

# Assignment 4

---

Student ID: 120090645    Name: Haopeng Chen

## Extra Credit

---

Extra work for `support boundary split` and `support mesh with boundary` is finished, and will be elaborated in the following.

## Details

---

### Task 1

The *de Casteljau's Algorithm* is given  $m$  points with identical dimensions (i.e., `Vector2D` or `Vector3D`) and a ratio  $t$ , using the `lerp()` function (i.e.  $p_{\text{new}} = \text{lerp}(p_i, p_{i+1}, t) = (1 - t)p_i + tp_{i+1}$ ), to convert them to  $m - 1$  points. And repeat this step until the result is one point.

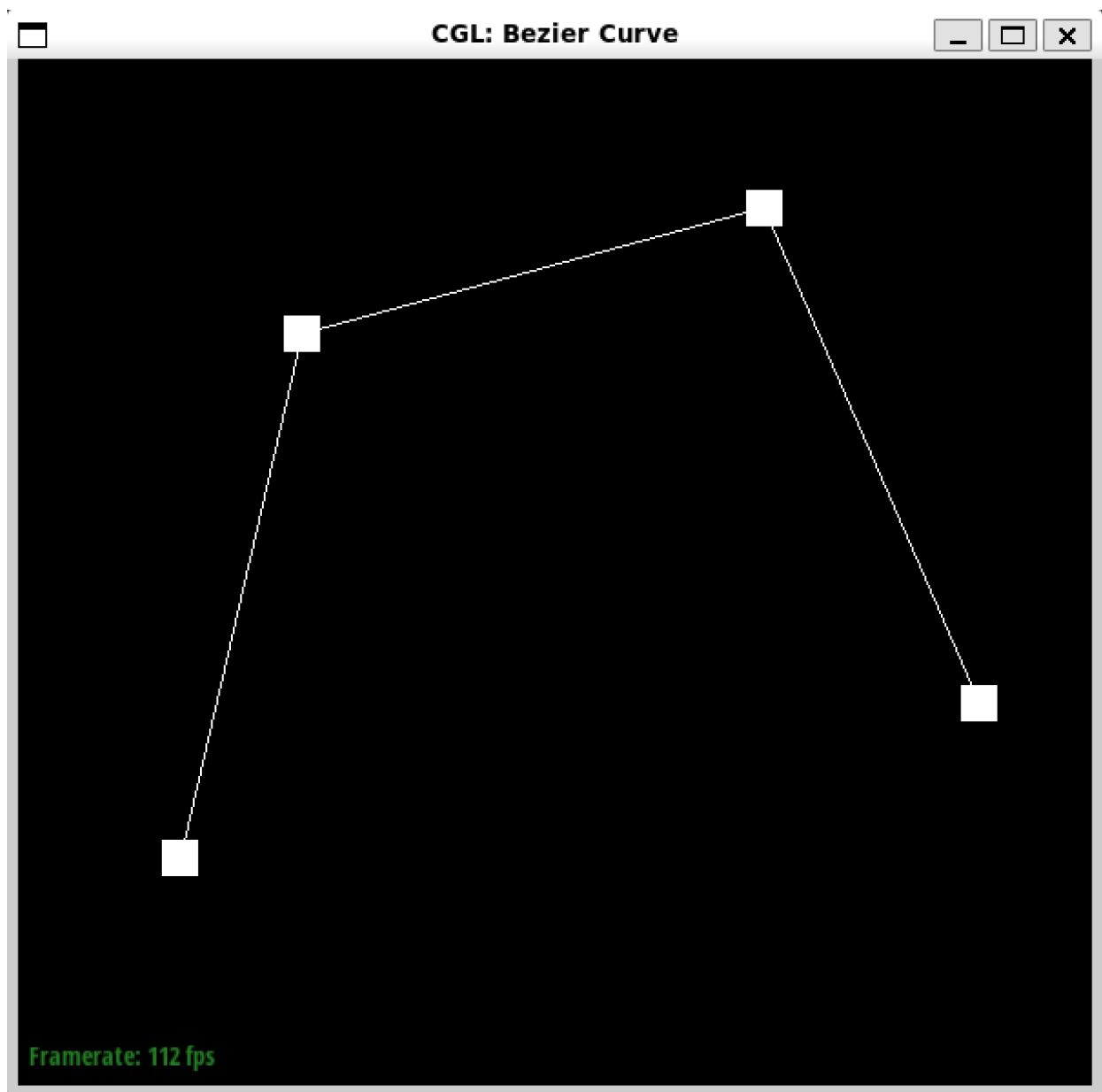
### Implement

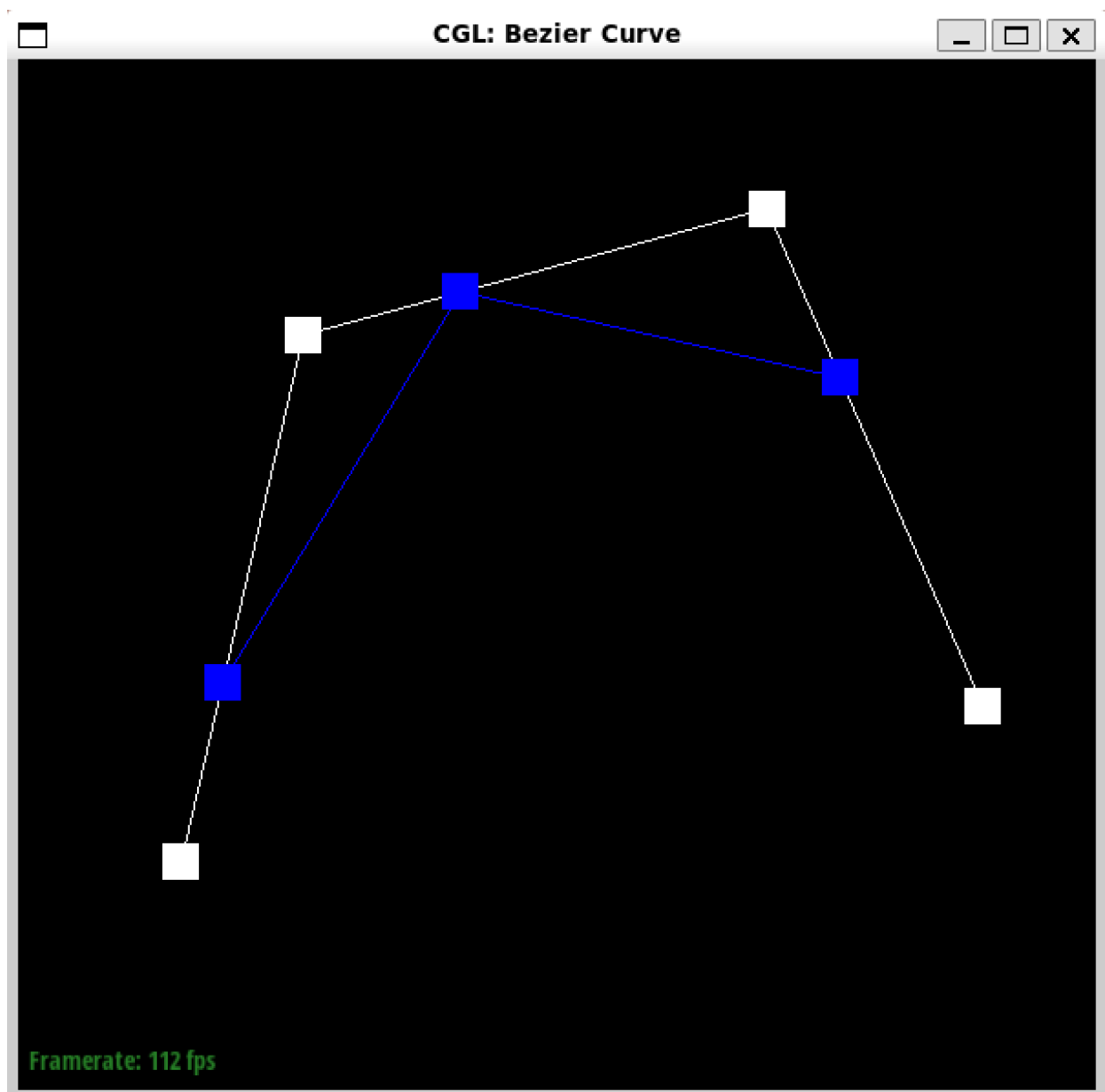
First traverse the input, applying the `lerp()` function on every two neighboring points and push the result to a `vector`. Finally return this `vector`. Do this recursively to get one point.

