

PHYS 4421: Introduction to Continuum Physics
Instructor: Predrag Cvitanović
Project Name?

Evangelos Siminos

February 5, 2004

1 Introduction

Our goal is to study the Kuramoto-Sivashinsky equation:

$$u_t = (u^2)_x - u_{xx} - \nu u_{xxxx} \quad (1)$$

where $u(x, t)$ is considered a function of one spatial coordinate x and the time t . The subscripts denote partial differentiation and ν is a damping parameter, which we will call the viscosity.

We assume periodic boundary conditions on the $x \in [0, L]$ interval:

$$u(x + L, t) = u(x, t) \quad (2)$$

which allows a Fourier series expansion:

$$u(x, t) = \sum_{-\infty}^{+\infty} b_k(t) e^{ik2\pi x/L} \quad (3)$$

Since $u(x, t)$ is real, it holds:

$$b_k = b_{-k}^* \quad (4)$$

Substituting eq. (3) into eq. (1) we get:

$$\dot{b}_k = (2\pi/L)^2 (k^2 - (2\pi/L)^2 \nu k^4) b_k + (2\pi/L) i k \sum_{m=-\infty}^{+\infty} b_m b_{k-m} \quad (5)$$

In general we will work with L as a controlling parameter and set $\nu = 1$. Yet, for the first numerical exploration of the K-S equation we will work with ν as a control parameter and set $L = 2\pi$ in order to compare our results with the previous ones given in [1].

From eq. (5) we notice that $\dot{b}_0 = 0$ and thus b_0 is an integral of the equations, or from (3), the average of the solution $\int dx u(x, t)$ is a constant, which (following [1]) we set to zero. This leads to $b_0 = 0$.

To simplify the system of equations further we choose the b_k 's purely imaginary:

$$b_k = ia_k \quad (6)$$

with a_k real. Then eq. (5) reads:

$$\dot{a}_k = (2\pi/L)^2 (k^2 - (2\pi/L)\nu k^4) a_k - (2\pi/L)k \sum_{m=-\infty}^{+\infty} a_m a_{k-m} \quad (7)$$

Inserting eq. (6) into eq. (4) we get:

$$a_{-k} = -a_k \quad (8)$$

To integrate this system of equations numerically we will truncate the system of equations to a finite length by setting $a_k = 0$ for $k > N$. Then eq. (7) with the help of eq. (8) can be cast into the form:

$$\begin{aligned} \dot{a}_k = & \left(\frac{2\pi}{L} \right)^2 (k^2 - (2\pi/L)\nu k^4) a_k \\ & - \frac{2\pi}{L} k \left(\sum_{m=1}^k a_m a_{k-m} - \sum_{m=k+1}^N a_m a_{m-k} - \sum_{m=1}^{N-k} a_m a_{k+m} \right) \end{aligned} \quad (9)$$

which only contains the a_k 's for which $1 \leq k \leq N$. Thus we only need N instead of $2N$ equations ($a_0 = 0$, since we demanded that the average of the solution vanishes). Following the arguments in [1] we choose $N=16$ and $\nu = 0.029910$, ($L = 2\pi$). For the integration we use a fourth order Runge-Kutta scheme with constant step size.

Two projections of a typical trajectory in the a_k space onto different three-dimensional subspaces are shown in Figures 1 and 2.

2 Bibliography

1. F. Christiansen, P. Cvitanović, V. Putkaradze *Hopf's last hope: spatiotemporal chaos in terms of unstable recurrent patterns*, Nonlinearity **10**, 50 (1997)
2. P. Holmes, J.L. Lumley and G. Berkooz, *Turbulence, Coherent Structures, Dynamical Systems and Symmetry*, Cambridge U. Press, Cambridge 1996.

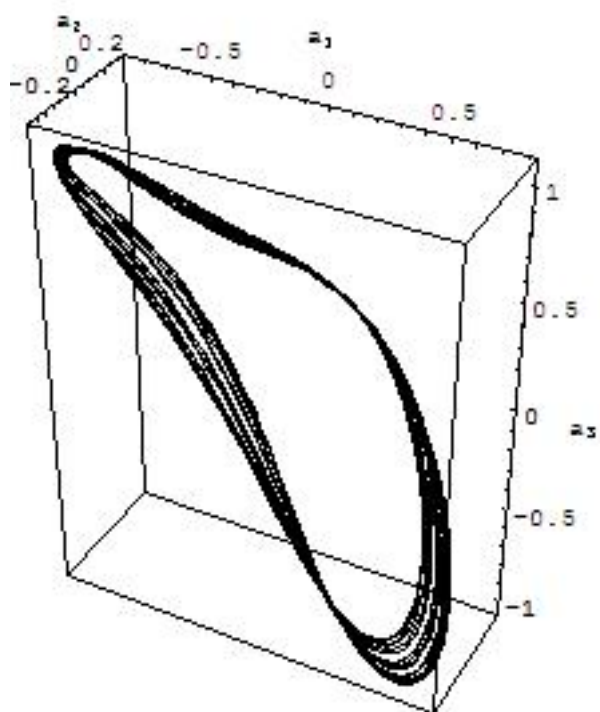


Figure 1: Projection of the trajectory onto the a_1, a_2, a_3 subspace. $N=16$ and $\nu = 0.029910$, ($L = 2\pi$).

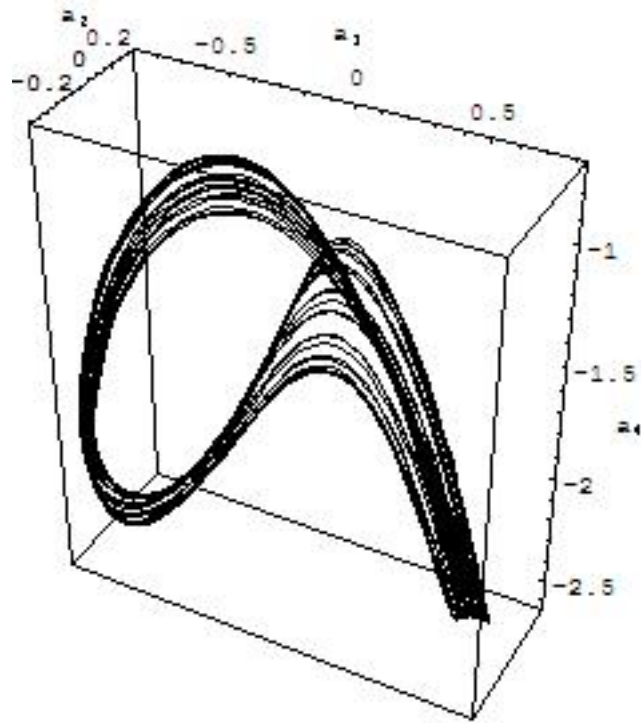


Figure 2: Projection of the trajectory onto the a_1, a_2, a_4 subspace. $N=16$ and $\nu = 0.029910$, ($L = 2\pi$).