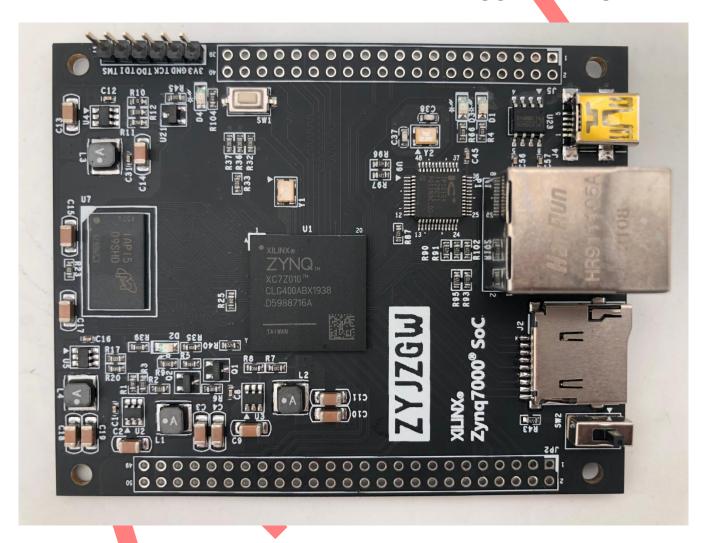
ZYJZGW ZYNQ XC7Z010 STARTER KIT

USER MANUAL



Preface

The ZYJZGW® ZYNQ7000 Starter Kit uses Xilinx Zynq®-7000 device which integrates the software programmability of an ARM®-based processor with the hardware programmability of an FPGA, enabling key analytics and hardware acceleration while integrating CPU, DSP, ASSP, and mixed signal functionality on a single device. Consisting of single-core Zynq-7000S and dual-core Zynq-7000 devices, the Zynq-7000 family is the best price to performance-per-watt, fully scalable SoC platform for your unique application requirements.



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1. Introduction

1.1 Document Scope

This user manual introduces the procedure to make the PetaLinux environment running on the ZYJZGW ZYNQ7000 Starter Kit. The PetaLinux environment mainly covers three parts: u-boot, Linux OS and file system. All of those parts are developed with PetaLinux 2019.2 under Ubuntu 18.04.1 (64bit) environment. The prerequisites before working with the PetaLinux are shown as below:

1. Preferred and verified Ubuntu version is Ubuntu 18.04.1 (64bit).

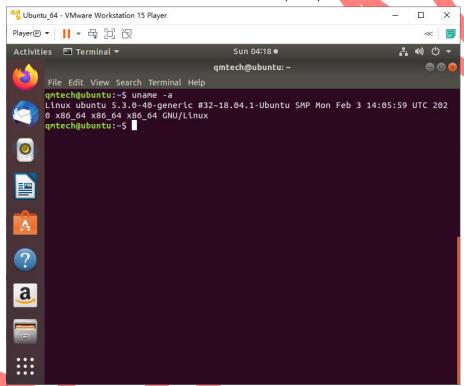


Figure 1-1. Ubuntu Version

 Users shall install the required packages before install the PetaLinux 2019.2 in Ubuntu. The detailed required packages are mentioned in UG1144: Table 2: Packages and Linux Workstation Environments.

Not<mark>ification: Users need to have root access to install the required packages mentioned in that table. The PetaLinux tools need to be installed as a non-root user.</mark>

3. Users shall have the basic knowledge about the usage of the Linux environment. Know how to use the cross-compile toolchain including arm-gcc-linux-, makefile, etc.

2. Getting Started

This chapter describes the detailed steps to create a customized PetaLinux. Comparing to the existing ZYNQ development board e.g. Xilinx ZC702, there are many differences in the ZYJZGW ZYNQ7000 Starter Kit. For example, there's only one 16bit width DDR3 memory chip connected to PS ARM core. And MII Ethernet interface is implemented at the PL side. Hence, the u-boot/ Linux device tree for the Bajie Board needs to be updated here.



