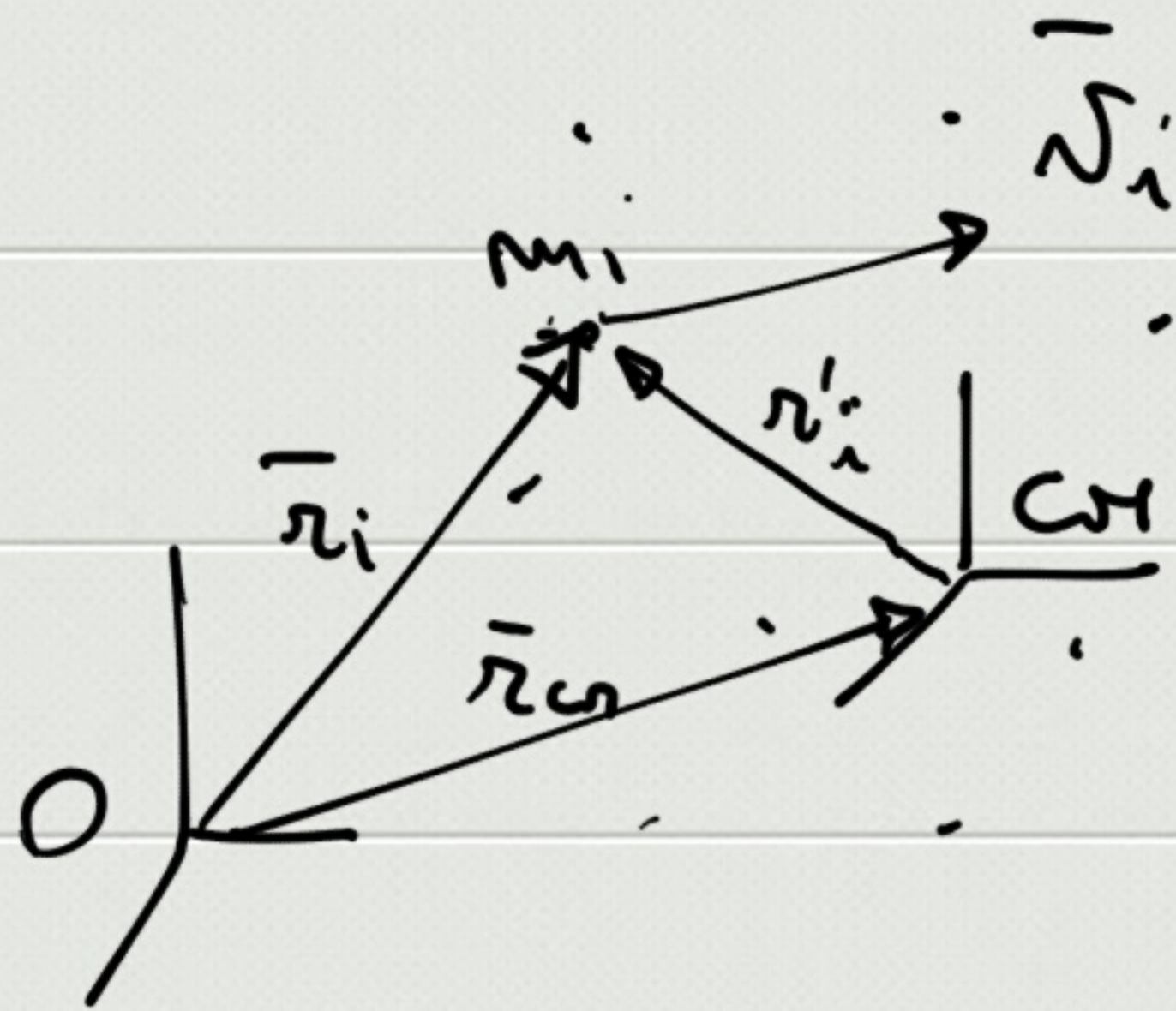


$$\vec{L}_O = \sum_i \vec{L}_{O,i} = \sum_i \underbrace{\vec{r}_i}_{\uparrow} \times m_i \underbrace{\vec{v}_i}_{\uparrow}$$



$$\vec{r}_i = \vec{r}'_i + \vec{r}_{CH}$$

$$\vec{v}_i = \vec{v}'_i + \vec{v}_{CH}$$

$$\Rightarrow \vec{L}_O = \sum_i (\vec{r}'_i + \vec{r}_{CH}) \times m_i (\vec{v}'_i + \vec{v}_{CH}) =$$

$$= \sum_i \vec{r}'_i \times m_i \vec{v}'_i + \sum_i \vec{r}'_i \times m_i \vec{v}_{CH} +$$

$$+ \sum_i \vec{r}_{CH} \times m_i \vec{v}'_i + \sum_i \vec{r}_{CH} \times m_i \vec{v}_{CH} =$$

