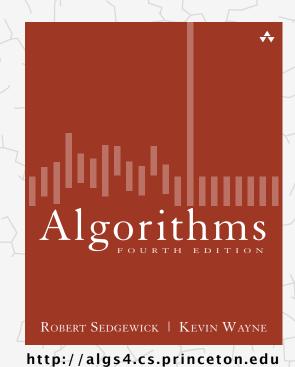
Algorithms



LINEAR PROGRAMMING

- brewer's problem
- simplex algorithm
- implementations
- reductions

Linear programming

What is it? Problem-solving model for optimal allocation of scarce resources, among a number of competing activities that encompasses:

• Shortest paths, maxflow, MST, matching, assignment, ...



• Ax = b, 2-person zero-sum games, ...

maximize	13A	+	23B		
subject	5A	+	15B	≤	480
to the	4A	+	4B	≤	160
constraints	35A	+	20B	≤	1190
	Α	,	В	≥	0

Why significant?

- Fast commercial solvers available.
- Widely applicable problem-solving model.
 Ex: Delta claims that LP saves \$100 million per year.
- Key subroutine for integer programming solvers.

Applications

Agriculture. Diet problem.

Computer science. Compiler register allocation, data mining.

Electrical engineering. VLSI design, optimal clocking.

Energy. Blending petroleum products.

Economics. Equilibrium theory, two-person zero-sum games.

Environment. Water quality management.

Finance. Portfolio optimization.

Logistics. Supply-chain management.

Management. Hotel yield management.

Marketing. Direct mail advertising.

Manufacturing. Production line balancing, cutting stock.

Medicine. Radioactive seed placement in cancer treatment.

Operations research. Airline crew assignment, vehicle routing.

Physics. Ground states of 3-D Ising spin glasses.

Telecommunication. Network design, Internet routing.

Sports. Scheduling ACC basketball, handicapping horse races.

Algorithms

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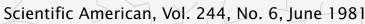
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Allocation of Resources by Linear Programming by Robert Bland

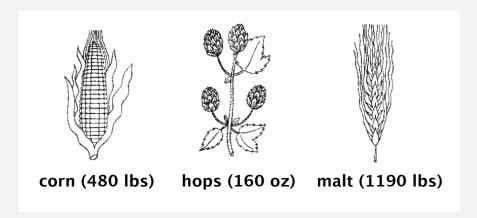
SCIENTIFIC AMERICAN



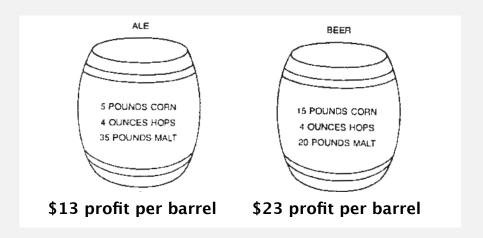
Toy LP example: brewer's problem

Small brewery produces ale and beer.

Production limited by scarce resources: corn, hops, barley malt.



• Recipes for ale and beer require different proportions of resources.



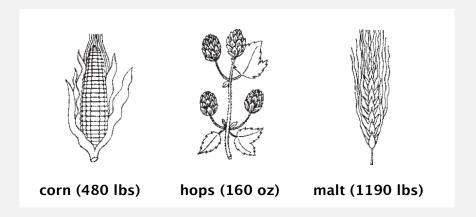
Toy LP example: brewer's problem

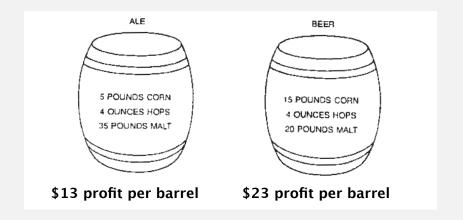
Brewer's problem: choose product mix to maximize profits.

34 barrels × 35 lbs malt = 1190 lbs [amount of available malt]

ale	beer	corn	hops	malt	profit
34	0	179	136	1190	\$442
0	32	480	128	640	\$736
19.5	20.5	405	160	1092.5	\$725
12	28	480	160	980	\$800
?	?				> \$800 ?

goods are divisible (ok to produce fractional barrels)



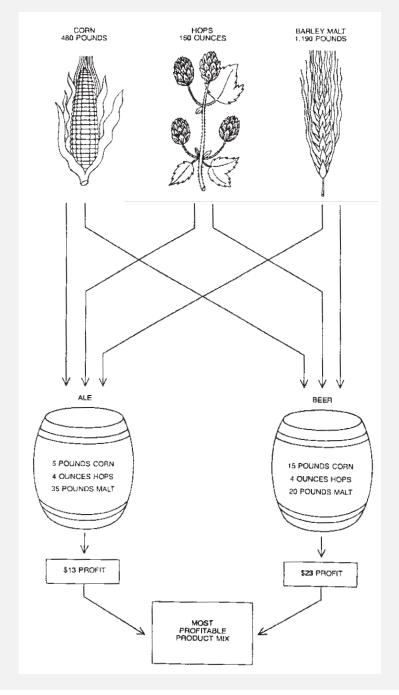


Brewer's problem: linear programming formulation

Linear programming formulation.