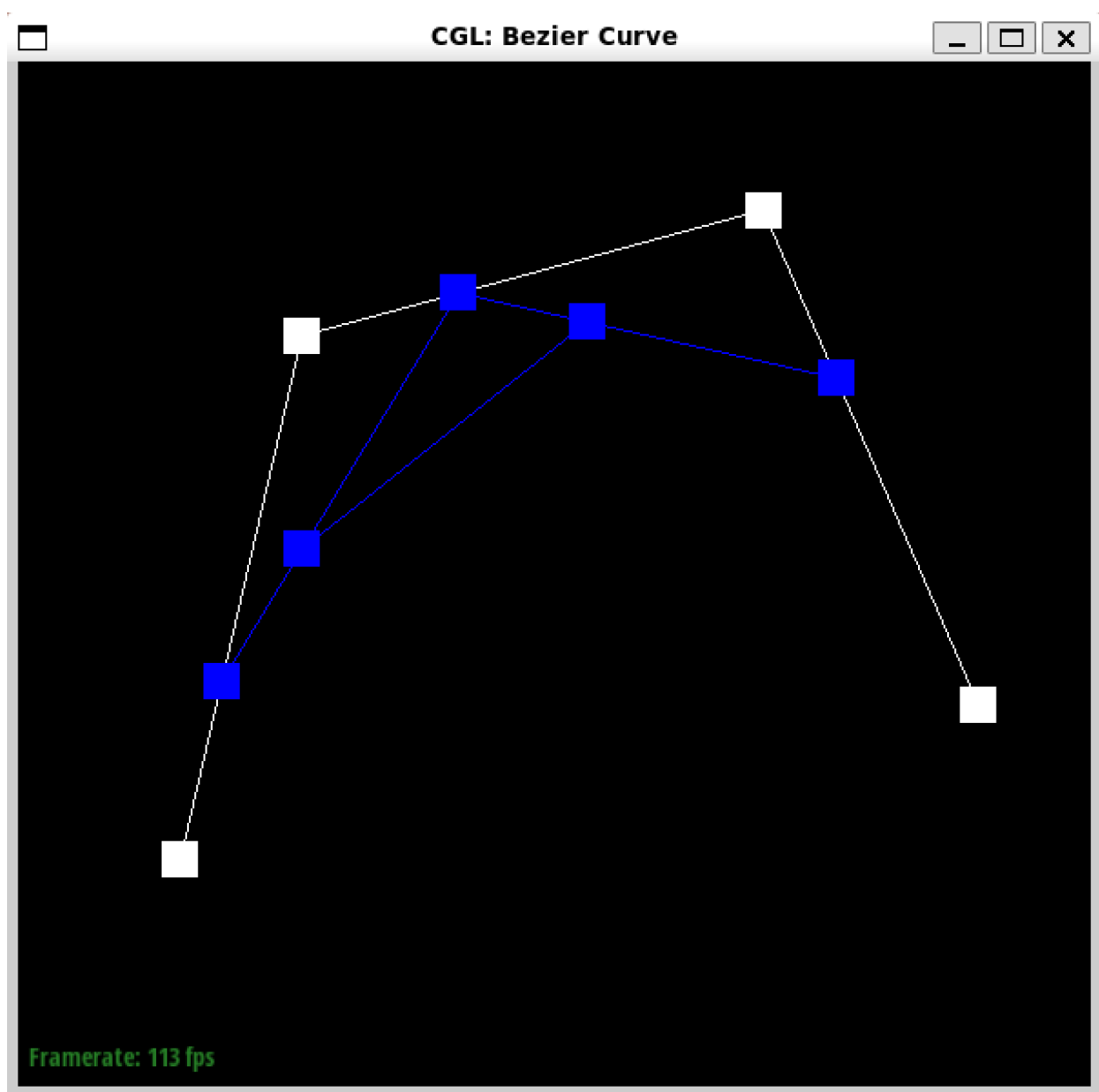
#### `lerp()` implementation in 2D

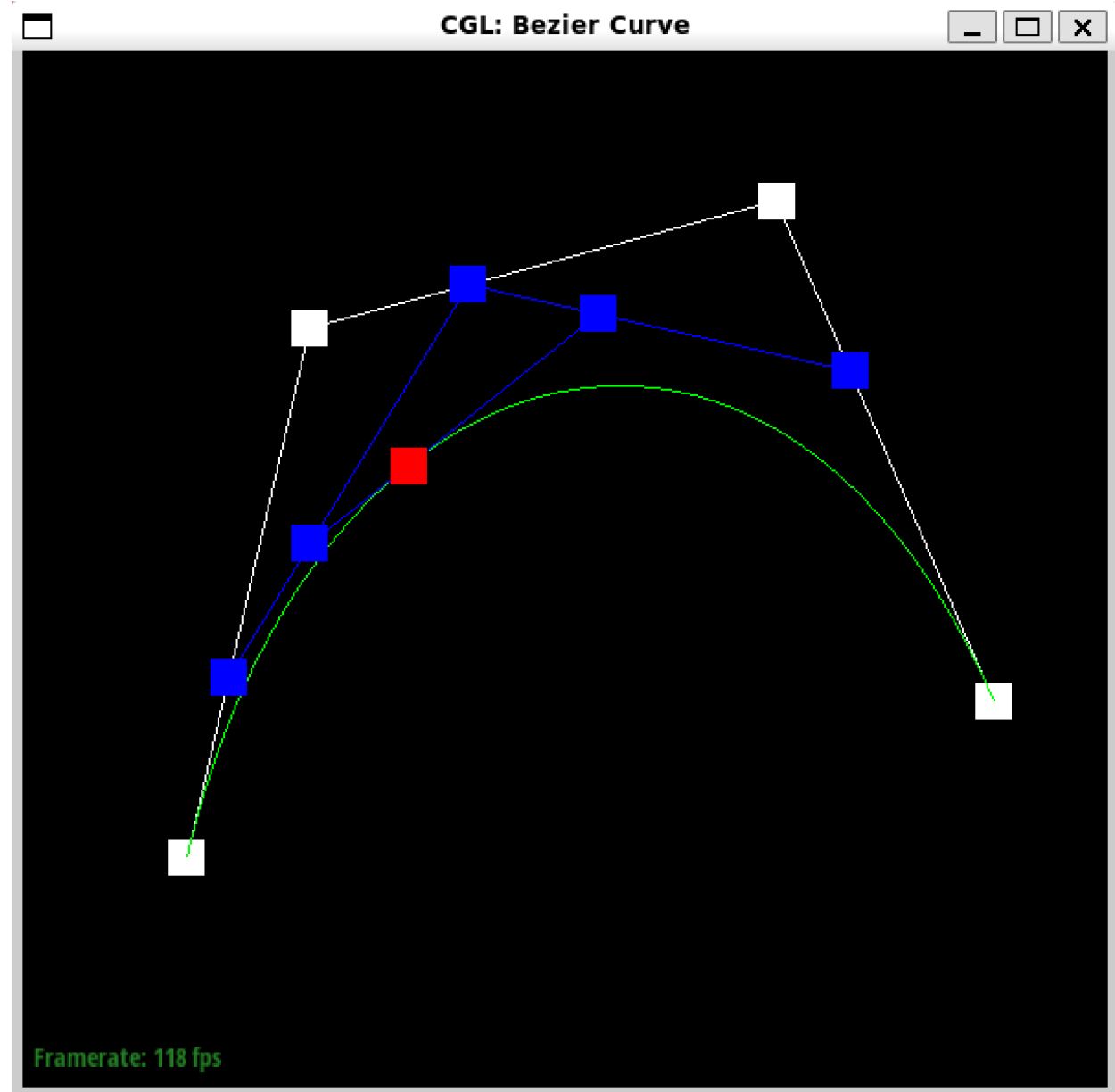
```
1 | Vector2D lerp(const Vector2D& point1, const Vector2D& point2, double ratio)
2 | {
3 |     return (1 - ratio) * point1 + ratio * point2;
4 | }
```

