$$a(t) = \frac{dv}{dt} \Rightarrow \int dv = \int a(t) dt$$

$$v_0 \qquad v_0 = v(t_0)$$

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty$$

$$Q(t) = costante = a \Rightarrow [N(t) = N_0 + Q(t - to)]$$

moto rettilines uniformente

acalerato

$$N(t) = \frac{dx}{dt} \Rightarrow x(t) = x_0 + \int_{t_0}^{t} N(t) dt$$

$$x(t) = x_0 + \int_{t_0}^{t} \left[ \sqrt{3} + \int_{t_0}^{t} a(t) dt \right] dt =$$

$$= x_0 + \int_{t_0}^{t} \sqrt{3} dt + \int_{t_0}^{t} \left[ \int_{t_0}^{t} a(t) dt \right] dt$$

$$\Rightarrow x(t) = x_0 + x_0(t - t_0) + \begin{cases} t \\ a(t) dt \end{cases} dt$$

$$a(t)$$
-cost=  $a \Rightarrow$ 

$$x(t) = x_0 + x_0 (t - t_0) + a \int_{t_0}^{t} \left[ \int_{t_0}^{t} dt \right] dt =$$

$$= x_0 + x_0 (t - t_0) + a \int_{t_0}^{t} (t - t_0) dt = dt^* = dt$$

= 
$$x_0 + N_0 (t - t_0) + a \int_{t_0}^{t} (t - t_0) dt = dt^* = dt$$

= 
$$x_0 + N_0(t-t_0) + a \int_0^{t-t_0} dt^* =$$

= 
$$x_0 + N_0(t-t_0) + Q\left[\frac{1}{2}t^{*2}\right]_0^{t-t_0} =$$

to=0 => 
$$\left(x(t)=x_0+x_0t+\frac{1}{2}at^2\right)$$

$$Q = \frac{dN}{dt} \quad x = x(t)$$

$$w = -x^2 \implies f(x) = e^w = f(w)$$

$$\sqrt{x(t)} \quad \alpha \left[x(t)\right]$$

$$g[f(x)] \frac{dg}{dx} = \frac{dg}{df} \frac{df}{dx}$$

$$Q(x) = \frac{dN(x)}{dt} = \frac{dN}{dx} \frac{dx}{dt} = \sqrt{\frac{dN}{dx}}$$

$$\int_{\mathbf{x}} \mathbf{x} = \int_{\mathbf{x}} \nabla(\mathbf{x}) d\mathbf{x}$$

$$\int_{\mathbf{x}} \mathbf{x} = \int_{\mathbf{x}} \nabla d\mathbf{x}$$

$$\Rightarrow \frac{1}{2} |\nabla^2|^{\sqrt{x}} = \int_{x_0}^{x_0} a(x) dx$$

$$\Rightarrow \frac{1}{2} \left( N^2(x) - N_0^2 \right) = \int_{\mathcal{H}} a(x) dx$$

$$\Rightarrow \int_{\mathcal{N}_{0}}^{2} (x) = \int_{0}^{2} + 2 \int_{\mathcal{N}_{0}}^{2} a(x) dx$$