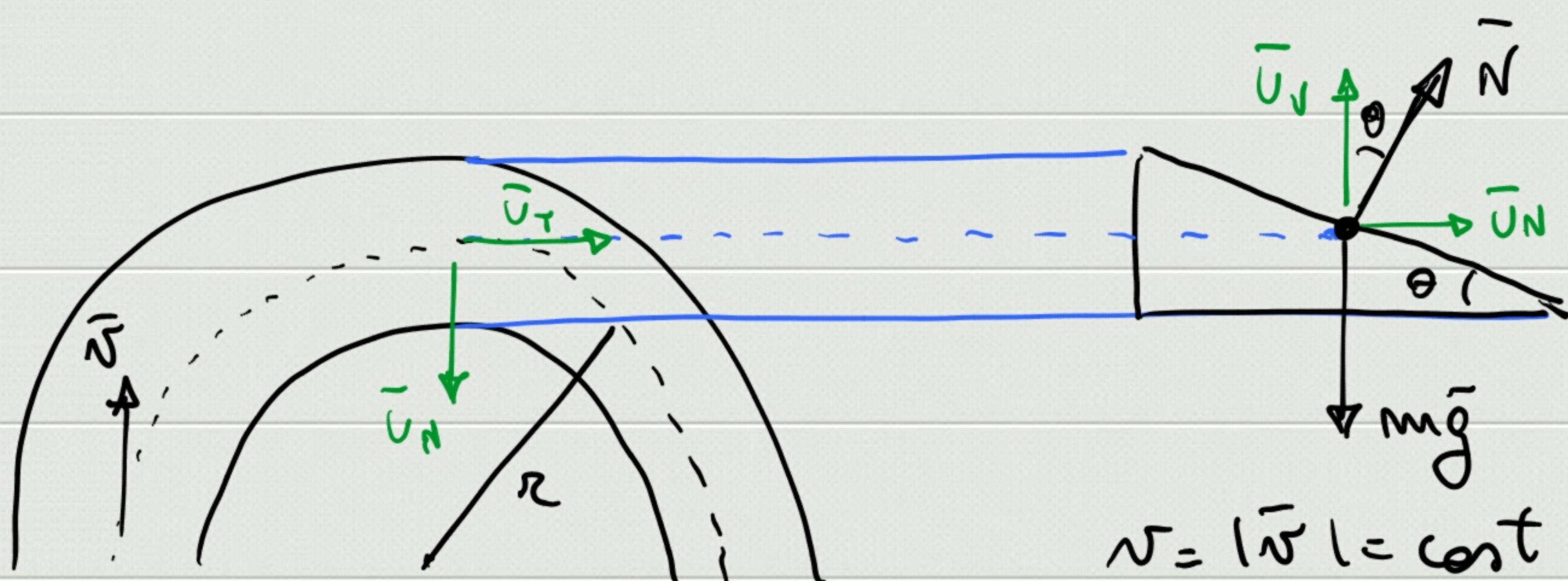


$$\vec{F} = m \vec{a} = m \vec{a}_T + m \vec{a}_N = m \underbrace{\frac{dv}{dt}}_{\vec{a}_T} \vec{u}_r + m \underbrace{\frac{v^2}{R}}_{\vec{a}_N} \vec{u}_N$$