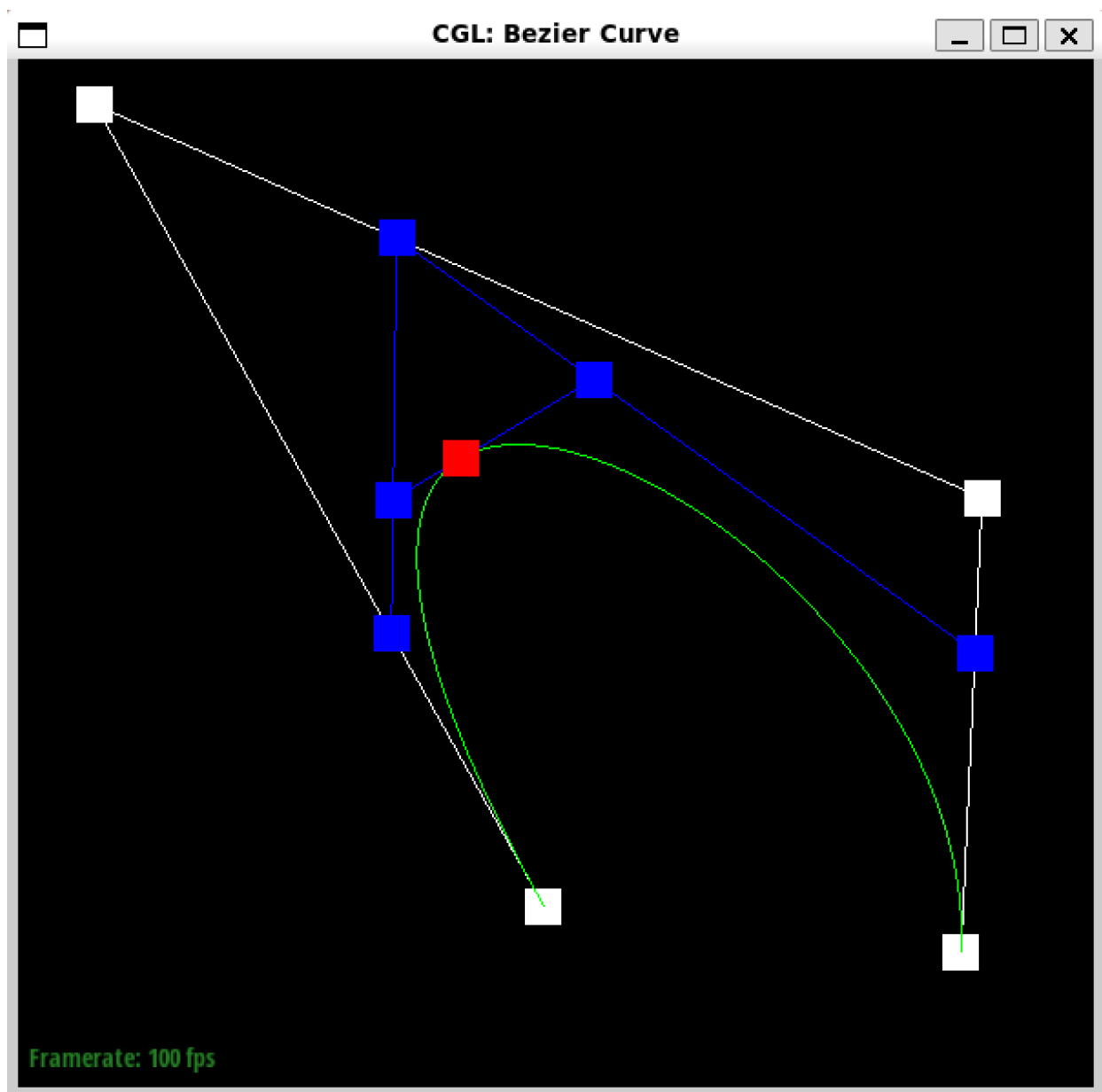
### Result











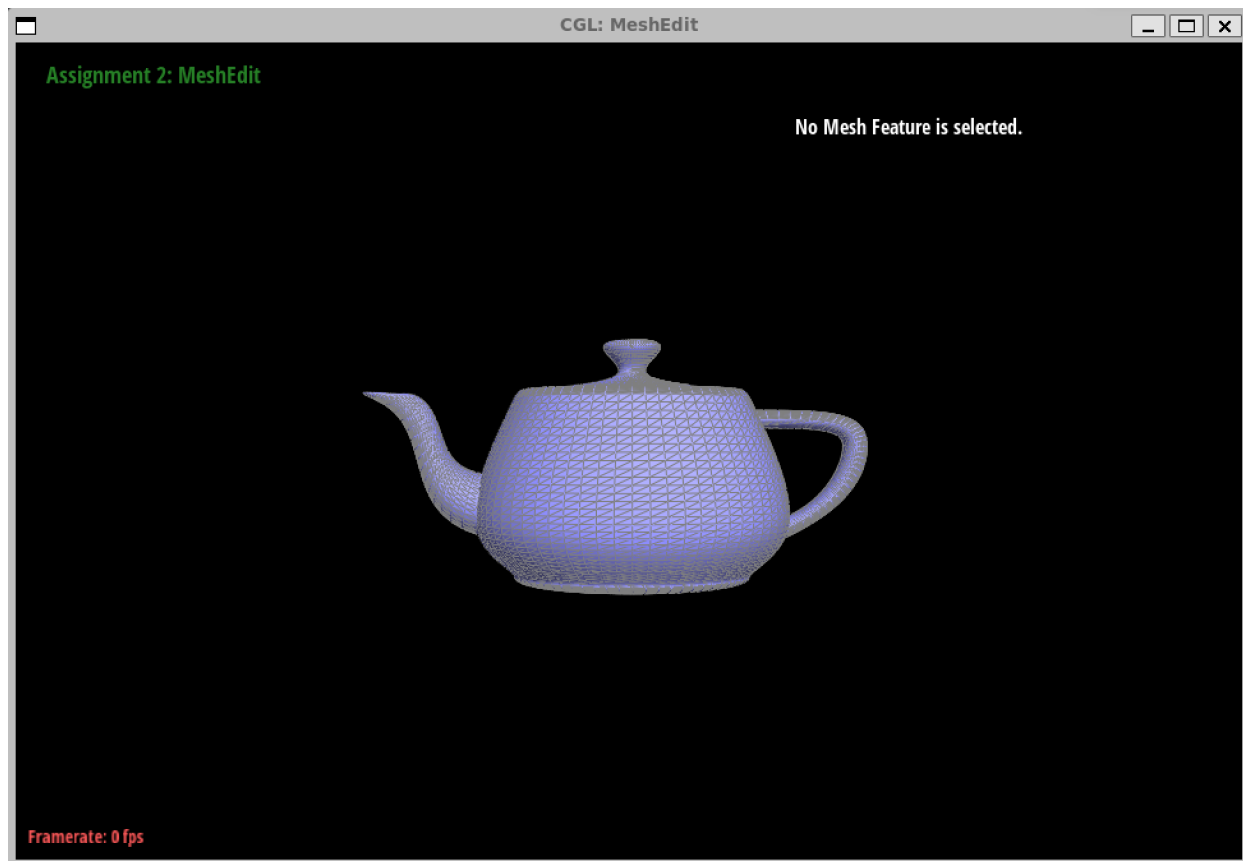
## Task 2

Through *de Casteljau Algorithm*, we can get a Bezier point finally. Bezier surface can be seen as a list of Bezier curves with identical points. By evaluate horizontal Bezier curves separately and collect the outcome we get a vertical Bezier curve, then evaluate this curve by *de Casteljau Algorithm* we can get the Bezier surface.

### lerp() implementation in 3D

```
1 Vector3D lerp(const Vector3D& point1, const Vector3D& point2, double ratio)
2 {
3     return (1 - ratio) * point1 + ratio * point2;
4 }
```

