



IBM Developer  
SKILLS NETWORK

# Winning Space Race with Data Science

<Name>

<Date>



# Outline

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- Executive Summary
- Introduction
- Methodology
- Results
- Conclusion
- Appendix

# Executive Summary

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CRISP-DM (Cross-Industry Standard Process for Data Mining): This is a widely used methodology that consists of six major phases:

- Business Understanding: Define the problem, the business goals, and the objectives you want to achieve using data analysis.
- Data Understanding: Collect and explore the data, understand its structure, quality, and completeness.
- Data Preparation: Clean, preprocess, and transform the data into a suitable format for analysis.
- Modeling: Choose and apply appropriate data analysis techniques, such as machine learning algorithms, to build predictive or descriptive models.
- Evaluation: Assess the performance and effectiveness of the models using various metrics and validation techniques.
- Deployment: Integrate the models into the business process and make them accessible to stakeholders.

The results of this project contain final probability of spaceX will reuse their stage 1 rocket and the price of their single rocket launch

# Introduction

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This project is proposed to help the Space Y in making such new rocket launches competing the company's competitor SpaceX owned by Allon Musk. SpaceX is the most successful rocket launcher company by current time. So it is so useful for us to study from them about rocket launch to make ours as good as theirs.

This project will help readers about the price of a single rocket launch and the probability of weather SpaceX will reuse their stage 1 rocket or not.



Section 1

# Methodology

# Methodology

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## Executive Summary

- Data collection methodology:

We use GET request and web scraping for data collection

- Perform data wrangling

We remove NaN value and replace them with the average value of the column. then we only take the valuable variable and make dataframe of them.

- Perform exploratory data analysis (EDA) using visualization and SQL
- Perform interactive visual analytics using Folium and Plotly Dash
- Perform predictive analysis using classification models

we use KNN, Decision tree, SVM, and Logistic regression as the predictive model

# Data Collection – SpaceX API

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first we use GET request and normalize the data with 'json\_normalize' function. the return is data frame with value of dictionaries. to get the value of variable we want, we have to use GET request again to the considered link and dont forget to add 'rocket' value to the url.

github link:

<https://github.com/arsya-ux/Capstone-DS/blob/9597a9ecb7667b2a45bdea1004ba71b3d361b380/SpaceX%20API.ipynb>

# Data Collection - Scraping

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- Web scraping is used to data collection, first we use GET request and parse the data with BeautifulSoup function. then we get the first table by 'find\_all' function which return with the name of columns. to get the table value, we call the second table and make the dataframe.

- Github URL:

<https://github.com/arsya-ux/Capstone-DS/blob/9597a9ecb7667b2a45bdea1004ba71b3d361b380/SpaceX%20Scraping.ipynb>



# Data Wrangling

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from dataset\_part\_1.csv file, we make new column called 'Class' represent the success or not the rocket launch. this column was made by the launch result column from the dataset file

- The Data Wrangling notebook can be accessed with this link:

<https://github.com/arsya-ux/Capstone-DS/blob/9597a9ecb7667b2a45bdea1004ba71b3d361b380/Data%20Wrangling.ipynb>

# EDA with Data Visualization

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- In this stage, we will visualize many of variable and see the correlation of each variable. such as launchsite vs payload, launchsite vs flight number and much more.

github url:

<https://github.com/arsya-ux/Capstone-DS/blob/9597a9ecb7667b2a45bdea1004ba71b3d361b380/EDA%20Data%20Visualization.ipynb>

# EDA with SQL

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- This stage queried dataframe which is used to gain information such as first successful rocket launch, maximum payload, and rocket boosters type.

