



M2 - TSI

UE31 LABORATORY REPORT

Signal Estimation

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1 Introduction

In this report various methods for the estimation of parameters of a given data set are evaluated and compared. To cut down the problem's complexity, we use a simple model for the flux of an elliptic galaxy, as is described by the Sersic profile, which provides us an initial data set. This data set - a noisy image of a elliptic galaxy as it would have been taken by a ground-based telescope - is then used to evaluate different estimation approaches as the least square estimation, maximum likelihood estimation and Bayesian estimation.

2 Modelling a galaxy

The Sersic profile is very common amongst astrophysicists to model the flux of observed elliptic galaxies in a simple way, and is given by the equation

$$I(l, c) = \exp(-R(l, c)^{\frac{1}{n}}) \quad (1)$$

which describes the variation of intensity with respect to the distance of the galaxy's centre. The distance R of a pixel with the coordinates (l, c) from the galaxies centre is given by

$$R(l, c)^2 = \left(\frac{(l - l_0) \sin(\alpha) - (c - c_0) \cos(\alpha)}{\sigma_l} \right)^2 + \left(\frac{(l - l_0) \cos(\alpha) - (c - c_0) \sin(\alpha)}{\sigma_c} \right)^2 \quad (2)$$

with (l_0, c_0) being the galaxy's centre coordinates, (σ_l, σ_c) the two galaxy's axes length and the horizontal angle α .

This leads to the following equation modelling the data

$$d(l, c) = s + aI(l, c) + n(l, c) \quad (3)$$

with a as the amplitude of the galaxy, s the amplitude of the sky's background and $n(l, c)$ as noise.

Using the Sersic profile we can now generate an artificial elliptic galaxy, see fig. 1.

By assuming a Gaussian white noise with the known variance σ_n^2 and using the initial image of the galaxy, we can model the elliptic galaxy as it would have been seen by a ground-based telescope, see fig. 2.

The parameters used to create above mentioned figure are given as follows

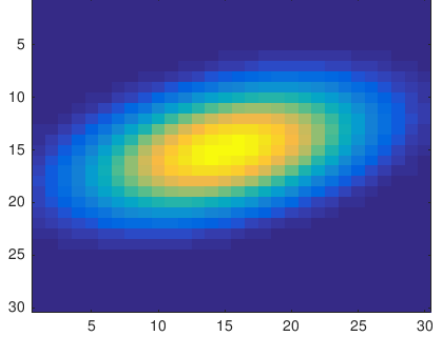


Figure 1: Initial data set

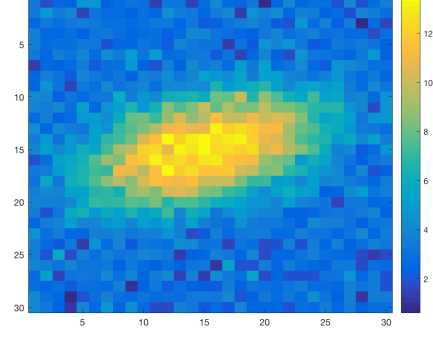


Figure 2: Random noise added

$$\begin{array}{llll}
 L, C = 30px & l_0, c_0 = 15 & \sigma_l = 10 & \sigma_c = 5 \\
 \alpha = 0.3 & n = 0.4 & a = 10 & s = 3
 \end{array}$$

with L, C as height respectively width of image in pixels, l_0, c_0 the galaxy's centre in pixel coordinates and σ_l, σ_c as length parameters.

3 Estimation with known Galaxy's location and shape parameters

Having successfully modelled a simple elliptic galaxy, this model is used as input data for the simulation of an estimation of the galaxy's and sky background's amplitude, while assuming that the galaxy's position and shape parameters are known. This estimation can be formulated via:

$$\mathbf{y} = \mathbf{H}\boldsymbol{\theta} + \mathbf{n}(c, l) \quad (4)$$

Here, \mathbf{y} is the actual measurement, in our case it is the intensity of the galaxy. However, one has to keep in mind that for the following steps, we use the simulated galaxy intensity as described above as our measured galaxy intensity. $\boldsymbol{\theta}$ is the vector of estimated parameters, which are in our case the galaxy's amplitude a and the background's amplitude s , so $\boldsymbol{\theta} = [s, a]^T$. \mathbf{H} is a matrix describing the underlying model, which in our case also depends on the pixel position since the intensity described by the sersic function depends on the distance towards the centre of the galaxy, and $\mathbf{n}(l, c)$ is a noise component also depending on the pixel position (l, c) . In order to satisfy equation 3 using equation 6, one has to define \mathbf{H} in a special matrix form, which is given by:

$$H_{l,c} = \begin{pmatrix} 1 & \exp(-R_{l,c}^{\frac{1}{n}}) \end{pmatrix} \quad (5)$$

probably
don't
need
this
ex-
plana-
tion
here,
see
above
text

Thus, \mathbf{H} is a $2 \times (L \cdot C)$ matrix, describing the intensity profile of the galaxy for each pixel (l,c). Therefore, our data \mathbf{d} describing the measured data for all pixels yields:

$$\mathbf{d} = \mathbf{H}\boldsymbol{\theta} + \mathbf{n}(c, l), \quad (6)$$

where \mathbf{d} is a vector with $L \cdot C$ elements.