2.1 Steps to Customize the PetaLinux

The first step is to customize the hardware info required by PetaLinux. The hardware info could be retrieved from below Vivado project:

\$ZYJZGW_XC7Z010_STARTER_KIT_V01\PetaLinux\Project04_Uboot_20191101.zip

Below image shows the customized ZYNQ system in Vivado 2018.3. Make sure the project could successfully pass the three steps: Synthesis, implementation and Generate Bitstream.

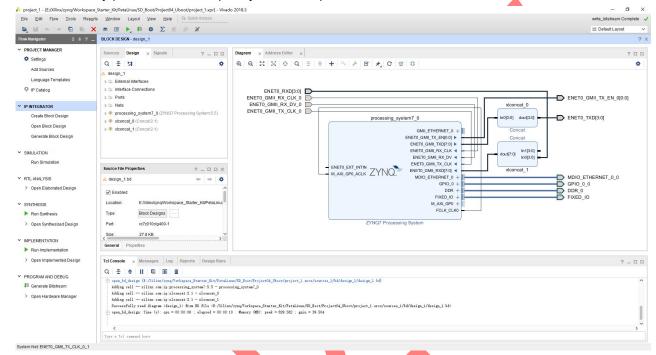


Figure 2-1. Modifications

Then users could retrieve the customized hardware info by clicking the [File] -> [Export] -> [Export Hardware]. And remember check the [Include Bitstream] before click the [OK] button.

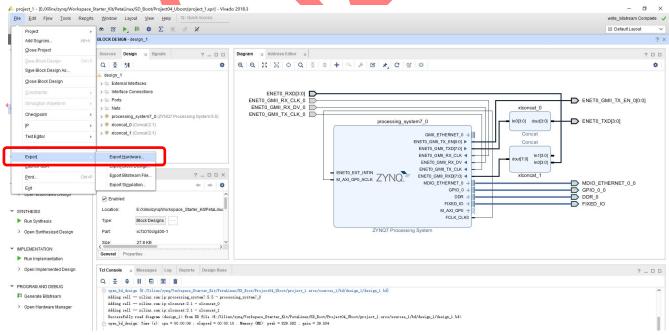


Figure 2-2. Export Hardware Info



The generated hardware info file could be found here: \$ZYJZGW_XC7Z010_STARTER_KIT_V01\PetaLinux\Project04_Uboot_20191101\project_1.sdk\design_1_wrapper.hdf

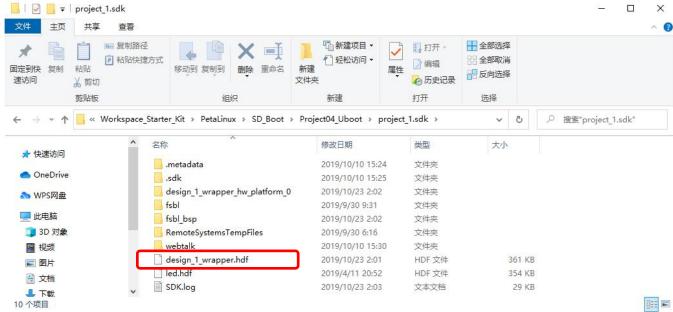


Figure 2-3. Target Hardware Info File

Copy the design_1_wrapper.hdf file into Ubuntu environment. E.g. put the file in folder \$workspace/ZYJZGW_Workspace/Linux_base_Starter_Kit_V02.sdk.

