# **Arth Shukla**

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#### **EDUCATION**

### University of California, San Diego

Bachelor of Science in Mathematics-Computer Science

GPA - 4.0

September 2021 – June 2025

#### **Relevant Coursework**

Completed: Deep Learning for 3D Data (Graduate Level), Rec Systems and Web Mining, Supervised Machine Learning, Optimization Methods for Machine Learning I and II, Design and Analysis of Algorithms, Data Science in Practice, Theory of Computation, Advanced Data Structures, Computer Organization and Systems Programming, Data Structures and Object-Oriented Design, Computer Science and Object-Oriented Programming - Java, Networks and Digital Communications, Data Warehousing to Big Data, Statistical Methods and Probability, Enumerative Combinatorics, Abstract Algebra I and II, Linear Algebra, Multivariable Calculus, Vector Calculus, Differential Equations

Currently Enrolled: Machine Learning for Robotics (Graduate Level)

#### **EXPERIENCE**

#### Al Research @ Hao Su Lab

June 2023 - Present

**Technologies Used:** <u>Development:</u> Jax, Pytorch, OpenAl Gymnasium, D4RL, ManiSkill, Mujoco, Adroit; <u>Tools</u>: WandB, Docker, Nautilus, Kubernetes (kubectl, PVCs, etc), Mamba/Conda

### **Current Projects**

- Use multimodal sensor data (depth images, joint q-positions/velocities) and metadata (target object coordinates relative to the robot) to train embodied agents which control articulated mobile manipulators (e.g. Fetch Robot)
- Develop scalable method for skill-chaining dexterous manipulation skills for long-horizon scene-level manipulation tasks base on Multi-Skill Mobile Manipulation (Gu et al.)
- Create and design environments and task definitions for scalable, efficient scene-level GPU simulation on SAPIEN and ManiSkill simulator team

### **Accepted Publications** (Citations below)

• Reverse Forward Curriculum Learning (ICLR 2024): Leverage human and expert-made demonstrations and curriculum learning to train embodied agents with extreme online sample efficiency. Tested on dexterous manipulation tasks using a variety of articulated robots (Franka Emika Panda Arm, Shadow Dexterous Hand, Sawyer Robot)

## Al Projects: <a href="https://github.com/arth-shukla">https://github.com/arth-shukla</a>; <a href="https://wandb.ai/arth-shukla/projects">https://github.com/arth-shukla</a>; <a href="https://wandb.ai/arth-shukla/projects">https://wandb.ai/arth-shukla/projects</a>

**Technologies Used:** <u>Development</u>: Pytorch (Torch, TorchVision, Datasets, Dataloaders, Cuda), OpenAl Gym, HuggingFace Transformers Library, TensorFlow, Keras, Gensim; <u>Concepts</u>: 3D CV (DenseFusion, PointNet), Reinforcement Learning (PPO, DDQN, DQN), NLP (Transfer Learning, Embeddings, Attention); <u>Tools/Technologies</u>: WandB, BERT/DistilBERT Pretrained, Conda **3D Computer Vision** 

- Win 1st place in 6D Pose Estimation competition in graduate-level course Deep Learning for 3D Data by implementing DenseFusion with altered loss + ICP Refinement: https://github.com/arth-shukla/densefusion
- Implement *PointNet: Deep learning on point sets for 3d classification and segmentation* (Qi et al. 2017) for part segmentation on chair point clouds: <a href="https://github.com/arth-shukla/pointnet-part-segmentation">https://github.com/arth-shukla/pointnet-part-segmentation</a>

### **Reinforcement Learning**

- Create PPO Agent to consistently beat Mario level 1-1 and 1-4 in under 1600-2000 episodes of training: https://github.com/arth-shukla/ppo-mario
- Implement DDQN from *Human-level control through deep reinforcement learning* (Deep Mind 2015) in Gymnasium to beat Mario level 1-1 in 13000 episodes of training: <a href="https://github.com/arth-shukla/ddqn-mario">https://github.com/arth-shukla/ddqn-mario</a>
- Train PPO Agent to consistently beat CartPole in under 140 episodes of: https://github.com/arth-shukla/ppo-gym-cartpole

## **Natural Language Processing**

- Use HuggingFace Transformers library to fine-tune DistilBERT model (transfer learning) trained on Stanford Question-Answer 2.0 (SQuAD 2.0) to answer a question given some context (article, paragraph, etc): <a href="https://github.com/arth-shukla/squad2.0-bert-question-answer">https://github.com/arth-shukla/squad2.0-bert-question-answer</a>
- Fine-tune DistilBERT model (transfer learning) to classify and approximate sentiment for Stanford Sentiment140 1.4-million Tweet Dataset: https://github.com/arth-shukla/sentiment140-bert-transfer-learning
- Use TensorFlow Keras to build LSTM and CNN and use Gensim to refit GLoVE word embeddings for IMDB Review Sentiment Classification: https://github.com/arth-shukla/gensim-embedding-training-imdb

## ACM Al's Element.Al Competition https://github.com/acmucsd/Element.Al

I led development and organization of Element.Al, an \$8000 RL competition at UCSD with over 200 participants.

**Technologies Used:** Python, Conda, Java, Maven, OpenAl Gym, PettingZoo, PyGame, Jackson, Squid, Bash *Lead Developer* 

July 2022 - Feb 2023

- Build multi-agent Gym environment using LuxAl runner and PettngZoo to run participant bots at scale
- Create Java sdk for 45 participants (~22.5% of all participants) using Java with Maven
- In coordination with UCSD ITS, use Squid proxy, IPTables and bash scripts to create instructor tools, allowing us to enable/revoke access to wifi, whitelist sites, enable/revoke access to files, and in general control the competition accounts with granularity, both targeted and en masse
- Write proposals and attend meetings to obtain \$10,000 in sponsorships, attracting 200 participants (limited primarily by the number of UCSD Linux lab machines) with over 100 submissions

## Nefeli Networks (now under Cloudflare)

**Technologies Used:** Backend: Go, Docker, Kubernetes, etcd; Frontend: Angular, Less; DevOps: Git, Coder, Agile **Software Engineering Intern**June 2023 – August 2023

- Integrate Infracost API in backend for Terraform cloud object cost and diff calculation
- Code used in production (23.09 release)

#### **ACM AI UCSD**

ACM AI is UCSD's largest AI student org which fosters a community for those interested in AI and research.

**Technologies Used**: Al/ML Workshops and Projects: Python, PyTorch, TensorFlow; Web Development: TypeScript, React

\*\*President\*\*

May 2023 – Present

- Build AI competitions (100-200 submissions on average), run events (technical workshops, seminars, socials), lead AI board
- Previously Director of Operations 2022-23, Event Lead 2021-22, ACM AI Projects participant 2021

### **Bittner Development Group**

**Technologies Used:** Web Development: React, SCSS, Node.js; DevOps: GitLab, Git, WSL; Scripting and Automation: TypeScript, JavaScript, Java; Development Standards: WCAG 2.1 AAA, Aria APG, Norton Design System; Processes: Agile Methodology **Software Engineering Intern**November 2019 – June 2023

- Develop React component library and enterprise web application 'Interactive Builder'
- Web development, QA, and devops of over 10 education interactive projects in React to WCAG accessibility standards
- Manage and train two interns to complete projects using React and SCSS, GitLab, Git, and WSL
- Propose, lead, and develop internal and for-client automation projects using Node and native JavaScript

# Web Development Projects: https://github.com/arth-shukla

**Technologies Used:** Web Development: TypeScript, React, Rollup, Jest, Webpack, Storybook, SCSS; <u>DevOps</u>: Netlify, Git, GitHub Pages, GitHub Packages; <u>Development Standards</u>: WCAG 2.1 AAA, Aria Authoring Practices Guide (APG) *Independent Developer* 

- Personal website using React Typescript, SCSS, and Material UI, accessible by WCAG 2.1 AA standard: <a href="https://arth.website">https://arth.website</a>
- Icon Library with React TypeScript and SCSS, publish to GitHub packages: <a href="https://github.com/arth-shukla/arth-components">https://arth-shukla.github.io/my-icons-documentation</a> code demos and documentation: <a href="https://arth-shukla.github.io/my-icons-documentation">https://arth-shukla.github.io/my-icons-documentation</a>
- Code mobile-compatible Dice Roller web app on React: <a href="https://arth-shukla.github.io/dice-roller">https://arth-shukla.github.io/dice-roller</a>

### **CONFERENCES AND PUBLICATIONS**

## RFCL: Reverse Forward Curriculum Learning for Extreme Sample and Demonstration Efficiency in RL

International Conference on Learning Representations (ICLR) 2024 | May 2024, Vienna, Austria (Accepted) Stone Tao, **Arth Shukla**, Kevin Chan, Hao Su.

arXiv | Project Page

### **SKILLS**

- Programming Languages Python, C++, Go, TypeScript, JavaScript, Node, React, Java, Ruby, Bash, SCSS, LESS, CSS, C, R
- Packages and Libraries Pytorch, TorchVision, Jax, Keras, HuggingFace, OpenAl Gym, PettingZoo, Rollup, Jest, Webpack
- Programs and Software Nautilus, Docker, WandB, Tensorboard, Git, GitHub, GitLab, Mamba/Conda, Maven, Visual Studio
  Code, WSL, Netlify, Storybook, Android Studio, Matlab, Microsoft Office, Microsoft Excel, Microsoft Powerpoint
- **Development Standards** Web Content Accessibility Guidelines (WCAG) 2.1 AAA, Aria Authoring Practices Guide (APG)
- Languages Fluent in English and French, Spoken Hindi