In order to obtain maximum likelihood estimator for $\boldsymbol{\theta}$ as a function of \mathbf{d} , one has to calculate:

$$\boldsymbol{\theta} = (\mathbf{H}'\mathbf{H})^{-1} \cdot \mathbf{H} \cdot \mathbf{d} \quad (7)$$

The bias of that estimator could be calculated using $b_{\boldsymbol{\theta}}(\boldsymbol{\theta}_{init}) = E_{Y|\boldsymbol{\theta}_{init}}(\boldsymbol{\theta}) - \boldsymbol{\theta}_{init}$, where $\boldsymbol{\theta}_{init}$ is the vector of the true parameters that we want to find out. However, this bias is only applicable for a larger sets of simulations. The used matlab code performing this is shown in the appendix. The resulting maximum likelihood estimators for the galaxy's and the sky background's amplitudes are:

$$\boldsymbol{\theta} = [2.9576 \ 10.0131]^T$$

This result is very close to the original parameters used for the simulation of the data with $\boldsymbol{\theta}_{initial} = [3 \ 10]^T$ (see list of parameters above). However, we assumed the galaxy center and shape to be known, which drastically reduces the number of unknowns in this fit, and therefore results in a very good fit result.

4 Maximum likelihood estimation of all parameters

In the next step, we assumed that the galaxy's position and shape are unknown for the fit. Thus, now also the parameter vector $\boldsymbol{\nu} = [l_0, c_0, \sigma_l, \sigma_c, n]$ also needs to be fitted simultaneously to $\boldsymbol{\theta}$. Again, the corresponding model can be formulated as:

$$\mathbf{d} = \mathbf{H}(\boldsymbol{\nu})\boldsymbol{\theta} + \mathbf{n}(c, l),$$

The only difference now is that \mathbf{H} depends on the variable $\boldsymbol{\nu}$. Again, \mathbf{H} is a $2 \times (L \cdot C)$ - matrix, $\boldsymbol{\theta} = [s, a]^T$, \mathbf{d} a vector with $L \cdot C$ components and $\boldsymbol{\nu}$ as defined above a vector with six components. The goal is to obtain the maximum likelihood estimator by minimizing the quadratic cost function \mathbf{J} :

$$\mathbf{J}(\boldsymbol{\theta}, \boldsymbol{\nu}) = (\mathbf{d} - \mathbf{H}(\boldsymbol{\nu})\boldsymbol{\theta})^T (\mathbf{d} - \mathbf{H}(\boldsymbol{\nu})\boldsymbol{\theta}) \quad (8)$$

The optimization problem thus is a least square optimization. The maximum likelihood estimators are then given by:

$$(\boldsymbol{\theta}_{ML}, \boldsymbol{\nu}_{ML}) = \operatorname{argmin}(\mathbf{J})$$

For a large number of samples, this maximum likelihood estimator is unbiased with a variance equal to the inverse of the Fisher matrix: $\boldsymbol{\sigma}^2 = \mathbf{F}(\boldsymbol{\theta})^{-1}$

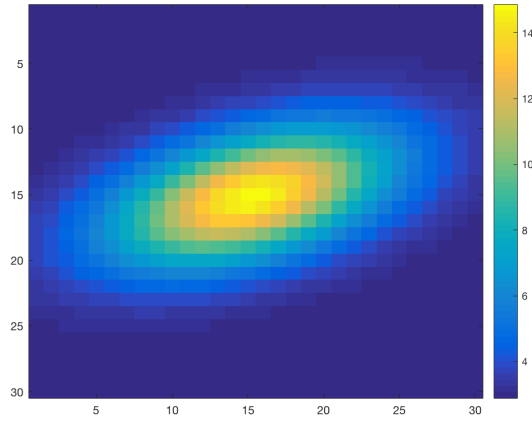


Figure 3: estimated galaxy from noisy data

5 Estimation in the Bayesian framework

5.1 Maximum a posteriori estimator

5.2 Posterior mean estimator

A Sersic function**B Least Square estimation**