



<http://algs4.cs.princeton.edu>

4.4 SHORTEST PATHS

- ▶ *APIs*
- ▶ *shortest-paths properties*
- ▶ *Dijkstra's algorithm*
- ▶ *edge-weighted DAGs*
- ▶ *negative weights*

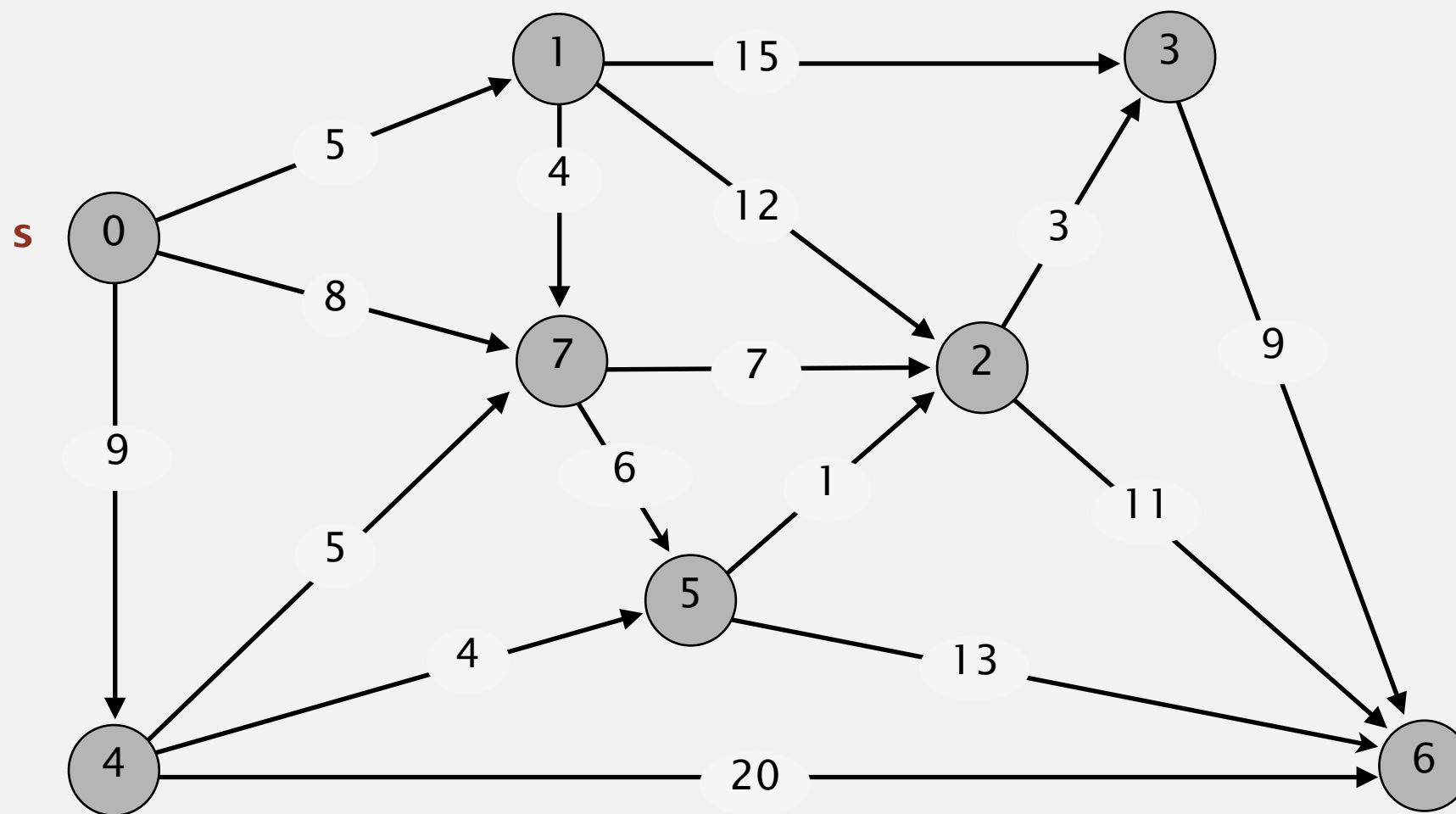
Acyclic edge-weighted digraphs

Q. Suppose that an edge-weighted digraph has no directed cycles. Is it easier to find shortest paths than in a general digraph?

A. Yes!

Acyclic shortest paths demo

- Consider vertices in topological order.
- Relax all edges pointing from that vertex.

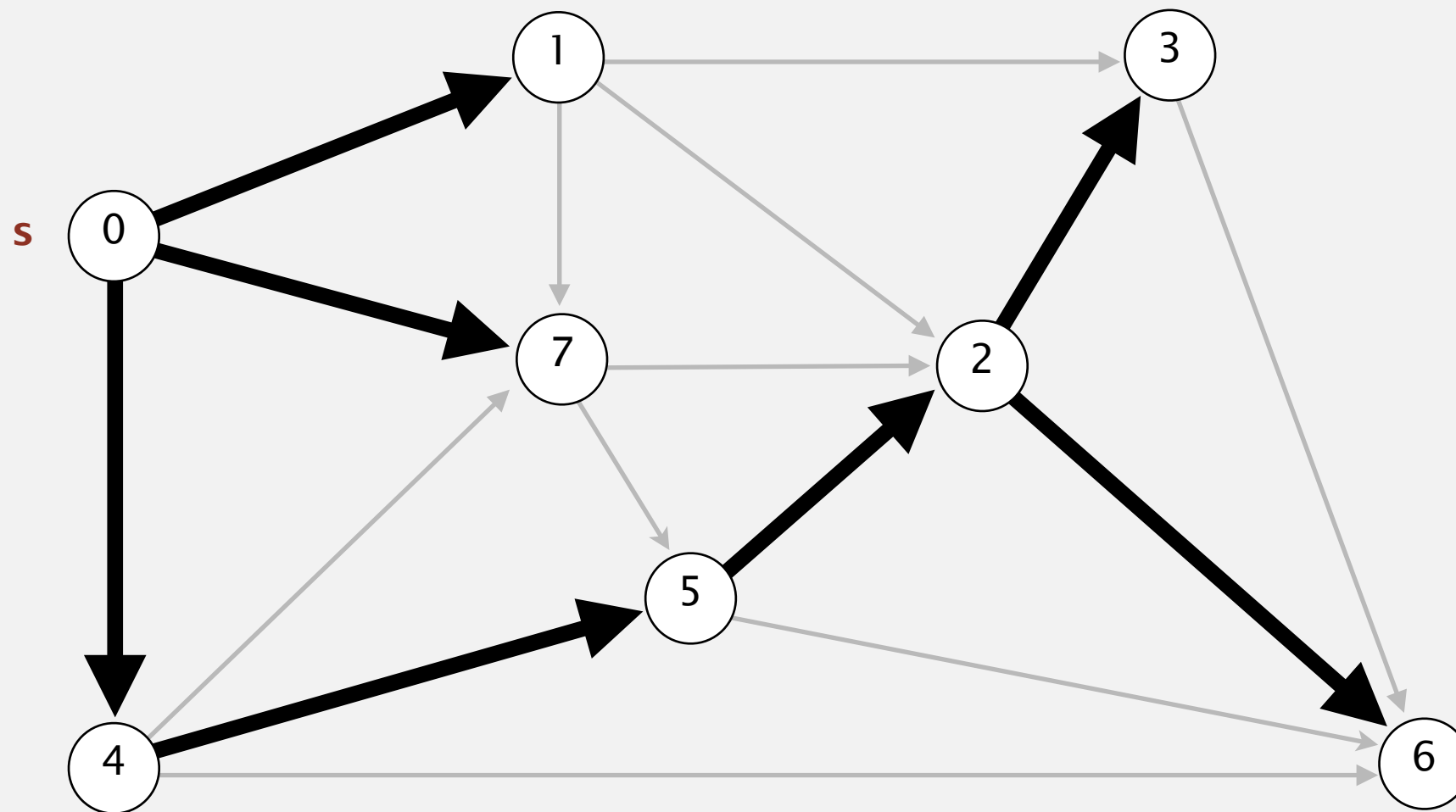


an edge-weighted DAG

0→1	5.0
0→4	9.0
0→7	8.0
1→2	12.0
1→3	15.0
1→7	4.0
2→3	3.0
2→6	11.0
3→6	9.0
4→5	4.0
4→6	20.0
4→7	5.0
5→2	1.0
5→6	13.0
7→5	6.0
7→2	7.0

Acyclic shortest paths demo

- Consider vertices in topological order.
- Relax all edges pointing from that vertex.



shortest-paths tree from vertex s

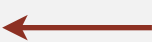

	0	1	4	7	5	2	3	6
v	distTo[]		edgeTo[]					
0	0.0		-					
1	5.0		0→1					
2	14.0		5→2					
3	17.0		2→3					
4	9.0		0→4					
5	13.0		4→5					
6	25.0		2→6					
7	8.0		0→7					

Shortest paths in edge-weighted DAGs

Proposition. Topological sort algorithm computes SPT in any edge-weighted DAG in time proportional to $E + V$.

edge weights
can be negative!