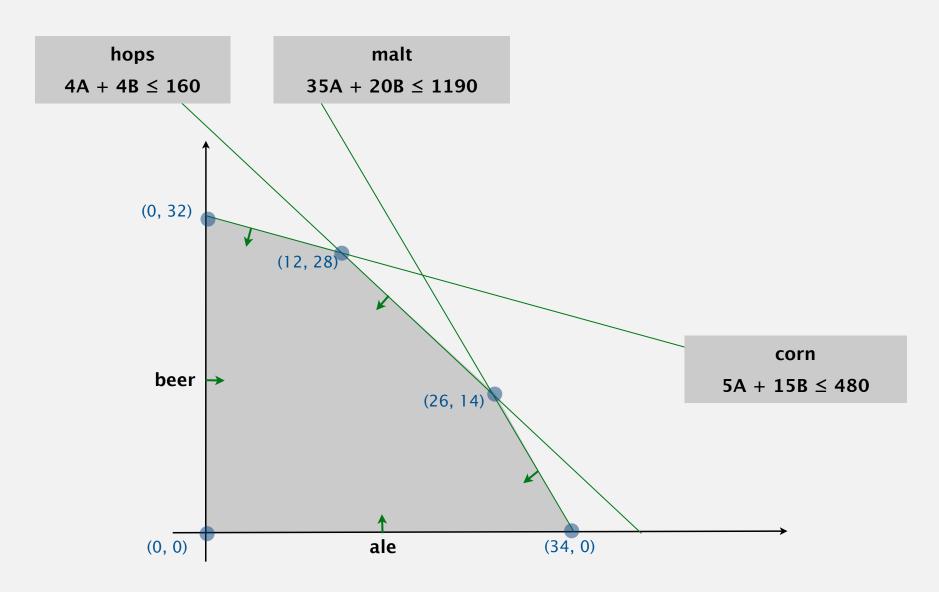
- Let *A* be the number of barrels of ale.
- Let *B* be the number of barrels of beer.

	ale		beer			
maximize	13A	+	23B			profits
subject	5A	+	15B	≤	480	corn
to the	4A	+	4B	≤	160	hops
constraints	35A	+	20B	≤	1190	malt
	Α	,	В	≥	0	

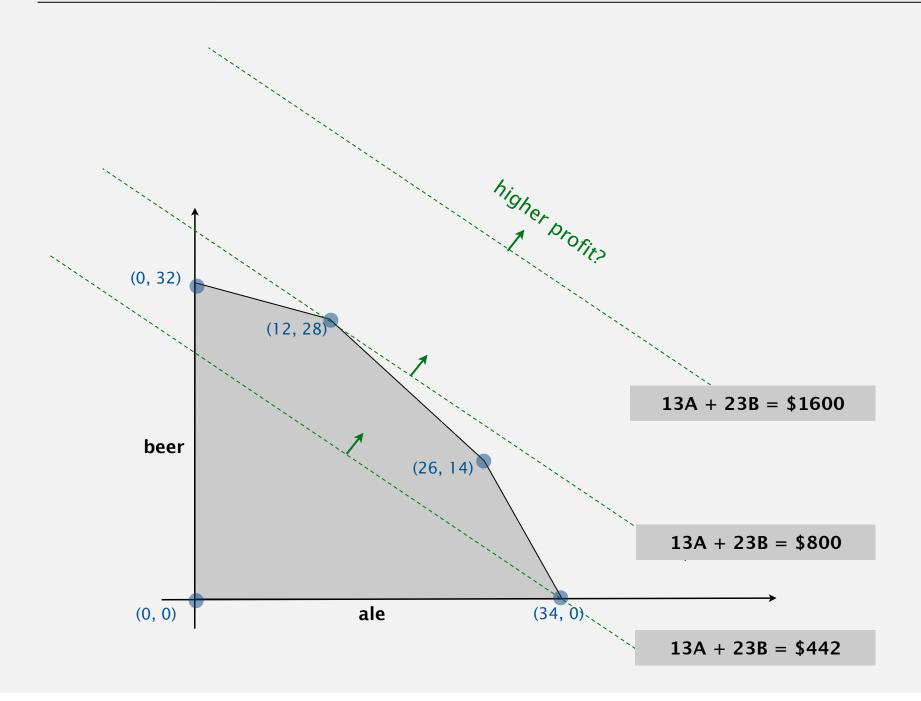


Brewer's problem: feasible region

Inequalities define halfplanes; feasible region is a convex polygon.



