

Texture Synthesis by Quilting

In this assignment, you will develop code to stitch together image patches sampled from an input texture in order to synthesize new texture images. You can download the test image used to generate the example above from assignment folder Canvas.

You should start by reading through the whole assignment, looking at the provided code in detail to make sure you understand what it does. The main fucntion *quilt_demo* appears at the end. You will need to write several subroutines in order for it to function properly.

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1. Shortest Path [25 pts]

Write a function *shortest_path* that takes an 2D array of *costs, of shape HxW, as input and finds the shortest vertical path* from top to bottom through the array. A vertical path is specified by a single horizontal location for each row of the H rows. Locations in

successive rows should not differ by more than 1 so that at each step the path either goes straight or moves at most one pixel to the left or right. The cost is the sum of the costs of each entry the path traverses. Your function should return an length H vector that contains the index of the path location (values in the range 0..W-1) for each of the H rows.

You should solve the problem by implementing the dynamic programming algorithm described in class. You will have a for-loop over the rows of the "cost-to-go" array (M in the slides), computing the cost of the shortest path up to that row using the recursive formula that depends on the costs-to-go for the previous row. Once you have get to the last row, you can then find the smallest total cost. To find the path which actually has this smallest cost, you will need to do backtracking. The easiest way to do this is to also store the index of whichever minimum was selected at each location. These indices will also be an HxW array. You can then backtrack through these indices, reading out the path.

Finally, you should create at least three test cases by hand where you know the shortest path and see that the code gives the correct answer.

In your implementation you will need to have a *for-loop* over the rows of the cost matrix since the computation has to be carried out in a squential order. However, the computation for each row can be done in a vectorized manner without an explicit loop (e.g., my implementation used the **numpy** operations **concatenate,stack,min,argmin**). If you get stuck I recommend first implementing a version with nested loops to make sure you get the algorithm correct and then go back and see how to "vectorize" it.

```
Parameters
costs: 2D float array of shape HxW
     An array of cost values with W>=3
Returns
_____
path: 1D array of length H
   indices of a vertical path. path[i] contains the column index of
   the path for each row i.
0.00
H, W = costs.shape
assert W >= 3, "Width of the cost matrix must be at least 3."
# DP table to store the minimum cost to reach each cell
M = np.zeros((H, W))
M[0] = costs[0] # First row is just the cost itself
# Backtracking table to reconstruct the path
backtrack = np.zeros((H, W), dtype=int)
# Fill DP table
for i in range(1, H):
    for j in range(W):
        # Get the cost from the three possible previous positions
       candidates = []
       if j > 0:
            candidates.append((M[i-1, j-1], j-1)) # Left
       candidates.append((M[i-1, j], j)) # Middle
       if j < W-1:
            candidates.append((M[i-1, j+1], j+1)) # Right
       # Select the minimum cost move (prioritizing left in case of tie)
       min_prev_cost, best_prev_col = min(candidates, key=lambda x: (x[0], x[1]))
       M[i, j] = costs[i, j] + min_prev_cost
       backtrack[i, j] = best_prev_col
# Find the end point of the optimal path (minimum cost in last row)
path = np.zeros(H, dtype=int)
last_row = M[-1]
```

```
min_cost = np.min(last_row) # Get the minimum value
candidates = np.where(last_row == min_cost)[0] # Find all columns with min cost

# Choose column 2 if it's a candidate, otherwise take the leftmost
path[-1] = 2 if 2 in candidates else candidates[0]

# Reconstruct the path by backtracking

for i in range(H-2, -1, -1):
    path[i] = backtrack[i+1, path[i+1]]
return path
```

```
In [3]: #
        # Your test code goes here. Come up with at least 3 more test cases by manually
        # constructing a cost matrix where you know what the shortest path should be.
        # Example test cases
        costs = np.array([
           [4, 1, 3],
           [2, 8, 1],
            [6, 3, 2]
        1)
        path = shortest_path(costs)
        optpath=np.array([1,2,2])
        assert np.array_equal(path, optpath), "Test failed!"
        print("Test (1) passed!")
        print("\n")
        costs2 = np.array([
            [10, 2, 10],
            [3, 5, 2],
            [8, 1, 4],
            [2, 2, 1]
        ])
        path2 = shortest_path(costs2)
        optpath2=np.array([1,2,1,2])
```

```
assert np.array_equal(path2, optpath2), "Test failed!"
print("Test (2) passed!")
print("\n")
costs3 = np.array([
   [3, 1, 2, 3],
   [3, 2, 1, 3],
   [3, 3, 1, 2],
   [1, 1, 1, 1]
])
optpath3 = np.array([1, 2, 2, 2]) # The correct optimal path
path3 = shortest_path(costs3)
assert np.array_equal(path3, optpath3), "Test failed!"
print("Test (3) passed!")
print("\n")
# One of your tests should be a case where a simple greedy forward search
# (i.e., finding the min in the first row and then repeatedly choosing the
# min of the 3 neighbors below it) fails but your dynamic program finds the
# global optimum.
costs4 = np.array([[1,0,1,1],[1,1,1,1],[1,1,1,0],[0,1,1,0]])
optpath4 = np.array([1,2,3,3])
path4 = shortest_path(costs4)
assert np.array_equal(path4, optpath4), "Test failed!"
print("Test (4) passed!")
#assert that path1 matches optpath1
```