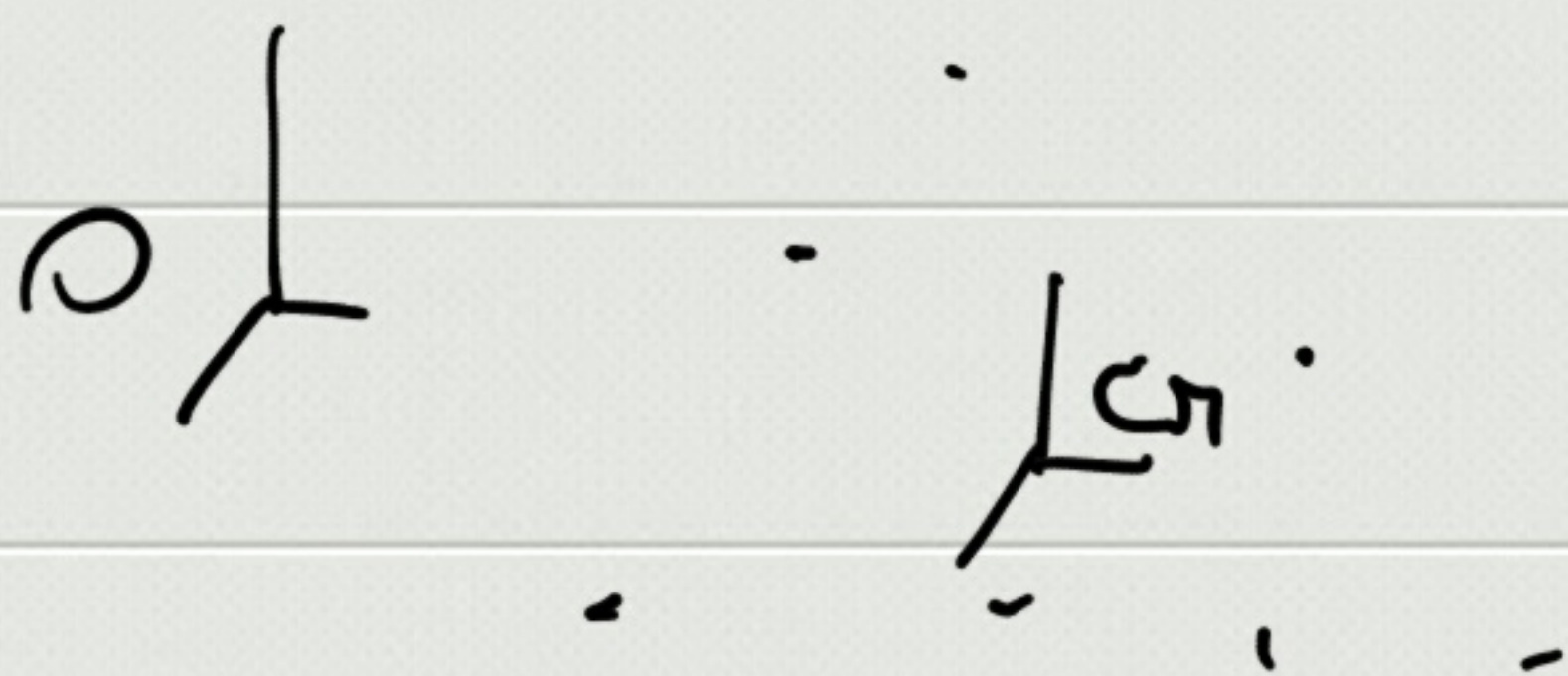
$$= \sum_i \vec{L}'_{CH,i} + \underbrace{\left(\sum_i m_i \vec{r}'_i \right)}_{\vec{0}} \times \vec{v}_{CH} + \vec{r}_{CH} \times \underbrace{\left(\sum_i m_i \vec{v}'_i \right)}_{\vec{0}} + \vec{r}_{CH} \times \sum_i m_i \vec{v}_{CH}$$

$$= \vec{L}'_{CH} + \vec{r}_{CH} \times M_{\text{tot}} \vec{v}_{CH}$$

$$\boxed{\vec{L}_O = \vec{L}'_{CH} + \vec{L}_{O,CH}}$$

T. König per le
momento angolare

$$\vec{v}_i = \vec{v}_i' + \vec{v}_{cm}$$



$$E_k = \sum_i E_{k,i} = \sum_i \frac{1}{2} m_i v_i^2 =$$

$$v_i^2 = \vec{v}_i \cdot \vec{v}_i$$

$$= \sum_i \frac{1}{2} m_i (\vec{v}_i' + \vec{v}_{cm})^2 =$$

$$= \sum_i \frac{1}{2} m_i v_i'^2 + \sum_i \frac{1}{2} m_i v_{cm}^2 + \sum_i \frac{1}{2} m_i \cdot 2 \vec{v}_i' \cdot \vec{v}_{cm} =$$

$$= \sum_i E_{k,i}' + \frac{1}{2} m_{tot} v_{cm}^2 + \left(\sum_i m_i \vec{v}_i' \right) \cdot \vec{v}_{cm}$$

$$= E_k' + \frac{1}{2} m_{tot} v_{cm}^2$$

$$\boxed{E_k = E_k' + E_{k,cm}}$$

Il König per
l'energia cinetica

$$E_k = E_k' + E_{k,cm}$$

SdR del CM



$(\bar{P}' = 0)$
 $(\bar{R}^E = 0)$ } moto di
traslazione

$$\bar{P} = m_{TOT} \bar{V}_{CM}$$

$$\bar{R}^E = m_{TOT} \bar{Q}_{CM}$$

$$\bar{L}_O = \bar{L}'_{CM} + \bar{L}_{O,CM}$$

$$\bar{M}_O^E = \bar{M}'_{CM} + \bar{M}_{O,CM}$$

$$E_K = E'_K + E_{K,CM}$$

} \Rightarrow moto di
rotazione