- github url:

<https://github.com/arsya-ux/Capstone-DS/blob/9597a9ecb7667b2a45bdea1004ba71b3d361b380/EDA%20SQL.ipynb>

# Predictive Analysis (Classification)

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- We use KNN, SVM, Decision tree, and logistic regression. we test our model by using 'score' function to see its accuracy and rebuilt the model with different parameters until we get the highest accuracy

github url:

<https://github.com/arsya-ux/Capstone-DS/blob/9597a9ecb7667b2a45bdea1004ba71b3d361b380/Predictive%20Analysis.ipynb>

# Results

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- The results of these stages are spacex data frame which contain important variable like class, serial, launchsite, flight number and much more
- data visualization of each variable to see the correlation of variables
- predictive analysis using KNN, decision tree, Logistic regression, and SVM to predict the probability of spaceX reuse their rocket boosters.
- queried dataframe which is used to gain information such as first successful rocket launch, maximum payload, and rocket boosters type.



The background of the slide is an abstract composition. It features a solid blue area on the left side, which transitions into a dynamic pattern of diagonal streaks in shades of blue and red on the right. These streaks are layered over a faint, grid-like pattern, creating a sense of depth and movement, reminiscent of a digital or data visualization theme.

Section 2

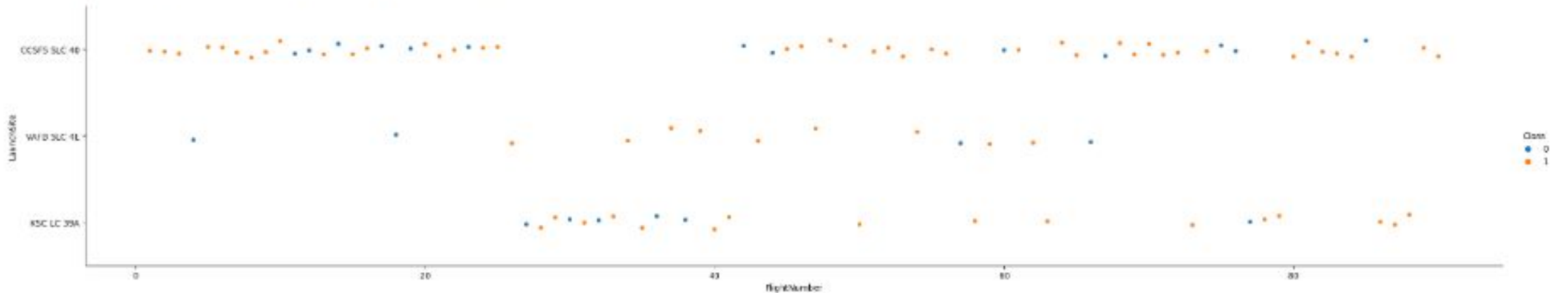
# Insights drawn from EDA



# Flight Number vs. Launch Site

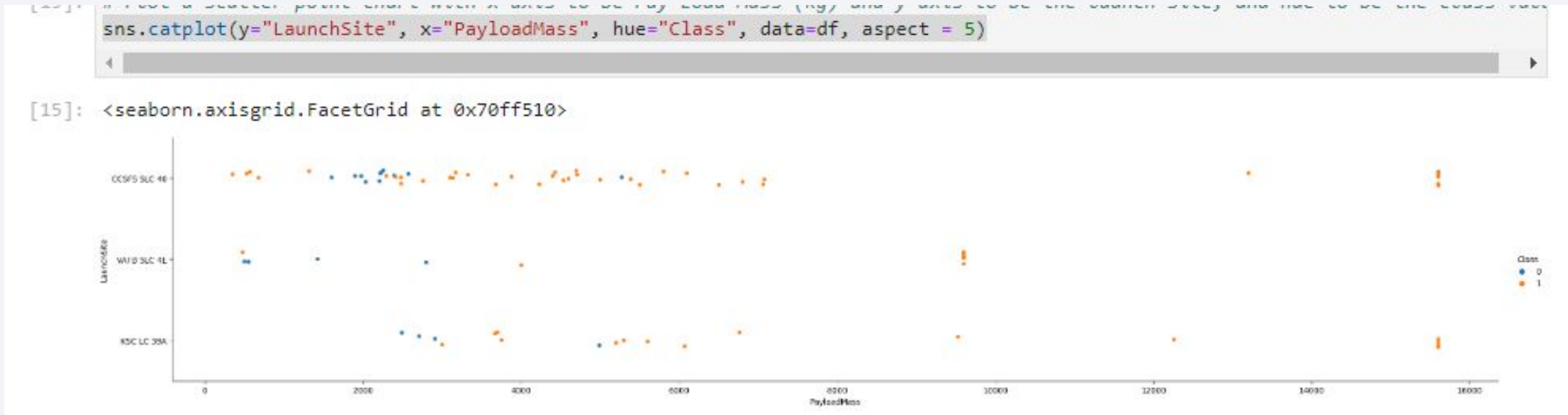
```
sns.catplot(y="LaunchSite", x="FlightNumber", hue="Class", data=df, aspect = 5)
```

```
[In]: <seaborn.axisgrid.FacetGrid at 0x60c9b10>
```



