

NB: disegno NON in scala

## Costanti geometriche

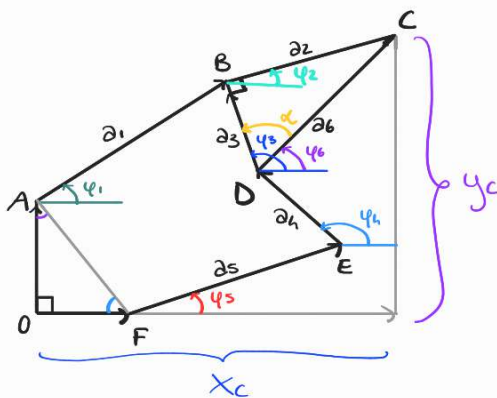
$$\begin{aligned} y_A &= 50 \text{ mm} & a_2 &= 50 \text{ mm} \\ x_F &= 100 \text{ mm} & a_3 &= 50 \text{ mm} \\ x_C &= 180 \text{ mm} & a_4 &= 90 \text{ mm} \\ y_C &= 150 \text{ mm} & a_5 &= 70 \text{ mm} \end{aligned}$$

## Soluzione

Inserire qui i risultati con una cifra decimale

**Analisi Cinematica di POSIZIONE (9 punti)**

movente  $q = a_1 = 159$



$$\begin{aligned} y_A &= 50 & a_2 &= 50 & a_4 &= 90 \\ x_F &= 100 & a_3 &= 50 & a_5 &= 70 \\ x_C &= 180 & y_C &= 150 & a_1 &= q = 159 \end{aligned}$$

$$a_6 = \sqrt{a_2^2 + a_3^2} = \sqrt{50^2 + 50^2} = 70,71 \text{ mm}$$

$$C \begin{cases} x_C = 180 \text{ mm} \\ y_C = 150 \text{ mm} \end{cases}$$

$$\alpha = \arccos\left(\frac{a_3^2 + a_6^2 - a_2^2}{2 a_3 a_6}\right) = 45^\circ \rightarrow \angle BDC = \angle BCD = 45^\circ$$

$$\overline{AF} = \sqrt{x_F^2 + y_A^2} = 111,80 \text{ mm}$$

$$\angle O\hat{F}A = \arctg\left(\frac{y_A}{x_F}\right) = 26,56^\circ$$

$$\angle O\hat{A}F = 90^\circ - 26,56^\circ = 63,44^\circ$$

$$AC = \sqrt{(x_C)^2 + (y_C - y_A)^2} = 205,9 \text{ mm}$$

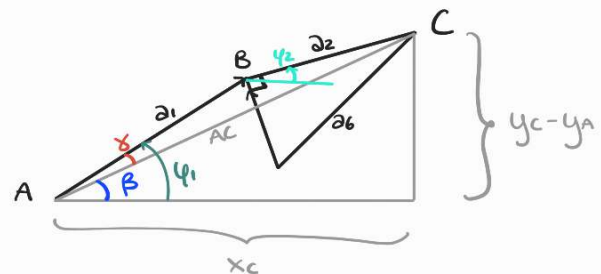
$$\beta = \arctg\left(\frac{y_C - y_A}{x_C}\right) = \arctg\left(\frac{100}{180}\right) = 29^\circ$$

$$\gamma = \arccos\left(\frac{a_1^2 + AC^2 - a_2^2}{2 a_1 \cdot AC}\right) = 5,5^\circ$$

$$\varphi_1 = \beta + \gamma = 34,5^\circ$$

$$B \begin{cases} x_B = a_1 \cos \varphi_1 = 131,03 \text{ mm} \sim 131 \text{ mm} \\ y_B = y_A + a_1 \sin \varphi_1 = 140,1 \text{ mm} \end{cases}$$

$$\varphi_2 = \arctg\left(\frac{y_C - y_B}{x_C - x_B}\right) = 11,4^\circ$$



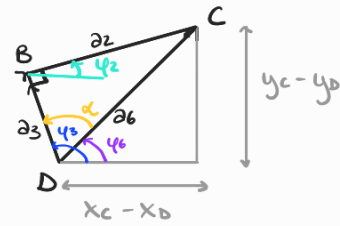
$$\begin{cases} a_3^2 = (x_D - x_B)^2 + (y_D - y_B)^2 \\ a_6^2 = (x_D - x_C)^2 + (y_D - y_C)^2 \end{cases} \quad \begin{cases} a_3^2 = x_D^2 - 2x_D x_B + x_B^2 + y_D^2 - 2y_D y_B + y_B^2 \\ a_6^2 = x_D^2 - 2x_D x_C + x_C^2 + y_D^2 - 2y_D y_C + y_C^2 \end{cases}$$

