

# ESERCIZI SCHEDA 1

## ESERCIZIO 1

$$q_1 = -1,50 \text{ nC} = -1,50 \cdot 10^{-9} \text{ C}$$

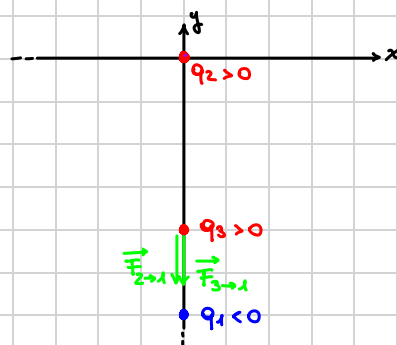
$$y_1 = -0,600 \text{ m}$$

$$q_2 = +3,20 \text{ nC} = +3,20 \cdot 10^{-9} \text{ C}$$

$$y_2 = 0 \text{ m}$$

$$q_3 = +5,00 \text{ nC} = +5,00 \cdot 10^{-9} \text{ C}$$

$$y_3 = -0,400 \text{ m}$$



$$\vec{F}_{3,1} = -k \frac{|q_1 q_3|}{(y_1 - y_3)^2} \hat{y}$$

$$\vec{F}_{2,1} = -k \frac{|q_1 q_2|}{(y_2 - y_1)^2} \hat{y}$$

$$\Rightarrow \vec{F}_3 = \vec{F}_{1 \rightarrow 3} + \vec{F}_{2 \rightarrow 3} = \left( -k \frac{|q_1 q_3|}{(y_1 - y_3)^2} - k \frac{|q_2 q_3|}{(y_2 - y_3)^2} \right) \hat{y}$$

$$= -k |q_3| \left( \frac{|q_1|}{(y_1 - y_3)^2} + \frac{|q_2|}{(y_2 - y_3)^2} \right) \hat{y}$$

$$= -8,988 \cdot 10^9 \frac{\text{Nm}^2}{\text{C}^2} \cdot 5 \cdot 10^{-9} \text{ C} \left( \frac{1,5 \cdot 10^{-9} \text{ C}}{(0,2 \text{ m})^2} + \frac{3,2 \cdot 10^{-9} \text{ C}}{(0,4 \text{ m})^2} \right) \hat{y}$$

$$= (-2,584 \cdot 10^{-6} \text{ N}) \hat{y} = (-2,584 \mu\text{N}) \hat{y} = \begin{bmatrix} 0 \\ -2,584 \mu\text{N} \\ 0 \end{bmatrix}$$

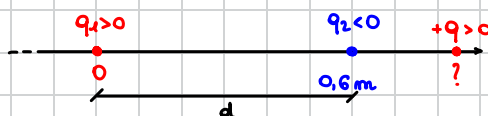
## ESERCIZIO 2

$$q_1 = 2,50 \mu\text{C} = 2,50 \cdot 10^{-6} \text{ C}$$

$$x_1 = 0 \text{ m}$$

$$q_2 = -3,50 \mu\text{C} = -3,50 \cdot 10^{-6} \text{ C}$$

$$x_2 = 0,600 \text{ m}$$



Devo trovare un punto  $x_0$  tale che  $\vec{F}(x_0) = \vec{F}_1(x_0) + \vec{F}_2(x_0) = 0$ :

$$\vec{F}(x_0) = k \frac{|q_1 q_1|}{x_0^2} \hat{x} - k \frac{|q_1 q_2|}{(d - x_0)^2} \hat{x} = 0$$

L'eliminazione algebrica del termine  $|q_1|$  giustifica la risposta affermativa alla seconda domanda.