Pf.

- Each edge $e = v \rightarrow w$ is relaxed exactly once (when v is relaxed), leaving $\text{distTo}[w] \leq \text{distTo}[v] + e.\text{weight}()$.
- Inequality holds until algorithm terminates because:
 - $\text{distTo}[w]$ cannot increase  $\text{distTo}[]$ values are monotone decreasing
 - $\text{distTo}[v]$ will not change  because of topological order, no edge pointing to v will be relaxed after v is relaxed
- Thus, upon termination, shortest-paths optimality conditions hold. ■

Shortest paths in edge-weighted DAGs

```
public class AcyclicSP
{
    private DirectedEdge[] edgeTo;
    private double[] distTo;

    public AcyclicSP(EdgeWeightedDigraph G, int s)
    {
        edgeTo = new DirectedEdge[G.V()];
        distTo = new double[G.V()];

        for (int v = 0; v < G.V(); v++)
            distTo[v] = Double.POSITIVE_INFINITY;
        distTo[s] = 0.0;

        Topological topological = new Topological(G);
        for (int v : topological.order())
            for (DirectedEdge e : G.adj(v))
                relax(e);
    }
}
```

← topological order

Content-aware resizing

Seam carving. [Avidan and Shamir] Resize an image without distortion for display on cell phones and web browsers.



Shai Avidan
Mitsubishi Electric Research Lab
Ariel Shamir
The interdisciplinary Center & MERL

<http://www.youtube.com/watch?v=vIFCV2spKtg>

Content-aware resizing

Seam carving. [Avidan and Shamir] Resize an image without distortion for display on cell phones and web browsers.



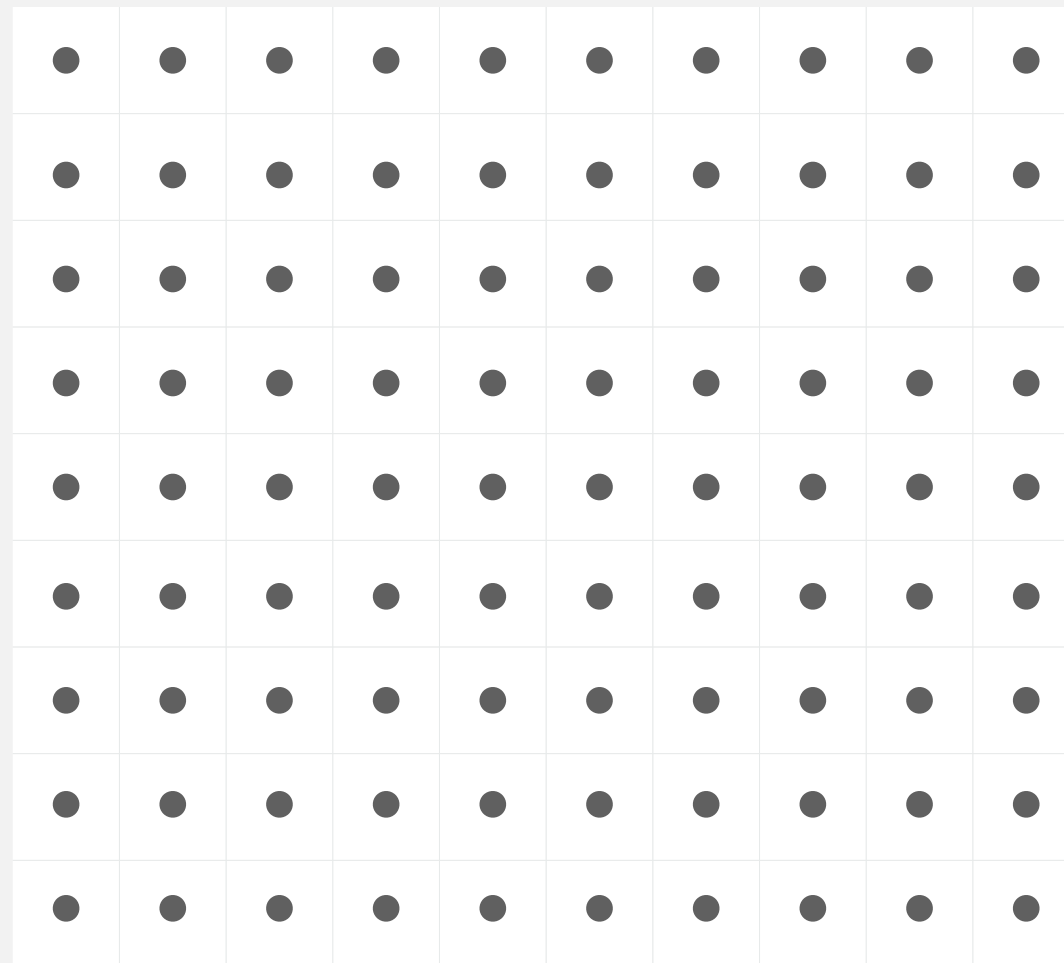
In the wild. Photoshop CS 5, Imagemagick, GIMP, ...



Content-aware resizing

To find vertical seam:

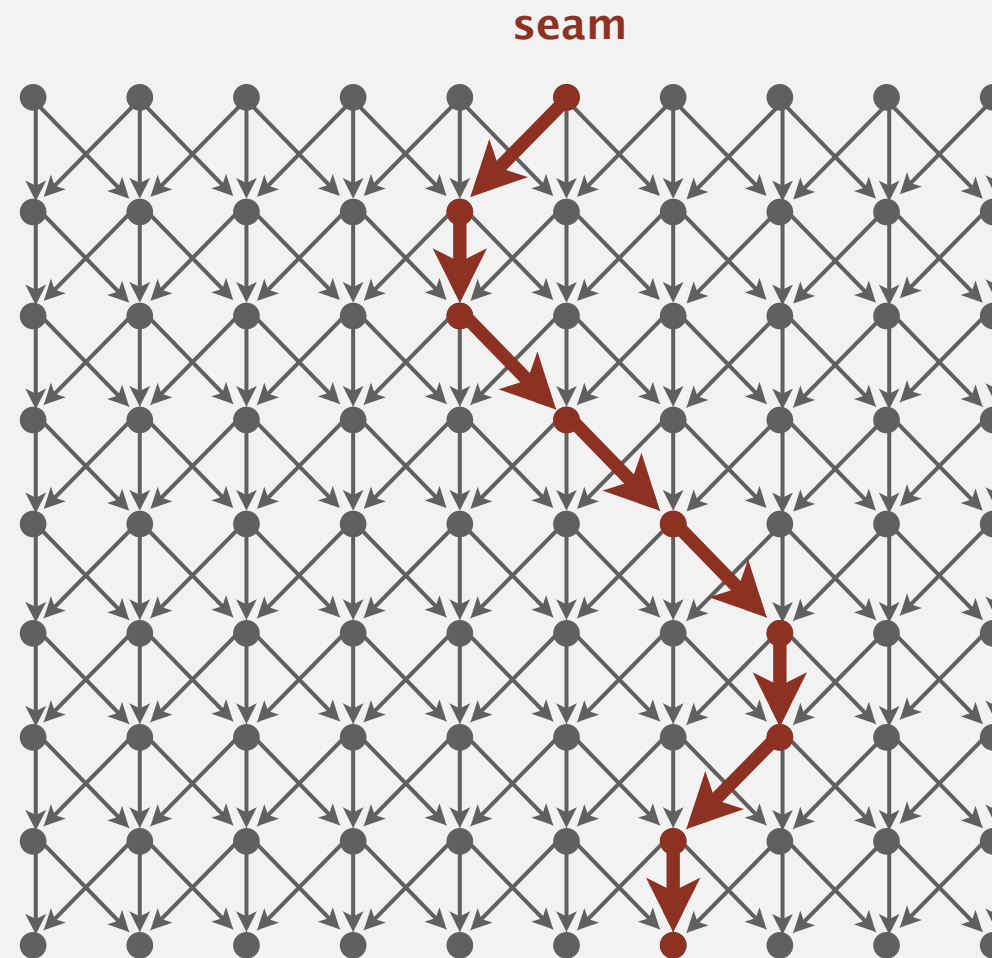
- Grid DAG: vertex = pixel; edge = from pixel to 3 downward neighbors.
- Weight of pixel = energy function of 8 neighboring pixels.
- Seam = shortest path (sum of vertex weights) from top to bottom.