CCSFS SLC-40 is used to do more launches than any other launchsite

# Payload vs. Launch Site

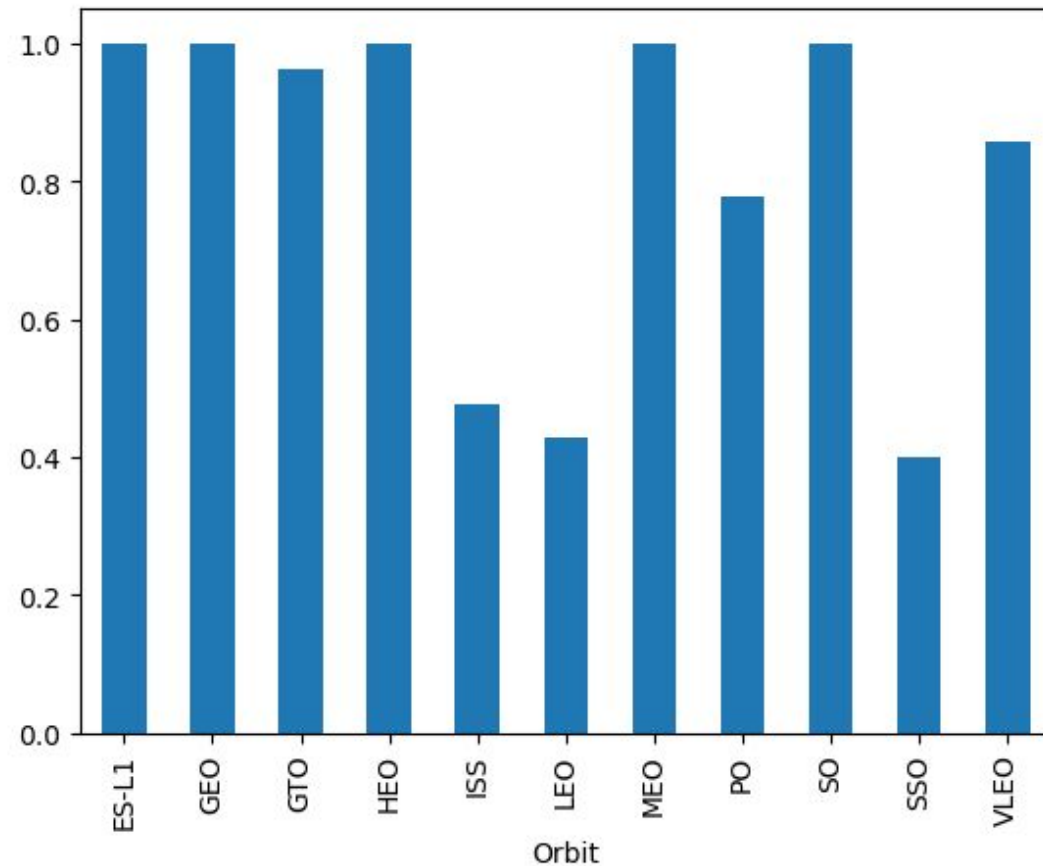


CCSFS SLC-40 have the highest number of total launch that carried the maximum payload mass

# Success Rate vs. Orbit Type

- There are multiple of orbit type that has the highest success rate (100%)