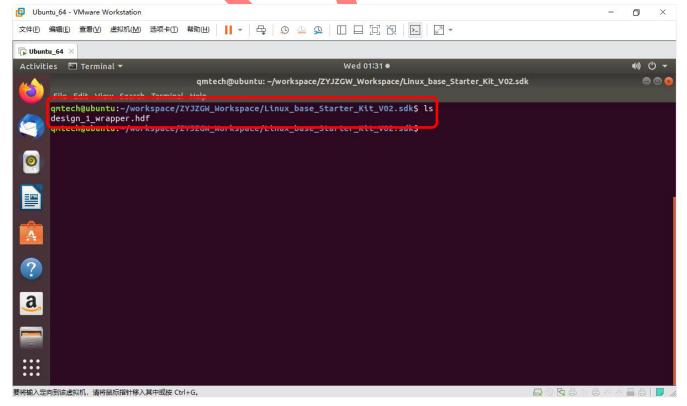


Figure 2-4. Import Hardware Info File



In our example, the PetaLinux 2019.2 package is installed in folder /opt/pkg/petalinux. Users need change the below commands according to the detailed directory that contains the PetaLinux. Type command in the terminal to source the PetaLinux: /opt/pkg/petalinux/settings.sh. Create a new folder named as ZYJZGW_Starter_Kit by typing command: petalinux-create --type project --template zynq --name ZYJZGW_Starter_Kit. This new folder is in the same directory as the Linux_base_Starter_Kit_V02.sdk and used as the PetaLinux workspace.

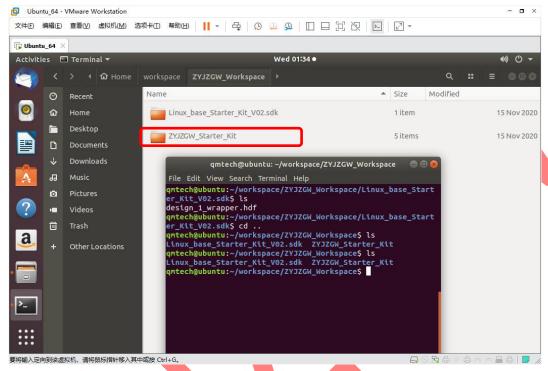


Figure 2-5. Create PetaLinux Working Folder

Then enter into the folder ZYJZGW_Starter_Kit.

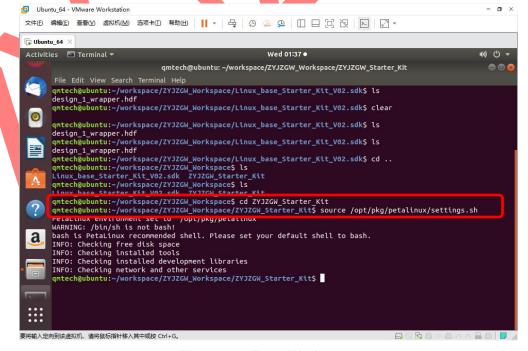


Figure 2-6. Enter Workspace



Import the hardware info into PetaLinux by command: **petalinux-config --get-hw-description ../linux_base.sdk**. Below configuration image will display and nothing needs to be changed here.

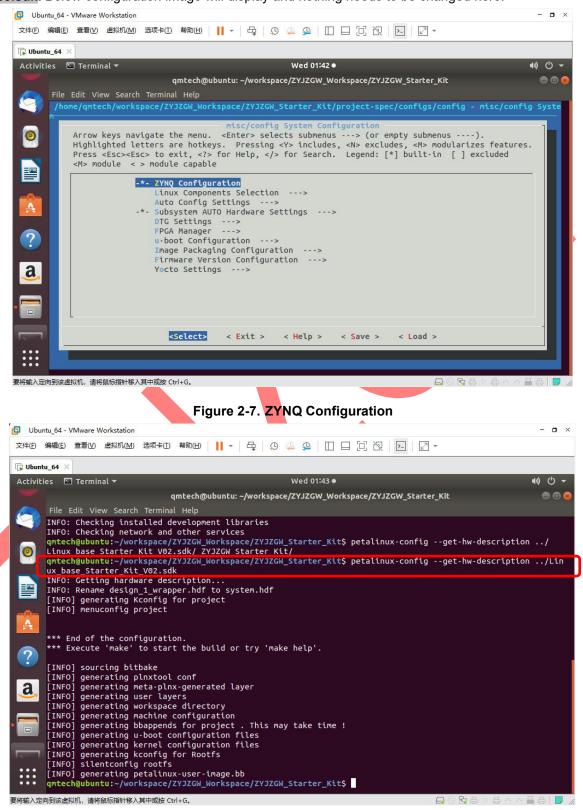


Figure 2-8. Import Hardware Info



Once the hardware info is successfully imported, users may start to configure the PetaLinux kernel by command: **petalinux-config -c kernel**

This step may take a really long time. Be patient here and make sure the VM's network status is perfect.