## Result

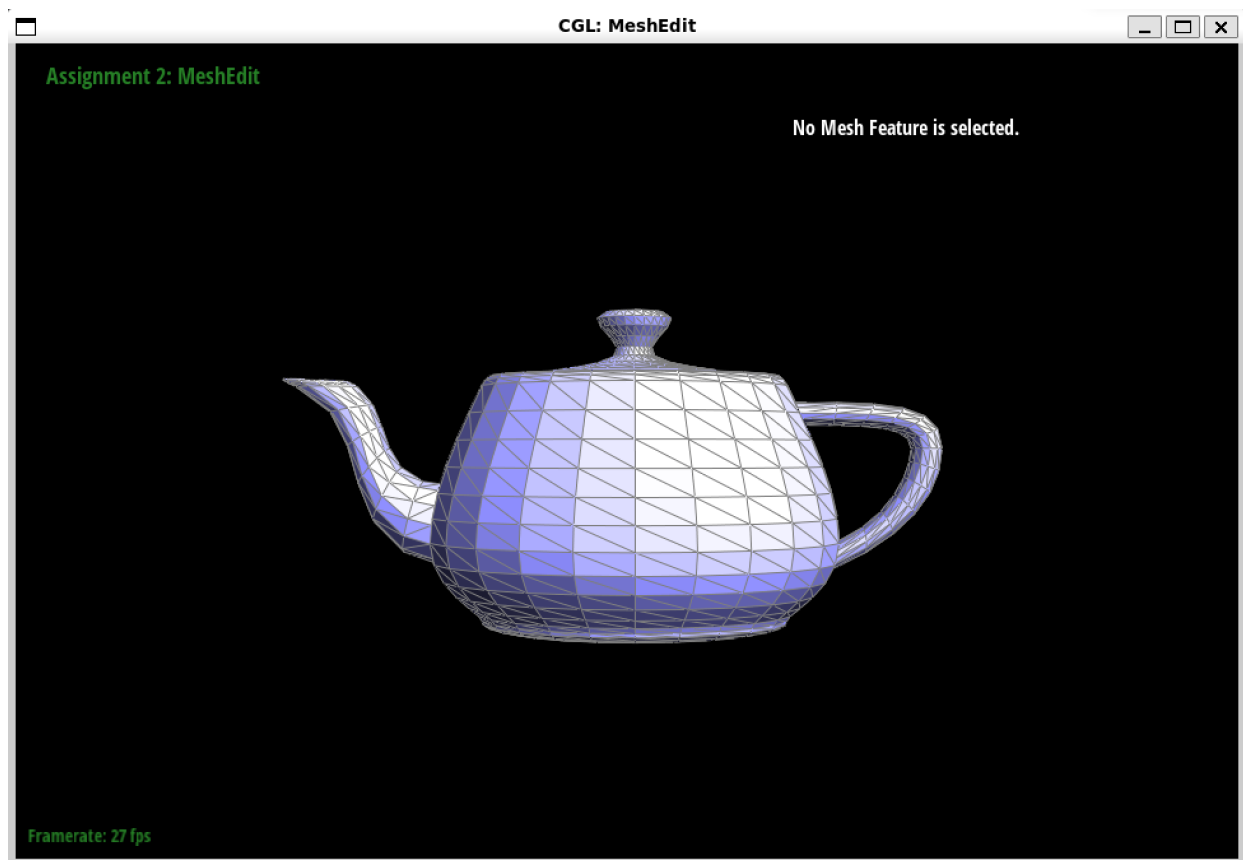


## Task 3

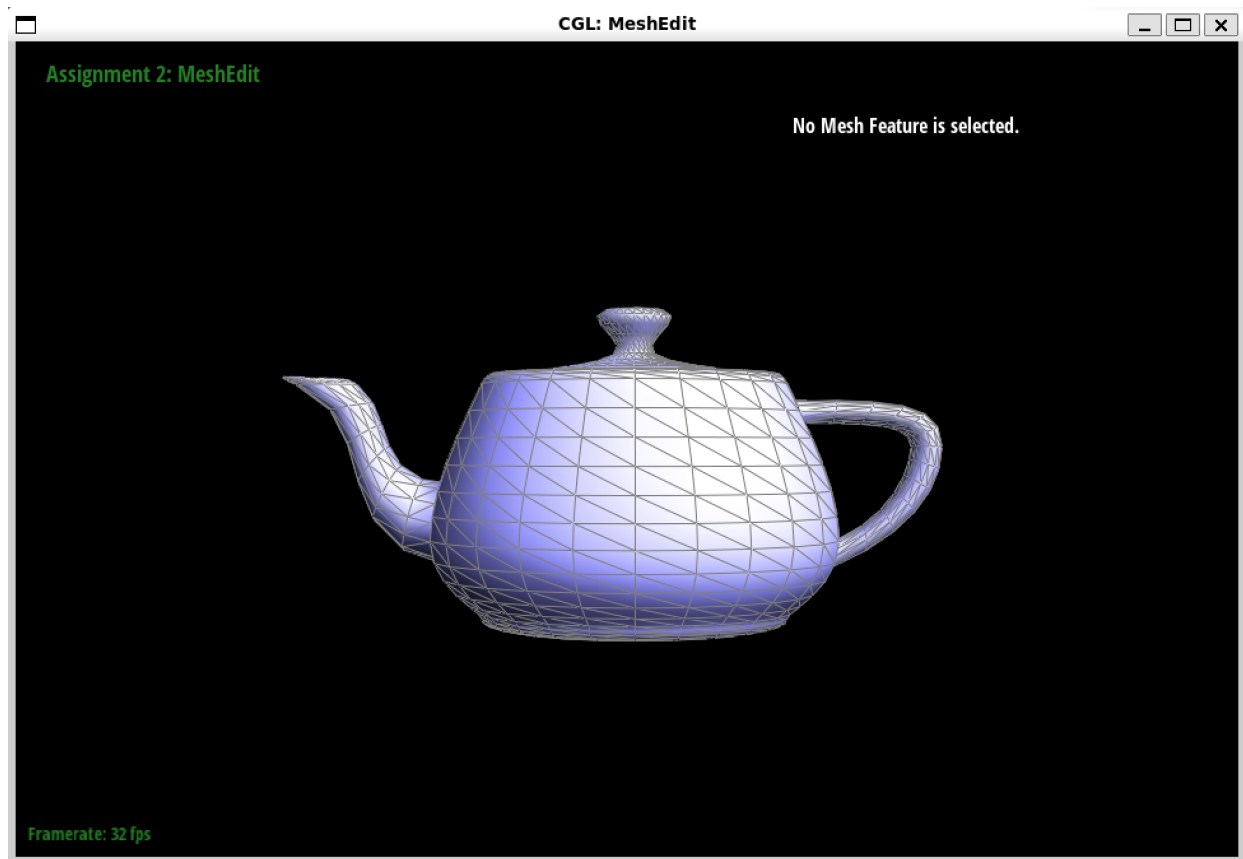
The vertex normal is calculated by area weighted surrounding faces' normal. The face normal is provided. The face area can be calculated by `0.5 * cross(a, b).norm()`, add the weighted face normal to result and normalize the result, we get the vertex normal.