Content-aware resizing

To find vertical seam:

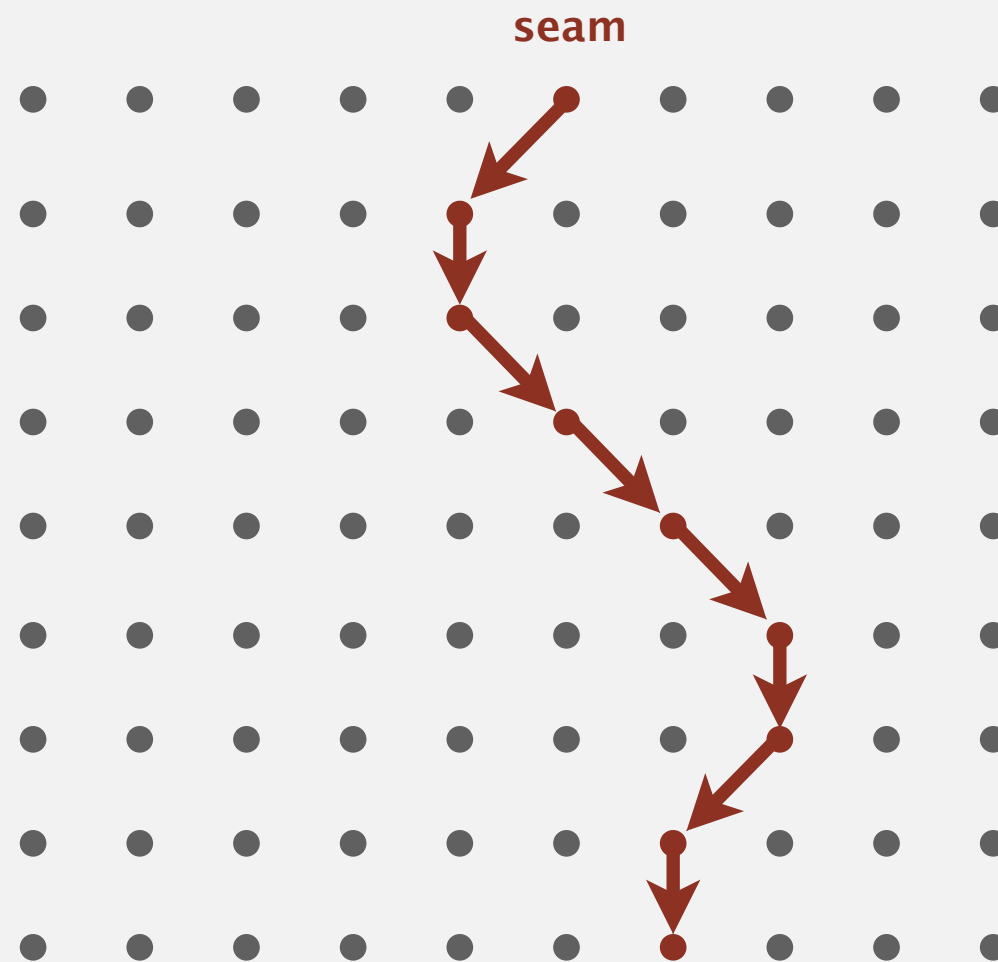
- Grid DAG: vertex = pixel; edge = from pixel to 3 downward neighbors.
- Weight of pixel = energy function of 8 neighboring pixels.
- Seam = shortest path (sum of vertex weights) from top to bottom.



Content-aware resizing

To remove vertical seam:

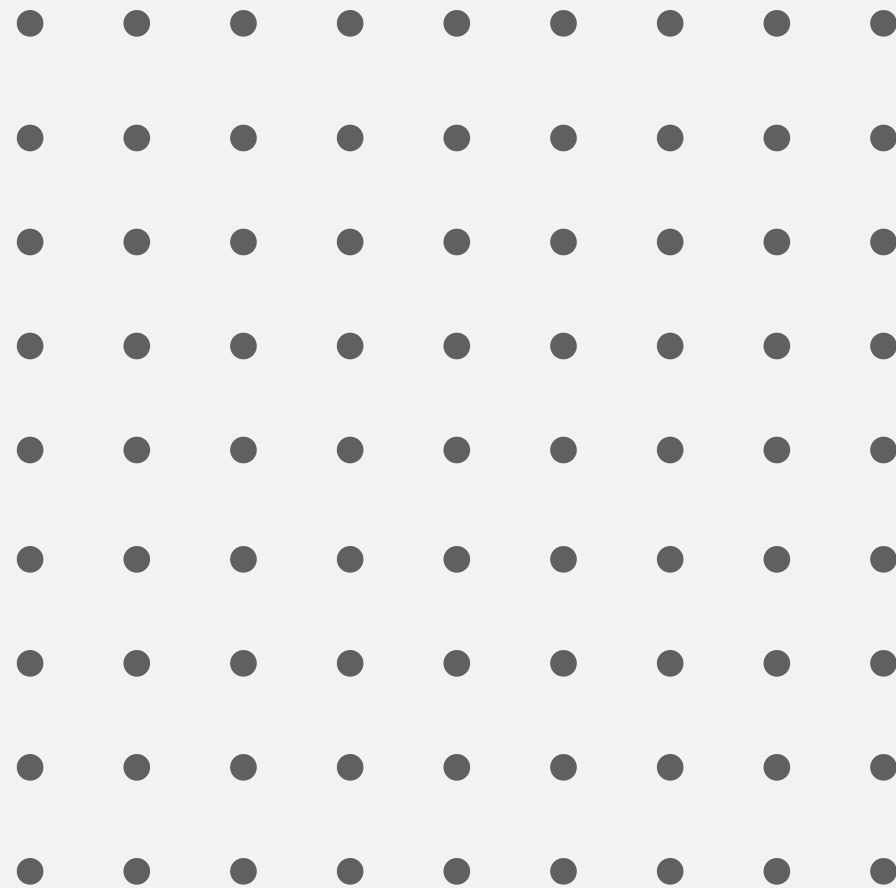
- Delete pixels on seam (one in each row).



Content-aware resizing

To remove vertical seam:

- Delete pixels on seam (one in each row).



Longest paths in edge-weighted DAGs

Formulate as a shortest paths problem in edge-weighted DAGs.