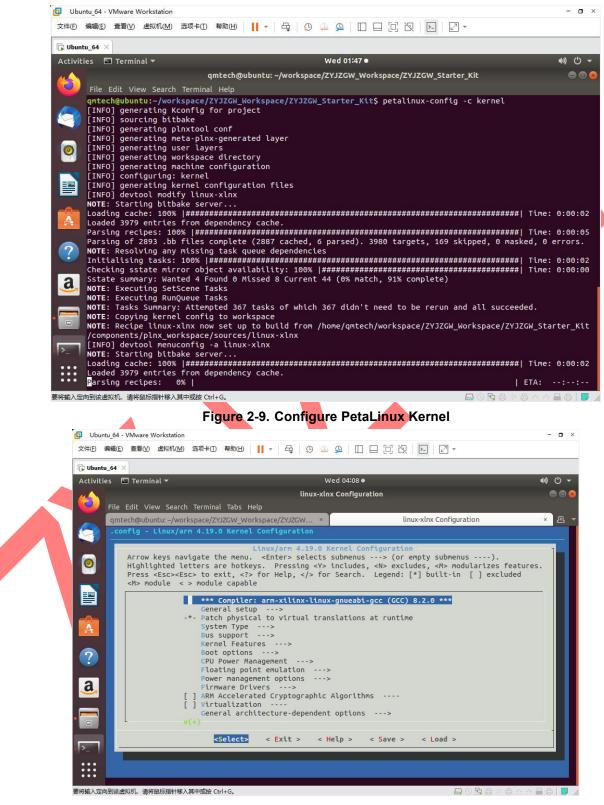


Figure 2-10. No Need to change the Kernel Configurations



Once the PetaLinux Kernel info is successfully configured, users may start to configure the PetaLinux file system by command: **petalinux-config -c rootfs**

Below image will display and nothing needs to be changed here.

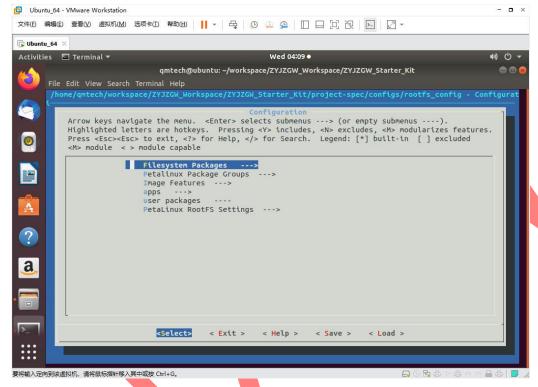


Figure 2-11. No Need to change the rootfs

Start to build the PetaLinux by command: petalinux-build

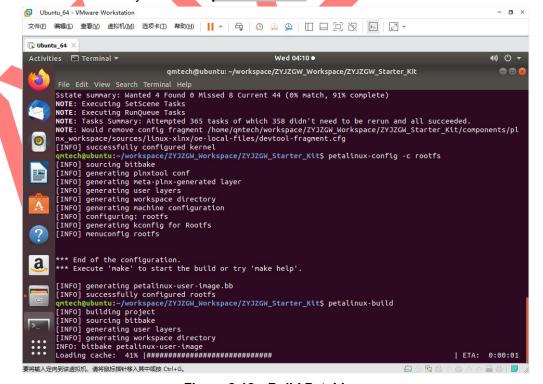
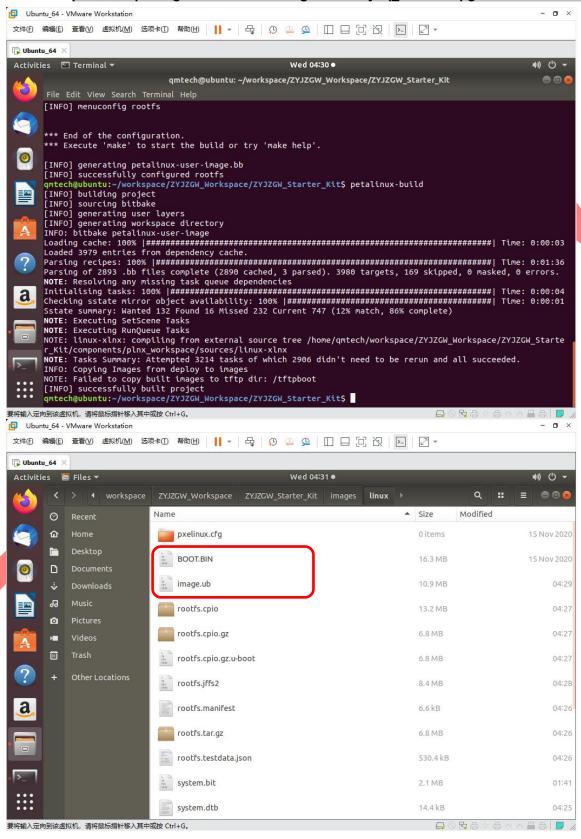


