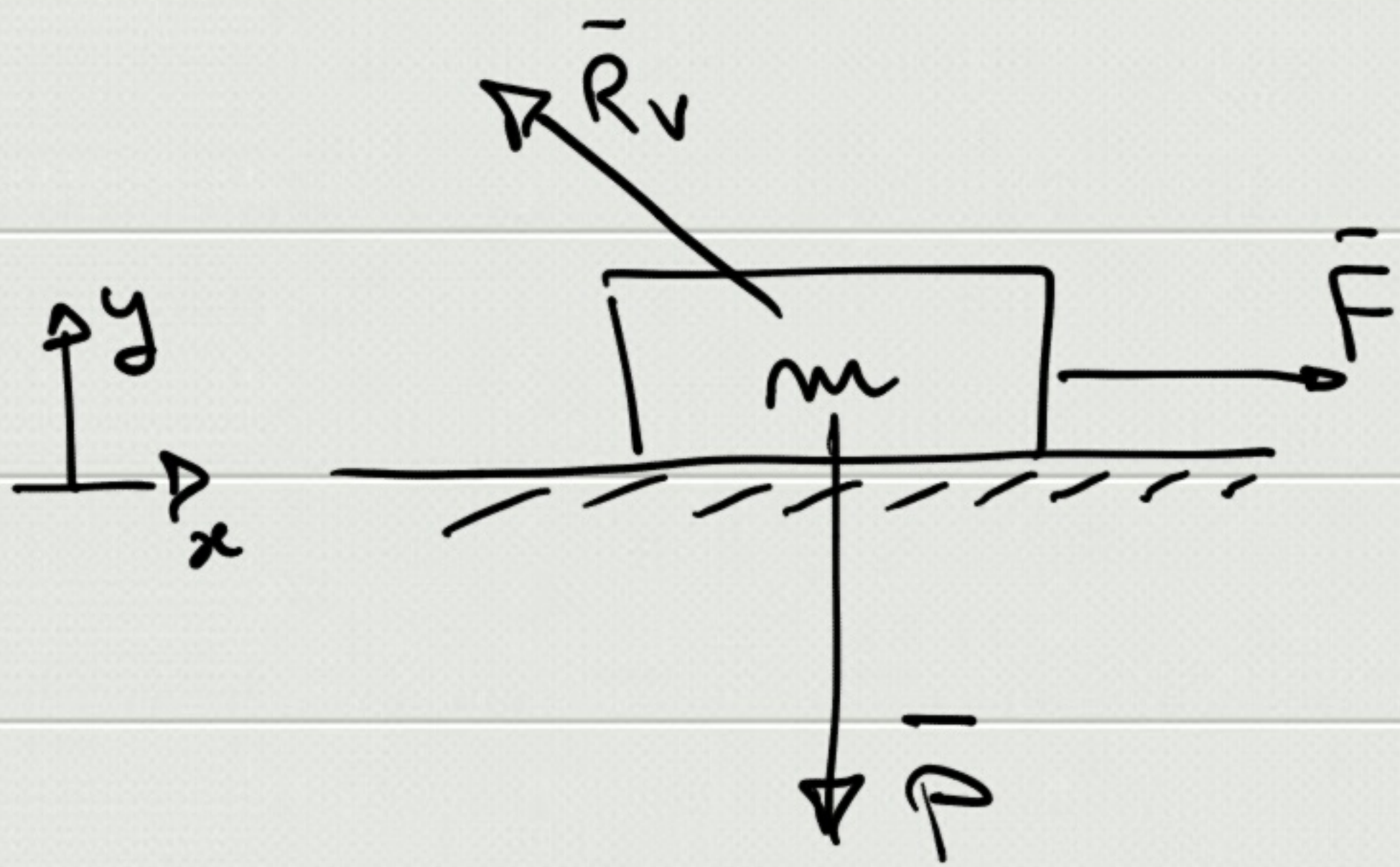


superficie scabra



Staticità



$$\Sigma \vec{F}_i = m \vec{a} = 0$$

$$\vec{R}_v + \vec{F} + \vec{P} = 0$$

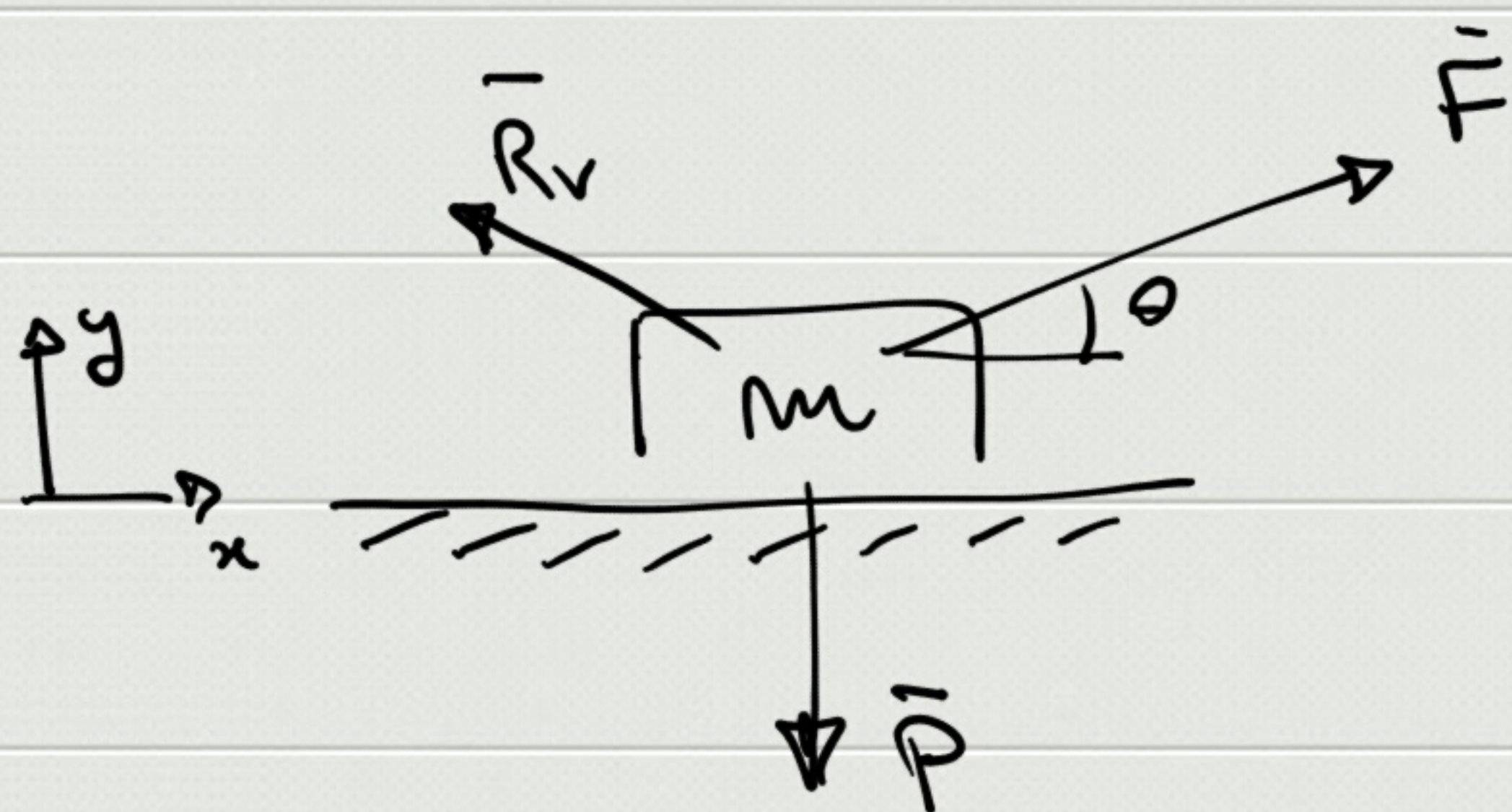
$$\vec{F} = F \hat{u}_x \quad \vec{P} = -mg \hat{u}_y$$

$$x: \begin{cases} R_{vx} + F = 0 \end{cases} \Rightarrow R_{vx} = F_{\text{att}} = -F$$

$$y: \begin{cases} R_{vy} - mg = 0 \end{cases} \Rightarrow R_{vy} = N = mg$$

Forse di attrito statico :