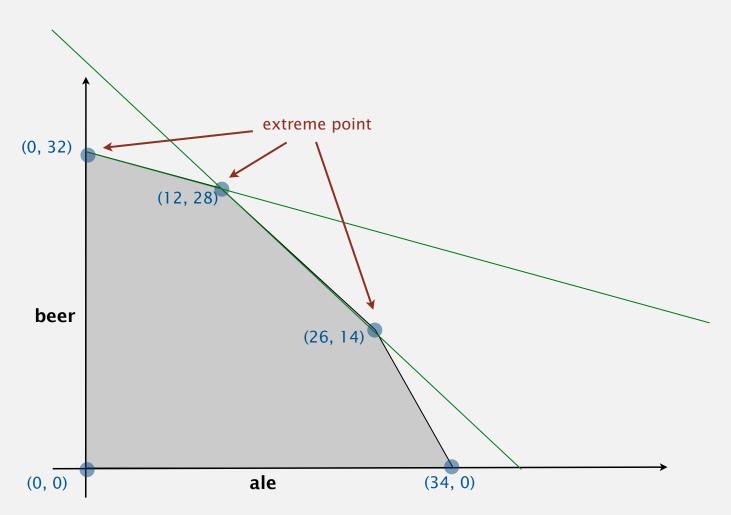
Brewer's problem: objective function



Brewer's problem: geometry

Optimal solution occurs at an extreme point.





Standard form linear program

Goal. Maximize linear objective function of n nonnegative variables, subject to m linear equations.

- Input: real numbers a_{ij} , c_j , b_i .
- Output: real numbers x_j .

linear means no x^2 , xy, arccos(x), etc.

primal problem (P)

maximize	c ₁ x ₁ +	C ₂ X ₂ +	+ C _n X _n		
	$a_{11} x_1 +$	$a_{12} x_2 +$	+ a _{1n} x _n	=	b_1
subject to the	$a_{21} x_1 +$	a ₂₂ x ₂ +	+ a _{2n} x _n	=	b ₂
constraints	÷	: :	:		÷
	am1 X1 +	a _{m2} x ₂ +	+ a _{mn} x _n	=	b_{m}
	X1 ,	X2 ,	, Xn	≥	0

matrix version

maximize	c ^T x
subject to the	A x = b
constraints	x ≥ 0

Caveat. No widely agreed notion of "standard form."

Converting the brewer's problem to the standard form

Original formulation.

maximize	13A	+	23B		
subject	5A	+	15B	≤	480
to the	4A	+	4B	≤	160
constraints	35A	+	20B	≤	1190
	Α	,	В	≥	0

Standard form.

- Add variable Z and equation corresponding to objective function.
- Add slack variable to convert each inequality to an equality.
- Now a 6-dimensional problem.

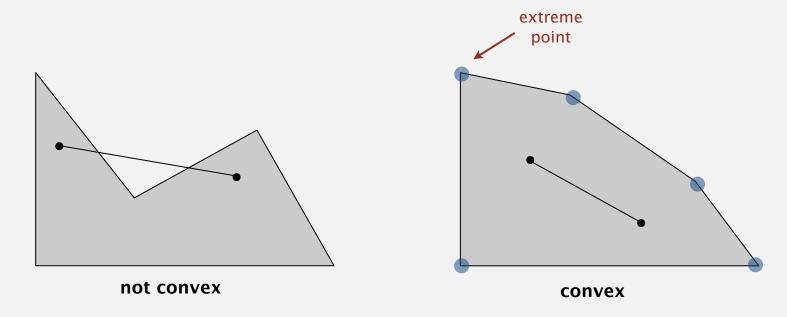
maximize	Z											
	13A	+	23B							– Z	_ =	0
subject to the	5A	+	15B	+	Sc						=	480
constraints	4A	+	4B			+	Sн				=	160
	35A	+	20B					+	S_M		=	1190
	Α	,	В	,	Sc	,	Sc	,	Ѕм		≥	0

Geometry

Inequalities define halfspaces; feasible region is a convex polyhedron.

A set is convex if for any two points a and b in the set, so is $\frac{1}{2}(a+b)$.

An extreme point of a set is a point in the set that can't be written as $\frac{1}{2}(a+b)$, where a and b are two distinct points in the set.

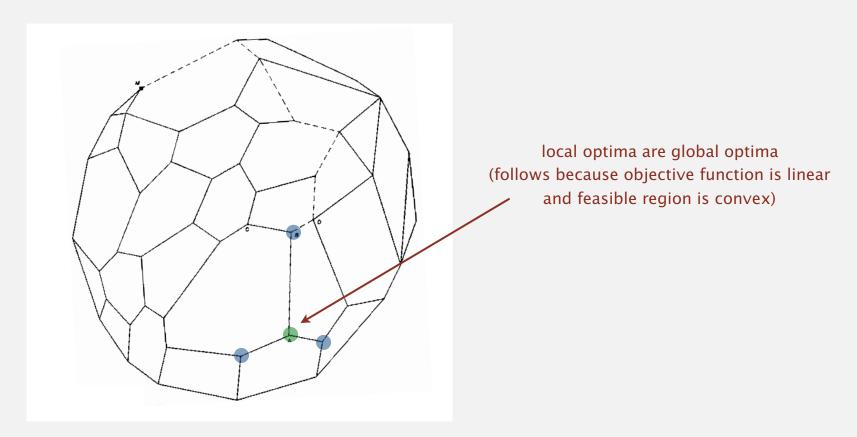


Warning. Don't always trust intuition in higher dimensions.