Test (1) passed!

Test (2) passed!

Test (3) passed!

Test (4) passed!

2. Image Stitching: [25 pts]

Write a function *stitch* that takes two gray-scale images, *left_image* and *right_image* and a specified *overlap* and returns a new output image by stitching them together along a vertical seam where the two images have very similar brightness values. If the input images are of widths *w1* and *w2* then your stitched result image returned by the function should be of width *w1+w2-overlap* and have the same height as the two input images.

You will want to first extract the overlapping strips from the two input images and then compute a cost array given by the absolute value of their difference. You can then use your *shortest_path* function to find the seam along which to stitch the images where they differ the least in brightness. Finally you need to generate the output image by using pixels from the left image on the left side of the seam and from the right image on the right side of the seam. You may find it easiest to code this by first turning the path into an binary (alpha) mask for each image and then using the standard blending approach we used in the previous assignment.

```
In [4]:

def stitch(left_image, right_image, overlap):
    """

This function takes a pair of images with a specified overlap and stitches them togther by finding a minimal cost seam in the overlap region.

Parameters
------
left_image: 2D float array of shape HxW1
    Left image to stitch

right_image: 2D float array of shape HxW2
    Right image to stitch

overlap: int
    Width of the overlap zone between left and right image

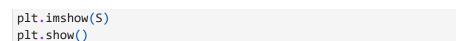
Returns
------
stitched: 2D float array of shape Hx(W1+W2-overlap)
    The resulting stitched image
"""

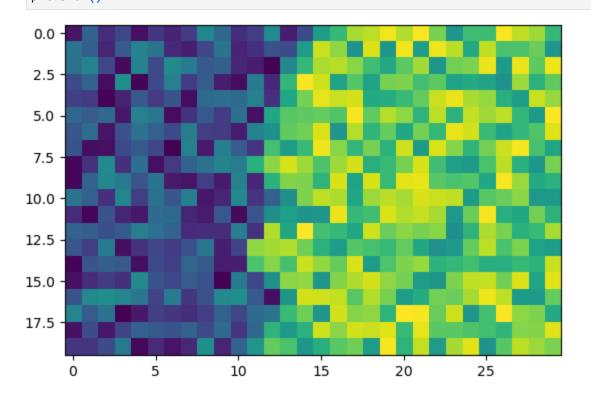
H, W1 = left_image.shape
W2 = right_image.shape[1]
```

```
overlap_left = left_image[:, -overlap:]
overlap_right = right_image[:, :overlap]
cost = np.abs(overlap_left - overlap_right)
seam = shortest_path(cost)
mask_left = np.ones((H, overlap))
mask_right = np.ones((H, overlap))
for i in range(H):
   mask_left[i, seam[i]:] = 0
   mask_right[i, :seam[i]] = 0
alpha = np.linspace(1, 0, overlap).reshape(1, -1)
blended = mask_left * overlap_left + mask_right * overlap_right
stitched = np.hstack([left_image[:, :-overlap], blended, right_image[:, overlap:]])
assert stitched.shape == (H, W1 + W2 - overlap)
# inputs should be the same height
assert(left_image.shape[0]==right_image.shape[0])
assert(overlap>=3)
# your code here
assert(stitched.shape[0]==left_image.shape[0])
assert(stitched.shape[1]==(left_image.shape[1]+right_image.shape[1]-overlap))
return stitched
```

```
In [5]: # a simple test visualization of stitching two random
    # tiles which have different overall brightness so we
    # can easily see where the seam is

L = np.random.rand(20,20)+1
R = np.random.rand(20,20)+2
S = stitch(L,R,10)
```