$$\begin{cases} 50^2 = x_D^2 - 262x_D + 131^2 + y_D^2 - 280,2y_D + 140,1^2 \\ 70,71^2 = x_D^2 - 360x_D + 180^2 + y_D^2 - 300y_D + 150^2 \end{cases}$$

$$\begin{cases} x_D^2 + y_D^2 - 262x_D - 280,2y_D = 50^2 - 140,1^2 - 131^2 \\ x_D^2 + y_D^2 - 360x_D - 300y_D = 70,71^2 - 150^2 - 180^2 \end{cases}$$

$$98x_D + 19,8y_D = 15611,08$$

$$x_D = \frac{15611,08 - 19,8y_D}{98} = 159,29 - 0,202y_D$$



OPPURE VEDEVO CHE  $\varphi_3 = \varphi_2 + 90^\circ$

$$D \begin{cases} x_D = a_1 \cos \varphi_1 - a_3 \cos \varphi_3 \\ y_D = y_A + a_1 \sin \varphi_1 - a_3 \sin \varphi_3 \end{cases}$$

$$25373,3 + 0,0408y_D^2 - 64,35y_D + y_D^2 - 41734 + 53y_D - 280,2y_D = 50^2 - 140,1^2 - 131^2$$

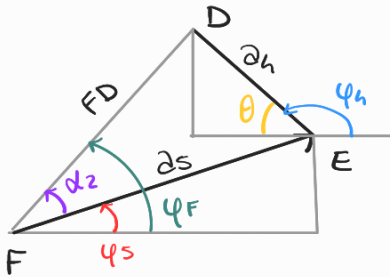
$$1,0408y_D^2 - 291,55y_D + 17928,3 = 0$$

$$y_D = \frac{291,55 \pm 101,8}{2,0816} < \begin{matrix} 188,96 \text{ NO} \\ 91,15 \text{ SI} \end{matrix}$$

$$D \begin{cases} y_D = 91,1 \text{ mm} \\ x_D = 140,8 \text{ mm} \end{cases}$$

$$\varphi_6 = \arctg\left(\frac{y_c - y_D}{x_c - x_D}\right) = 56,35^\circ$$

$$\varphi_3 = \varphi_6 + \alpha = 101,35^\circ \sim 101,4^\circ$$



$$\overline{FD} = \sqrt{y_D^2 + (x_D - x_F)^2} = 99,82 \text{ mm}$$

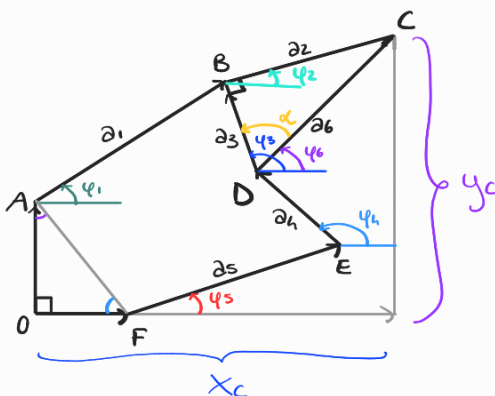
$$\varphi_F = \arctg\left(\frac{y_D - y_F}{x_D - x_F}\right) = 65,87^\circ$$

$$\alpha_2 = \arccos\left(\frac{FD^2 + a_5^2 - a_2^2}{2 \cdot FD \cdot a_5}\right) = 61,05^\circ$$

$$\varphi_5 = \varphi_F - \alpha_2 = 4,82^\circ \sim 4,8^\circ$$

$$E \begin{cases} x_E = x_F + a_5 \cos \varphi_5 = 169,8 \text{ mm} \\ y_E = a_5 \sin \varphi_5 = 5,9 \text{ mm} \end{cases}$$

$$\theta = \arctg\left(\frac{y_D - y_E}{x_E - x_D}\right) = 71,2^\circ \rightarrow \varphi_4 = 180^\circ - \theta = 108,8^\circ$$



$$\dot{a}_1 = 9 \text{ mm/s}$$

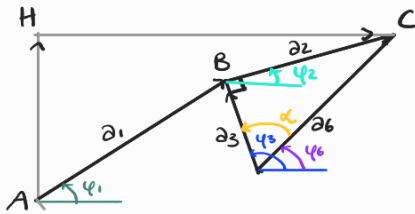
$$\begin{cases} x_F + a_5 \cos \varphi_5 + a_4 \cos \varphi_4 + a_3 \cos \varphi_3 - a_1 \cos \varphi_1 = 0 \\ a_5 \sin \varphi_5 + a_4 \sin \varphi_4 + a_3 \sin \varphi_3 - a_1 \sin \varphi_1 - y_A = 0 \end{cases}$$

