

$$r(t) = t^3 + 2t^2$$

$$|\bar{a}(t_1)| = a_1 = 16\sqrt{2} \text{ m/s}^2$$

$$t_1 = 2 \text{ s}$$

$$R = ?$$

$$|\bar{a}(t_1)| = \sqrt{a_T^2(t_1) + a_N^2(t_1)}$$

↑↑

~~$$a_T(t) = \cos t$$~~

~~$$a_T(t) = 3t^2 + 4t$$~~ $\leftarrow v(t)$

~~$$a_T(t) = 0$$~~

$$a_T(t) = 6t + 4 \quad *$$

$$r(t) = t^3 + 2t^2$$

$$v(t) = \frac{dr}{dt} = 3t^2 + 4t \quad \leftarrow$$

$$[a_T(t) = \frac{dv}{dt} = 6t + 4$$

$$a_N = \frac{v^2}{R} \Rightarrow [a_N(t) = \frac{v^2(t)}{R} = \frac{(3t^2 + 4t)^2}{R}$$

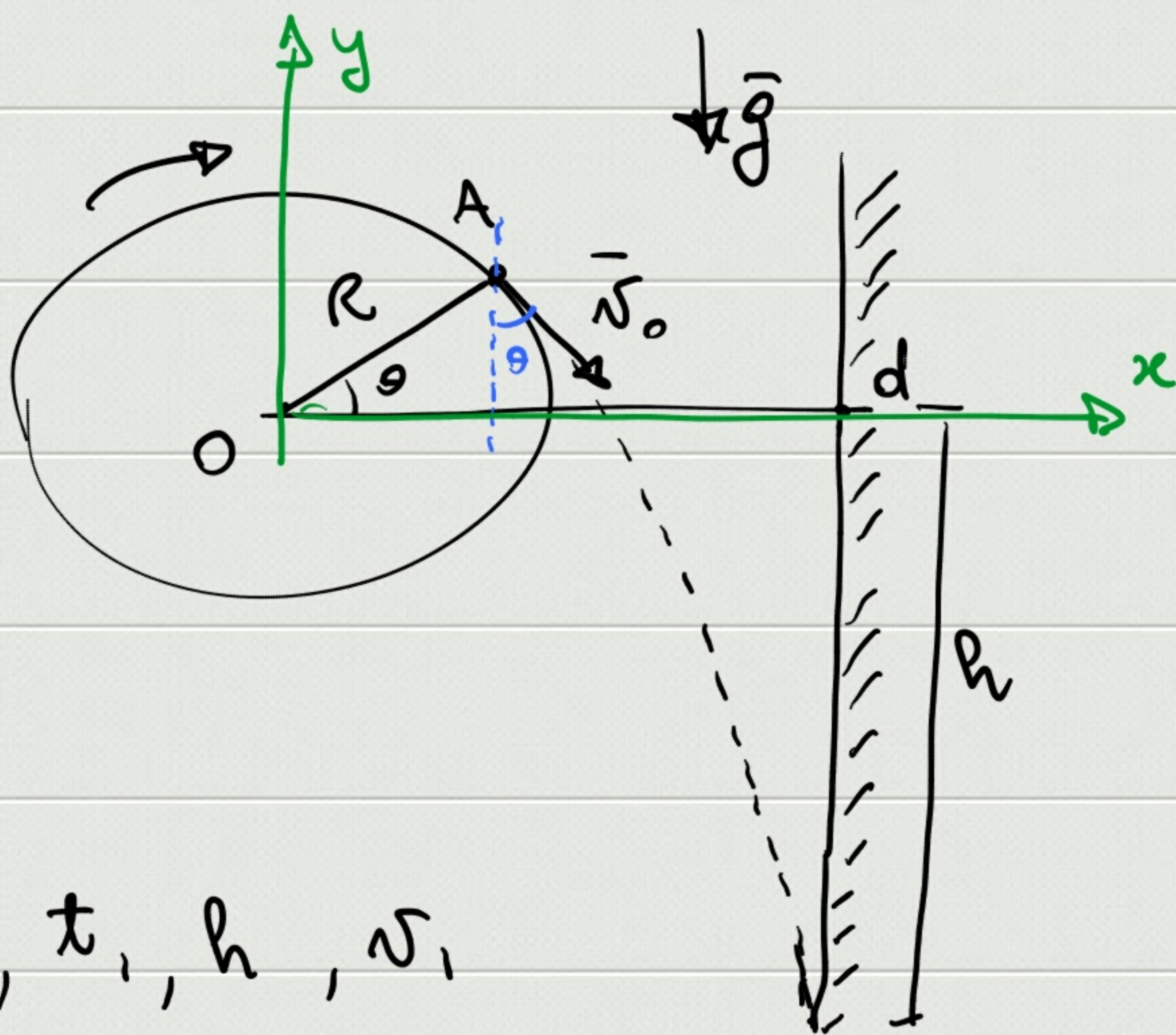
↑

$$a^2(t_1) = a_1^2 = a_T^2(t_1) + a_N^2(t_1)$$

$$a_N^2(t_1) = a_1^2 - a_T^2(t_1)$$

$$\frac{(3t_1^2 + 4t_1)^4}{R^2} = a_1^2 - (6t_1 + 4)^2$$

$$\Rightarrow R = \frac{(3t_1^2 + 4t_1)^2}{\sqrt{a_1^2 - (6t_1 + 4)^2}} = 25 \text{ m}$$



$$R = 0.4 \text{ m}$$

$$f = 1 \text{ g: } \omega / \text{s}$$

$$\theta = \pi/6$$

$$d = 0.8 \text{ m}$$

$$\vec{v}_0, t_1, h, v_1$$

$$f = \frac{1}{T} \quad v_0 = \frac{2\pi R}{T} = 2\pi R f = 2.52 \text{ m/s}$$

$$v_{0x} = v_0 \sin \theta$$

$$v_{0y} = -v_0 \cos \theta$$

$$\vec{r}(t) = \vec{r}_0 + \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$$

$$- x(t) = R \cos \theta + v_0 \sin \theta \cdot t \quad *$$

$$- x(t) = R \sin \theta - v_0 \cos \theta \cdot t$$

$$- x(t) = R \cos \theta + v_0 \sin \theta \cdot t - \frac{1}{2} g t^2$$

$$- x(t) = R \sin \theta + v_0 \cos \theta \cdot t - \frac{1}{2} g t^2$$

$$d = x(t_1) \Rightarrow t_1 = \frac{d - R \cos \theta}{v_0 \sin \theta} = 0.36 \text{ s}$$

$$y(t) = y_0 + v_{0y}t - \frac{1}{2}gt^2 =$$

$$= R \sin \theta - v_0 \cos \theta \cdot t - \frac{1}{2}gt^2$$

$$-h = R \sin \theta - v_0 \cos \theta \cdot t_1 - \frac{1}{2}gt_1^2$$

$$\Rightarrow h = 1.22 \text{ m}$$

$$\vec{v}(t) = \vec{v}_0 + \vec{a}t = \vec{v}_0 - \vec{g}t$$

$$\begin{cases} v_x = v_x(t_1) = v_{0x} = v_0 \sin \theta = 1.26 \text{ m/s} \\ v_y = v_y(t_1) = v_{0y} - gt_1 = -v_0 \cos \theta - gt_1 = \\ = -5.71 \text{ m/s} \end{cases}$$

$$v_1 = |\vec{v}_1| = \sqrt{v_{1x}^2 + v_{1y}^2} = 5.8 \text{ m/s}$$