3. Texture Quilting: [25 pts]

Write a function *synth_quilt* that takes as input an array indicating the set of texture tiles to use, an array containing the set of available texture tiles, the *tilesize* and *overlap* parameters and synthesizes the output texture by stitching together the tiles. *synth_quilt* should utilize your stitch function repeatedly. First, for each horizontal row of tiles, construct the stitched row by successively stitching the next tile in the row on to the right side of your row image. Once you have row images for all the rows, you can stitch them together to get the final image. Since your stitch function only works for vertical seams, you will want to transpose the rows, stitch them together, and then transpose the result. You may find it useful to look at the provided code below which simply puts down the tiles with the specified overlap but doesn't do stitching. Your quilting function will return a similar result but with much smoother transitions between the tiles.

```
In [6]: | def synth_quilt(tile_map,tiledb,tilesize,overlap):
            This function takes as input an array indicating the set of texture tiles
            to use at each location, an array containing the database of available texture
            tiles, tilesize and overlap parameters, and synthesizes the output texture by
            stitching together the tiles
            Parameters
            tile map : 2D array of int
                Array storing the indices of which tiles to paste down at each output location
            tiledb : 2D array of int
                Collection of sample tiles to select from. The array is of size ntiles x npixels
                where each tile image is stored in vectorized form as a row of the array.
            tilesize : (int,int)
                Size of a tile in pixels
            overlap : int
                Amount of overlap between tiles
            Returns
            _____
            output : 2D float array
                The resulting synthesized texture of size
            # determine output size based on overlap and tile size
            outh = (tilesize[0]-overlap)*tile_map.shape[0] + overlap
            outw = (tilesize[1]-overlap)*tile_map.shape[1] + overlap
            output = np.zeros((outh, outw))
            row_images = []
            for i in range(tile_map.shape[0]):
                row = None
                for j in range(tile_map.shape[1]):
                    tile_vec = tiledb[tile_map[i, j], :]
                    tile_image = np.reshape(tile_vec, tilesize)
                    if row is None:
```

```
row = tile_image
        else:
            row = stitch(row, tile_image, overlap)
    row images.append(row)
final_image = row_images[0]
for i in range(1, len(row images)):
   final_image = stitch(final_image.T, row_images[i].T, overlap).T
return final_image
# The code below is a dummy implementation that pastes down each
# tile in the correct position in the output image. You need to
# replace this with your own version that stitches each row and then
# stitches together the colums
#for i in range(tile_map.shape[0]):
    #for j in range(tile_map.shape[1]):
        #icoord = i*(tilesize[0]-overlap)
       #jcoord = j*(tilesize[1]-overlap)
        #tile_vec = tiledb[tile_map[i,j],:];
        #tile image = np.reshape(tile vec,tilesize)
       #output[icoord:(icoord+tilesize[0]),jcoord:(jcoord+tilesize[1])] = tile_image;
#return output
```

4. Texture Synthesis Demo [25pts]

The function provided below *quilt_demo* puts together the pieces. It takes a sample texture image and a specified output size and uses the functions you've implemented previously to synthesize a new texture sample.