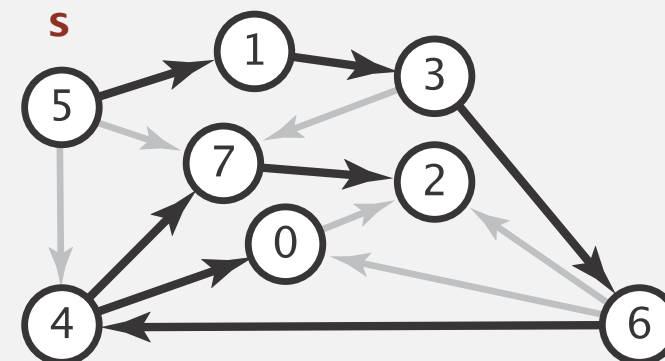
- Negate all weights.
 - Find shortest paths.
 - Negate weights in result.
- equivalent: reverse sense of equality in relax()

longest paths input

5→4 0.35
4→7 0.37
5→7 0.28
5→1 0.32
4→0 0.38
0→2 0.26
3→7 0.39
1→3 0.29
7→2 0.34
6→2 0.40
3→6 0.52
6→0 0.58
6→4 0.93

shortest paths input

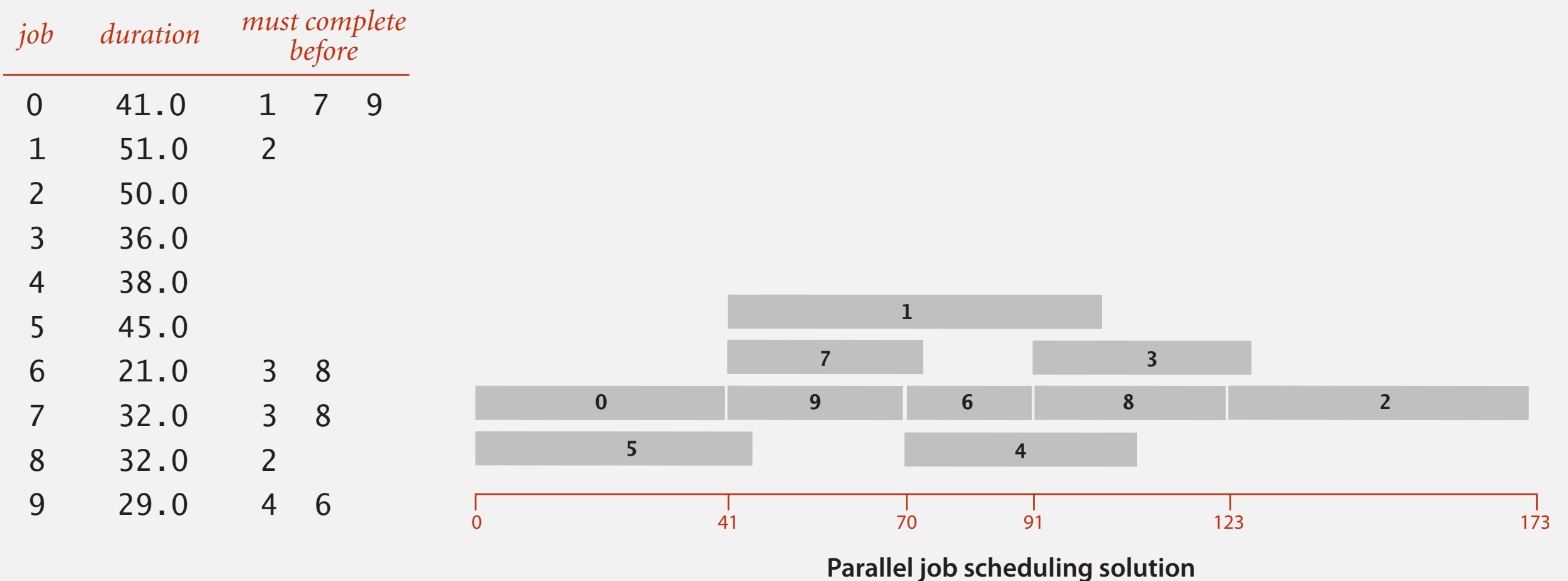
5→4 -0.35
4→7 -0.37
5→7 -0.28
5→1 -0.32
4→0 -0.38
0→2 -0.26
3→7 -0.39
1→3 -0.29
7→2 -0.34
6→2 -0.40
3→6 -0.52
6→0 -0.58
6→4 -0.93



Key point. Topological sort algorithm works even with negative weights.

Longest paths in edge-weighted DAGs: application

Parallel job scheduling. Given a set of jobs with durations and precedence constraints, schedule the jobs (by finding a start time for each) so as to achieve the minimum completion time, while respecting the constraints.

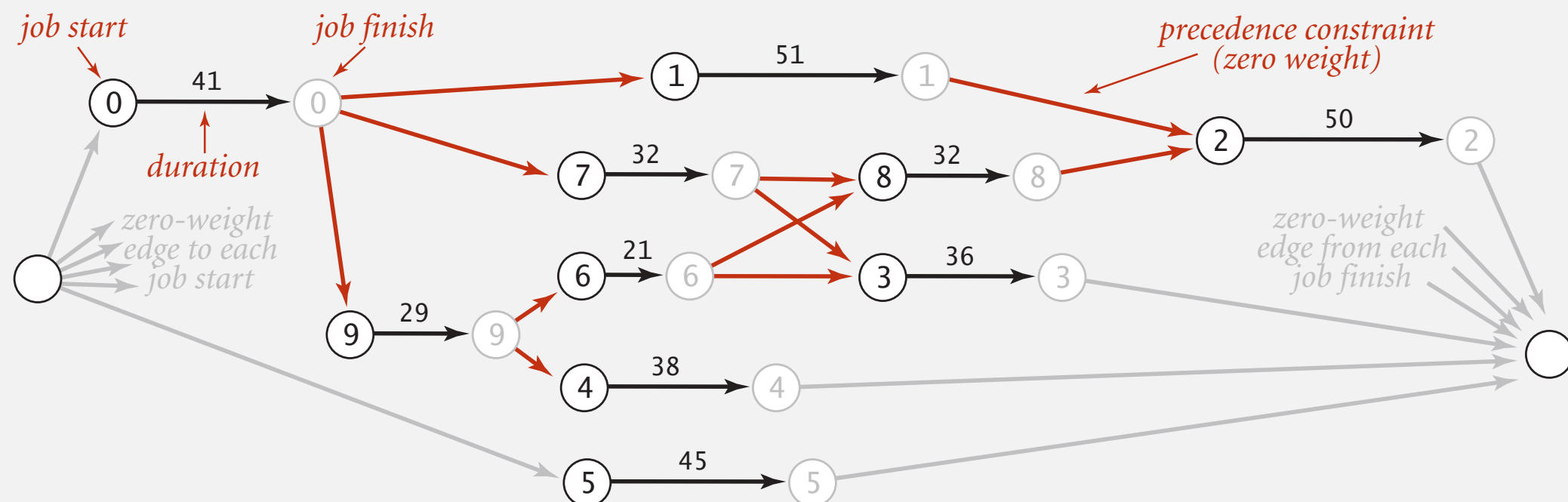


Critical path method

CPM. To solve a parallel job-scheduling problem, create edge-weighted DAG:

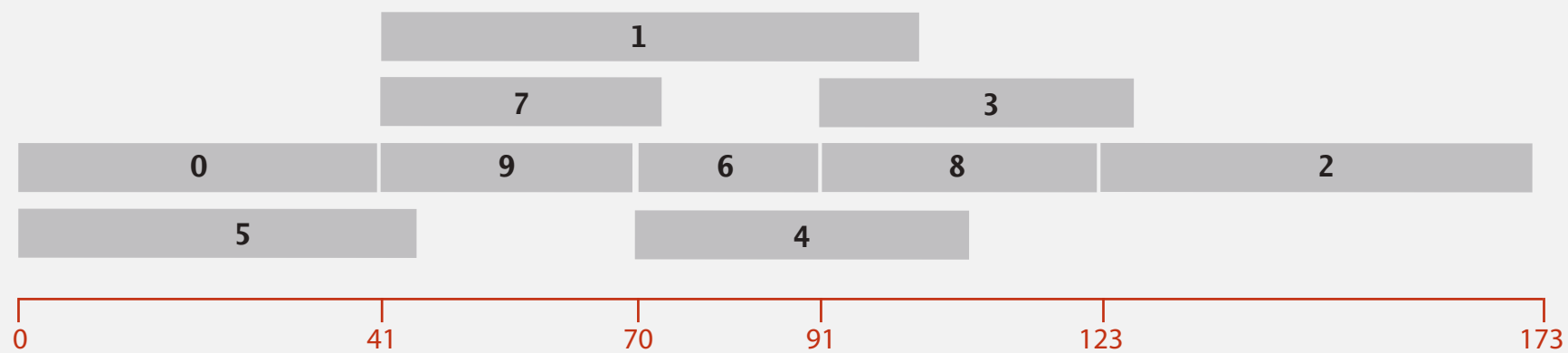
- Source and sink vertices.
- Two vertices (begin and end) for each job.
- Three edges for each job.
 - begin to end (weighted by duration)
 - source to begin (0 weight)
 - end to sink (0 weight)
- One edge for each precedence constraint (0 weight).