## Result

*flat shading*



### Phong shading

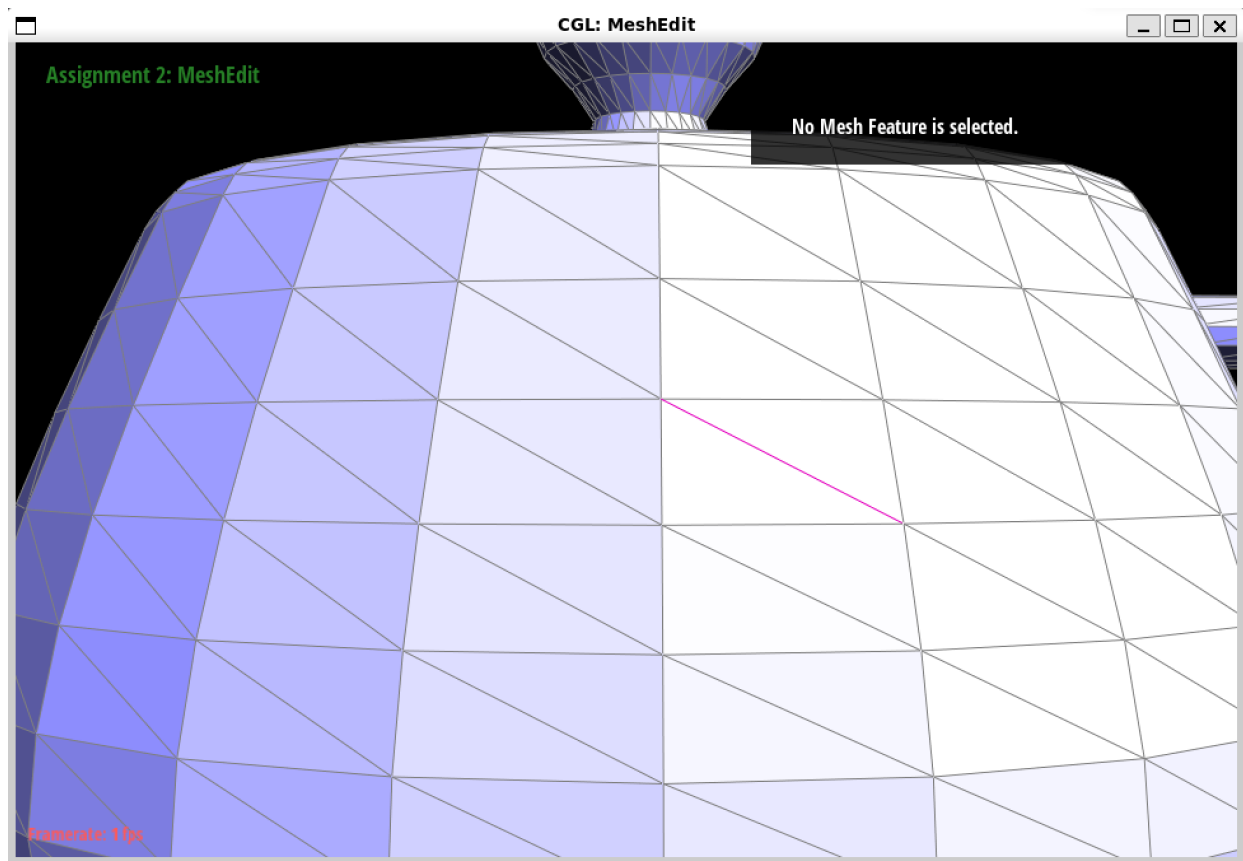


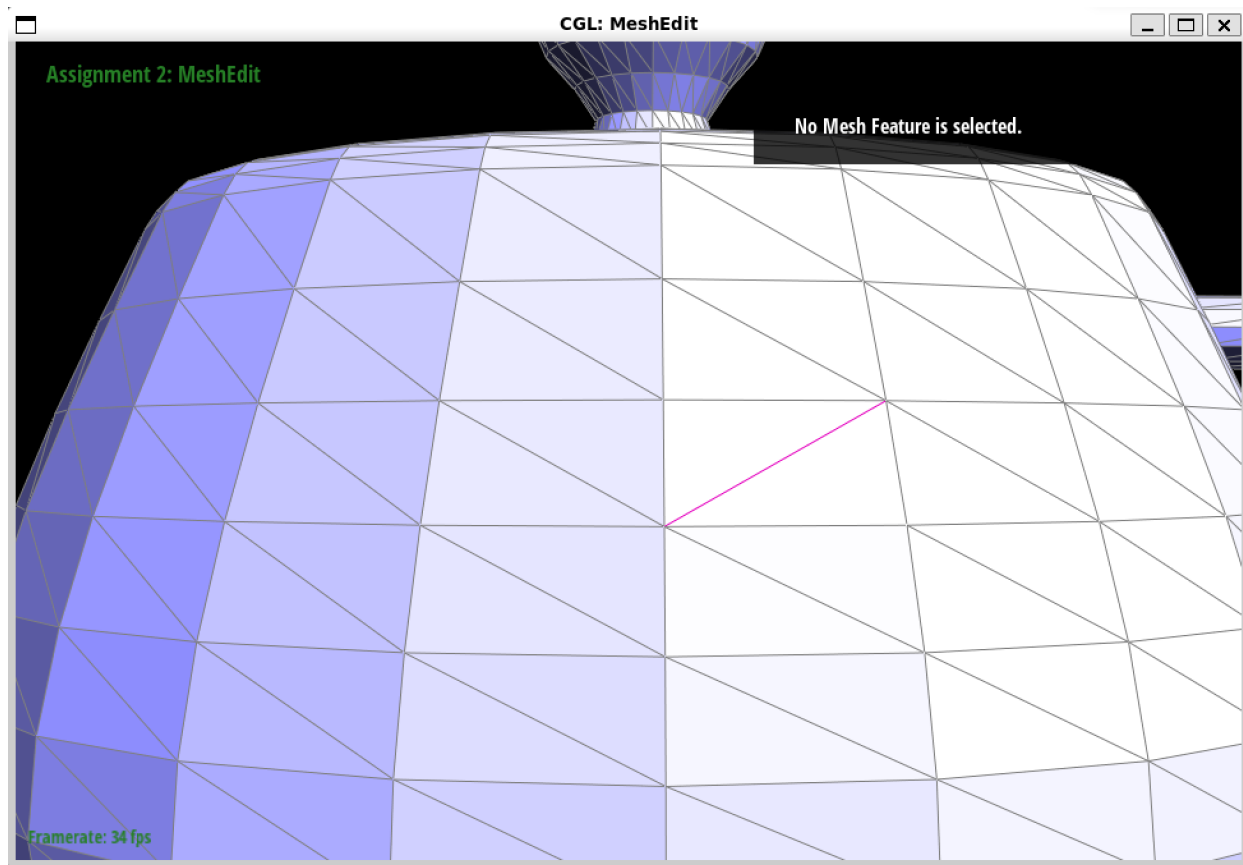


## Task 4

If the selected edge is on the boundary, do nothing. Otherwise, we should access the twin and all relevant vertices and edges, and map them into corresponding members.

## Result



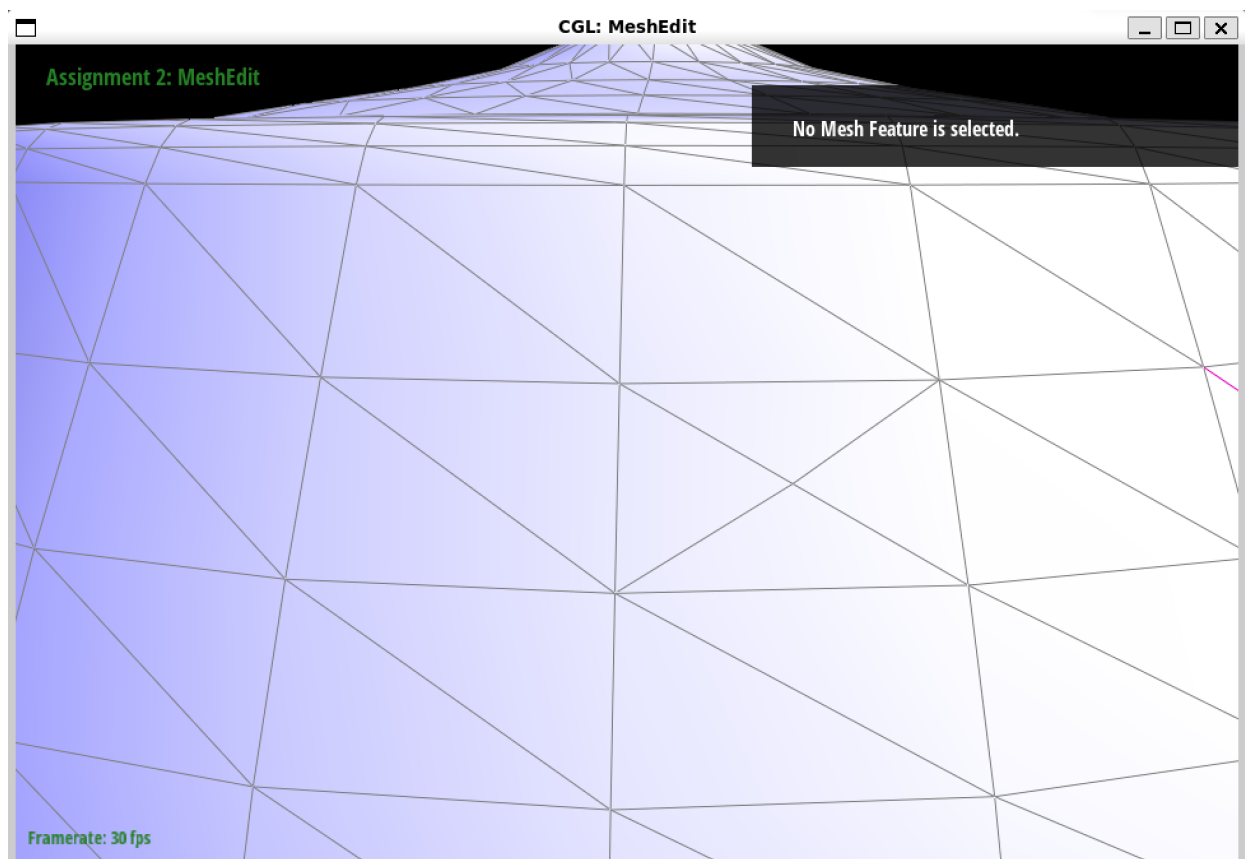
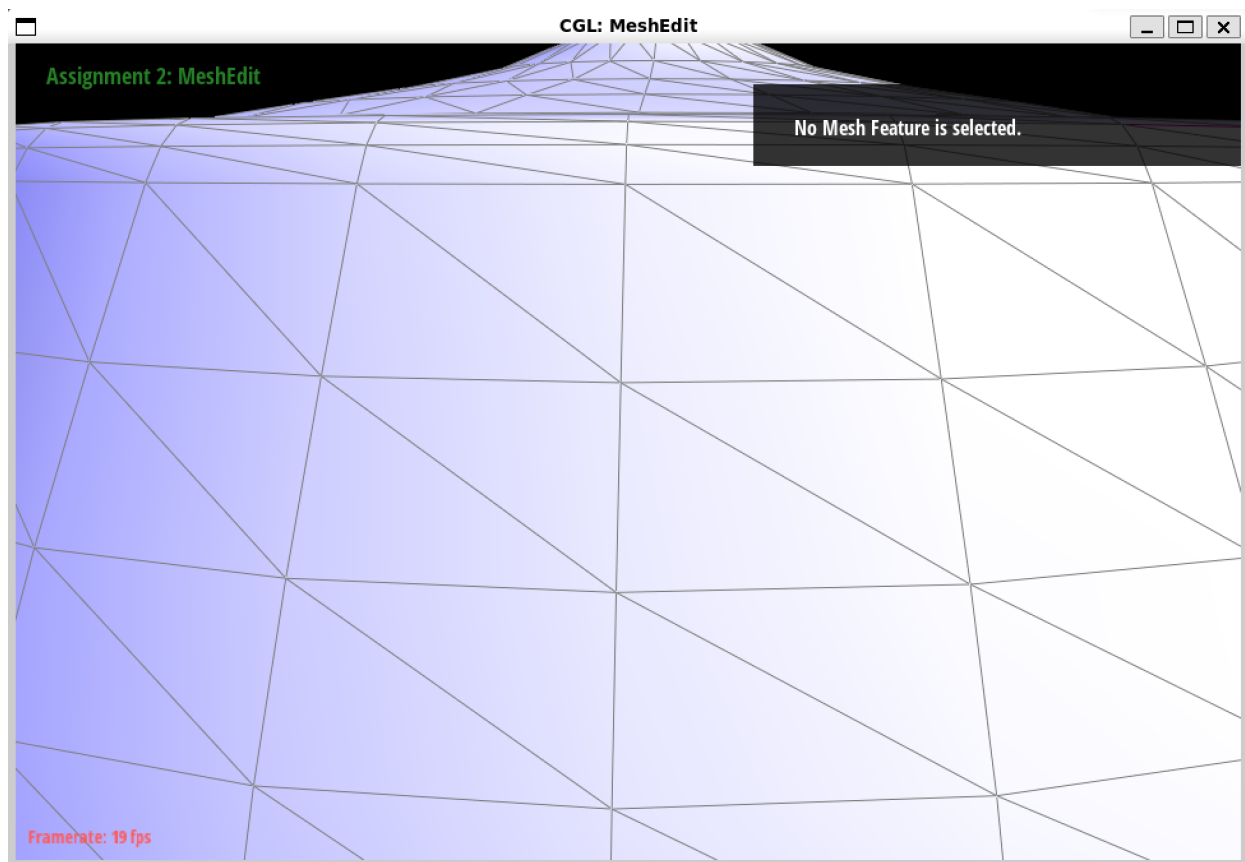