You should write some additional code in the cells that follow to in order demonstrate the final result and experiment with the algorithm parameters in order to produce a compelling visual result and write explanations of what you discovered.

Test your code on the provided image *rock_wall.jpg*. There are three parameters of the algorithm. The *tilesize*, *overlap* and *K*. In the provided ***texture_demo*** code below, these have been set at some default values. Include in your demo below images of three

example texture outputs when you: (1) increase the tile size, (2) decrease the overlap, and (3) increase the value for K. For each result explain how it differs from the default setting of the parameters and why.

Test your code on two other texture source images of your choice. You can use images from the web or take a picture of a texture yourself. You may need to resize or crop your input image to make sure that the *tiledb* is not overly large. You will also likely need to modify the *tilesize* and *overlap* parameters depending on your choice of texture. The resolution of your output image should be at least 3-4x larger than your input image. Once you have found good settings for these parameters, synthesize a nice output texture. Make sure you display both the image of the input sample and the output synthesis for your two other example textures in your submitted pdf.

```
In [7]: #skimage is only needed for sample tiles code provided below
        #you should not use it elsewhere in your own code
        import skimage as ski
        def sample tiles(image, tilesize, randomize=True):
            This function generates a library of tiles of a specified size from a given source image
            Parameters
            image: float array of shape HxW
                Input image
            tilesize : (int,int)
                Dimensions of the tiles in pixels
            Returns
            tiles : float array of shape numtiles x numpixels
                The library of tiles stored as vectors where npixels is the
                product of the tile height and width
            0.00
            tiles = ski.util.view as windows(image, tilesize)
            ntiles = tiles.shape[0]*tiles.shape[1]
            npix = tiles.shape[2]*tiles.shape[3]
            assert(npix==tilesize[0]*tilesize[1])
```

```
print("library has ntiles = ",ntiles,"each with npix = ",npix)
   tiles = tiles.reshape((ntiles,npix))
   # randomize tile order
   if randomize:
       tiles = tiles[np.random.permutation(ntiles),:]
   return tiles
def topkmatch(tilestrip,dbstrips,k):
   This function finds the top k candidate matches in dbstrips that
   are most similar to the provided tile strip.
   Parameters
   tilestrip : 1D float array of length npixels
       Grayscale values of the query strip
   dbstrips : 2D float array of size npixels x numtiles
       Array containing brightness values of numtiles strips in the database
       to match to the npixels brightness values in tilestrip
   k : int
       Number of top candidate matches to sample from
   Returns
   matches: list of ints of length k
       The indices of the k top matching tiles
   0.00
   assert(k>0)
   assert(dbstrips.shape[0]>k)
   error = (dbstrips-tilestrip)
   ssd = np.sum(error*error,axis=1)
   ind = np.argsort(ssd)
   matches = ind[0:k]
   return matches
```

```
def quilt_demo(sample_image, ntilesout=(10,20), tilesize=(30,30), overlap=5, k=5):
   This function takes an image and quilting parameters and synthesizes a
   new texture image by stitching together sampled tiles from the source image.
   Parameters
    _____
   sample_image : 2D float array
       Grayscale image containing sample texture
   ntilesout : list of int
       Dimensions of output in tiles, e.g. (3,4)
   tilesize : int
       Size of the square tile in pixels
   overlap : int
       Amount of overlap between tiles
   k : int
       Number of top candidate matches to sample from
   Returns
   img : list of int of length K
       The resulting synthesized texture of size
   # generate database of tiles from sample
   tiledb = sample_tiles(sample_image,tilesize)
   # number of tiles in the database
   nsampletiles = tiledb.shape[0]