Geometry (continued)

Extreme point property. If there exists an optimal solution to (P), then there exists one that is an extreme point.

- Good news: number of extreme points to consider is finite.
- Bad news: number of extreme points can be exponential!



Greedy property. Extreme point optimal iff no better adjacent extreme point.

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Simplex algorithm

Simplex algorithm. [George Dantzig, 1947]

- Developed shortly after WWII in response to logistical problems, including Berlin airlift.
- Ranked as one of top 10 scientific algorithms of 20th century.

Generic algorithm.

Start at some extreme point.

Pivot from one extreme point to an adjacent one.

Repeat until optimal.

How to implement? Linear algebra.

never decreasing objective function

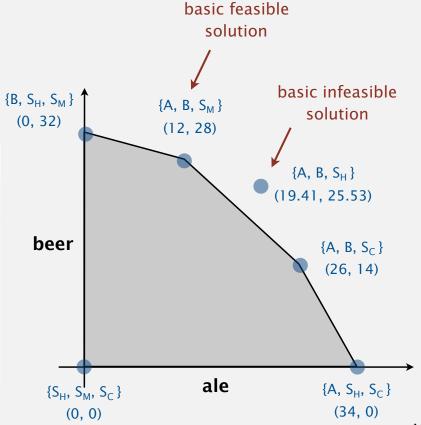
Simplex algorithm: basis

A basis is a subset of *m* of the *n* variables.

Basic feasible solution (BFS).

- Set n-m nonbasic variables to 0, solve for remaining m variables.
- Solve m equations in m unknowns.
- If unique and feasible ⇒ BFS.
- BFS ⇔ extreme point.

maximize	Z										
	13A	+	23B						- Z	=	0
subject to the	5A	+	15B +	Sc						=	480
constraints	4A	+	4B		+	S _H				=	160
	35A	+	20B				+	S_M		=	1190
	Α	,	В,	Sc	,	S _H	,	S _M		<u>></u>	0



Simplex algorithm: initialization

maximize	Z												
	13A	+	23B							_	Z	=	0
subject to the	5A	+	15B	+	Sc							=	480
constraints	4A	+	4B			+	Sн					=	160
	35A	+	20B					+	S_M			=	1190
	Α	,	В	,	Sc	,	Ѕн	,	Ѕм			<u>></u>	0

basis =
$$\{S_C, S_H, S_M\}$$

 $A = B = 0$
 $Z = 0$
 $S_C = 480$
 $S_H = 160$
 $S_M = 1190$

no algebra needed

one basic variable per row

Initial basic feasible solution.

- Start with slack variables $\{S_C, S_H, S_M\}$ as the basis.
- Set non-basic variables A and B to 0.
- 3 equations in 3 unknowns yields $S_C = 480$, $S_H = 160$, $S_M = 1190$.

basis =
$$\{S_C, S_H, S_M\}$$

 $A = B = 0$
 $Z = 0$
 $S_C = 480$
 $S_H = 160$
 $S_M = 1190$

substitute $B = (1/15) (480 - 5A - S_C)$ and add B into the basis (rewrite 2nd equation, eliminate B in 1st, 3rd, and 4th equations)

which basic variable does B replace?

maximize	Z		
	(16/3) A	$- (23/15) S_C - Z =$	-736
subject to the	(1/3) A +	$B + (1/15) S_C =$	= 32
constraints	(8/3) A	$-$ (4/15) $S_C + S_H =$	= 32
	(85/3) A	$-$ (4/3) S_C + S_M =	550
	Α,	B , S_C , S_H , S_M \geq	0

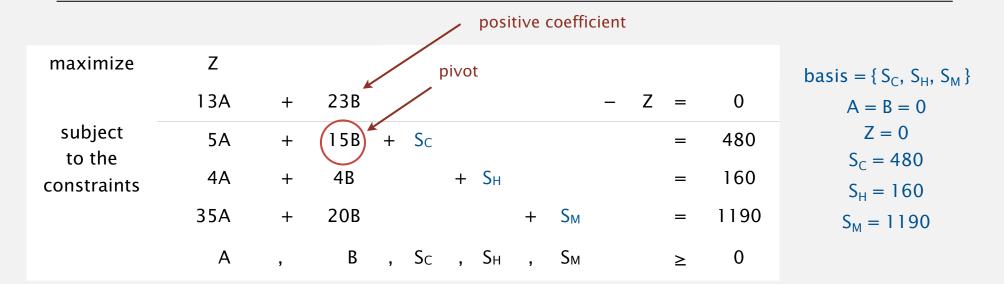
basis = { B,
$$S_H$$
, S_M }
$$A = S_C = 0$$