job	duration	must complete before		
0	41.0	1	7	9
1	51.0	2		
2	50.0			
3	36.0			
4	38.0			
5	45.0			
6	21.0	3	8	
7	32.0	3	8	
8	32.0	2		
9	29.0	4	6	

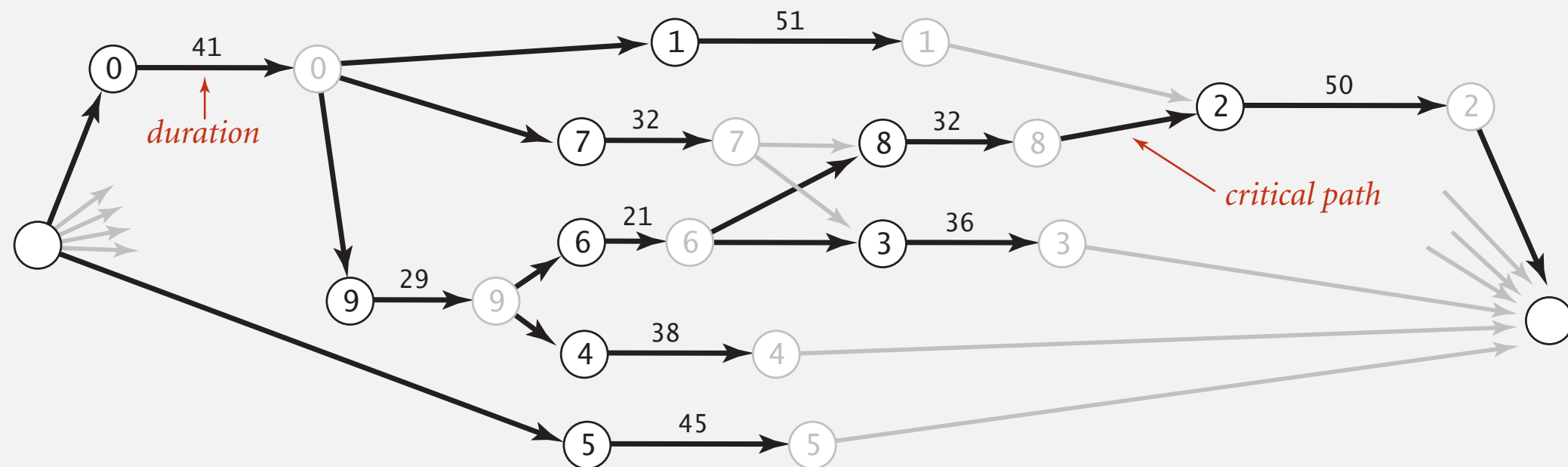


Critical path method

CPM. Use **longest path** from the source to schedule each job.



Parallel job scheduling solution





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- ▶ *negative weights*



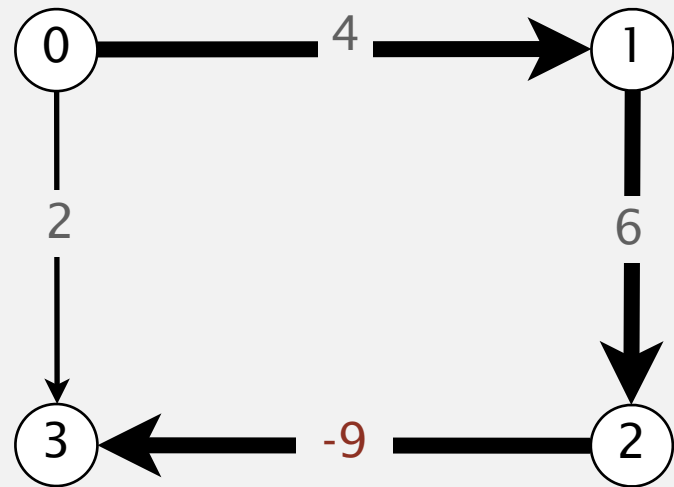
<http://algs4.cs.princeton.edu>

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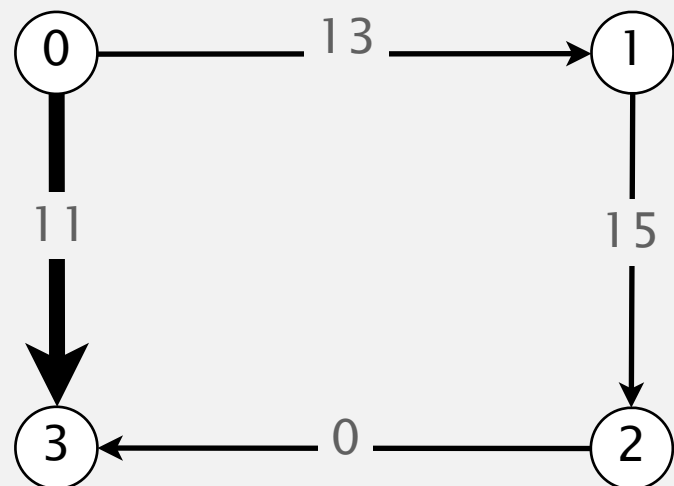
Shortest paths with negative weights: failed attempts

Dijkstra. Doesn't work with negative edge weights.



Dijkstra selects vertex 3 immediately after 0.
But shortest path from 0 to 3 is $0 \rightarrow 1 \rightarrow 2 \rightarrow 3$.

Re-weighting. Add a constant to every edge weight doesn't work.



Adding 9 to each edge weight changes the
shortest path from $0 \rightarrow 1 \rightarrow 2 \rightarrow 3$ to $0 \rightarrow 3$.

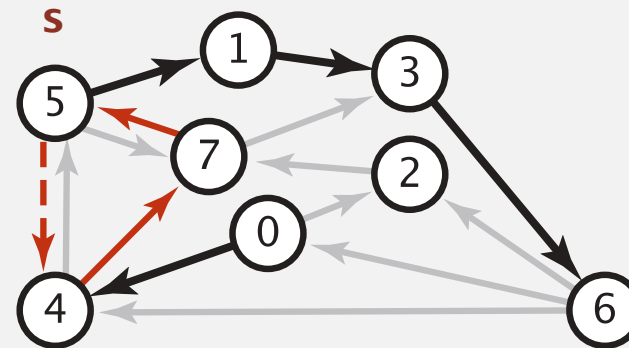
Conclusion. Need a different algorithm.

Negative cycles

Def. A **negative cycle** is a directed cycle whose sum of edge weights is negative.

digraph

4→5	0.35
5→4	-0.66
4→7	0.37
5→7	0.28
7→5	0.28
5→1	0.32
0→4	0.38
0→2	0.26
7→3	0.39
1→3	0.29
2→7	0.34
6→2	0.40
3→6	0.52
6→0	0.58
6→4	0.93



negative cycle $(-0.66 + 0.37 + 0.28)$

5→4→7→5

shortest path from 0 to 6

0→4→7→5→4→7→5...→1→3→6

Proposition. A SPT exists iff no negative cycles.

assuming all vertices reachable from s

Bellman-Ford algorithm

Bellman-Ford algorithm

Initialize $\text{distTo}[s] = 0$ and $\text{distTo}[v] = \infty$ for all other vertices.