   if (nsampletiles<k):</pre>
        print("Error: tile database is not big enough!")
   # generate indices of the different tile strips so we can easily
   # extract the left, right, top or bottom overlap strip from a tile
   i,j = np.mgrid[0:tilesize[0],0:tilesize[1]]
   top_ind = np.ravel_multi_index(np.where(i<overlap),tilesize)</pre>
   bottom_ind = np.ravel_multi_index(np.where(i>=tilesize[0]-overlap),tilesize)
```

```
left ind = np.ravel multi index(np.where(j<overlap),tilesize)</pre>
right_ind = np.ravel_multi_index(np.where(j>=tilesize[1]-overlap),tilesize)
# initialize an array to store which tile will be placed
# in each location in the output image
tile_map = np.zeros(ntilesout, 'int')
print('row:')
for i in range(ntilesout[0]):
    print(i)
    for j in range(ntilesout[1]):
        if (i==0)&(j==0):
                                           # first row first tile
            matches = np.zeros(k) #range(nsampletiles)
        elif (i==0):
                                           # first row (but not first tile)
            left_tile = tile_map[i,j-1]
            tilestrip = tiledb[left_tile,right_ind]
            dbstrips = tiledb[:,left_ind]
            matches = topkmatch(tilestrip,dbstrips,k)
        elif (j==0):
                                           # first column (but not first row)
            above_tile = tile_map[i-1,j]
            tilestrip = tiledb[above_tile,bottom_ind]
            dbstrips = tiledb[:,top_ind]
            matches = topkmatch(tilestrip,dbstrips,k)
        else:
                                           # neigbors above and to the left
            left tile = tile_map[i,j-1]
            tilestrip_1 = tiledb[left_tile,right_ind]
            dbstrips_1 = tiledb[:,left_ind]
            above_tile = tile_map[i-1,j]
            tilestrip_2 = tiledb[above_tile,bottom_ind]
            dbstrips_2 = tiledb[:,top_ind]
            # concatenate the two strips
            tilestrip = np.concatenate((tilestrip_1, tilestrip_2))
            dbstrips = np.concatenate((dbstrips_1,dbstrips_2),axis=1)
            matches = topkmatch(tilestrip,dbstrips,k)
        #choose one of the k matches at random
        tile_map[i,j] = matches[np.random.randint(0,k)]
```

```
output = synth_quilt(tile_map,tiledb,tilesize,overlap)
return output
```

```
In [8]: import skimage.color as color
        # load in rock_wall.jpg
        # run and display results for quilt demo with
        # (0) default parameters
        # (1) increased tile size
        # (2) decrease the overlap
        # (3) increase the value for K.
        image_path='rock_wall.jpg'
        def run_texture_synthesis(image_path, tilesize, overlap, k, ntilesout=(10, 20)):
            sample_image = color.rgb2gray(plt.imread(image_path))
            if (sample_image.dtype == np.uint8):
                sample_image = sample_image.astype(float) / 256
            #sample_image=plt.imread(image_path)
            output = quilt_demo(sample_image, ntilesout=ntilesout, tilesize=tilesize, overlap=overlap, k=k)
            plt.figure(figsize=(10, 5))
            plt.subplot(1, 2, 1)
            plt.title("Input Texture")
            plt.imshow(sample_image, cmap='gray')
            plt.axis('off')
            plt.subplot(1, 2, 2)
            plt.title("Synthesized Texture")
            plt.imshow(output, cmap='gray')
            plt.axis('off')
            plt.show()
        # Load rock_wall.jpg and test different parameters
        default_params = {'tilesize': (30, 30), 'overlap': 5, 'k': 5}
        increased_tile = {'tilesize': (50, 50), 'overlap': 5, 'k': 5}
        decreased overlap = {'tilesize': (30, 30), 'overlap': 3, 'k': 5}
        increased_k = {'tilesize': (30, 30), 'overlap': 5, 'k': 10}
        # Run tests
```

```
print("Default Parameters:")
 run_texture_synthesis(image_path, **default_params)
 print("Increased Tile Size:")
 run_texture_synthesis(image_path, **increased_tile)
 print("Increased K:")
 run_texture_synthesis(image_path, **increased_k)
 print("Decreased Overlap:")
 run_texture_synthesis(image_path, **decreased_overlap)
Default Parameters:
library has ntiles = 29241 each with npix = 900
row:
0
1
2
3
4
5
6
7
8
9
```