$$Z = 736$$

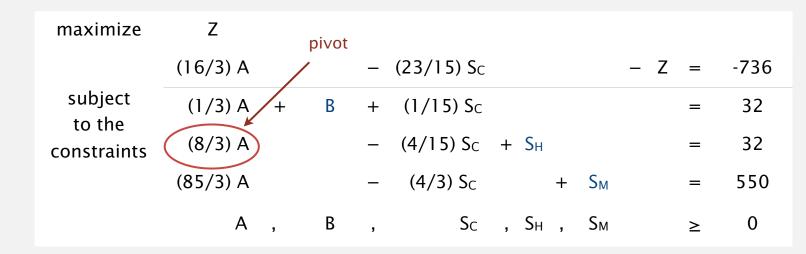
$$B = 32$$

$$S_H = 32$$

$$S_M = 550$$



- Q. Why pivot on column 2 (corresponding to variable *B*)?
 - Its objective function coefficient is positive. (each unit increase in *B* from 0 increases objective value by \$23)
 - Pivoting on column 1 (corresponding to A) also OK.
- Q. Why pivot on row 2?
 - Preserves feasibility by ensuring RHS ≥ 0 .
 - Minimum ratio rule: min { 480/15, 160/4, 1190/20 }.



basis = { B,
$$S_H$$
, S_M }
$$A = S_C = 0$$

$$Z = 736$$

$$B = 32$$

$$S_H = 32$$

$$S_M = 550$$

substitute $A = (3/8) (32 + (4/15) S_C - S_H)$ and add A into the basis (rewrite 3rd equation, eliminate A in 1st, 2nd, and 4th equations)

which basic variable does A replace?

maximize	Z										
			_	Sc	_	2 S _H		_	Z	=	-800
subject to the		В	+	(1/10) S _C	+	(1/8) Ѕн				=	28
constraints	Α		-	(1/10) S _C	+	(3/8) Ѕн				=	12
			-	(25/6) S _C	_	(85/8) S _H +	S_M			=	110
	Α	, B	,	Sc	,	S _H ,	Ѕм			>	0

basis = { A, B,
$$S_M$$
 }
 $S_C = S_H = 0$
 $Z = 800$
 $B = 28$
 $A = 12$
 $S_M = 110$

Simplex algorithm: optimality

- Q. When to stop pivoting?
- A. When no objective function coefficient is positive.
- Q. Why is resulting solution optimal?
- A. Any feasible solution satisfies current system of equations.
 - In particular: $Z = 800 S_C 2 S_H$
 - Thus, optimal objective value $Z^* \leq 800$ since S_C , $S_H \geq 0$.
 - Current BFS has value 800 ⇒ optimal.

maximize	Z									
			_	Sc	_	2 S _H		– Z	<u> </u>	-800
subject to the		В	+	(1/10) S _C	+	(1/8) S _H			=	28
constraints	Α		-	(1/10) S _C	+	(3/8) S _H			=	12
			-	(25/6) S _C	-	(85/8) S _H +	S_M		=	110
	Α	, B	,	Sc	,	S _H ,	Ѕм		≥	0

basis = { A, B,
$$S_M$$
 }
 $S_C = S_H = 0$
 $Z = 800$
 $B = 28$
 $A = 12$
 $S_M = 110$

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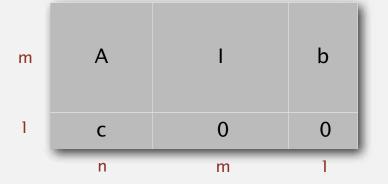
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Simplex tableau

Encode standard form LP in a single Java 2D array.

maximize	Z											
	13A	+	23B							_	Z =	0
subject	5A	+	15B	+	Sc						=	480
to the constraints	4A	+	4B			+	Sн				=	160
	35A	+	20B					+	Ѕм		=	1190
	Α	,	В	,	Sc	,	Sн	,	Ѕм		≥	0

5	15	1	0	0	480
4	4	0	1	0	160
35	20	0	0	1	1190
13	23	0	0	0	0



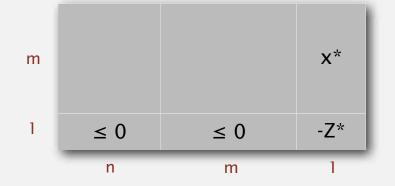
initial simplex tableaux

Simplex tableau

Simplex algorithm transforms initial 2D array into solution.

maximize	Z									
			_	S_C	_	2 S _H		- Z	=	-800
subject to the		В	+	(1/10) S _C	+	(1/8) S _H			=	28
constraints	Α		_	(1/10) S _C	+	(3/8) S _H			=	12
			_	(25/6) S _C	-	(85/8) S _H +	S _M		=	110
	Α	, B	,	Sc	,	S _H ,	Ѕм		>	0