$$\begin{cases} 80 - a_2 \cos \varphi_2 - a_3 \cos \varphi_3 - a_4 \cos \varphi_4 - a_5 \cos \varphi_5 = 0 \\ 150 - a_2 \sin \varphi_2 - a_3 \sin \varphi_3 - a_4 \sin \varphi_4 - a_5 \sin \varphi_5 = 0 \end{cases}$$

$$\begin{cases} -a_5 \sin \varphi_5 \cdot \dot{\varphi}_5 - a_4 \sin \varphi_4 \cdot \dot{\varphi}_4 - a_3 \sin \varphi_3 \cdot \dot{\varphi}_3 + a_1 \sin \varphi_1 \cdot \dot{\varphi}_1 - \dot{a}_1 \cos \varphi_1 = 0 \\ a_5 \cos \varphi_5 \cdot \dot{\varphi}_5 + a_4 \cos \varphi_4 \cdot \dot{\varphi}_4 + a_3 \cos \varphi_3 \cdot \dot{\varphi}_3 - a_1 \cos \varphi_1 \cdot \dot{\varphi}_1 - \dot{a}_1 \sin \varphi_1 = 0 \end{cases}$$

$$\begin{cases} a_2 \sin \varphi_2 \cdot \dot{\varphi}_2 + a_3 \sin \varphi_3 \cdot \dot{\varphi}_3 + a_4 \sin \varphi_4 \cdot \dot{\varphi}_4 + a_5 \sin \varphi_5 \cdot \dot{\varphi}_5 = 0 \\ -a_2 \cos \varphi_2 \cdot \dot{\varphi}_2 - a_3 \cos \varphi_3 \cdot \dot{\varphi}_3 - a_4 \cos \varphi_4 \cdot \dot{\varphi}_4 - a_5 \cos \varphi_5 \cdot \dot{\varphi}_5 = 0 \end{cases}$$

dove  $\dot{\varphi}_2 = \dot{\varphi}_3$  poiché  
 $\varphi_3 = \varphi_2 + 90^\circ$



$$\begin{cases} a_1 \cos \varphi_1 + a_2 \cos \varphi_2 - x_C = 0 \\ a_1 \sin \varphi_1 + a_2 \sin \varphi_2 - (y_C - y_A) = 0 \end{cases}$$

$$y_C - y_A = 100$$

$$\begin{cases} -a_1 \sin \varphi_1 \cdot \dot{\varphi}_1 - a_2 \sin \varphi_2 \cdot \dot{\varphi}_2 + \dot{a}_1 \cos \varphi_1 = 0 \\ a_1 \cos \varphi_1 \cdot \dot{\varphi}_1 + a_2 \cos \varphi_2 \cdot \dot{\varphi}_2 + \dot{a}_1 \sin \varphi_1 = 0 \end{cases}$$

$$\begin{bmatrix} -a_1 \sin \varphi_1 & -a_2 \sin \varphi_2 \\ a_1 \cos \varphi_1 & a_2 \cos \varphi_2 \end{bmatrix} \begin{Bmatrix} \dot{\varphi}_1 \\ \dot{\varphi}_2 \end{Bmatrix} = \begin{Bmatrix} -\cos \varphi_1 \\ -\sin \varphi_1 \end{Bmatrix} \dot{a}_1$$

$$\begin{Bmatrix} \dot{\varphi}_1 \\ \dot{\varphi}_2 \end{Bmatrix} = \frac{1}{a_1 a_2 \sin(\varphi_2 - \varphi_1)} \begin{bmatrix} a_2 \cos \varphi_2 & a_2 \sin \varphi_2 \\ -a_1 \cos \varphi_1 & -a_1 \sin \varphi_1 \end{bmatrix} \begin{Bmatrix} -\cos \varphi_1 \\ -\sin \varphi_1 \end{Bmatrix} \dot{a}_1$$

$$\begin{Bmatrix} \dot{\varphi}_1 \\ \dot{\varphi}_2 \end{Bmatrix} = \frac{1}{a_1 a_2 \sin(\varphi_2 - \varphi_1)} \begin{bmatrix} -a_2 \cos \varphi_2 \cos \varphi_1 - a_2 \sin \varphi_2 \sin \varphi_1 \\ a_1 \cos \varphi_1 \cos \varphi_1 + a_1 \sin \varphi_1 \sin \varphi_1 \end{bmatrix} \dot{a}_1$$

