Arsalan Bashir

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## **EDUCATION**

Founder

#### National Institute of Technology

Bachelor of Technology, Mechanical Engineering

Kashmir, India Mar. 2013 - Aug. 2017

## Work Experience

## LiveDocs, Inc (https://livedocs.io)

Dubai, United Arab Emirates Jan 2019 - Present

• Launched LiveDocs, a programmable text editor that helps companies create self-updating documents and

- automate business logic. • Full-stack developer: built the backend API, web frontend, and mobile apps to serve +20 enterprise customers.
- Designed and developed a new document model to provide programmatic control (with a streaming API) over structure, formatting and content of the text-editor.
- o Tech: Python (Flask, Celery), JavaScript (React, Redux), AWS, Redis, MongoDB, GraphQL, Apollo

## MyScoot Ltd (https://www.myscoot.in)

New Delhi, India

Software Engineer

Feb 2018 - Jan 2019

- Launched Scoot (YC W19), a cross-platform web app for hosting and attending home-hosted parties, social events, and meetups with locals
- First engineer on the team: Built the backend RESTful API and frontend, from scratch. Mentored new hires.
- Built an internal identity verification framework to verify and rank attendees' identity in +400 user-hosted events.
- o Tech: Python (Flask, Celery, Jinja2), JavaScript (jQuery), Firebase, Redis, Websockets, Webpack, Semantic UI

## Smart Spin Ltd (https://thesmartspin.com)

London, United Kingdom

Co-founder

Aug 2017 - Jan 2018

- Launched Smart Spin, a cross-platform Wikipedia for homeschooled students (+2000 daily active users).
- Backend developer: Built a RESTful API, with built-in moderation and curation tools for parents.
- Developed the "Smart Spin" mobile apps (iOS and Android) for students.
- o Tech: Python (Flask), JavaScript (React, React Native), MySQL, Firebase, AWS

#### National Institute of Technology, Srinagar

Kashmir, India

Undergraduate Research Project

Mar 2016 - Mar 2017

- Built an autonomous chess playing robot capable of playing chess with a human opponent.
- o Control engineer: Designed and developed an open-loop feedback control system (with Java and FeedbackControl4J) that used information acquired from multiple cameras to control the pose and motion of a chess-playing robotic arm.
- o Optimized drawings of multiple prototypes with Linear Stress Analysis (with SolidWorks and MATLAB) and identified feasible design options.

# SIDE PROJECTS AND OPEN SOURCE

## • TidyStory (https://tidystory.com)

Feb 2018 - Oct 2018

- An open-source Twitter bot that converts a Twitter thread to a webpage that can be annotated by other users.
- o Tech: Python (Flask), JavaScript (jQuery), Selenium, Docker, Firebase, AWS

## Awards

• Awards: EdCIL Scholarship, multiple national and international honors for debating, Kairos Fellowship 2015, Thiel Fellowship Finalist 2014, Lemmings I/O Batch 4, Pioneer December 2018

## Programming Skills

- Languages: Python (Flask, Django, etc), JavaScript (ReactJS, React Native, Angular, etc), C, C++, Java, Statistical Analysis (using R, MATLAB, Octave, etc)
- Tools and technologies: Firebase, AWS, MongoDB, SQL, HTML/CSS, Docker, GraphQL, Apollo, Nginx, Supervisor, Version control using Git, experience with Unix/Linux environments. Design tools like Figma, Sketch, Photoshop