

# Kefan (Arthur) Chen

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EDUCATION	<b>Brown University</b> , Ph.D. student in Computer Science 2022 – 2027 <ul style="list-style-type: none"><li>Research focus: 3D Computer Vision, Deep Learning, Robotics</li></ul>
	<b>University of Toronto</b> , Bachelor in Electrical Engineering 2014 – 2018
SKILLS	Python, C++, C, Tensorflow, Pytorch, Computer Vision, Deep Learning, Research
INDUSTRIAL EXPERIENCE	<b>Pinterest</b> , Machine Learning Engineer, Toronto Jan 2022 – Sep 2022 <ul style="list-style-type: none"><li>Develop machine learning models to extract various attributes of interest from the shopping websites.</li></ul>
	<b>Gatik AI</b> , Software Engineer, Toronto Sep 2020 – Dec 2021 <ul style="list-style-type: none"><li>Research and develop long-range multimodal perception and sensor fusion for autonomous delivery.</li><li>Coordinate and manage long-term research projects with universities and academic labs.</li></ul>
	<b>Google Research</b> , Researcher, New York City Jun 2018 – Aug 2020 <ul style="list-style-type: none"><li>Conduct research on 3D computer vision and geometric representation learning for computer vision.</li><li>Published a first-authored paper at CVPR and co-authored paper at NeurIPS.</li><li>Developed a novel algorithm for camera pose estimation that achieves state-of-the-art performance.</li><li>Designed various models and implemented large-scale distributed training in Tensorflow.</li></ul>
	<b>NVIDIA</b> , Research Intern, Toronto May 2017 – Aug 2017 <ul style="list-style-type: none"><li>Conduct research on deep learning in animation and pose estimation for robotics using domain transfer.</li><li>Designed and built a robotic perception model with only synthetic data to play board games and demonstrated the demo at ACM SIGGRAPH 2017. (Video link)</li></ul>
PUBLICATION	<ul style="list-style-type: none"><li>[1] <b>Kefan Chen</b>, Noah Snaveley, Ameesh Makadia, “Wide-Baseline Relative Camera Pose Estimation with Directional Learning,” <i>Conference on Computer Vision and Pattern Recognition (CVPR)</i>, 2021.</li><li>[2] Jake Levinson, Carlos Esteves, <b>Kefan Chen</b>, Noah Snaveley, Angjoo Kanazawa, Afshin Rostamizadeh, Ameesh Makadia, “An Analysis of SVD for Deep Rotation Estimation,” <i>Conference on Neural Information Processing Systems (NeurIPS)</i>, 2020.</li></ul>
ACADEMIC EXPERIENCE	<b>Brown Interactive 3D Vision &amp; Learning Lab</b> , PhD Researcher Sep 2022 – Current <ul style="list-style-type: none"><li>Research on learning 3D representation of human hand and objects as well as hand-object interaction through multi-view images and videos.</li></ul>
	<b>UofT Machine Learning Group</b> , Research Assistant Feb 2017 – May 2018 <ul style="list-style-type: none"><li>Researched on Motion Generation using Adversarial Training supervised by Prof. Sanja Fidler.<ul style="list-style-type: none"><li>Proposed using Gated Graph Sequence Neural Network (GGS-NN) with a soft attention mechanism to learn the spatial-temporal representation for motion capture data.</li></ul></li><li>Researched on Homography Estimation for Sports Analytics, supervised by Prof. Raquel Urtasun.<ul style="list-style-type: none"><li>Designed and implemented a convolutional neural network to localize the hockey rink and estimate the homography between the template and the rink in the frames from broadcast videos.</li></ul></li></ul>
AWARDS & SCHOLARSHIPS	<ul style="list-style-type: none"><li>Dean’s Honor List, Department of Electrical and Computer Engineering 2014 – 2017</li><li>Summer Research Studentship, Department of Electrical and Computer Engineering May 2016</li><li>University Entrance Scholarship, University of Toronto Sep 2014</li></ul>