[n];
    while ((i > 1) and (a[|i/2|] < item)) do
        a[i] := a[|i/2|]; i := |i/2|;
    a[i] := item; return true;
```

```
Algorithm Sort(a, n)
// Sort the elements a[1:n].
    for i := 1 to n do lnsert(a, i);
    for i := n to 1 step -1 do
        DelMax(a, i, x); a[i] := x;
```

```
Algorithm MergeSort(low, high)

  \begin{array}{c}
    2 \\
    3 \\
    4 \\
    5 \\
    6 \\
    7 \\
    8 \\
    9
  \end{array}

      // a[low: high] is a global array to be sorted.
     // Small(P) is true if there is only one element
      // to sort. In this case the list is already sorted.
           if (low < high) then // If there are more than one element
                 // Divide P into subproblems.
                      // Find where to split the set.
10
                            mid := \lfloor (low + high)/2 \rfloor;
                     Solve the subproblems.
                      MergeSort(low, mid);
12
                      MergeSort(mid + 1, high);
 13
                     Combine the solutions.
 14
                      Merge(low, mid, high);
15
16
```

```
Algorithm Merge(low, mid, high)
2345
    // a[low: high] is a global array containing two sorted
    // subsets in a[low:mid] and in a[mid+1:high]. The goal
    // is to merge these two sets into a single set residing
    // in a[low: high]. b[] is an auxiliary global array.
6
7
8
         h := low; i := low; j := mid + 1;
         while ((h \le mid) \text{ and } (j \le high)) do
9
              if (a[h] \leq a[j]) then
10
11
                  b[i] := a[h]; h := h + 1;
12
13
14
              else
15
                  b[i] := a[j]; j := j + 1;
16
17
18
         f if (h > mid) then
19
20
21
              for k := j to high do
22
                  b[i] := a[k]; i := i + 1;
23
24
25
         else
26
              for k := h to mid do
27
                  b[i] := a[k]; i := i + 1;
28
29
         for k := low to high do a[k] := b[k];
30
31
```

```
Algorithm NQueens(k, n)
    // Using backtracking, this procedure prints all
    // possible placements of n queens on an n \times n
4
5
       chessboard so that they are nonattacking.
         for i := 1 to n do
             if Place(k, i) then
10
                 x[k] := i;
                  if (k = n) then write (x[1:n]);
                  else NQueens(k+1,n);
12
13
14
```

```
Algorithm Place(k, i)
   // Returns true if a queen can be placed in kth row and
    // ith column. Otherwise it returns false. x[] is a
   // global array whose first (k-1) values have been set.
    // Abs(r) returns the absolute value of r.
        for j := 1 to k-1 do
            if ((x[j] = i) // Two in the same column
                  or (\mathsf{Abs}(x[j]-i) = \mathsf{Abs}(j-k))
10
                      // or in the same diagonal
                 then return false:
        return true;
```

```
Algorithm Partition(a, m, p)
\frac{2}{3} \frac{4}{4} \frac{5}{6} \frac{6}{7} \frac{8}{9}
     // Within a[m], a[m+1], \dots, a[p-1] the elements are
     // rearranged in such a manner that if initially t = a[m],
     // then after completion a[q] = t for some q between m
     // and p-1, a[k] \le t for m \le k < q, and a[k] \ge t
     // for q < k < p. q is returned. Set a[p] = \infty.
          v := a[m]; i := m; j := p;
          repeat
10
11
               repeat
                    i := i + 1;
12
               until (a[i] > v);
13
14
               repeat
15
                    i := i - 1;
               until (a[i] \leq v);
16
17
               if (i < j) then Interchange(a, i, j);
          } until (i \geq j);
18
19
          a[m] := a[j]; a[j] := v; return j;
20
     Algorithm Interchange(a, i, j)
12345
     // Exchange a[i] with a[j].
         p := a[i];
          a[i] := a[j]; a[j] := p;
6
```

```
Algorithm QuickSort(p, q)

  \begin{array}{c}
    1 \\
    2 \\
    3 \\
    4 \\
    5 \\
    6 \\
    7 \\
    8 \\
    9
  \end{array}

     // Sorts the elements a[p], \ldots, a[q] which reside in the global
     // array a[1:n] into ascending order; a[n+1] is considered to
      // be defined and must be \geq all the elements in a[1:n].
           if (p < q) then // If there are more than one element
                // divide P into two subproblems.
                      i := \mathsf{Partition}(a, p, q + 1);
10
                           //j is the position of the partitioning element.
                // Solve the subproblems.
                      QuickSort(p, i-1);
12
                      QuickSort(j+1, q):
13
                 // There is no need for combining solutions.
14
15
16
```

```
Algorithm RQuickSort(p, q)
\frac{2}{3} \frac{3}{4} \frac{4}{5} \frac{5}{6}
     // Sorts the elements a[p], \ldots, a[q] which reside in the global
     // array a[1:n] into ascending order. a[n+1] is considered to
         be defined and must be \geq all the elements in a[1:n].
          if (p < q) then
               if ((q-p) > 5) then
                    Interchange(a, Random() mod (q - p + 1) + p, p);
9
               j := \mathsf{Partition}(a, p, q + 1);
10
                    //j is the position of the partitioning element.
11
12
               RQuickSort(p, j-1);
               RQuickSort(j + 1, q);
13
14
```

```
Algorithm SumOfSub(s, k, r)
    // Find all subsets of w[1:n] that sum to m. The values of x[j],
   //1 \le j < k, have already been determined. s = \sum_{j=1}^{k-1} w[j] * x[j]
    // and r = \sum_{j=k}^{n} w[j]. The w[j]'s are in nondecreasing order.
5
    // It is assumed that w[1] \leq m and \sum_{i=1}^n w[i] \geq m.
         // Generate left child. Note: s + w[k] \le m since B_{k-1} is true.
         x[k] := 1;
         if (s+w[k]=m) then write (x[1:k]); // Subset found
             // There is no recursive call here as w[j] > 0, 1 \le j \le n.
10
         else if (s + w[k] + w[k+1] \le m)
11
               then SumOfSub(s+w[k], k+1, r-w[k]);
12
         // Generate right child and evaluate B_k.
13
         if ((s+r-w[k] \ge m) \text{ and } (s+w[k+1] \le m)) then
15
             x[k] := 0;
16
             SumOfSub(s, k+1, r-w[k]);
17
18
19
```