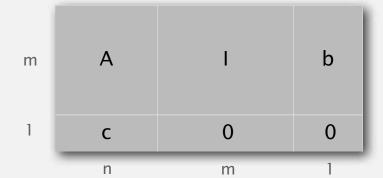
0	1	1/10	1/8	0	28
- 1	0	-1/10	3/8	0	12
0	0	-25/6	-85/8	1	110
0	0	-1	-2	0	-800



final simplex tableaux

Simplex algorithm: initial simplex tableaux

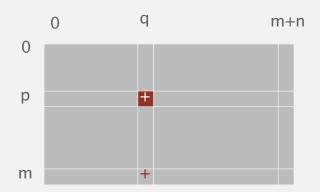
Construct the initial simplex tableau.



```
public class Simplex
                                                                     constructor
   private double[][] a; // simplex tableaux
   private int m, n;  // M constraints, N variables
   public Simplex(double[][] A, double[] b, double[] c)
      m = b.length;
      n = c.length;
      a = new double[m+1][m+n+1];
                                                                    put A[1[1] into tableau
      for (int i = 0; i < m; i++)
         for (int j = 0; j < n; j++)
            a[i][j] = A[i][j];
                                                                    put I[][] into tableau
      for (int j = n; j < m + n; j++) a[j-n][j] = 1.0;
                                                                    put c[] into tableau
      for (int j = 0; j < n; j++) a[m][j] = c[j];
                                                                    put b[] into tableau
      for (int i = 0; i < m; i++) a[i][m+n] = b[i];
```

Simplex algorithm: Bland's rule

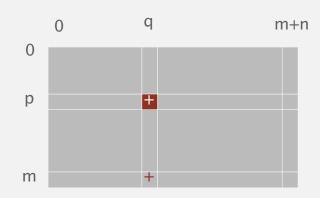
Find entering column q using Bland's rule: index of first column whose objective function coefficient is positive.



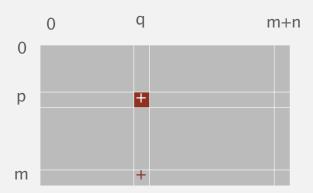
```
private int bland()
{
   for (int q = 0; q < m + n; q++)
     if (a[M][q] > 0) return q;
   return -1;
}
entering column q has positive
objective function coefficient
optimal
```

Simplex algorithm: min-ratio rule

Find leaving row *p* using min ratio rule. (Bland's rule: if a tie, choose first such row)



Pivot on element row p, column q.



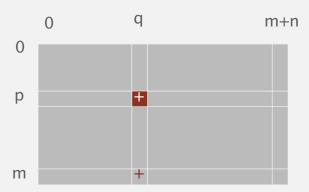
```
public void pivot(int p, int q)
{
    for (int i = 0; i <= m; i++)
        for (int j = 0; j <= m+n; j++)
        if (i != p && j != q)
            a[i][j] -= a[p][j] * a[i][q] / a[p][q];

    for (int i = 0; i <= m; i++)
        if (i != p) a[i][q] = 0.0;

    for (int j = 0; j <= m+n; j++)
        if (j != q) a[p][j] /= a[p][q];
    a[p][q] = 1.0;
}</pre>
```

Simplex algorithm: bare-bones implementation

Execute the simplex algorithm.



```
public void solve()
{
    while (true)
    {
        int q = bland();
        if (q == -1) break;

        int p = minRatioRule(q);
        if (p == -1) ...

        pivot(p, q);
    }
}

    pivot on row p, column q
```

Simplex algorithm: running time

Remarkable property. In typical practical applications, simplex algorithm terminates after at most 2(m + n) pivots.

"Yes. Most of the time it solved problems with m equations in 2m or 3m steps—that was truly amazing. I certainly did not anticipate that it would turn out to be so terrific. I had had no experience at the time with problems in higher dimensions, and I didn't trust my geometrical intuition. For example, my intuition told me that the procedure would require too many steps wandering from one adjacent vertex to the next. In practice it takes few steps. In brief, one's intuition in higher dimensional space is not worth a damn! Only now, almost forty years from the time when the simplex method was first proposed, are people beginning to get some insight into why it works as well as it does."

— George Dantzig 1984

Simplex algorithm: running time

Remarkable property. In typical practical applications, simplex algorithm terminates after at most 2(m + n) pivots.

Pivoting rules. Carefully balance the cost of finding an entering variable with the number of pivots needed.

- No pivot rule is known that is guaranteed to be polynomial.
- Most pivot rules are known to be exponential (or worse) in worst-case.

Smoothed Analysis of Algorithms: Why the Simplex Algorithm Usually Takes Polynomial Time

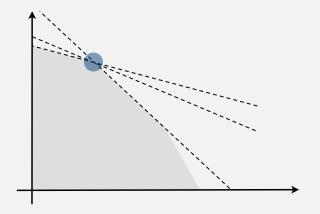
Daniel A. Spielman*
Department of Mathematics
M.I.T.
Cambridge, MA 02139
spielman@mit.edu

Shang-Hua Teng^T
Akamai Technologies Inc. and
Department of Computer Science
University of Illinois at Urbana-Champaign
steng@cs.uiuc.edu

Simplex algorithm: degeneracy

Degeneracy. New basis, same extreme point.