Figure 2-12. Build PetaLinux

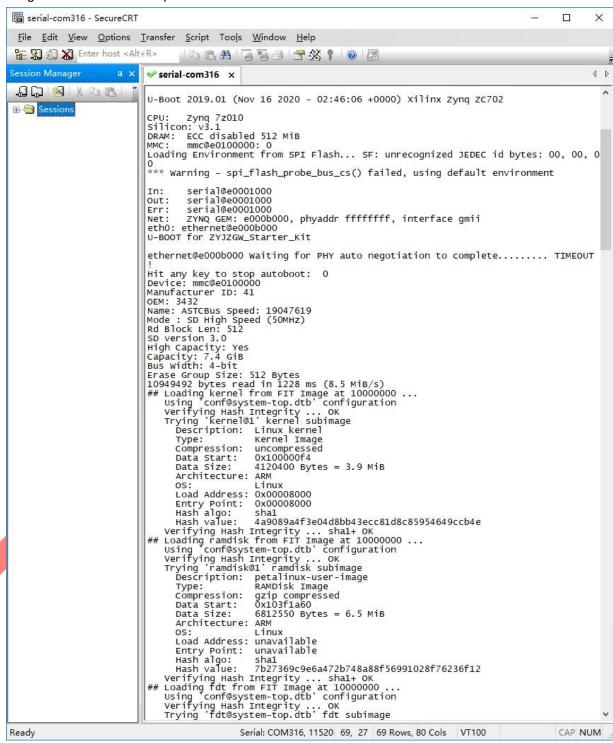


After the PetaLinux is successfully built, users could generate the target BOOT.bin and image.ub by command: petalinux-package --boot --fsbl ./images/linux/zyng fsbl.elf --fpga --u-boot --force