$$v = |\vec{v}| = \text{cost}$$

liscio

moto circolare uniforme: $a_T = 0$ $a_N \neq 0$

$$m\vec{g} + \vec{N} = m\vec{a} = m\vec{a}_N$$

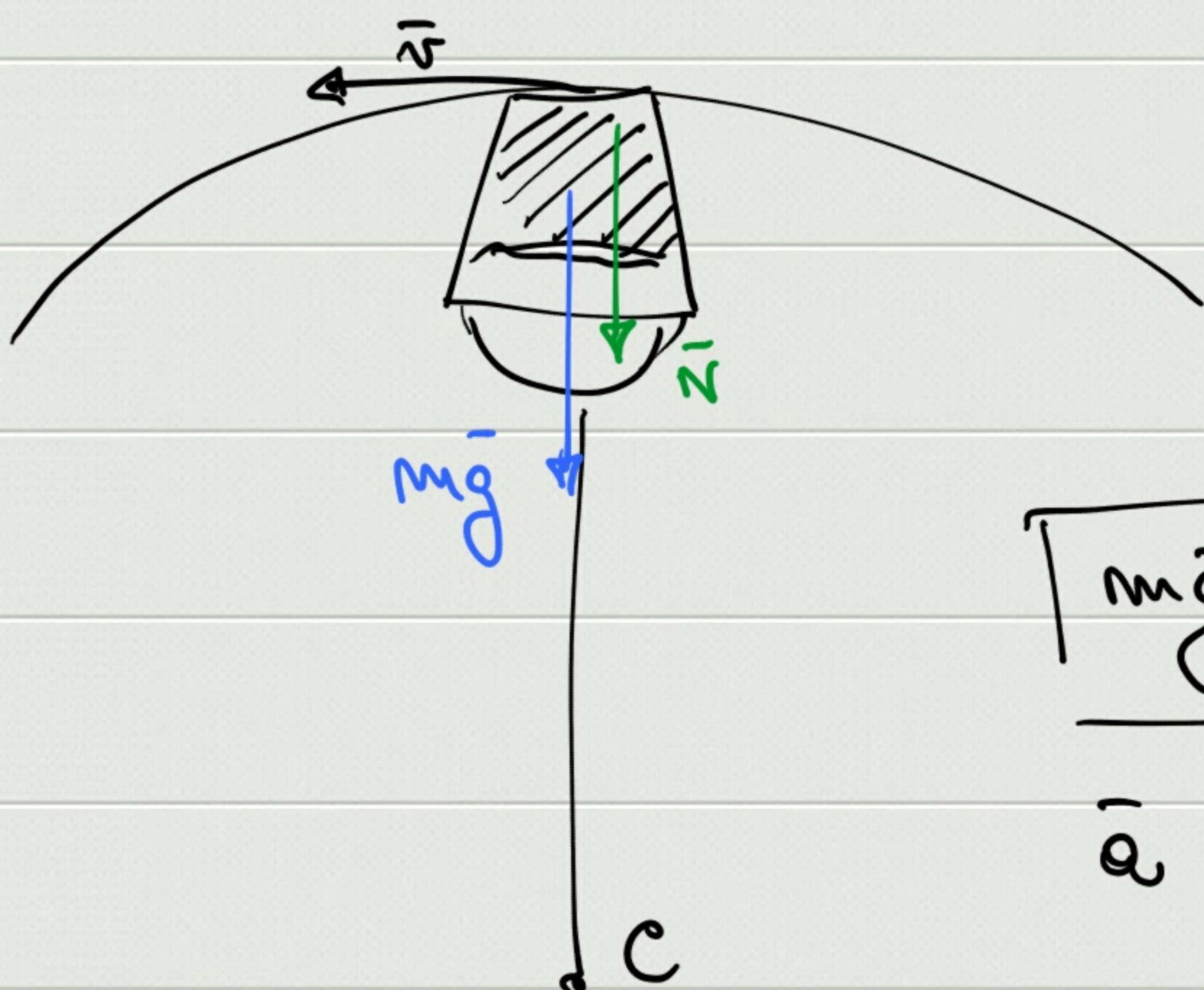
$$\vec{u}_N: N \sin \theta = m \frac{v^2}{r}$$

$$\vec{u}_r: N \cos \theta - mg = 0 \Rightarrow N = \frac{mg}{\cos \theta}$$

$$\Rightarrow \cancel{mg} \tan \theta = \cancel{m} \frac{v^2}{r} \Rightarrow \boxed{\tan \theta = \frac{v^2}{rg}}$$

