

# Ringmaster ASGD: The First Asynchronous SGD with Optimal Time Complexity

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Problem setup



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Different ways of parallelizing SGD



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## Different ways of parallelizing SGD

Synchronized approaches



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- Synchronized approaches

- Asynchronous SGD





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- Synchronized approaches

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## Problems of ASGD



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## Problems of ASGD

## Ringmaster ASGD



# The core optimization problem in Machine Learning (and beyond)

$$\min_{x \in \mathbb{R}^d} \{f(x) := \mathbb{E}_{\xi \sim \mathcal{D}} [f(x; \xi)]\}$$

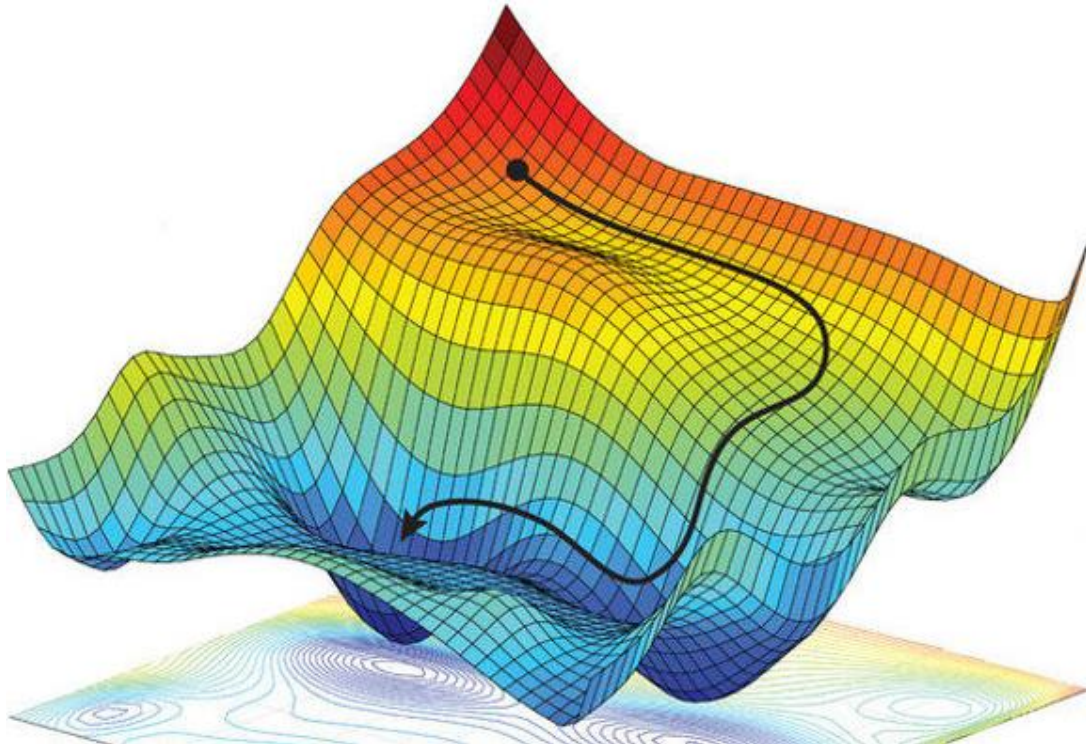
Loss of a data sample  $\xi$

The distribution of the training dataset

$$\mathcal{D} = \text{Uniform}([m])$$

$$\frac{1}{m} \sum_{i=1}^m f(x; \xi_i)$$

# A common method in ML is Stochastic Gradient Descent (SGD)



Stepsize / Learning rate

$$x^{k+1} = x^k - \gamma g(x^k)$$

Unbiased gradient estimator, e.g.,

$$\begin{aligned} &\nabla f(x^k; \xi^k) \\ &\frac{1}{B} \sum_{i=1}^B \nabla f(x^k; \xi_i^k) \end{aligned}$$