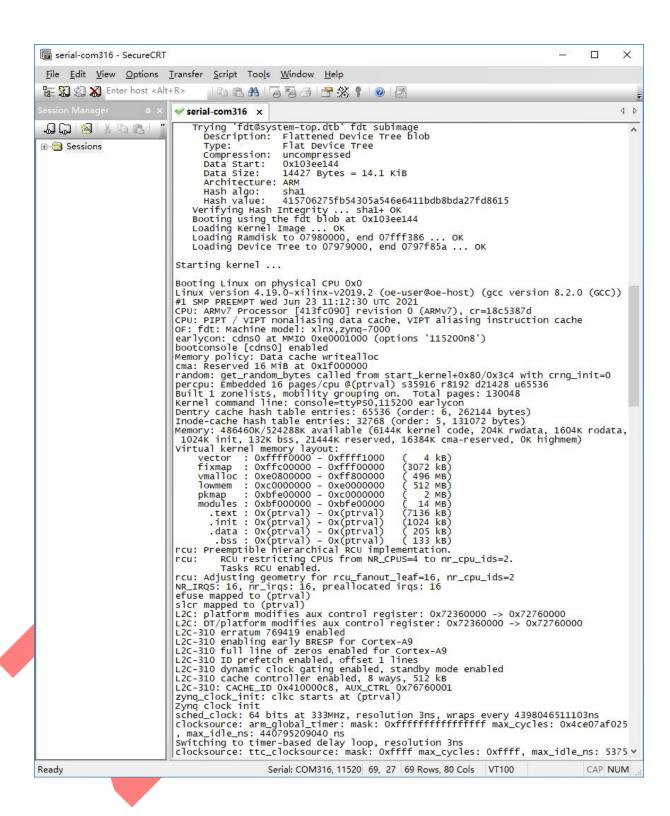




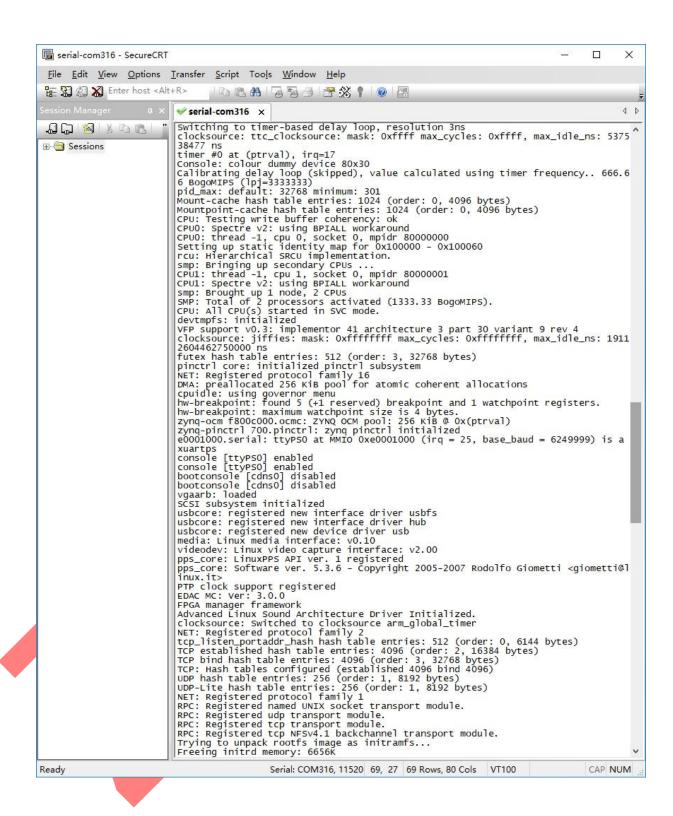
Copy the BOOT.bin and image.ub into MicroSD card and then insert the MicroSD card into ZYNQ7000 Starter Kit. Plug the MiniUSB cable into the board and then power on the power source switch. Below image shows the serial output from the board.