Cycling. Get stuck by cycling through different bases that all correspond to same extreme point.

- Doesn't occur in the wild.
- Bland's rule guarantees finite # of pivots.

choose lowest valid index for entering and leaving columns

Simplex algorithm: implementation issues

To improve the bare-bones implementation.

- Avoid stalling.
- Maintain sparsity.
- Numerical stability.
 requires advanced math
- Detect infeasibility.
 run "phase I" simplex algorithm
- Detect unboundedness.

 no leaving row

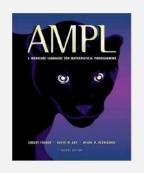
Best practice. Don't implement it yourself!

Basic implementations. Available in many programming environments. Industrial-strength solvers. Routinely solve LPs with millions of variables. Modeling languages. Simplify task of modeling problem as LP.











LP solvers: industrial strength

- " a benchmark production planning model solved using linear programming would have taken 82 years to solve in 1988, using the computers and the linear programming algorithms of the day. Fifteen years later—in 2003—this same model could be solved in roughly 1 minute, an improvement by a factor of roughly 43 million. Of this, a factor of roughly 1,000 was due to increased processor speed, whereas a factor of roughly 43,000 was due to improvements in algorithms!"
 - Designing a Digital Future(Report to the President and Congress, 2010)

Brief history

- 1939. Production, planning. [Kantorovich]
- 1947. Simplex algorithm. [Dantzig]
- 1947. Duality. [von Neumann, Dantzig, Gale-Kuhn-Tucker]
- 1947. Equilibrium theory. [Koopmans]
- 1948. Berlin airlift. [Dantzig]
- 1975. Nobel Prize in Economics. [Kantorovich and Koopmans]
- 1979. Ellipsoid algorithm. [Khachiyan]
- 1984. Projective-scaling algorithm. [Karmarkar]
- 1990. Interior-point methods. [Nesterov-Nemirovskii, Mehorta, ...]



Kantorovich



George Dantzig



von Neumann



Koopmans



Khachiyan



Karmarkar

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Reductions to standard form

Minimization problem. Replace min 13A + 15B with max - 13A - 15B.

 \geq constraints.

Replace $4A + 4B \ge 160$ with $4A + 4B - S_H = 160$, $S_H \ge 0$.

Unrestricted variables. Replace B with $B = B_0 - B_1$, $B_0 \ge 0$, $B_1 \ge 0$.

nonstandard form

minimize
$$13A + 15B$$

subject to: $5A + 15B \le 480$
 $4A + 4B \ge 160$
 $35A + 20B = 1190$
 $A \ge 0$
 B is unrestricted

standard form

Modeling

Linear "programming" (1950s term) = reduction to LP (modern term).

- Process of formulating an LP model for a problem.
- Solution to LP for a specific problem gives solution to the problem.
- 1. Identify variables.
- 2. Define constraints (inequalities and equations).
- 3. Define objective function.
- 4. Convert to standard form. ← software usually performs this step automatically

Examples.

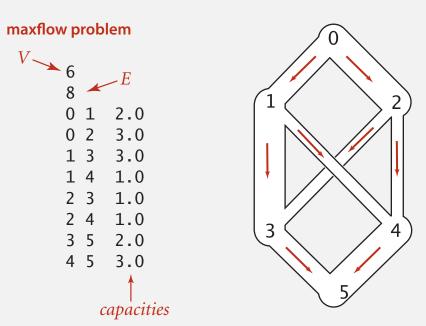
- Maxflow.
- Shortest paths.
- Bipartite matching.
- Assignment problem.
- 2-person zero-sum games.

. . .

Maxflow problem (revisited)

Input. Weighted digraph G, single source s and single sink t.

Goal. Find maximum flow from *s* to *t*.



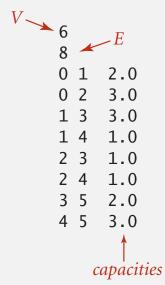
Modeling the maxflow problem as a linear program

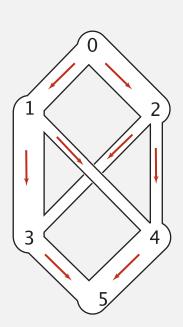
Variables. $x_{vw} = \text{flow on edge } v \rightarrow w$.

Constraints. Capacity and flow conservation.

Objective function. Net flow into *t*.







LP formulation

Maximize $x_{35} + x_{45}$ subject to the constraints

$$0 \le x_{01} \le 2$$

$$0 \le x_{02} \le 3$$

$$0 \le x_{13} \le 3$$

$$0 \le x_{14} \le 1$$

$$0 \le x_{23} \le 1$$

$$0 \le x_{24} \le 1$$

$$0 \le x_{35} \le 2$$

$$0 \le x_{45} \le 3$$

$$x_{01} = x_{13} + x_{14}$$

$$x_{02} = x_{23} + x_{24}$$

$$x_{13} + x_{23} = x_{35}$$

$$x_{14} + x_{24} = x_{45}$$

$$capacity constraints$$

$$flow conservation constraints$$

Maximum cardinality bipartite matching problem

Input. Bipartite graph.