$$k |q_1| \hat{x} \left( \frac{|q_1|}{x_0^2} - \frac{|q_2|}{(d - x_0)^2} \right) = 0 \Leftrightarrow |q_1| (d - x_0)^2 - |q_2| x_0^2 = 0$$

$$\Leftrightarrow |q_1| (d^2 + x_0^2 - 2dx_0) - |q_2| x_0^2 = 0$$

$$\Leftrightarrow (|q_1| - |q_2|) x_0^2 - 2d |q_1| x_0 + |q_1| d^2 = 0$$

Per chi non se la ricordasse, sto usando la formula del  $\Delta$ , utilizzabile quando in  $ax^2 + bx + c = 0$  b è pari:

$$x_{1,2} = \frac{-b \pm \sqrt{\left(\frac{b}{2}\right)^2 - ac}}{a}$$

$$x_{0,2} = \frac{d |q_1| \pm \sqrt{d^2 |q_1|^2 - |q_1| d^2 (|q_1| - |q_2|)}}{|q_1| - |q_2|}$$

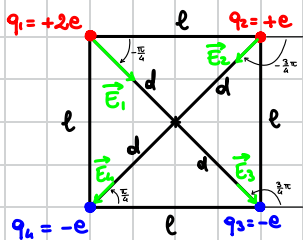
$$= \frac{d |q_1| \pm \sqrt{d^2 (|q_1|^2 - |q_1|^2 + |q_1| |q_2|)}}{|q_1| - |q_2|}$$

$$= d \frac{|q_1| \pm \sqrt{|q_1 q_2|}}{|q_1| - |q_2|}$$

$$x_{0,1} = d \frac{|q_1| - \sqrt{|q_1 q_2|}}{|q_1| - |q_2|} = 0,275 \text{ m} \quad \text{impossibile}$$

$$x_{0,2} = d \frac{|q_1| + \sqrt{|q_1 q_2|}}{|q_1| - |q_2|} = -3,275 \text{ m}$$

### ESERCIZIO 3



$$e = 1,602 \cdot 10^{-19} \text{ C}$$

$$l = 2 \text{ m} \quad \text{geometricamente, } d = \frac{\sqrt{2} l}{2}$$

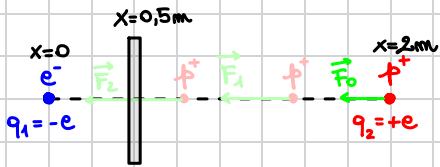
Viene comoda la scrittura vettoriale

$$\begin{aligned} \vec{E} &= \vec{E}_1 + \vec{E}_2 + \vec{E}_3 + \vec{E}_4 = \begin{pmatrix} k \frac{|q_1|}{d^2} \cos\left(\frac{\pi}{4}\right) \\ k \frac{|q_1|}{d^2} \sin\left(-\frac{\pi}{4}\right) \end{pmatrix} + \begin{pmatrix} k \frac{|q_1|}{d^2} \cos\left(-\frac{3\pi}{4}\right) \\ k \frac{|q_1|}{d^2} \sin\left(-\frac{3\pi}{4}\right) \end{pmatrix} + \begin{pmatrix} -k \frac{|q_1|}{d^2} \cos\left(\frac{3\pi}{4}\right) \\ -k \frac{|q_1|}{d^2} \sin\left(\frac{3\pi}{4}\right) \end{pmatrix} + \begin{pmatrix} -k \frac{|q_1|}{d^2} \cos\left(\frac{\pi}{4}\right) \\ -k \frac{|q_1|}{d^2} \sin\left(\frac{\pi}{4}\right) \end{pmatrix} \\ &= \begin{pmatrix} k \frac{2e}{d^2} \frac{\sqrt{2}}{2} \\ -k \frac{2e}{d^2} \frac{\sqrt{2}}{2} \end{pmatrix} + \begin{pmatrix} -k \frac{e}{d^2} \frac{\sqrt{2}}{2} \\ -k \frac{e}{d^2} \frac{\sqrt{2}}{2} \end{pmatrix} + \begin{pmatrix} k \frac{e}{d^2} \frac{\sqrt{2}}{2} \\ -k \frac{e}{d^2} \frac{\sqrt{2}}{2} \end{pmatrix} + \begin{pmatrix} -k \frac{e}{d^2} \frac{\sqrt{2}}{2} \\ -k \frac{e}{d^2} \frac{\sqrt{2}}{2} \end{pmatrix} \\ (d = \frac{\sqrt{2} l}{2} \Rightarrow d^2 = \frac{l^2}{2}) &= \begin{pmatrix} k 2\sqrt{2} \frac{e}{l^2} \\ -k 2\sqrt{2} \frac{e}{l^2} \end{pmatrix} + \begin{pmatrix} -k \sqrt{2} \frac{e}{l^2} \\ -k \sqrt{2} \frac{e}{l^2} \end{pmatrix} + \begin{pmatrix} k \sqrt{2} \frac{e}{l^2} \\ -k \sqrt{2} \frac{e}{l^2} \end{pmatrix} + \begin{pmatrix} -k \sqrt{2} \frac{e}{l^2} \\ -k \sqrt{2} \frac{e}{l^2} \end{pmatrix} \\ &= \begin{bmatrix} k \frac{e}{l^2} (2\sqrt{2} - \sqrt{2} + \sqrt{2} - \sqrt{2}) \\ k \frac{e}{l^2} (-2\sqrt{2} - \sqrt{2} - \sqrt{2} - \sqrt{2}) \end{bmatrix} = \begin{bmatrix} \sqrt{2} k \frac{e}{l^2} \\ -5\sqrt{2} k \frac{e}{l^2} \end{bmatrix} = \begin{bmatrix} 5,091 \cdot 10^{-10} \text{ N/C} \\ -25,454 \cdot 10^{-10} \text{ N/C} \end{bmatrix} \end{aligned}$$