# How to parallelize SGD in heterogeneous systems?



$$\nabla f(x; \xi)$$

Compute time =  $\tau_1$

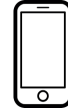
$$\tau_1$$



$$\nabla f(x; \xi)$$

Compute time =  $\tau_2$

$$\tau_2$$



$$\nabla f(x; \xi)$$

Compute time =  $\tau_3$

$$\tau_3$$

$$\mathbb{E}[g(x^k)] = \nabla f(x^k)$$



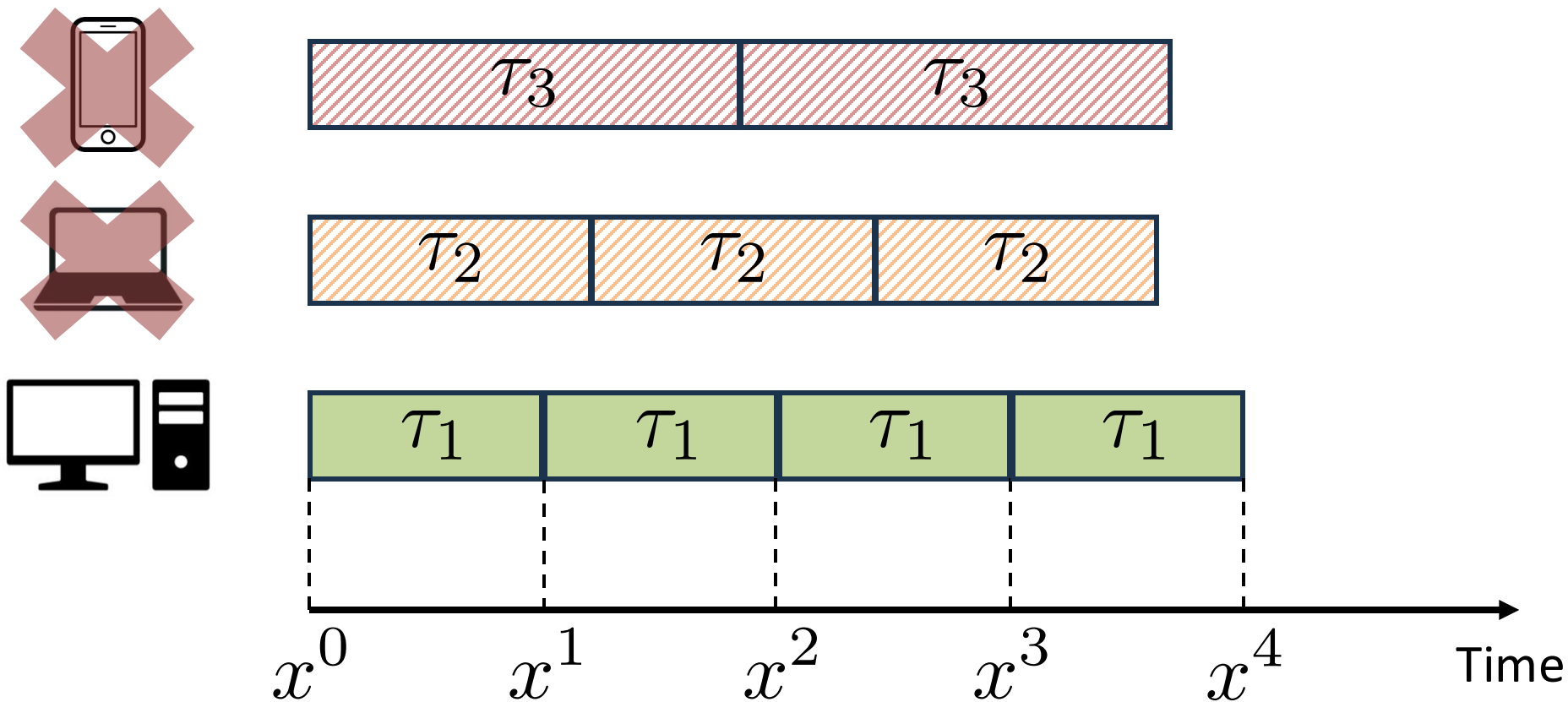
Server

$$x^{k+1} = x^k - \gamma g(x^k)$$

How to construct?