Repeat V times:

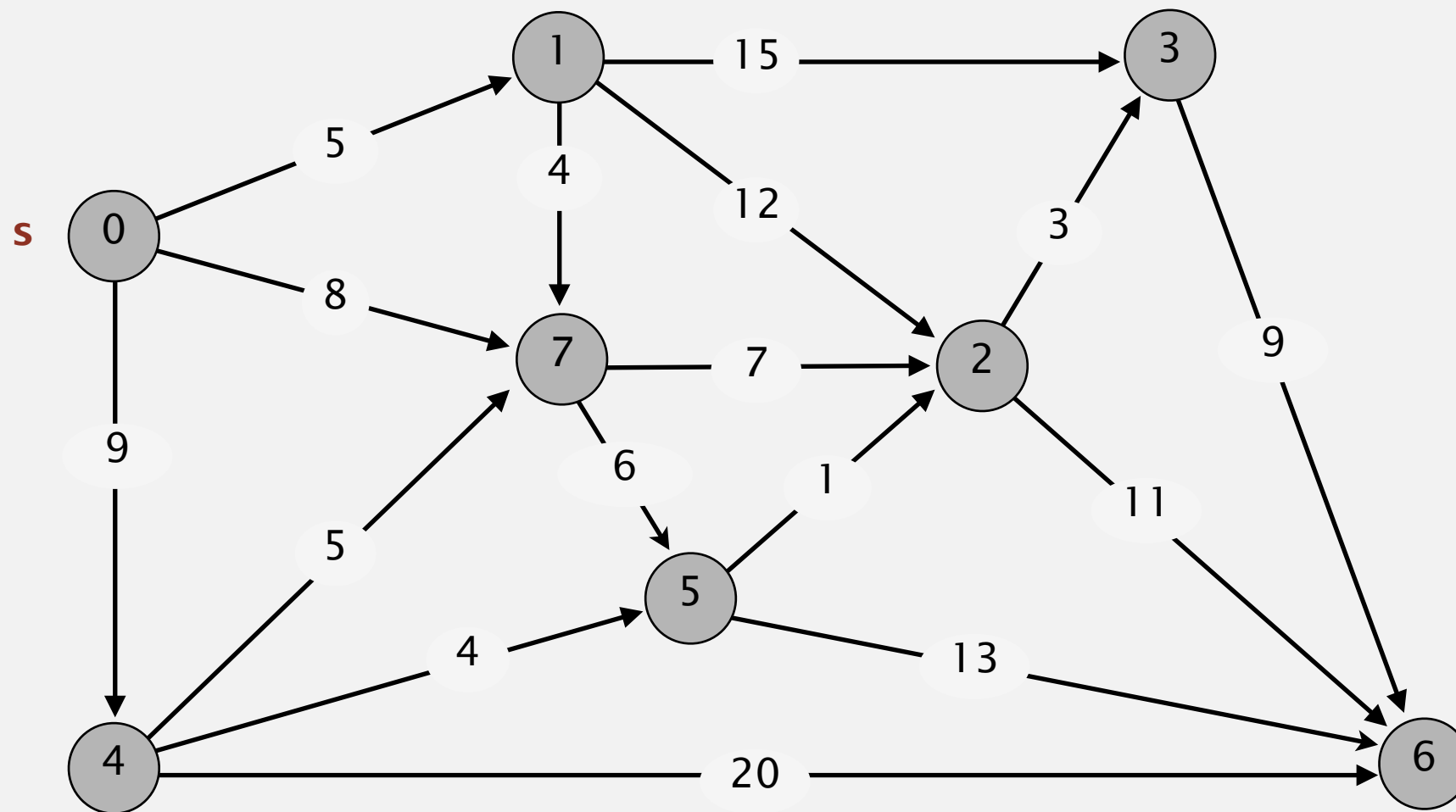
- Relax each edge.**
-

```
for (int i = 0; i < G.V(); i++)  
    for (int v = 0; v < G.V(); v++)  
        for (DirectedEdge e : G.adj(v))  
            relax(e);
```

← pass i (relax each edge)

Bellman-Ford algorithm demo

Repeat V times: relax all E edges.



0→1 5.0

0→4 9.0

0→7 8.0

1→2 12.0

1→3 15.0

1→7 4.0

2→3 3.0

2→6 11.0

3→6 9.0

4→5 4.0

4→6 20.0

4→7 5.0

5→2 1.0

5→6 13.0

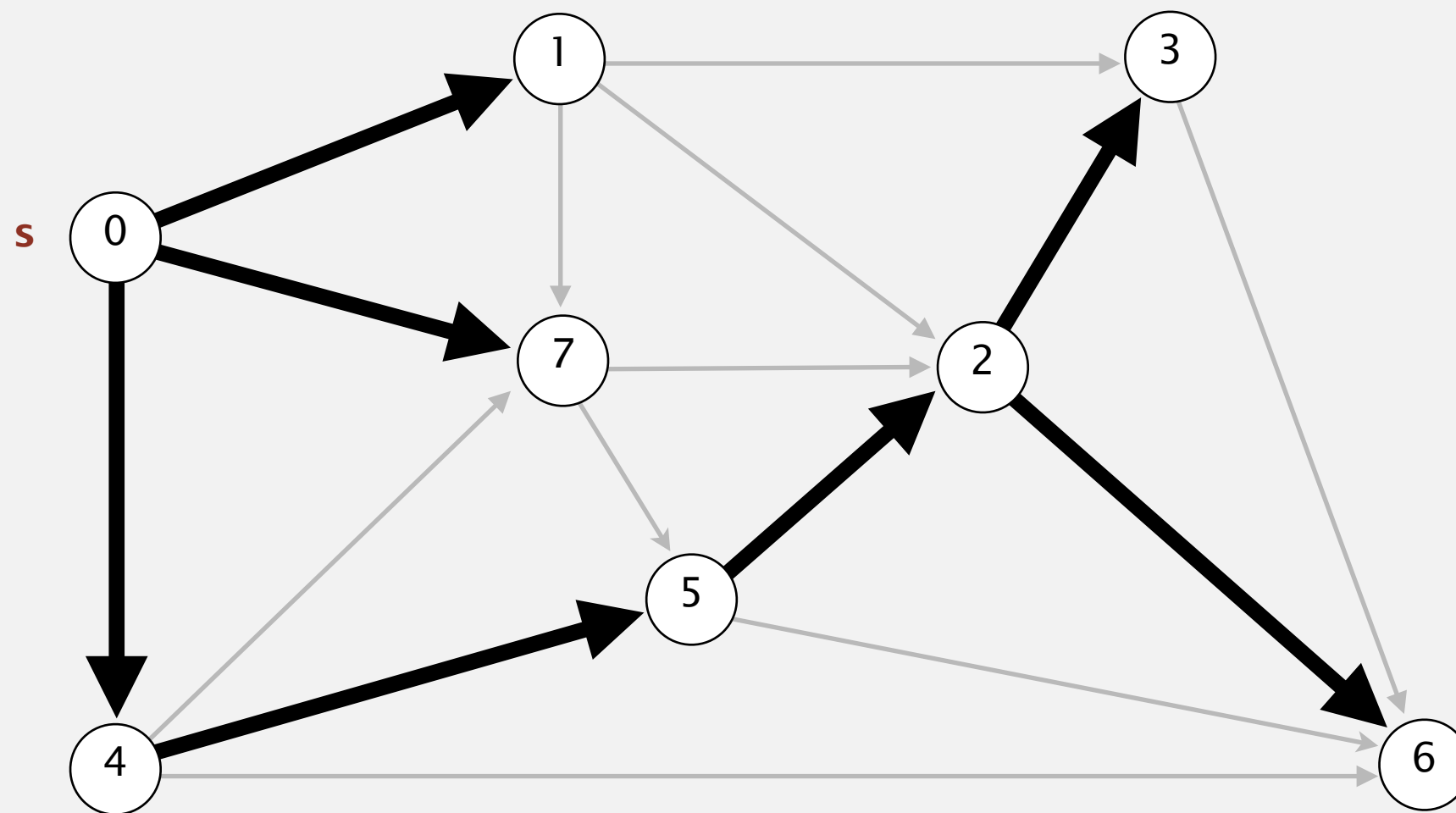
7→5 6.0

7→2 7.0

an edge-weighted digraph

Bellman-Ford algorithm demo

Repeat V times: relax all E edges.