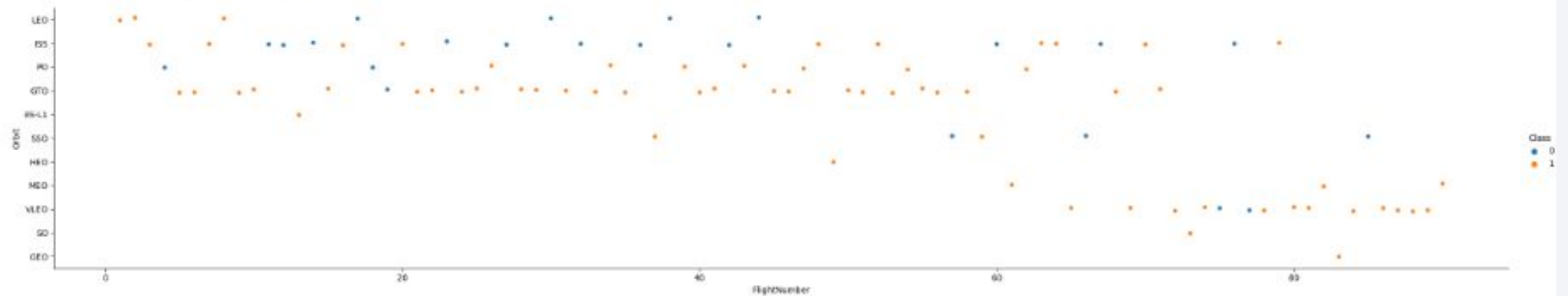
7]: <AxesSubplot:xlabel='Orbit'>



# Flight Number vs. Orbit Type

```
[18]: # Plot a scatter point chart with x axis to be FlightNumber and y axis to be the Orbit, and hue to be the class value  
sns.catplot(y="Orbit", x="FlightNumber", hue="Class", data=df, aspect = 5)
```

```
[18]: <seaborn.axisgrid.FacetGrid at 0x7248ff8>
```



The highest number of orbit target of all launches are from GTO to LEO

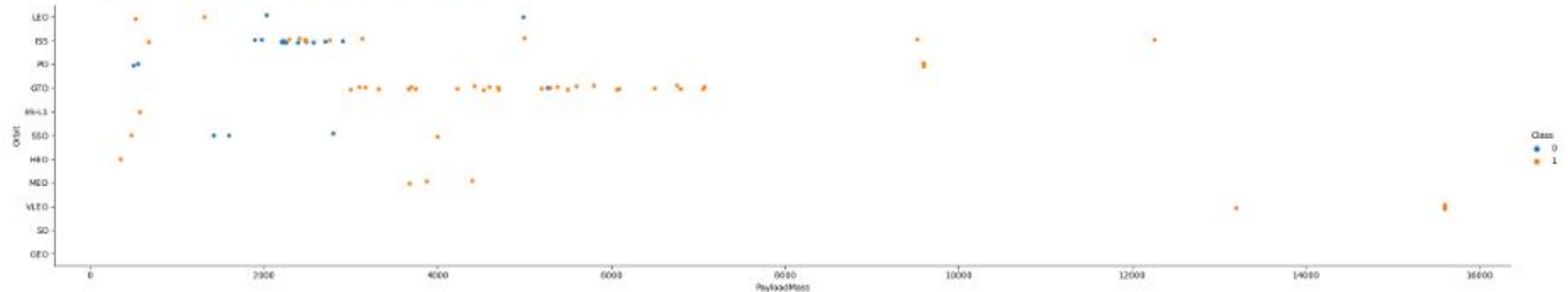


# Payload vs. Orbit Type

Similarly, we can plot the Payload vs. Orbit scatter point charts to reveal the relationship between Payload and Orbit type

```
[20]: # Plot a scatter point chart with x axis to be Payload and y axis to be the Orbit, and hue to be the class value  
sns.catplot(y="Orbit", x="PayloadMass", hue="Class", data=df, aspect = 5)
```

```
[20]: <seaborn.axisgrid.FacetGrid at 0x5986520>
```

