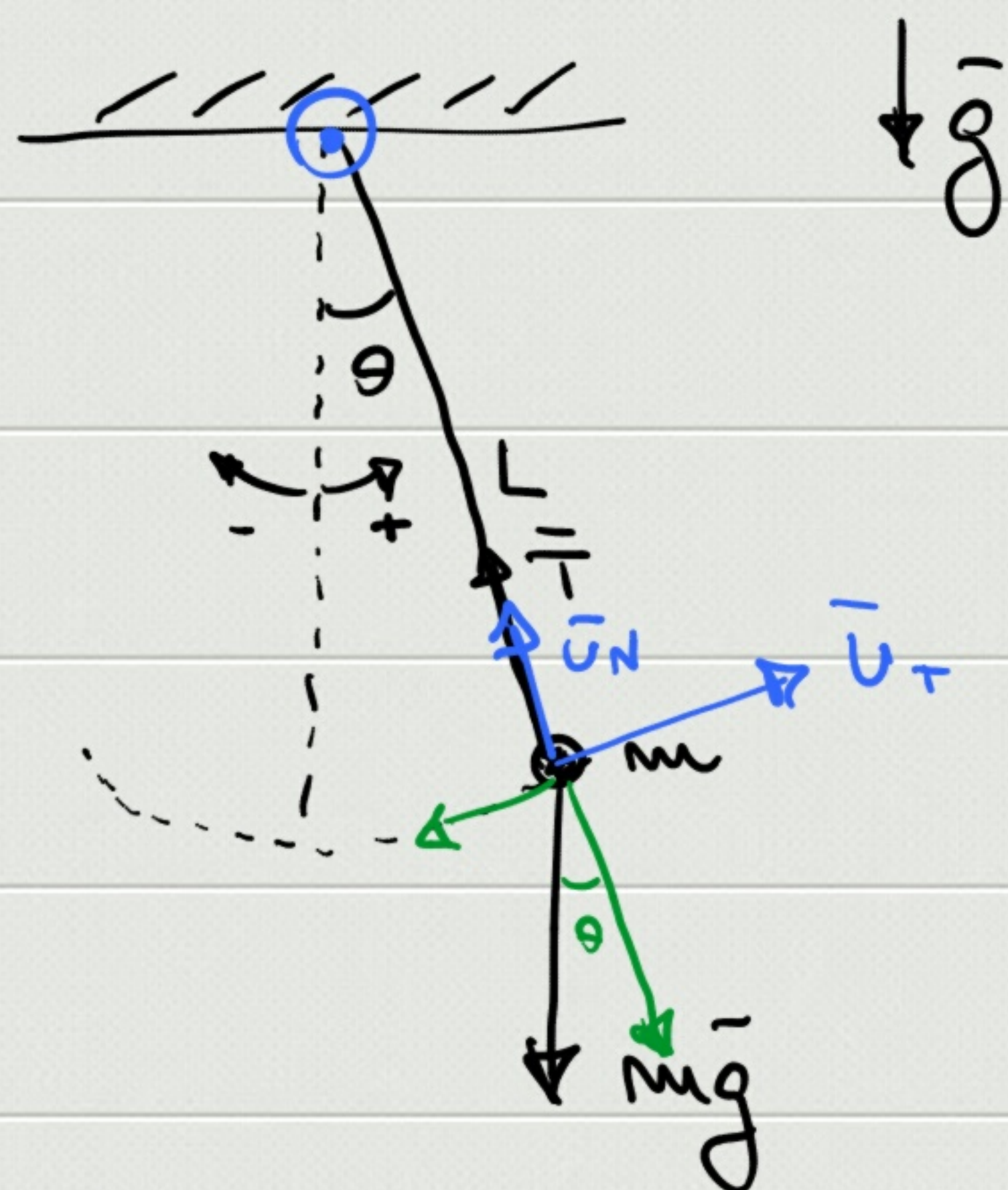


Pendolo semplice

$$m\vec{g} + \vec{T} = m\vec{a} = m(\vec{a}_T + \vec{a}_N)$$



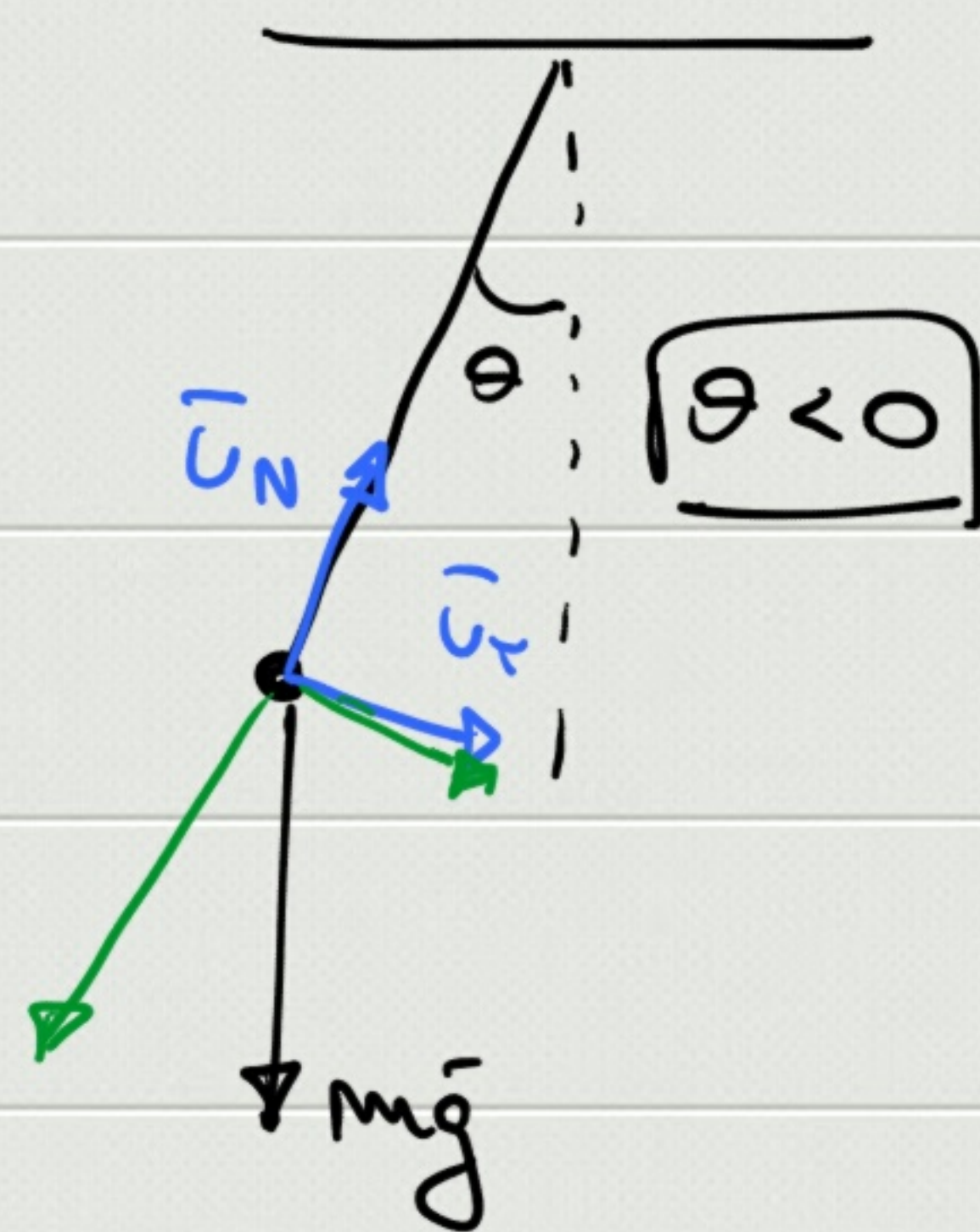
$$\vec{U}_T : \boxed{-mg \sin \theta = m a_T} \quad *$$

$$\vec{U}_N : -mg \cos \theta + T = m a_N = m \frac{v^2}{L}$$

$$a_T = \alpha L = \frac{d^2 \theta}{dt^2} L$$

$$\vec{U}_T : \frac{d^2 \theta}{dt^2} L = -g \sin \theta$$

$$\frac{d^2 \theta}{dt^2} + \frac{g}{L} \sin \theta = 0$$



piccole oscillazioni : $\boxed{\sin \theta \approx \theta} = \frac{\theta^3}{3!} + \dots$

$$\theta < 14^\circ \Rightarrow \sin \theta \approx \theta$$

$$\frac{g}{L} = \omega^2$$

$$\boxed{\frac{d^2 \theta}{dt^2} + \omega^2 \theta = 0}$$

$$\boxed{\theta(t) = \theta_0 \sin(\omega t + \phi)}$$

$$\boxed{T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{L}{g}}}$$

$$s(t) = \theta(t) L = L \theta_0 \sin(\omega t + \phi)$$

$$v(t) = \frac{ds}{dt} = L \theta_0 \omega \cos(\omega t + \phi)$$

$$T = mg \cos \theta + m \frac{v^2}{L} = T(t)$$