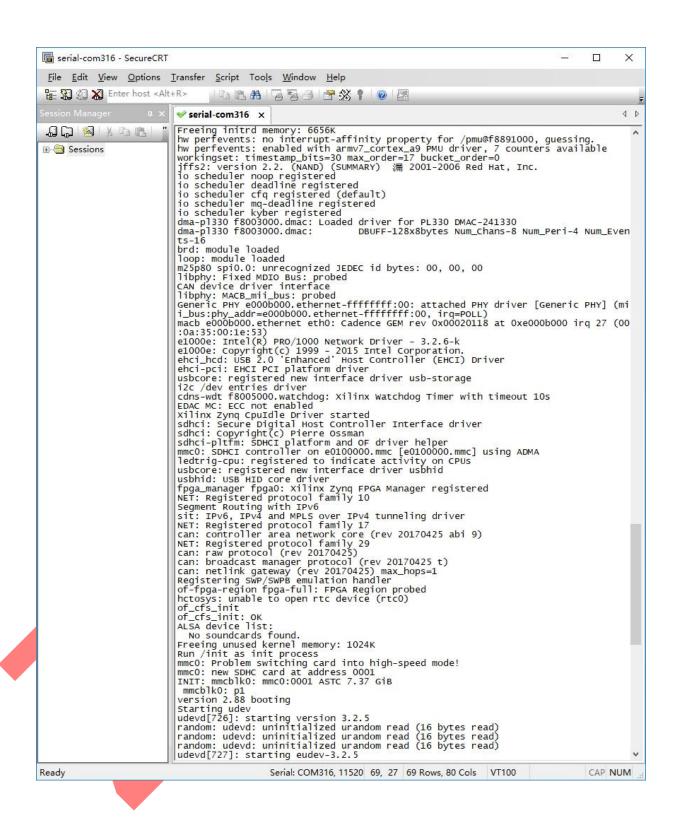














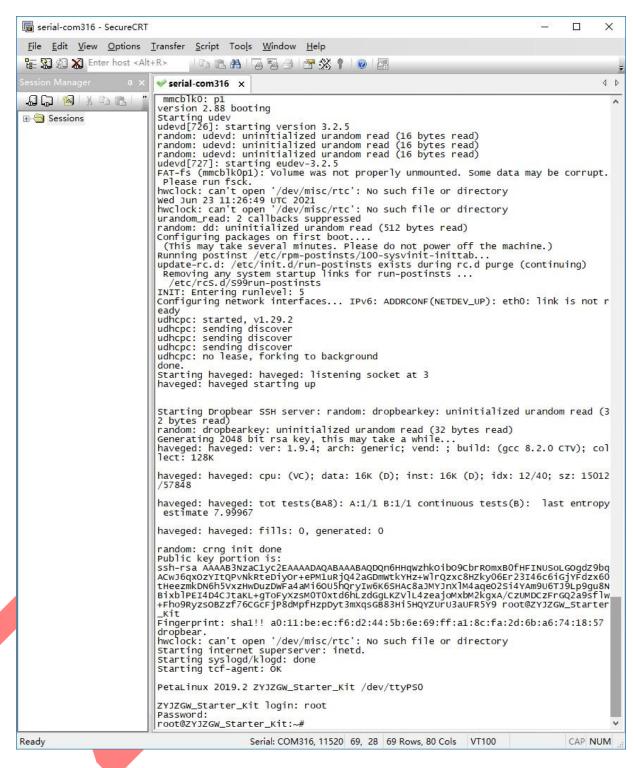


Figure 2-13. PetaLinux Boot Log



2.2 Test the Ethernet Under Linux Environment

Plug the ethernet cable into the Starter Kit and power on it. Below log will be displayed on the terminal tool when the ethernet link is ready. Users may type below ethernet test related commands to check the status of ethernet interface.

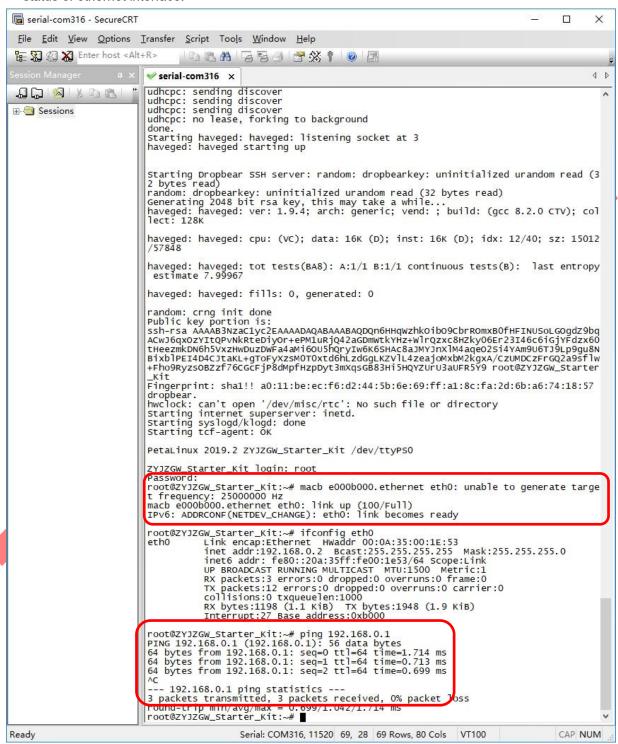


Figure 2-14. Log Info



Reference 3.

- [1] ug585-Zynq-7000-TRM.pdf
 [2] ds187-XC7Z010-XC7Z020-Data-Sheet.pdf
 [3] ug865-Zynq-7000-Pkg-Pinout.pdf
 [4] MT41K256M16TW-107:P.pdf
 [5] tps563201.pdf





4. Revision

Doc. Rev.	Date	Comments
0.1	03/06/2021	Initial Version.
1.0	23/06/2021	V1.0 Formal Release.