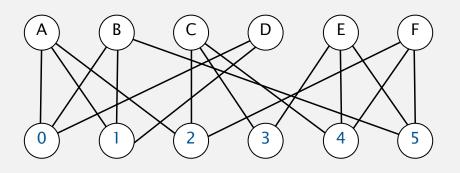
Goal. Find a matching of maximum cardinality.

set of edges with no vertex appearing twice

Interpretation. Mutual preference constraints.

- People to jobs.
- Students to writing seminars.

Adobe
Alice, Bob, Dave
Apple
Alice, Bob, Dave
Google
Alice, Carol, Frank
IBM
Carol, Eliza
Sun
Carol, Eliza, Frank
Yahoo
Bob, Eliza, Frank



matching of cardinality 6: A-1, B-5, C-2, D-0, E-3, F-4

Example: job offers

Maximum cardinality bipartite matching problem

LP formulation. One variable per pair. Interpretation. $x_{ij} = 1$ if person i assigned to job j.

```
X_{A0} + X_{A1} + X_{A2} + X_{B0} + X_{B1} + X_{B5} + X_{C2} + X_{C3} + X_{C4}
 maximize
                             + X_{D0} + X_{D1} + X_{E3} + X_{E4} + X_{E5} + X_{F2} + X_{F4} + X_{F5}
                    at most one job per person
                                                         at most one person per job
                      x_{A0} + x_{A1} + x_{A2} \le 1 x_{A0} + x_{B0} + x_{D0} \le 1
                      x_{B0} + x_{B1} + x_{B5} \le 1
                                                           x_{A1} + x_{B1} + x_{D1} \le 1
  subject
                      x_{C2} + x_{C3} + x_{C4} \le 1 x_{A2} + x_{C2} + x_{F2} \le 1
   to the
                          x_{D0} + x_{D1} \leq 1
                                                  \mathbf{x}_{C3} + \mathbf{x}_{E3}
                                                                                  ≤ ]
constraints
                       X_{F3} + X_{F4} + X_{F5} \le 1 X_{C4} + X_{F4} + X_{F4} \le 1
                       x_{F2} + x_{F4} + x_{F5} \leq 1
                                                           X_{B5} + X_{E5} + X_{F5} \leq 1
                                            all x_{ij} \geq 0
```

Theorem. [Birkhoff 1946, von Neumann 1953]

All extreme points of the above polyhedron have integer (0 or 1) coordinates. Corollary. Can solve matching problem by solving LP. — not usually so lucky!

Linear programming perspective

- Q. Got an optimization problem?
- Ex. Maxflow, bipartite matching, shortest paths, ... [many, many, more]

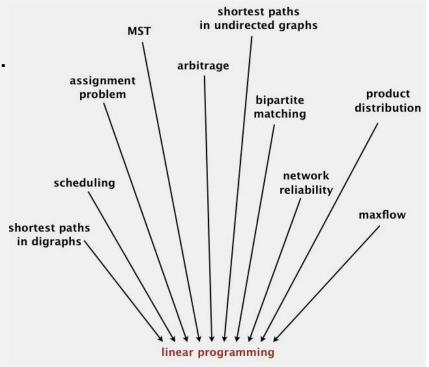
Approach 1: Use a specialized algorithm to solve it.

- Algorithms 4/e.
- Vast literature on algorithms.

Approach 2: Use linear programming.

- Many problems are easily modeled as LPs.
- Commercial solvers can solve those LPs.
- Might be slower than specialized solution (but you might not care).

Got an LP solver? Learn to use it!



Universal problem-solving model (in theory)

Is there a universal problem-solving model?

 Maxflow. Shortest paths. • Bipartite matching. Assignment problem. tractable Multicommodity flow. • Two-person zero-sum games. • Linear programming. Factoring intractable? • NP-complete problems.

see next lecture

Does P = NP? No universal problem-solving model exists unless P = NP.

LINEAR PROGRAMMING

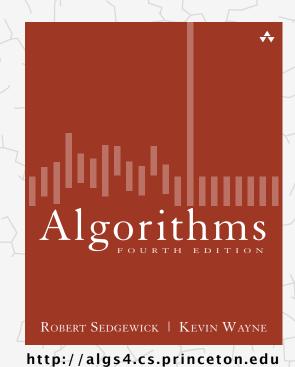
- brewer's problem
- simplex algorithm
- implementations
- reductions

Algorithms

ROBERT SEDGEWICK | KEVIN WAYNE

http://algs4.cs.princeton.edu

Algorithms



LINEAR PROGRAMMING

- brewer's problem
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