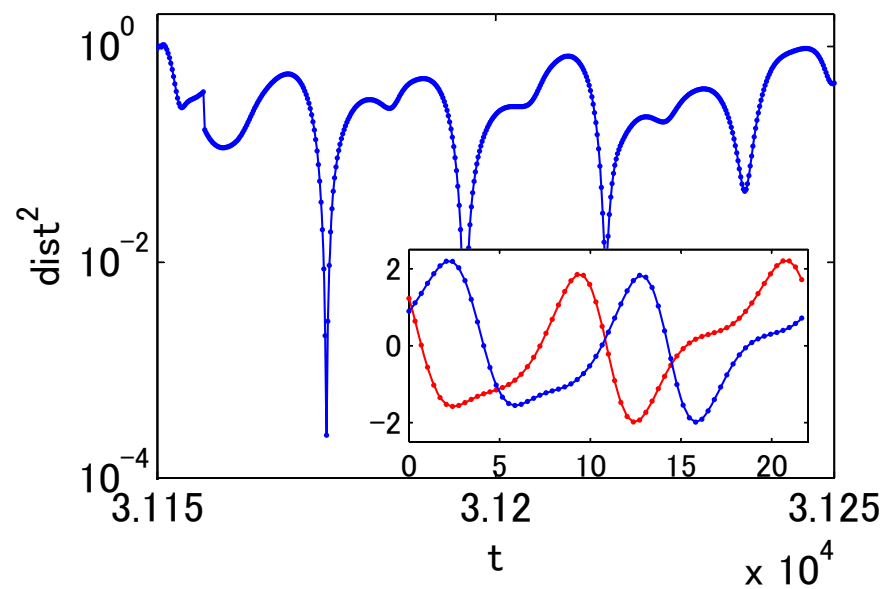
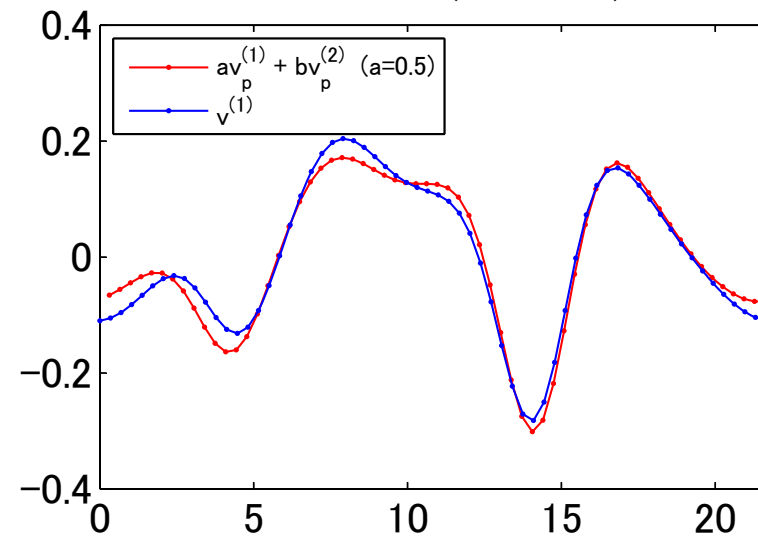


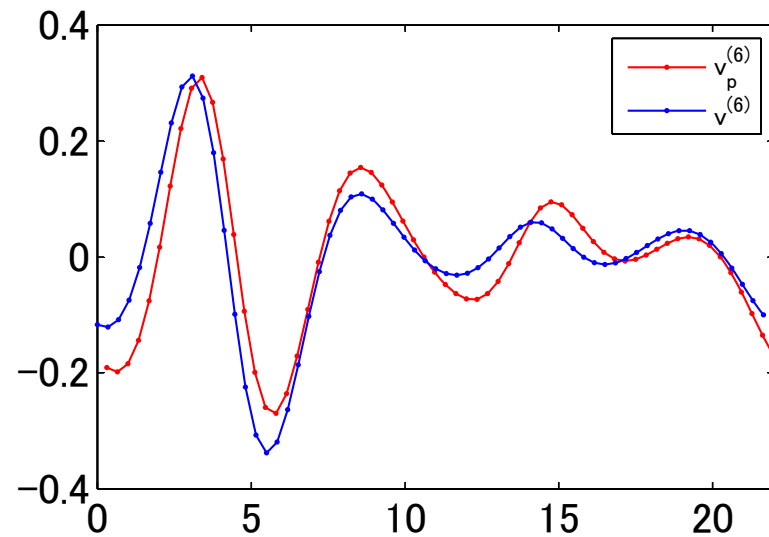
instant $t=31175$ is used.
inset: snapshot of trajectory and UPO



1st vector (x shifted)



6th vector



9th vector