$$\Rightarrow |\vec{E}| = \sqrt{E_x^2 + E_y^2} = 25,958 \cdot 10^{-10} \text{ N/C}$$

$$\Rightarrow \theta = \arctg\left(\frac{E_y}{E_x}\right) = -78,68^\circ = -1,373 \text{ rad}$$

#### Esercizio 4



$$x_i = 2 \text{ m}$$

$$\text{piastra: } x_p = 0,5$$

Cerco il tempo di collisione  $t_c$ :  $s(t) = s_0 + v_0 t - \frac{1}{2} a t^2$

$$s(t_c) = x_p = x_i - \frac{1}{2} a t_c^2$$

L'accelerazione è un'accelerazione media, ma in questo caso la forza non è costante, quindi neanche l'accelerazione. Uso il teorema della media integrale:

$$a = \frac{\bar{F}}{m} = \frac{1}{m} \cdot \frac{1}{x_p - x_i} \int_{x_i}^{x_p} F(x) dx = \frac{1}{m} \cdot \frac{1}{x_p - x_i} \int_{x_i}^{x_p} \frac{k |q_1 q_2|}{x^2} dx = \frac{1}{m} \cdot \frac{1}{x_p - x_i} \int_{x_i}^{x_p} \frac{k e^2}{x^2} dx = \frac{k e^2}{m (x_p - x_i)} \int_{x_i}^{x_p} \frac{1}{x^2} dx =$$

$$= \frac{k e^2}{m (x_p - x_i)} \left[ -\frac{1}{x} \right]_{x_i}^{x_p} = \frac{k e^2}{m (x_p - x_i)} \left( -\frac{1}{x_p} + \frac{1}{x_i} \right) = \frac{k e^2}{m (x_p - x_i)} \cdot \frac{x_p - x_i}{x_i x_p} = \frac{k e^2}{m x_i x_p}$$

$$\Rightarrow (x_i - x_p) - \frac{k e^2}{2 m x_i x_p} t_c^2 = 0 \Leftrightarrow t_c = \sqrt{\frac{2 m x_i x_p (x_i - x_p)}{k e^2}} = 4,66 \text{ s}$$

$$\text{massa protone} \approx 1,673 \cdot 10^{-27} \text{ kg}$$