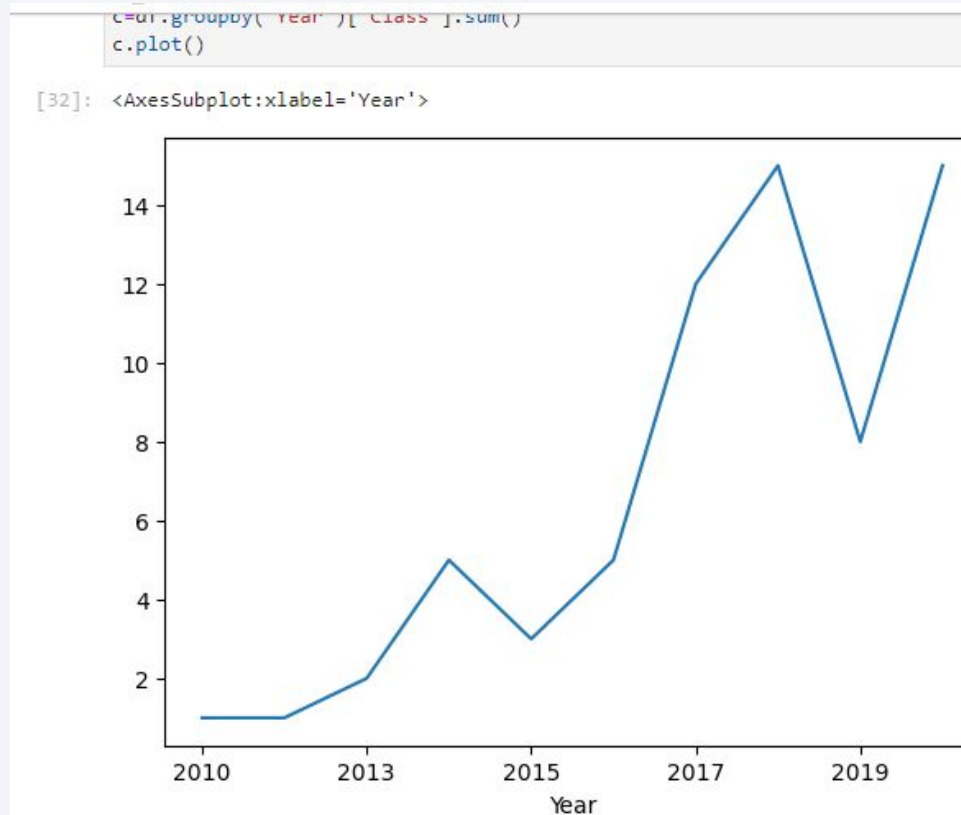


- The maximum payload carried is to VLEO Orbit

# Launch Success Yearly Trend

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From 2013, the success rate  
kee rising until 2020



# All Launch Site Names

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There is only 4 Launch Site name

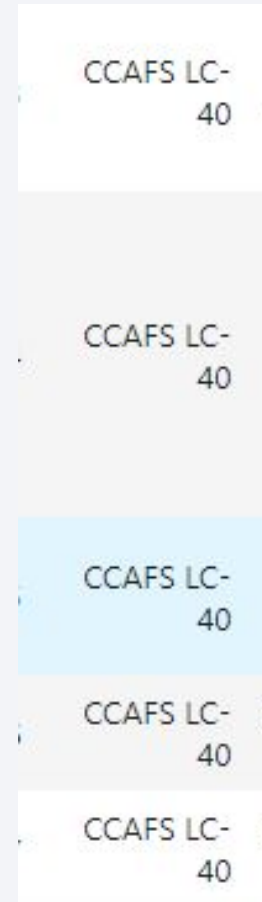
DONE.