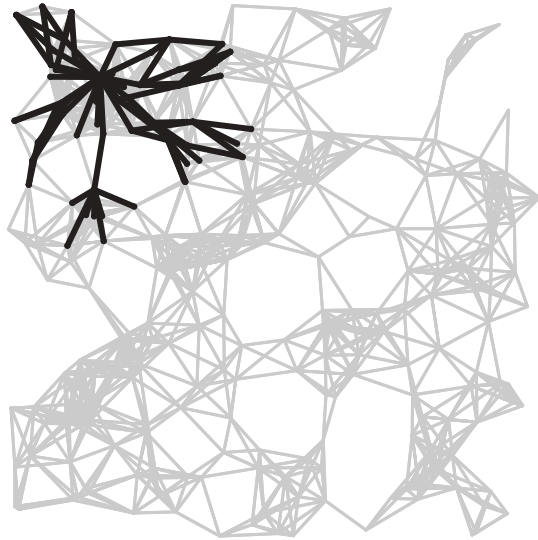


v	distTo[]	edgeTo[]
0	0.0	-
1	5.0	0→1
2	14.0	5→2
3	17.0	2→3
4	9.0	0→4
5	13.0	4→5
6	25.0	2→6
7	8.0	0→7

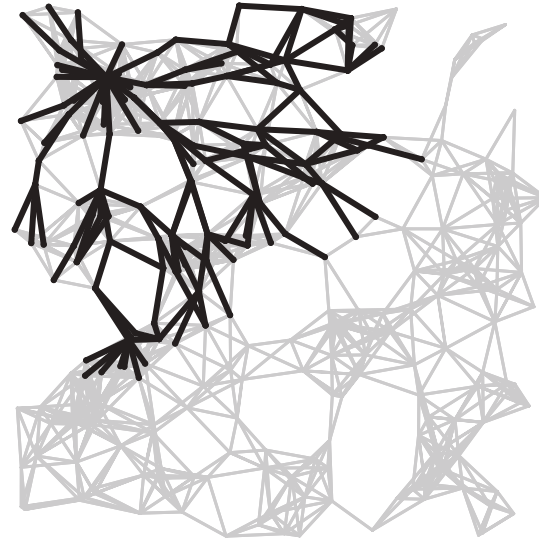
shortest-paths tree from vertex s

Bellman-Ford algorithm visualization

passes
4



7



10



13



SPT



Bellman-Ford algorithm: analysis

Bellman-Ford algorithm

Initialize $\text{distTo}[s] = 0$ and $\text{distTo}[v] = \infty$ for all other vertices.

Repeat V times:

- Relax each edge.**
-

Proposition. Dynamic programming algorithm computes SPT in any edge-weighted digraph with no negative cycles in time proportional to $E \times V$.

Pf idea. After pass i , found shortest path containing at most i edges.

Bellman-Ford algorithm: practical improvement

Observation. If $\text{distTo}[v]$ does not change during pass i , no need to relax any edge pointing from v in pass $i+1$.

FIFO implementation. Maintain **queue** of vertices whose $\text{distTo}[]$ changed.



be careful to keep at most one copy
of each vertex on queue (why?)

Overall effect.

- The running time is still proportional to $E \times V$ in worst case.
- But much faster than that in practice.

Single source shortest-paths implementation: cost summary

algorithm	restriction	typical case	worst case	extra space
topological sort	no directed cycles	$E + V$	$E + V$	V
Dijkstra (binary heap)	no negative weights	$E \log V$	$E \log V$	V
Bellman–Ford	no negative cycles	$E V$	$E V$	V
Bellman–Ford (queue-based)		$E + V$	$E V$	V

Remark 1. Directed cycles make the problem harder.

Remark 2. Negative weights make the problem harder.

Remark 3. Negative cycles makes the problem intractable.

Finding a negative cycle

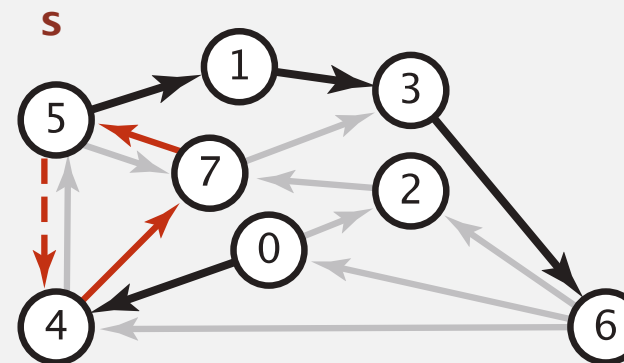
Negative cycle. Add two methods to the API for SP.

boolean hasNegativeCycle() *is there a negative cycle?*

Iterable <DirectedEdge> negativeCycle() *negative cycle reachable from s*

digraph

4->5 0.35
5->4 -0.66
4->7 0.37
5->7 0.28
7->5 0.28
5->1 0.32
0->4 0.38
0->2 0.26
7->3 0.39
1->3 0.29
2->7 0.34
6->2 0.40
3->6 0.52
6->0 0.58
6->4 0.93

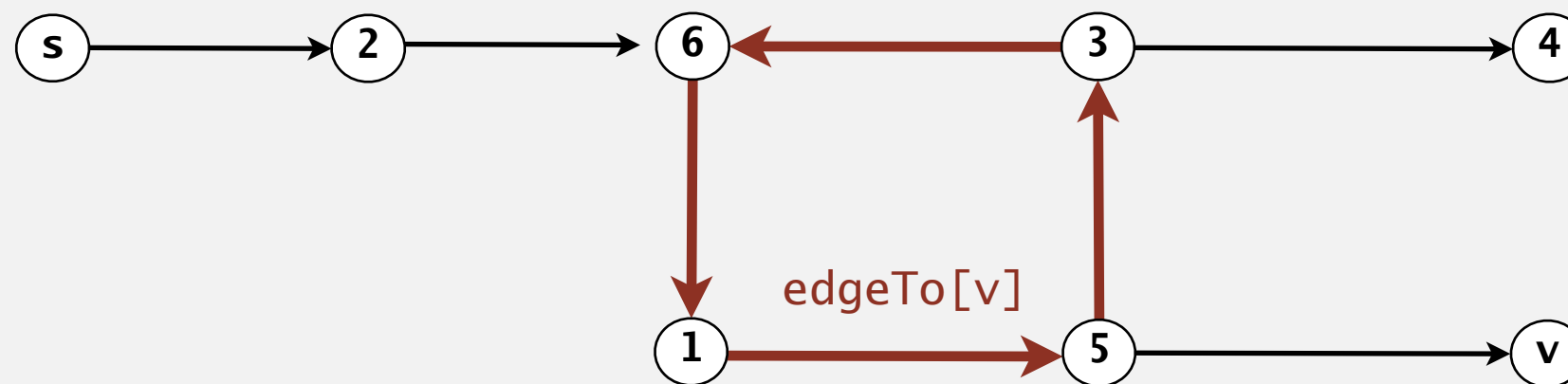


negative cycle (-0.66 + 0.37 + 0.28)

5->4->7->5

Finding a negative cycle

Observation. If there is a negative cycle, Bellman-Ford gets stuck in loop, updating `distTo[]` and `edgeTo[]` entries of vertices in the cycle.



Proposition. If any vertex v is updated in phase v , there exists a negative cycle (and can trace back `edgeTo[v]` entries to find it).


In practice. Check for negative cycles more frequently.

Negative cycle application: arbitrage detection

Problem. Given table of exchange rates, is there an arbitrage opportunity?

	USD	EUR	GBP	CHF	CAD
USD	1	0.741	0.657	1.061	1.011
EUR	1.350	1	0.888	1.433	1.366
GBP	1.521	1.126	1	1.614	1.538
CHF	0.943	0.698	0.620	1	0.953
CAD	0.995	0.732	0.650	1.049	1

Ex. \$1,000 \Rightarrow 741 Euros \Rightarrow 1,012.206 Canadian dollars \Rightarrow \$1,007.14497.