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4_quilting(ans)

Input Texture



位的

Synthesized Texture

Increased Tile Size:

library has ntiles = 22801 each with npix = 2500 row:

0

1

2

3

4

5

6

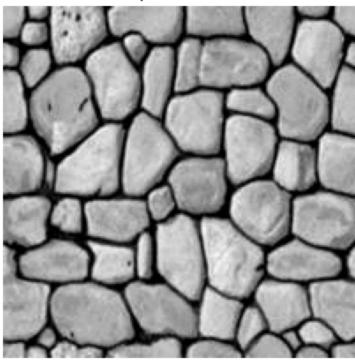
7

8

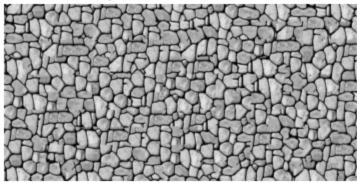
9

2/16/25, 5:00 PM

Input Texture



Synthesized Texture



Increased K:

library has ntiles = 29241 each with npix = 900 row:

0

1

2

2

4

5

6

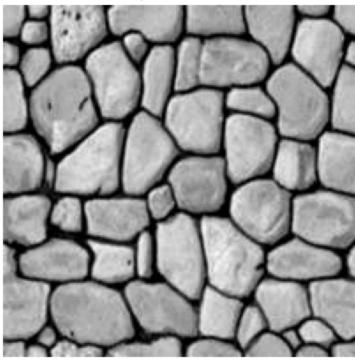
7

8

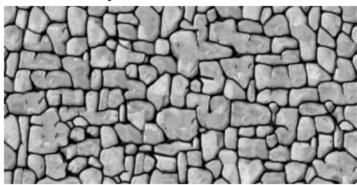
9

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Input Texture



Synthesized Texture



Decreased Overlap:

library has ntiles = 29241 each with npix = 900 row:

0

1

2

3

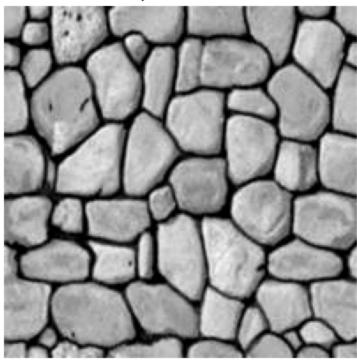
5

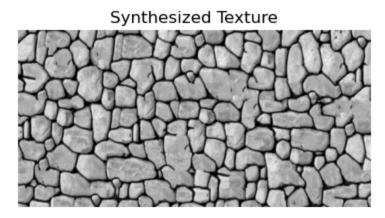
7

8 9

file:///C:/Users/arshi/OneDrive/Desktop/computer vision/assignment temps/temp assign 4/4_quilting(ans).html

Input Texture





For each result shown, explain here how it differs visually from the default setting of the parameters and explain why: . for the default image have some places that the colors of gray and black have a lot of difference