## Task 5

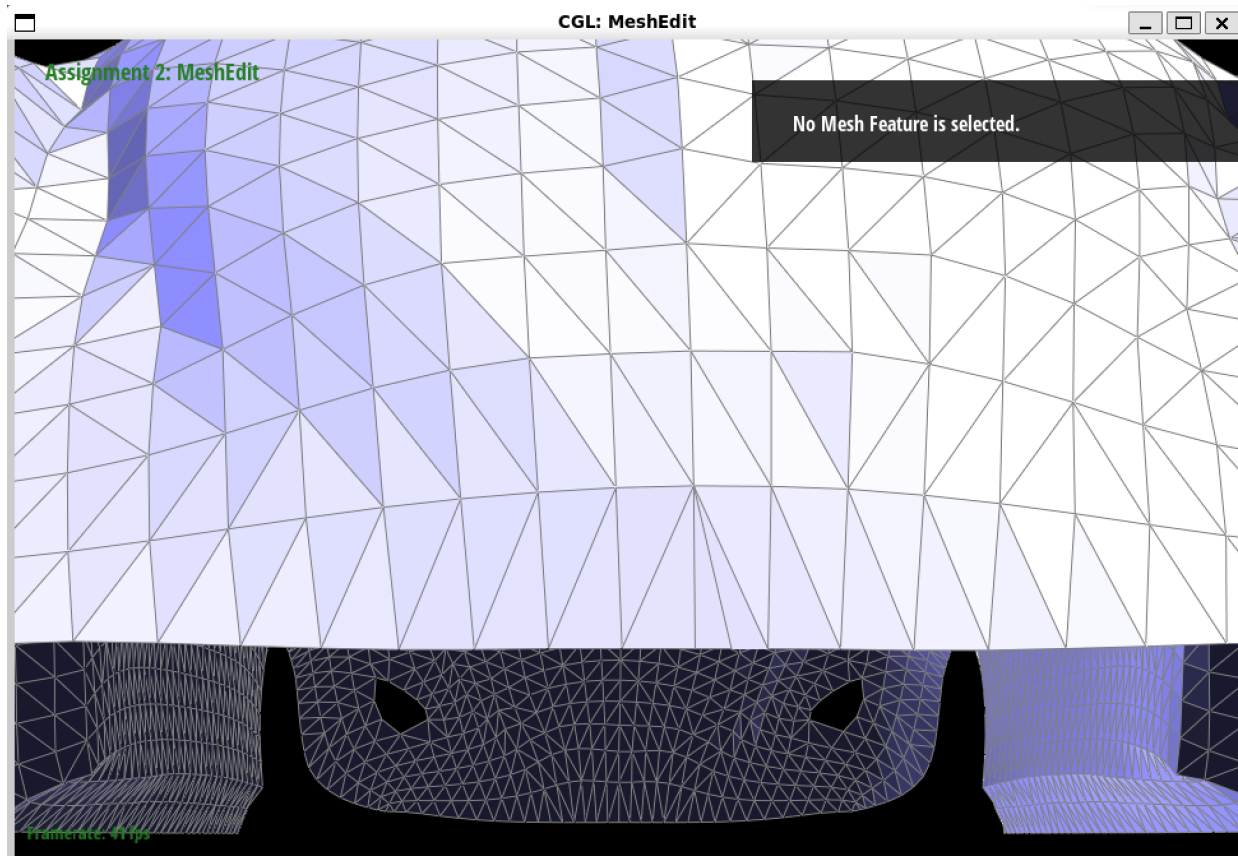
For interior, First we get the old mesh elements may need to change: `e0, v0, v1, v2, v3, f1, f2, h1, h2, h1_1, h1_2, h2_1, h2_2`, then create new mesh elements `e2-e4, f3-f4, h3-h8, m` using given `new()` function. If `e0->isNew`, we just set the position of `m` to `e0->newPosition`, if not, set the position of `m` to midpoint of `e0`. Then based on the above diagram, set the relationship of mesh elements.

## Result

*inferior split*



***boundary split***

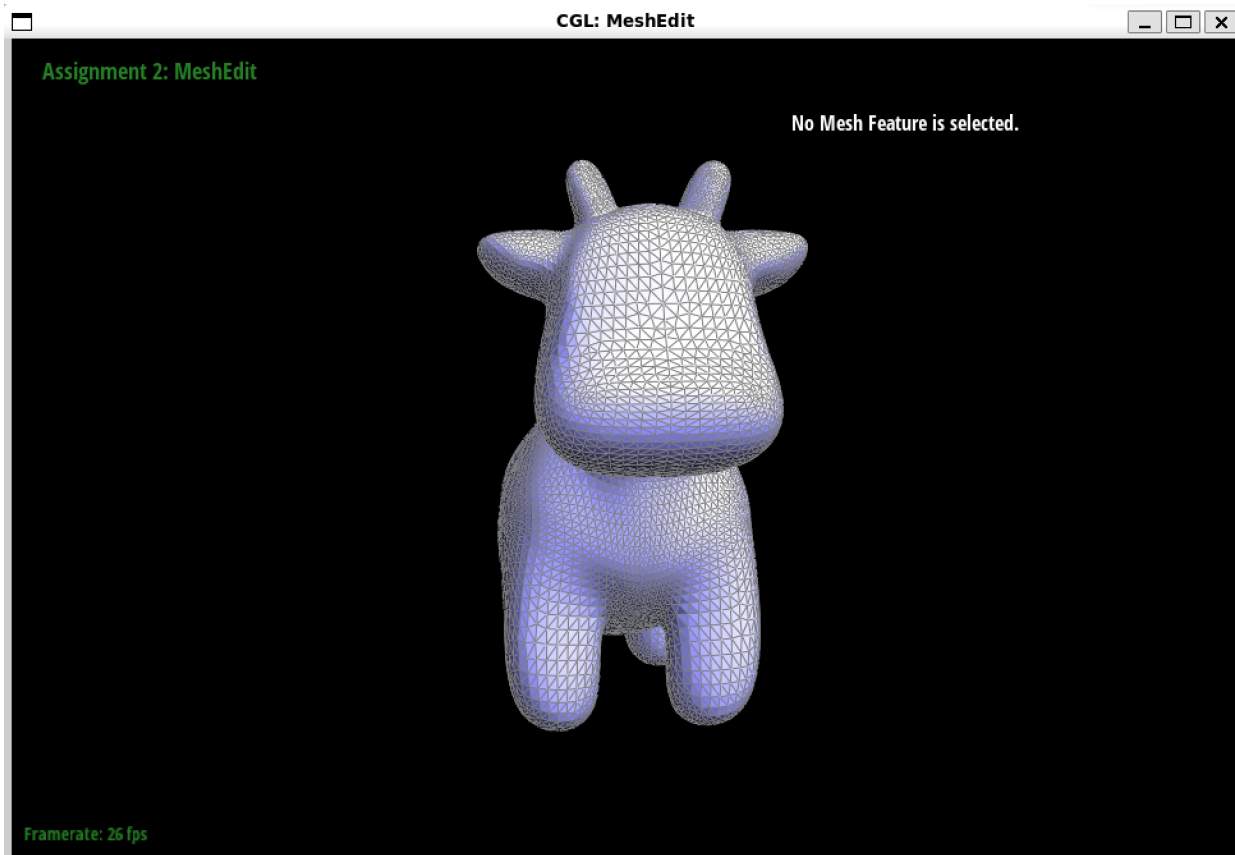
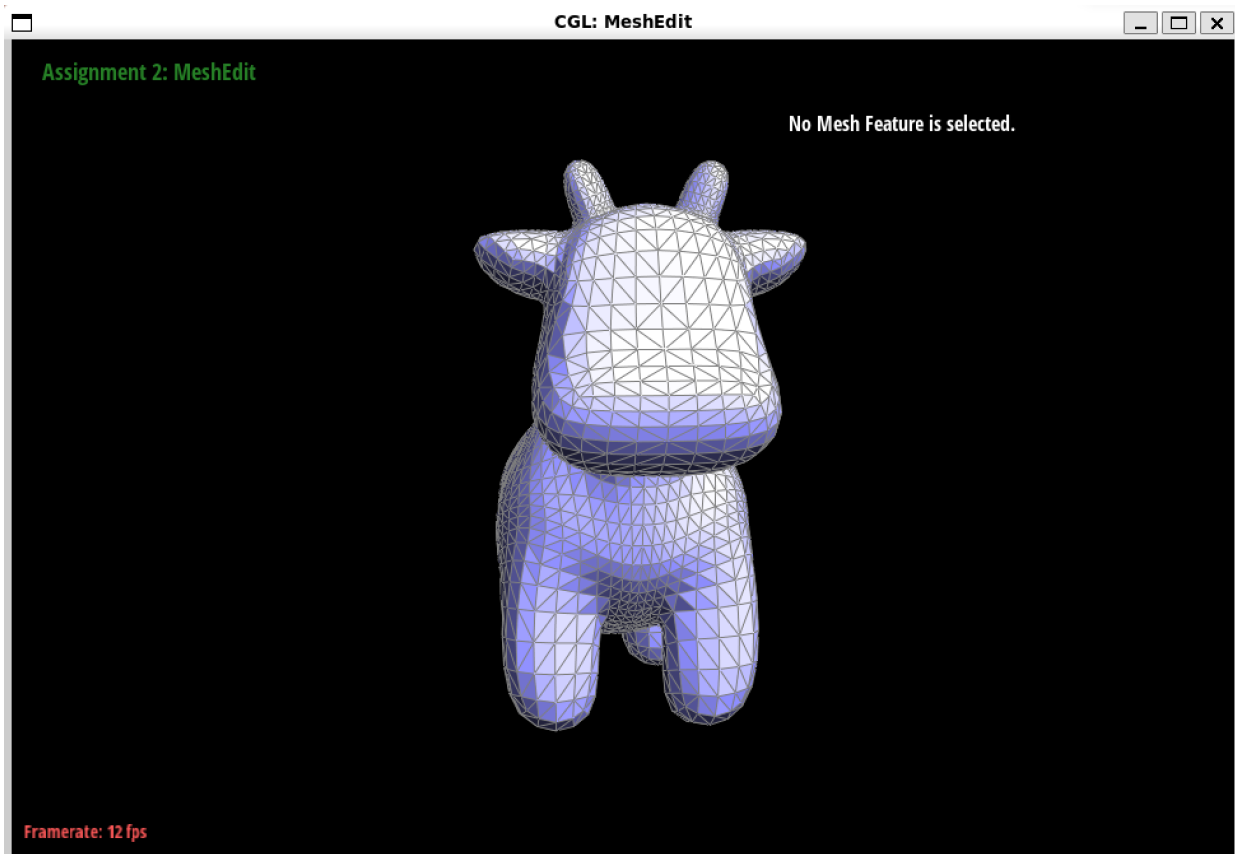