]:	<b>Launch_Site</b>
	CCAFS LC-40
	VAFB SLC-4E
	KSC LC-39A
	CCAFS SLC-40

# Launch Site Names Begin with 'CCA'

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All of the Launch Site that start with 'CCA' is CCAFS LC-40



CCAFS LC-40
CCAFS LC-40
CCAFS LC-40
CCAFS LC-40
CCAFS LC-40

# Total Payload Mass

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There is total of 45.6 tons of mass that carried by SpaceX rockets

```
Done.  
5]: TOTAL_MASS  
45596
```



# Average Payload Mass by F9 v1.1

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The average mass for each F9 v1.1 is 3 tons

```
Done.  
16]: AVERAGE_MASS  
-----  
2928.4
```

# First Successful Ground Landing Date

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The date is 22 December 2015

```
9]: SELECT MAX(DATE) AS FIRST_SUCCESSFUL_GROUND_LANDING_DATE
* sqlite:///my_data1.db
Done.
9]: FIRST_SUCCESSFUL_GROUND_LANDING_DATE
2015-12-22
```

Task 6

# Successful Drone Ship Landing with Payload between 4000 and 6000

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Here is the list of booster that landed successfully with payload between 4000 and 6000 kg

[21]: **Booster\_Version**

F9 FT B1021.1

F9 FT B1022

F9 FT B1023.1

F9 FT B1026

F9 FT B1029.1

F9 FT B1021.2

F9 FT B1029.2

F9 FT B1036.1

F9 FT B1038.1

F9 B4 B1041.1

F9 FT B1031.2

F9 B4 B1042.1

F9 B4 B1045.1

F9 B5 B1046.1

# Total Number of Successful and Failure Mission Outcomes

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There is almost 98% in successful landing

```
Done.  
[32]: COUNT(CASE WHEN Mission_Outcome = 'Success' THEN 1  
        ELSE NULL END)    COUNT(CASE WHEN Mission_Outcome LIKE 'Failure%%' THEN 1  
        ELSE NULL END)  
        98                1
```

# Boosters Carried Maximum Payload

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There is multiple of boosters type that carried the maximum amount of payload

```
* sqlite:///my_data1.db
Done.
[63]: Booster_Version
```

F9 B5 B1048.4
F9 B5 B1049.4
F9 B5 B1051.3
F9 B5 B1056.4
F9 B5 B1048.5
F9 B5 B1051.4
F9 B5 B1049.5
F9 B5 B1060.2
F9 B5 B1058.3
F9 B5 B1051.6
F9 B5 B1060.3
F9 B5 B1049.7



# 2015 Launch Records

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There is only two launch which all of that fail

[75]:					
YEAR	MONTH	Landing_Outcome	Booster_Version	Launch_Site	
2015	5	Failure (drone ship)	F9 v1.1 B1012	CCAFS LC-40	
2015	5	Failure (drone ship)	F9 v1.1 B1015	CCAFS LC-40	

# Rank Landing Outcomes Between 2010-06-04 and 2017-03-20

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The highest rank is no attemp and the lowest is failure(parachute)

[83]:

Landing_Outcome	Outcome_Count
No attempt	10
Success (ground pad)	5
Success (drone ship)	5
Failure (drone ship)	5
Controlled (ocean)	3
Uncontrolled (ocean)	2
Precluded (drone ship)	1
Failure (parachute)	1

A satellite view of Earth from space, showing the curvature of the planet and city lights at night. The image is a composite of a dark blue sky with stars and a view of the Earth's surface from space. The Earth's surface is mostly dark, with a dense network of yellow and orange lights representing city lights at night. The lights are concentrated in the lower right portion of the image, following the curve of the Earth. The upper portion of the image shows the dark blue sky with some stars visible.

Section 3

# Launch Sites Proximities Analysis

# Launch site location all over the globe

The launch site is in florida and california

The screenshot displays a JupyterLab environment. On the left, a file browser shows a directory structure with files like 'README.md' and 'Untitled Fol...'. The main area features a map of the United States with two blue location pins: one in California (near Los Angeles) and one in Florida (near Miami). The map is titled 'United States' and includes labels for major cities like Los Angeles, Phoenix, Toronto, New York, and Washington. Below the map, a code cell contains the following Python code:

```
[14]: print(df['Longitude'].unique())
      print(df['Latitude'].unique())
```

The bottom status bar indicates the current mode is 'Command' and the file is 'lab\_jupyter\_launch\_site\_location.jupyterlite.ipynb'. The system tray at the bottom shows the date as 28/08/2023 and the time as 18:12.