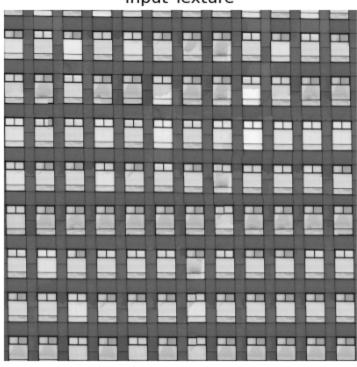
- . when we increase the tile of the image we get more rocks than usual but they are some places that we can see screen tering or like when pixels get shifted to the oposite sides and in the window example the windows get out of alignment becasue of it
- . when we increase the K we get different kinds of rocks in the generated image but less image tering and even in the window we have two window that is not the same with the others
- . decrease overlap have the best image and it is similar to the default image

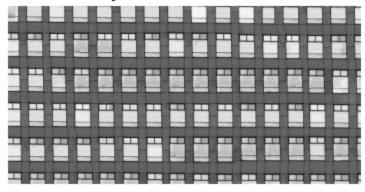
```
In [9]: #
# Load in yourimage1.jpg
#
# call quilt_demo, experiment with parameters as needed to get a good result
#
```

```
# display your source image and the resulting synthesized texture
image path='window.png'
def run_texture_synthesis(image_path, tilesize, overlap, k, ntilesout=(10, 20)):
    sample image = color.rgb2gray(plt.imread(image path))
    if (sample image.dtype == np.uint8):
        sample image = sample image.astype(float) / 256
    #sample image=plt.imread(image path)
    output = quilt demo(sample image, ntilesout=ntilesout, tilesize=tilesize, overlap=overlap, k=k)
    plt.figure(figsize=(10, 5))
    plt.subplot(1, 2, 1)
    plt.title("Input Texture")
    plt.imshow(sample_image, cmap='gray')
    plt.axis('off')
    plt.subplot(1, 2, 2)
    plt.title("Synthesized Texture")
    plt.imshow(output, cmap='gray')
    plt.axis('off')
    plt.show()
# Load rock wall.jpg and test different parameters
default params = {'tilesize': (30, 30), 'overlap': 5, 'k': 5}
increased_tile = {'tilesize': (50, 50), 'overlap': 5, 'k': 5}
decreased_overlap = {'tilesize': (30, 30), 'overlap': 3, 'k': 5}
increased k = {'tilesize': (30, 30), 'overlap': 5, 'k': 10}
# Run tests
print("Default Parameters:")
run_texture_synthesis(image_path, **default_params)
print("Increased Tile Size:")
run_texture_synthesis(image_path, **increased_tile)
print("Increased K:")
run_texture_synthesis(image_path, **increased_k)
print("Decreased Overlap:")
run texture synthesis(image path, **decreased overlap)
```

```
Default Parameters:
library has ntiles = 138383 each with npix = 900
row:
0
1
2
3
4
5
6
7
8
9
```

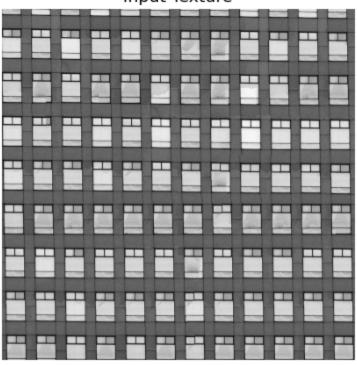
Input Texture

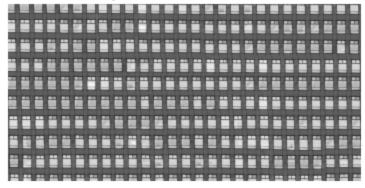




Increased Tile Size:
library has ntiles = 123903 each with npix = 2500
row:
0
1
2
3
4
5
6
7
8
9

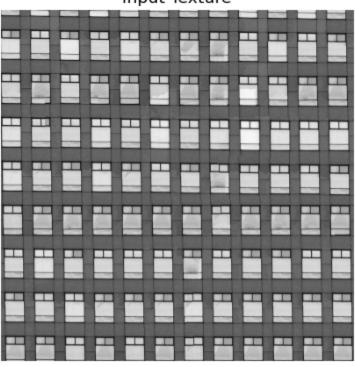
Input Texture

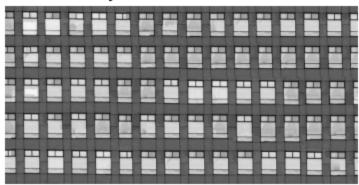




Increased K:
library has ntiles = 138383 each with npix = 900
row:
0
1
2
3
4
5
6
7
8
9