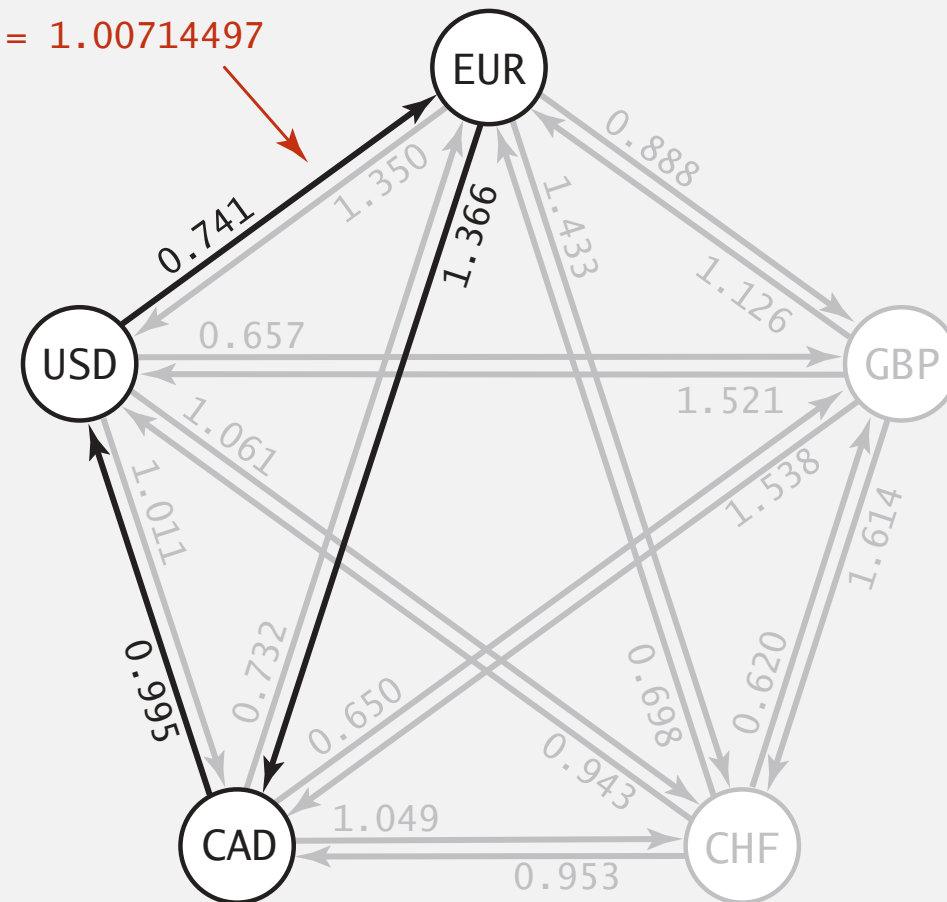

 $1000 \times 0.741 \times 1.366 \times 0.995 = 1007.14497$

Negative cycle application: arbitrage detection

Currency exchange graph.

- Vertex = currency.
- Edge = transaction, with weight equal to exchange rate.
- Find a directed cycle whose product of edge weights is > 1 .

$$0.741 * 1.366 * .995 = 1.00714497$$

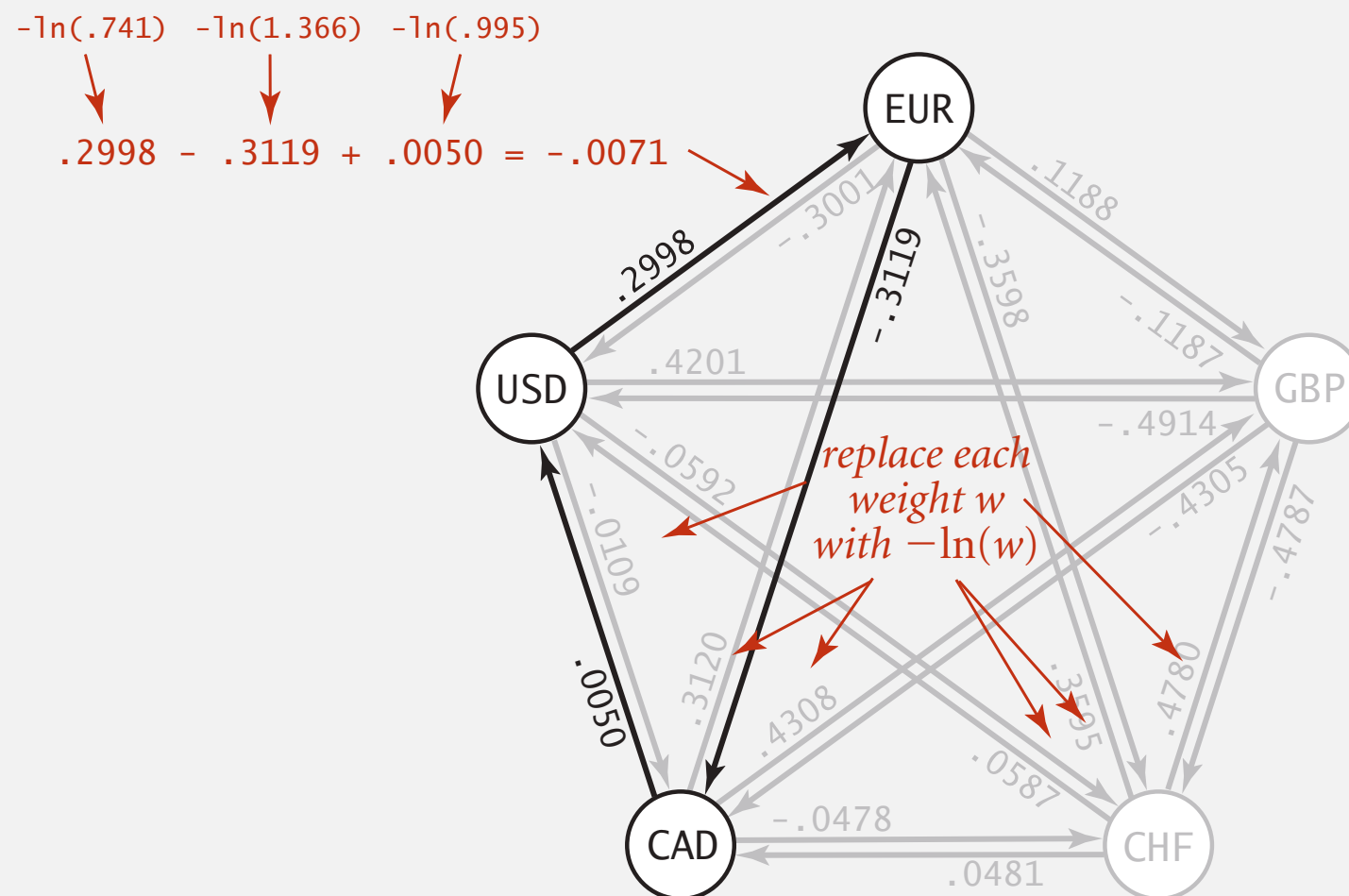


Challenge. Express as a negative cycle detection problem.

Negative cycle application: arbitrage detection

Model as a negative cycle detection problem by taking logs.

- Let weight of edge $v \rightarrow w$ be $-\ln$ (exchange rate from currency v to w).
- Multiplication turns to addition; > 1 turns to < 0 .
- Find a directed cycle whose sum of edge weights is < 0 (negative cycle).



Remark. Fastest algorithm is extraordinarily valuable!

Shortest paths summary

Dijkstra's algorithm.

- Nearly linear-time when weights are nonnegative.
- Generalization encompasses DFS, BFS, and Prim.

Acyclic edge-weighted digraphs.

- Arise in applications.
- Faster than Dijkstra's algorithm.
- Negative weights are no problem.

Negative weights and negative cycles.

- Arise in applications.
- If no negative cycles, can find shortest paths via Bellman-Ford.
- If negative cycles, can find one via Bellman-Ford.

Shortest-paths is a broadly useful problem-solving model.



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