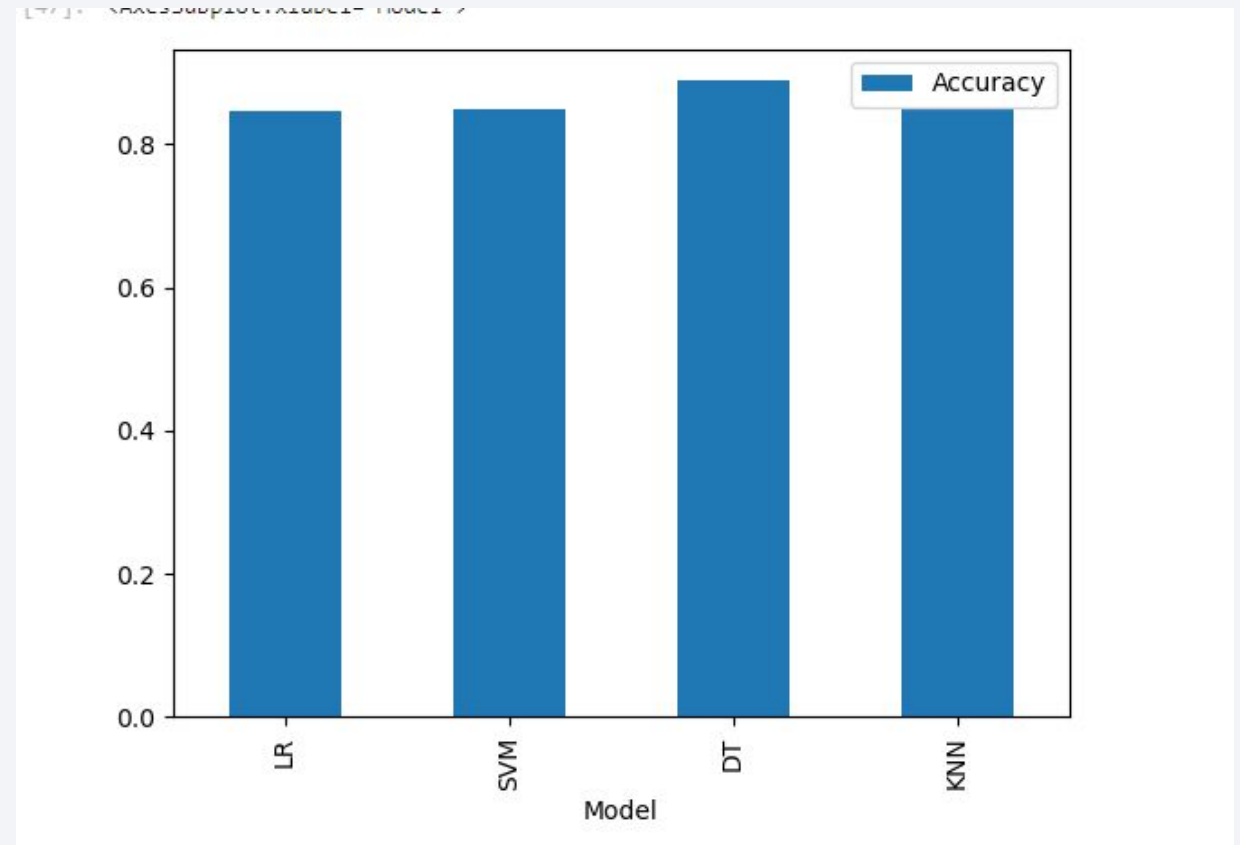
Section 5

# Predictive Analysis (Classification)

# Classification Accuracy

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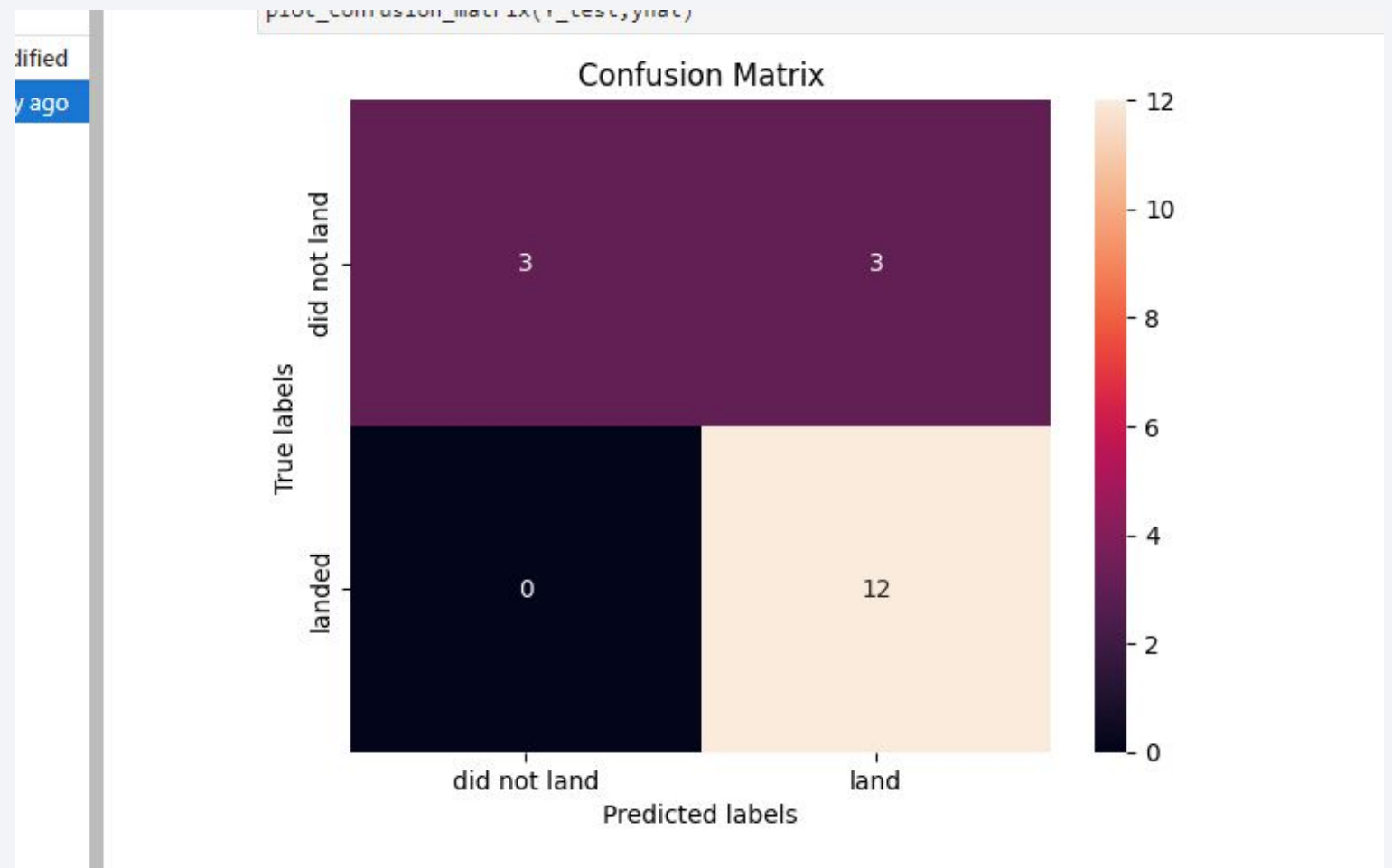
KNN and decision tree has the highest accuracy with 0.8482 accuracy value





# Confusion Matrix

There are such errors on land predictions. there are 3 value that supposed to be 'did not land' but our prediction predicted it as landed



# Conclusions

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SpaceX has multiple of boosters launchers that all of them has high success launch value. the cost of spaceX launcher are only in range of \$60M in price while other space exploration company's launchers price is almost touching \$160M. Most of spaceX launcher have the high probability of reusable rocket and success rate of launch



# Appendix

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dataset\_part\_1.csv  
dataset\_part\_2.csv  
dataset\_part\_3.csv

Thank you!