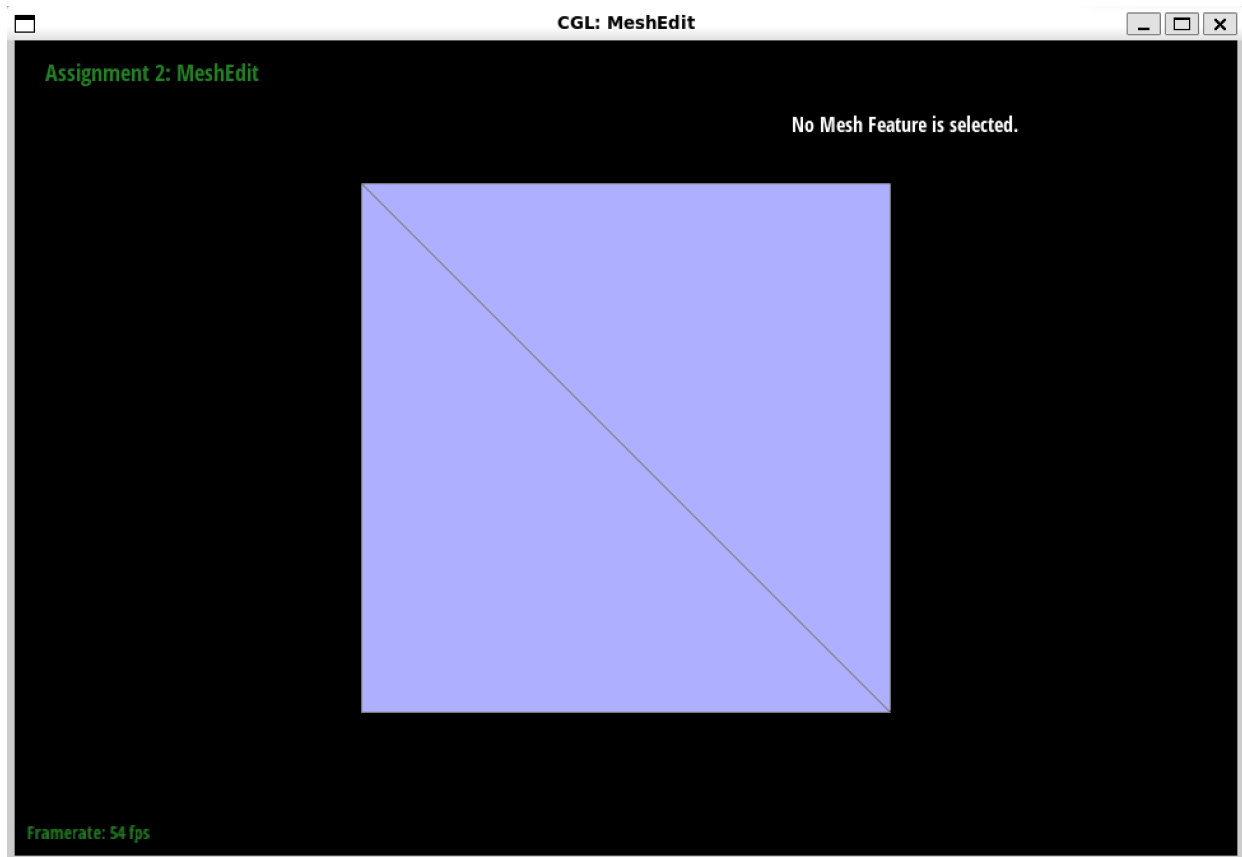
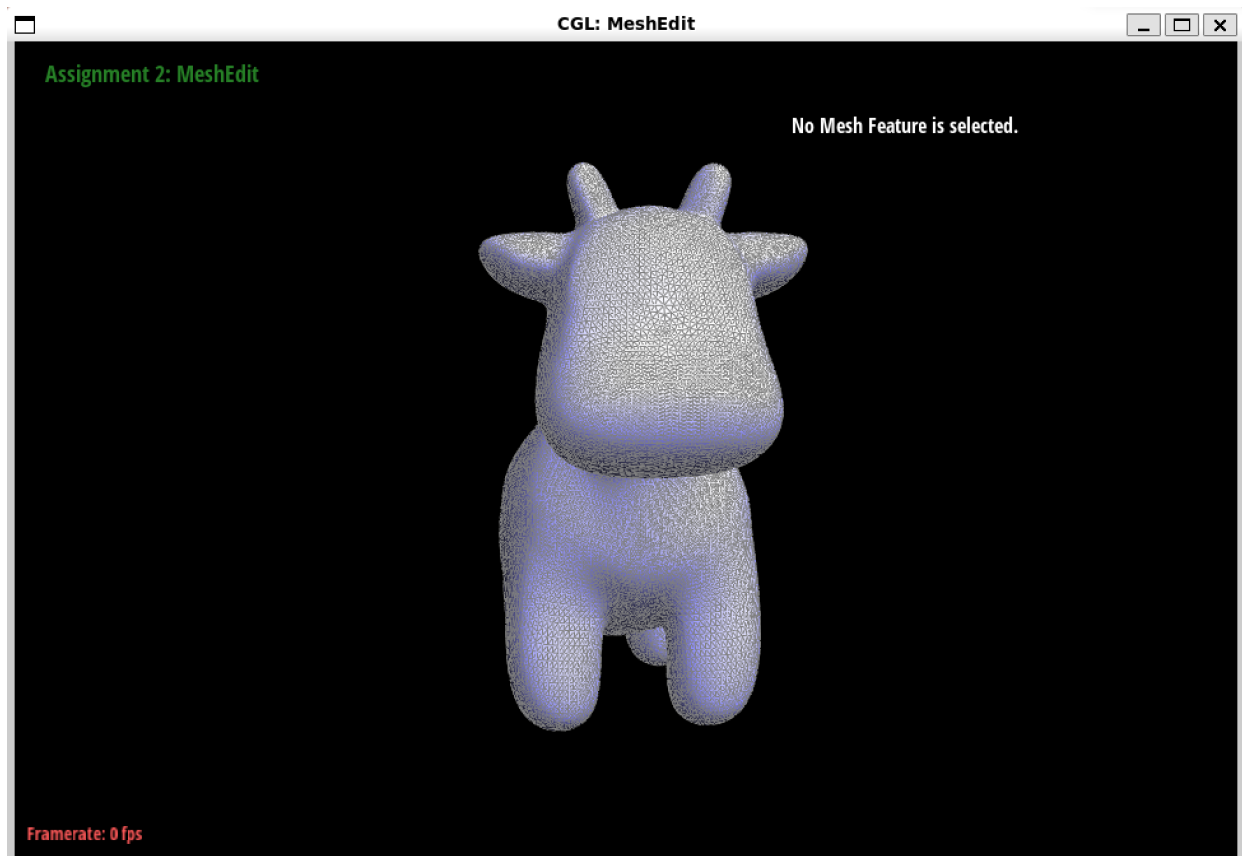
## Task 6