$$v = 120 \text{ km/h} = 33.3 \text{ m/s} \quad r \sim 20 \text{ m}$$

$$\Rightarrow \theta = 80^\circ$$

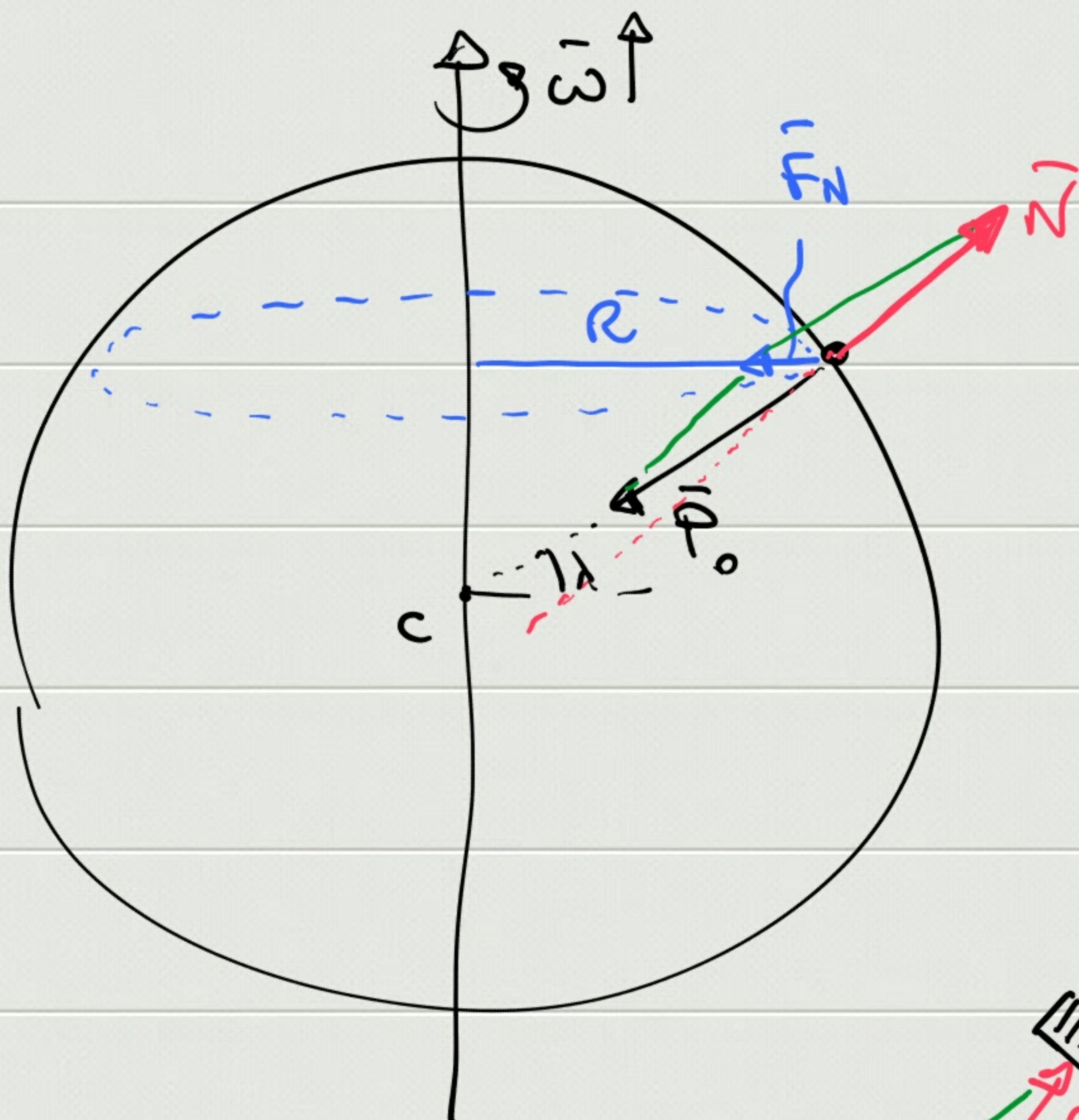


$$\boxed{m\vec{g} + \vec{N} = m\vec{a}}$$

$$\vec{a} = \vec{a}_N$$

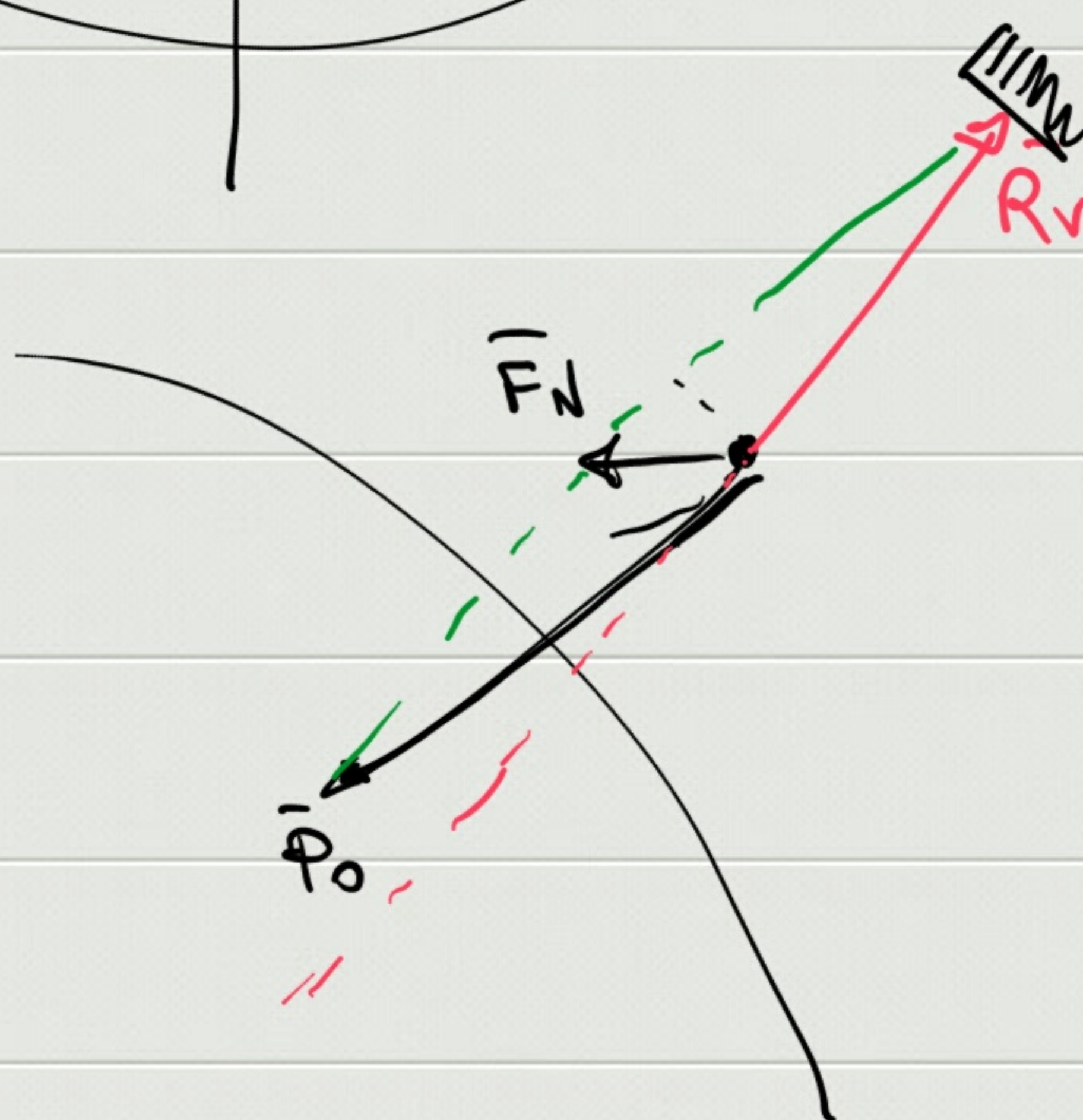
$$mg + N = m \frac{v^2}{R} \Rightarrow N = m \left(\frac{v^2}{R} - g \right) > 0$$

$$v^2 > gR \Rightarrow v > \sqrt{gR} = v_{\min}$$



$$\vec{p}_0 + \vec{R}_N = m \underbrace{\vec{a}_N}_{\vec{F}_N}$$

$$\boxed{\vec{p} = -\vec{N}}$$



$$a_N = \omega^2 R = \frac{2\pi}{24h} R_T \cos \lambda \approx 0.034 \cos \lambda \text{ m/s}^2$$