$$\boxed{F_{\text{as}} = F}$$

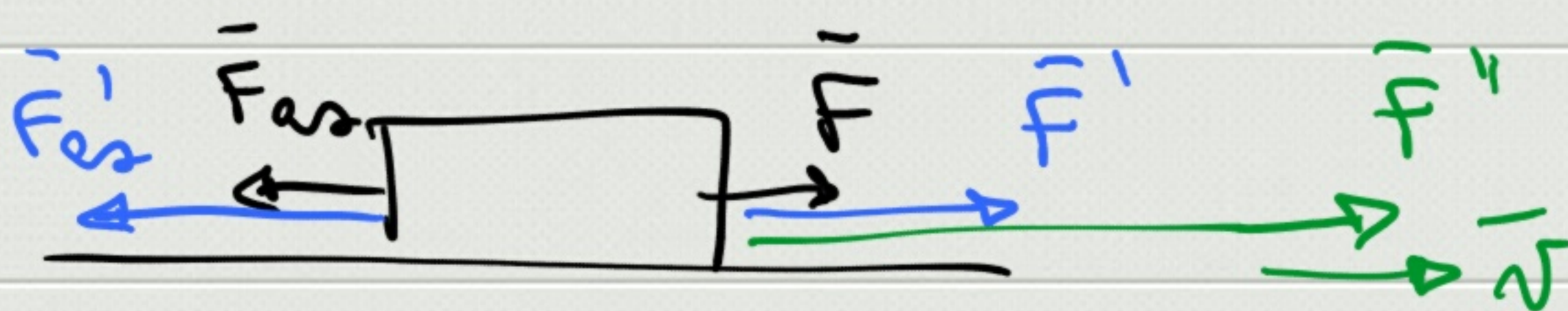


Statica

$$\bar{R}_v + \bar{F} + \bar{P} = 0$$

$$\left. \begin{aligned} x: R_{vx} + F \cos \theta &= 0 \Rightarrow R_{vx} = \boxed{F_{es} = -F \cos \theta} \\ y: R_{vy} + F \sin \theta - P &= 0 \Rightarrow R_{vy} = \boxed{N = P - F \sin \theta} \end{aligned} \right\} (*)$$

$$\left[N > 0 \quad F < \frac{mg}{\sin \theta} \right]$$



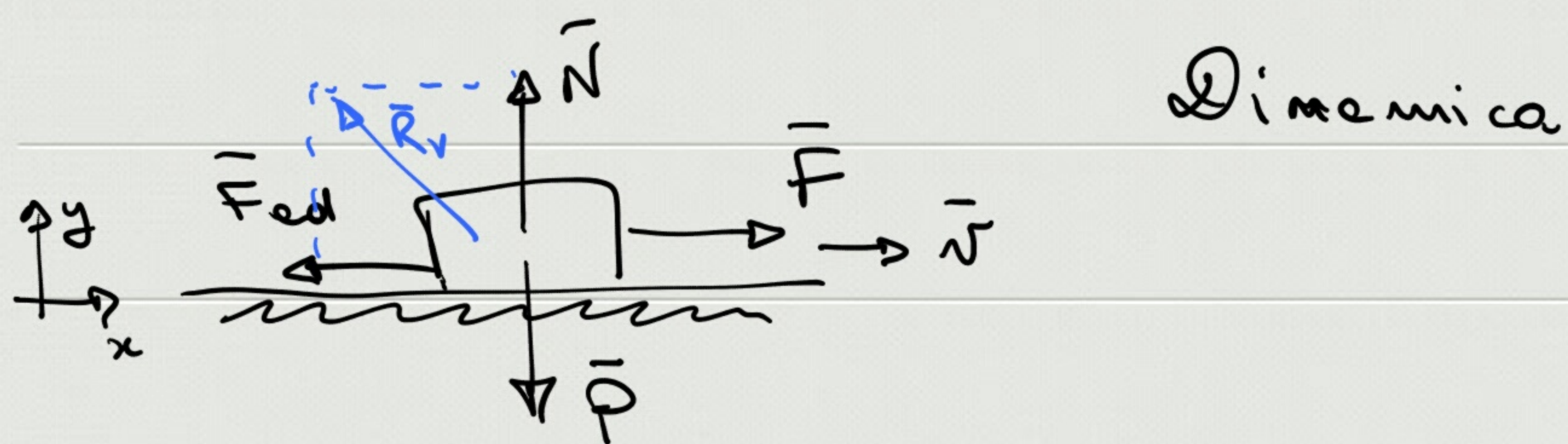
$$\boxed{F_{es} \leq F_{es, \max} = \mu_s N} \quad (\text{modulo})$$

μ_s : coefficiente di attrito statico

$$(*) \Rightarrow F_{es} = F \cos \theta \leq \mu_s N = \mu_s (mg - F \sin \theta)$$

$$F (\cos \theta + \mu_s \sin \theta) \leq \mu_s mg$$

$$\boxed{F \leq \frac{\mu_s mg}{\cos \theta + \mu_s \sin \theta}}$$



Dynamic

\Rightarrow Force of dynamic friction: \vec{F}_{ed}

$$\boxed{\vec{F}_{ed} = -\mu_d N \vec{U}_v}$$

μ_d : coefficient of dynamic friction

\vec{U}_v : vector of velocity

$$\overbrace{\vec{F}_{ed} + \vec{N}}^{\vec{R}_v} + \vec{F} + \vec{P} = m \vec{a}$$

$$x: -\mu_d N + F = m a_x$$

$$y: N - mg = m a_y = 0 \Rightarrow N = mg$$

$$\Rightarrow -\mu_d mg + F = m a$$

$$\Rightarrow \boxed{a = \frac{1}{m} (F - \mu_d mg)}$$