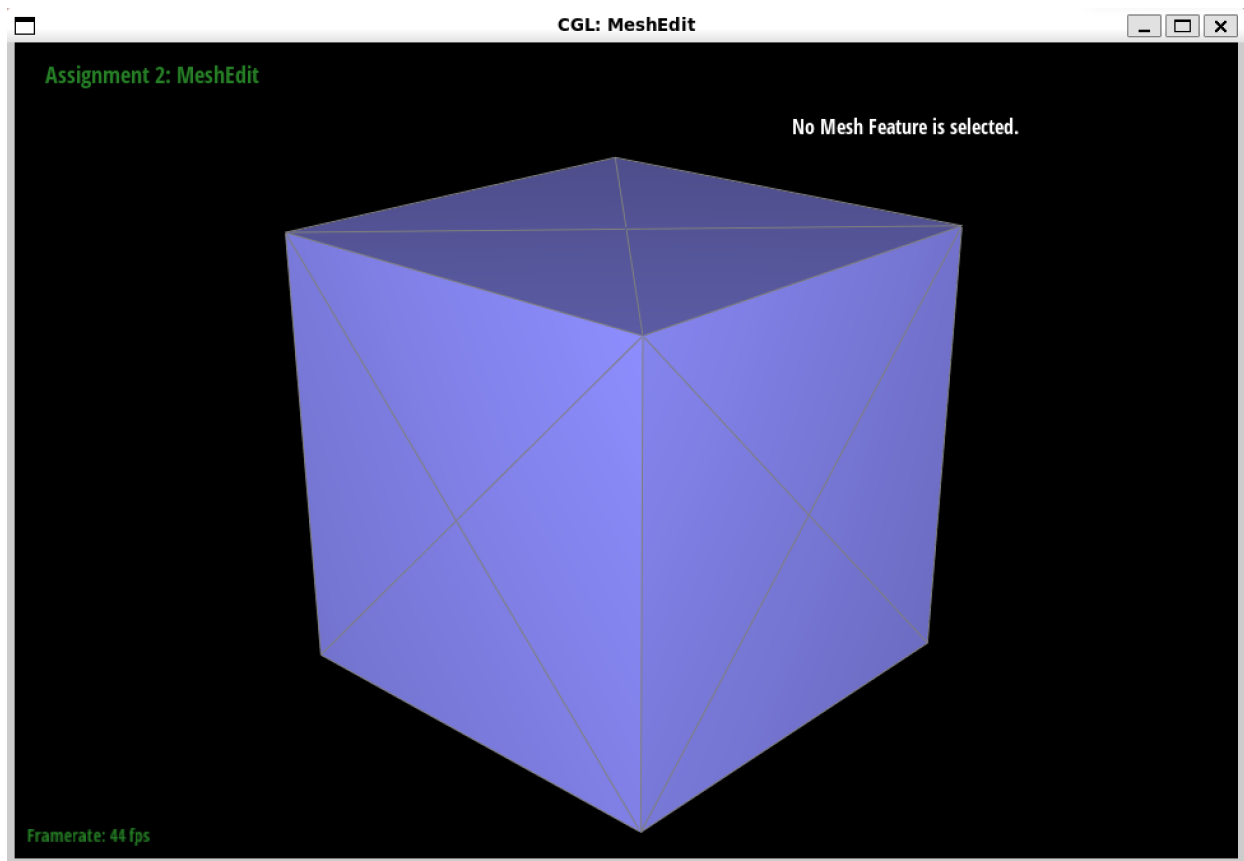
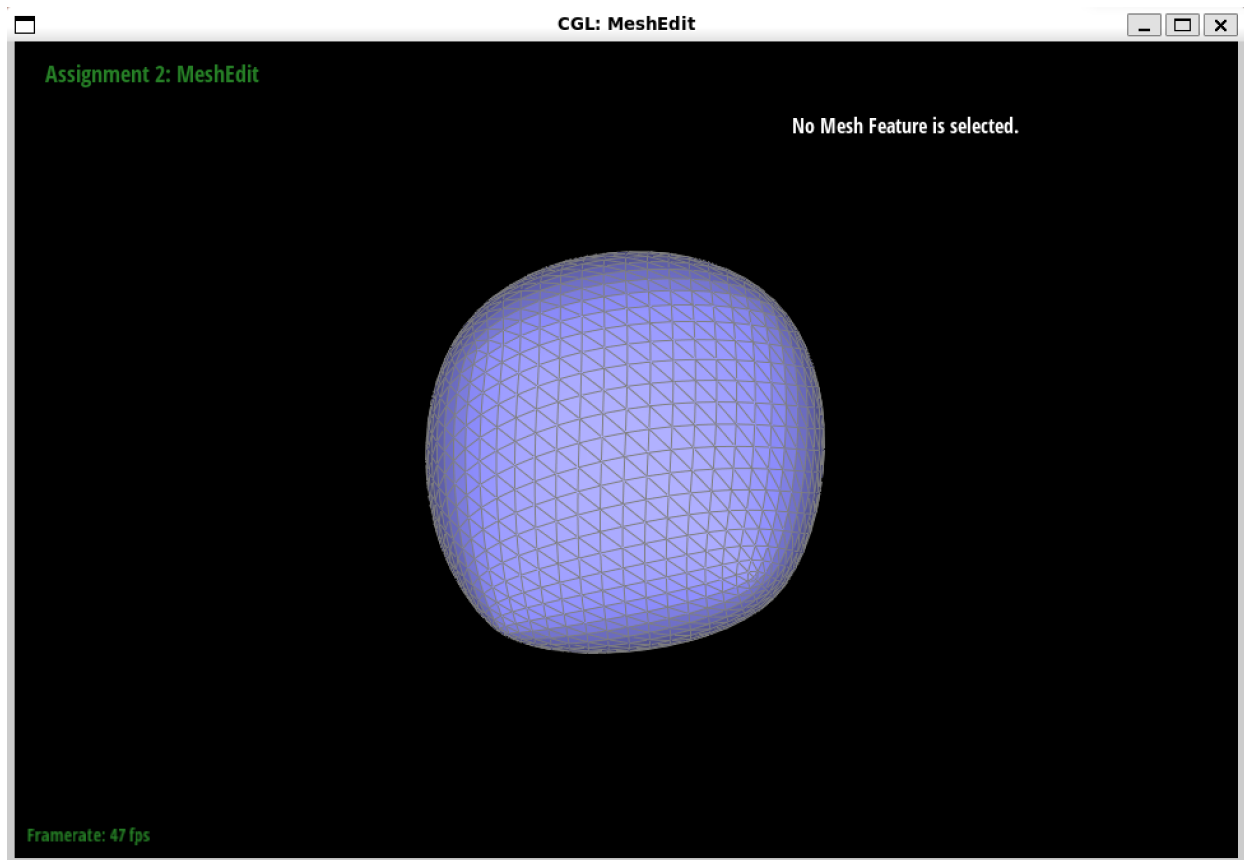
To implement this task: First we calculate the new position for old vertices.  $v \rightarrow \text{newPosition} = (1 - n \cdot u) \cdot v \rightarrow \text{position} + u \cdot \text{sum\_surrounding}$ ,  $\text{sum\_surrounding}$  is the sum of positions of neighboring points position. Then we calculate the position of new points by  $e \rightarrow \text{newPosition} = 0.125 \cdot (\text{sum\_v\_neighbor\_position}) + 0.375 \cdot (\text{sum\_v\_on\_position})$  and store the position to  $e \rightarrow \text{newPosition}$ . Then we call the `splitEdge()` function and set the value of new vertices, half\_edges, edges, faces. Then for each new created edge, if it connects one old vertex and one new vertex, `flip()` it. Finally we set the old vertices position to new position.

For mesh with boundary, the new position of boundary old vertices is  $v \rightarrow \text{newPosition} = 0.75 \cdot v \rightarrow \text{position} + 0.125 \cdot \text{sum\_two\_surrounding}$ ,  $\text{sum\_two\_surrounding}$  is the sum of position of neighbor boundary vertices. the position of new boundary vertex is  $e \rightarrow \text{newPosition} = 0.5 \cdot (v1 \rightarrow \text{position} + v2 \rightarrow \text{position})$ ,  $v1, v2$  are the vertices of edge.

## Result







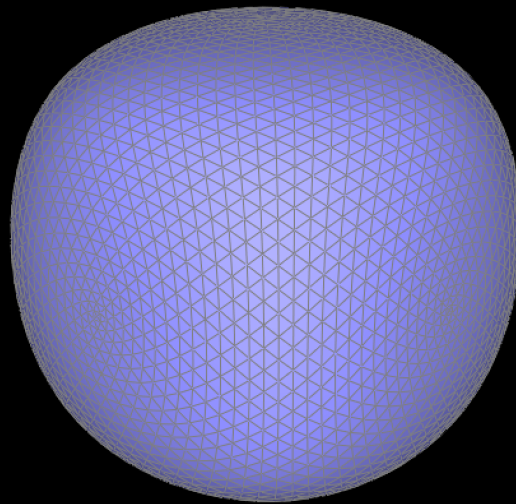


CGL: MeshEdit



Assignment 2: MeshEdit

No Mesh Feature is selected.



Framerate: 34 fps