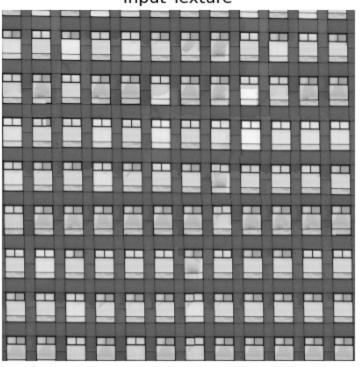
Input Texture





```
Decreased Overlap:
library has ntiles = 138383 each with npix = 900 row:
0
1
2
3
4
5
6
7
8
9
```

Input Texture



```
In [10]: #
    # load in yourimage2.jpg
    #
    # call quilt_demo, experiment with parameters as needed to get a good result
    #
```

```
# display your source image and the resulting synthesized texture
image path='flower.png'
def run_texture_synthesis(image_path, tilesize, overlap, k, ntilesout=(10, 20)):
    sample image = color.rgb2gray(plt.imread(image path))
    if (sample image.dtype == np.uint8):
        sample image = sample image.astype(float) / 256
    #sample image=plt.imread(image path)
    output = quilt demo(sample image, ntilesout=ntilesout, tilesize=tilesize, overlap=overlap, k=k)
    plt.figure(figsize=(10, 5))
    plt.subplot(1, 2, 1)
    plt.title("Input Texture")
    plt.imshow(sample_image, cmap='gray')
    plt.axis('off')
    plt.subplot(1, 2, 2)
    plt.title("Synthesized Texture")
    plt.imshow(output, cmap='gray')
    plt.axis('off')
    plt.show()
# Load rock wall.jpg and test different parameters
default params = {'tilesize': (30, 30), 'overlap': 5, 'k': 5}
increased_tile = {'tilesize': (50, 50), 'overlap': 5, 'k': 5}
decreased_overlap = {'tilesize': (30, 30), 'overlap': 3, 'k': 5}
increased k = {'tilesize': (30, 30), 'overlap': 5, 'k': 10}
# Run tests
print("Default Parameters:")
run_texture_synthesis(image_path, **default_params)
print("Increased Tile Size:")
run_texture_synthesis(image_path, **increased_tile)
print("Increased K:")
run_texture_synthesis(image_path, **increased_k)
print("Decreased Overlap:")
run texture synthesis(image path, **decreased overlap)
```

```
Default Parameters:
library has ntiles = 221841 each with npix = 900
row:
0
1
2
3
4
5
6
7
8
```

Input Texture

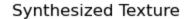


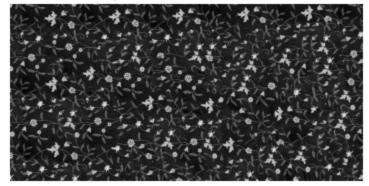


```
Increased Tile Size:
library has ntiles = 203401 each with npix = 2500
row:
0
1
2
3
4
5
6
7
8
```

Input Texture







9

```
Increased K:
library has ntiles = 221841 each with npix = 900
row:
0
1
2
3
4
5
6
7
8
```

Input Texture



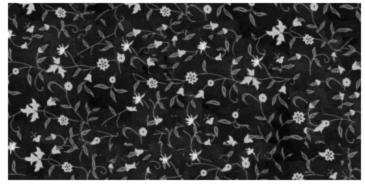


```
Decreased Overlap:
library has ntiles = 221841 each with npix = 900 row:
0
1
2
3
4
5
6
7
8
9
```

Input Texture



Synthesized Texture



In []:

In []: