

# Kefan Chen

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EDUCATION	<b>Brown University</b> , Ph.D. student in Computer Science 2022 – 2027 <ul style="list-style-type: none"><li>▪ Research focus: 3D Computer Vision, Generative AI</li></ul>	
	<b>University of Toronto</b> , Bachelor in Electrical Engineering 2014 – 2018	
SKILLS	Python, C++, C, Pytorch, Tensorflow, Computer Vision, Deep Learning, Research	
INDUSTRY EXPERIENCE	<b>Meta</b> , Research Scientist Intern Jun 2023 – Dec 2023 <ul style="list-style-type: none"><li>▪ Research 3D diffusion model and neural fields for hand generative modeling.</li><li>▪ Direct a research project and submit a first-author paper to CVPR 2024.</li></ul>	
	<b>Pinterest</b> , Machine Learning Engineer Jan 2022 – Sep 2022 <ul style="list-style-type: none"><li>▪ Develop ML models to extract various attributes of interest from the shopping websites for recommendation and other downstream applications.</li></ul>	
	<b>Gatik AI</b> , Software Engineer Sep 2020 – Dec 2021 <ul style="list-style-type: none"><li>▪ Research and develop long-range multimodal perception and sensor fusion for autonomous delivery.</li><li>▪ Coordinate and manage long-term research collaboration with universities and academic labs.</li></ul>	
	<b>Google Research</b> , AI Resident Jun 2018 – Aug 2020 <ul style="list-style-type: none"><li>▪ Conduct research on 3D computer vision and geometric representation learning for computer vision.</li><li>▪ Published a first-authored paper at CVPR and co-authored paper at NeurIPS.</li><li>▪ Developed a novel algorithm for camera pose estimation that achieves state-of-the-art performance.</li><li>▪ Designed various models and implemented large-scale distributed training in Tensorflow.</li></ul>	
	<b>NVIDIA</b> , Research Intern May 2017 – Aug 2017 <ul style="list-style-type: none"><li>▪ Conduct research on deep learning in animation and pose estimation for robotics using domain transfer.</li><li>▪ Designed and built a robotic perception model with only synthetic data to play board games and demonstrated the demo at ACM SIGGRAPH 2017. (Video link)</li></ul>	
PUBLICATION	<ul style="list-style-type: none"><li>[1] C Pokhariya, I Shah, A Xing, Z Li, <b>K Chen</b>, A Sharma, S Sridhar, “MANUS: Markerless Grasp Capture using Articulated 3D Gaussians,” <i>Conference on Computer Vision and Pattern Recognition (CVPR)</i>, 2024.</li><li>[2] C Lu, P Zhou, A Xing, C Pokhariya, A Dey, I Shah, R Mavidipalli, D Hu, A Comport, <b>K Chen</b>, S Sridhar, “DiVa-360: The Dynamic Visual Dataset for Immersive Neural Fields,” <i>Conference on Computer Vision and Pattern Recognition (CVPR)</i>, 2024.</li><li>[3] <b>Kefan Chen</b>, Noah Snavely, Ameesh Makadia, “Wide-Baseline Relative Camera Pose Estimation with Directional Learning,” <i>Conference on Computer Vision and Pattern Recognition (CVPR)</i>, 2021.</li><li>[4] Jake Levinson, Carlos Esteves, <b>Kefan Chen</b>, Noah Snavely, Angjoo Kanazawa, Afshin Rostamizadeh, Ameesh Makadia, “An Analysis of SVD for Deep Rotation Estimation,” <i>Conference on Neural Information Processing Systems (NeurIPS)</i>, 2020.</li></ul>	
ACADEMIC EXPERIENCE	<b>Brown Interactive 3D Vision &amp; Learning Lab</b> , PhD Researcher Sep 2022 – Current <ul style="list-style-type: none"><li>▪ Research on 3D computer vision and generative AI, diffusion model, and neural field.</li></ul>	
	<b>UofT Machine Learning Group</b> , Research Assistant Feb 2017 – May 2018 <ul style="list-style-type: none"><li>▪ Researched on Motion Generation using Adversarial Training supervised by Prof. Sanja Fidler.</li><li>▪ Researched on Homography Estimation for Sports Analytics, supervised by Prof. Raquel Urtasun.</li></ul>	