$$\dot{\varphi}_1 = \frac{-a_2 \cos(\varphi_2 - \varphi_1)}{a_1 a_2 \sin(\varphi_2 - \varphi_1)} \dot{a}_1 = \frac{-\cos(-23,1) \cdot 9}{159 \sin(-23,1)} = 7,6 \frac{\text{deg}}{\text{s}}$$

$$\dot{\varphi}_2 = \frac{a_1}{a_1 a_2 \sin(\varphi_2 - \varphi_1)} \dot{a}_1 = \frac{9 \text{ mm/s}}{50 \sin(-23,1)} = -0,4587 \frac{\text{rad}}{\text{s}} = -26,2 \frac{\text{deg}}{\text{s}}$$

$$\begin{cases} a_2 \sin \varphi_2 \cdot \dot{\varphi}_2 + a_3 \sin \varphi_3 \cdot \dot{\varphi}_2 + a_4 \sin \varphi_4 \cdot \dot{\varphi}_4 + a_5 \sin \varphi_5 \cdot \dot{\varphi}_5 = 0 \\ -a_2 \cos \varphi_2 \cdot \dot{\varphi}_2 - a_3 \cos \varphi_3 \cdot \dot{\varphi}_2 - a_4 \cos \varphi_4 \cdot \dot{\varphi}_4 - a_5 \cos \varphi_5 \cdot \dot{\varphi}_5 = 0 \end{cases}$$

$$\dot{\varphi}_4 = \frac{-a_2 \cos \varphi_2 \cdot \dot{\varphi}_2 - a_3 \cos \varphi_3 \cdot \dot{\varphi}_2 - a_5 \cos \varphi_5 \cdot \dot{\varphi}_5}{a_4 \cos \varphi_4}$$

$$a_5 \sin \varphi_5 \cdot \dot{\varphi}_5 = -a_2 \sin \varphi_2 \cdot \dot{\varphi}_2 - a_3 \sin \varphi_3 \cdot \dot{\varphi}_2 - a_4 \sin \varphi_4 \left( \frac{-a_2 \cos \varphi_2 \cdot \dot{\varphi}_2 - a_3 \cos \varphi_3 \cdot \dot{\varphi}_2 - a_5 \cos \varphi_5 \cdot \dot{\varphi}_5}{a_4 \cos \varphi_4} \right)$$

$$a_5 \sin \varphi_5 \cdot \dot{\varphi}_5 - a_5 \cos \varphi_5 \frac{a_4 \sin \varphi_4}{a_4 \cos \varphi_4} \dot{\varphi}_5 = -a_2 \sin \varphi_2 \cdot \dot{\varphi}_2 - a_3 \sin \varphi_3 \cdot \dot{\varphi}_2 + \underbrace{\frac{a_4 \sin \varphi_4 a_2 \cos \varphi_2 \cdot \dot{\varphi}_2}{a_4 \cos \varphi_4}}_{a_2 \tan \varphi_4 \cos \varphi_2 \cdot \dot{\varphi}_2} + \underbrace{\frac{a_4 \sin \varphi_4 a_3 \cos \varphi_3 \cdot \dot{\varphi}_2}{a_4 \cos \varphi_4}}_{a_3 \tan \varphi_4 \cos \varphi_3 \cdot \dot{\varphi}_2}$$

$$\dot{\varphi}_5 (a_5 \sin \varphi_5 - a_5 \cos \varphi_5 \operatorname{tg} \varphi_4) = (-a_2 \sin \varphi_2 - a_3 \sin \varphi_3 + a_2 \operatorname{tg} \varphi_4 \cos \varphi_2 + a_3 \operatorname{tg} \varphi_4 \cos \varphi_3) \dot{\varphi}_2$$

$$\dot{\varphi}_5 = \frac{(-a_2 \sin \varphi_2 - a_3 \sin \varphi_3 + a_2 \operatorname{tg} \varphi_4 \cos \varphi_2 + a_3 \operatorname{tg} \varphi_4 \cos \varphi_3) \dot{\varphi}_2}{(a_5 \sin \varphi_5 - a_5 \cos \varphi_5 \operatorname{tg} \varphi_4)} = 21,6 \frac{\text{deg}}{\text{s}}$$

$$\dot{\varphi}_4 = \frac{-a_2 \cos \varphi_2 \cdot \dot{\varphi}_2 - a_3 \cos \varphi_3 \cdot \dot{\varphi}_2 - a_5 \cos \varphi_5 \cdot \dot{\varphi}_5}{a_4 \cos \varphi_4} = 16,6 \frac{\text{deg}}{\text{s}}$$