# Hero SGD:

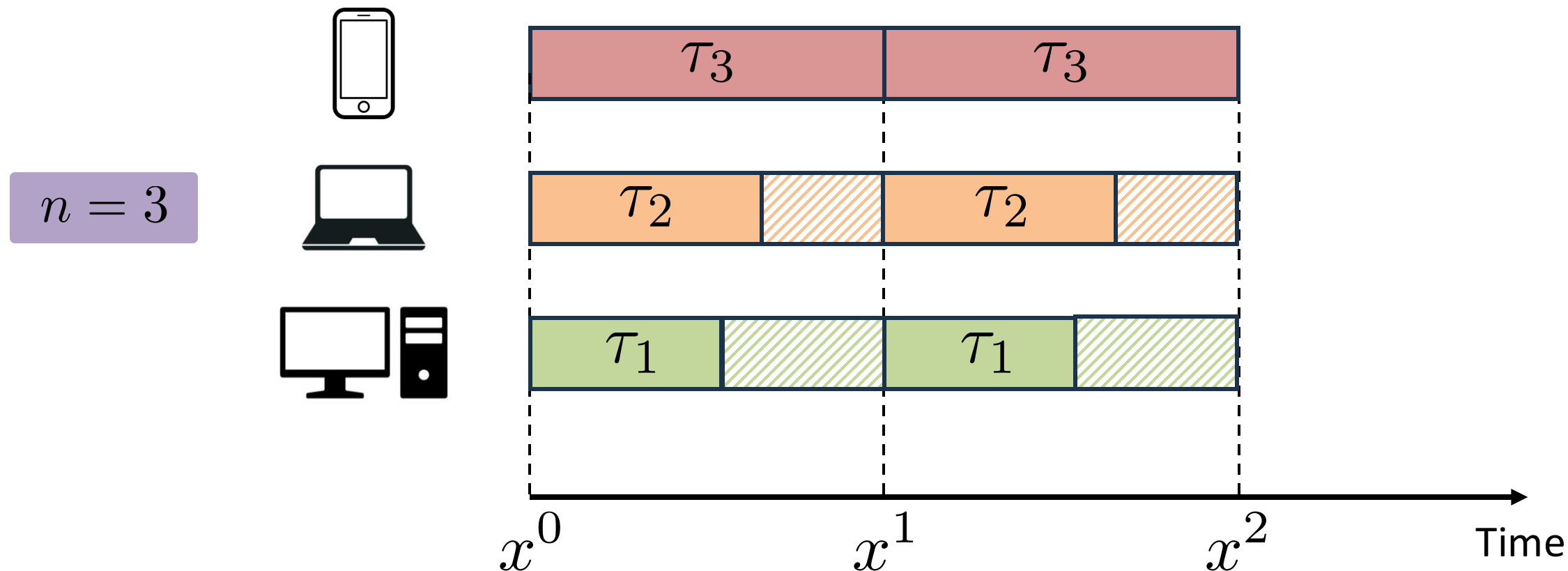
## The fastest worker does it all



$$x^{k+1} = x^k - \gamma \nabla f(x^k; \xi^k)$$

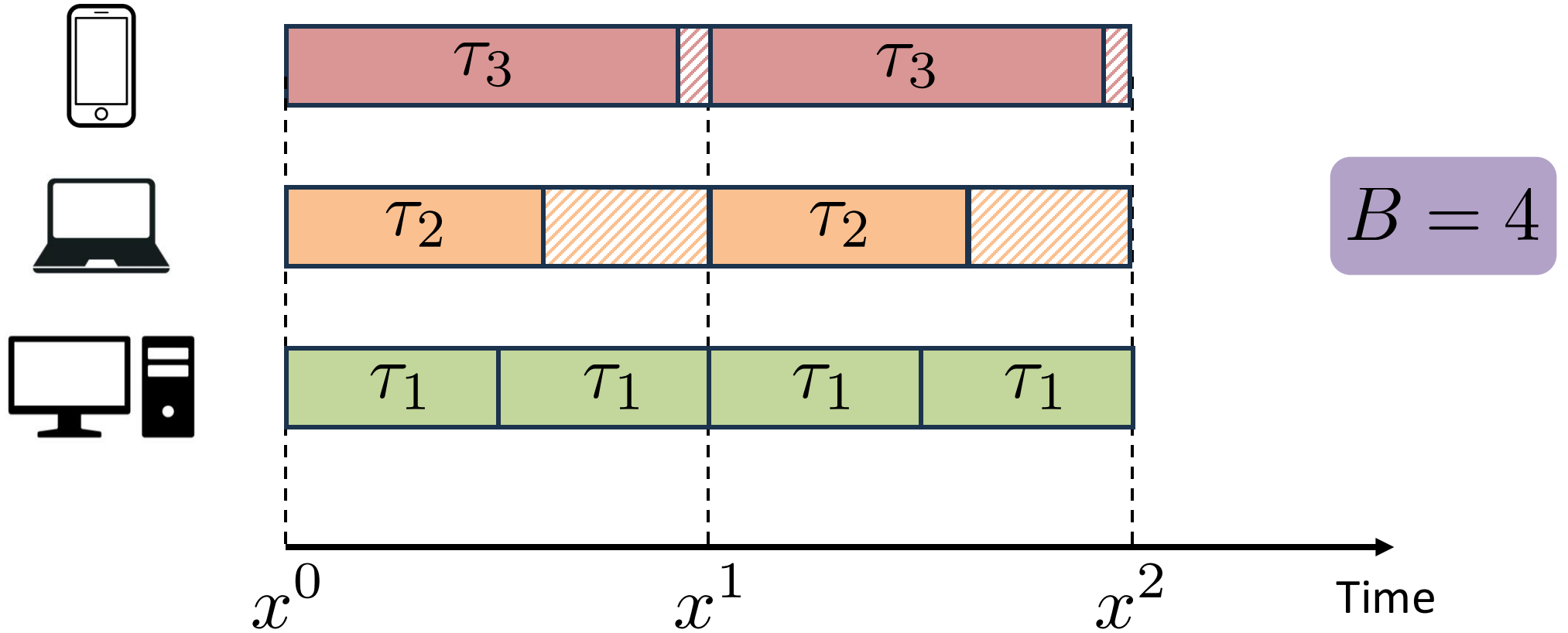
# Minibatch SGD:

Each worker does one job only



$$x^{k+1} = x^k - \gamma \frac{1}{n} \sum_{i=1}^n \nabla f(x^k; \xi_i^k)$$

# Rennala SGD: Asynchronous batch collection

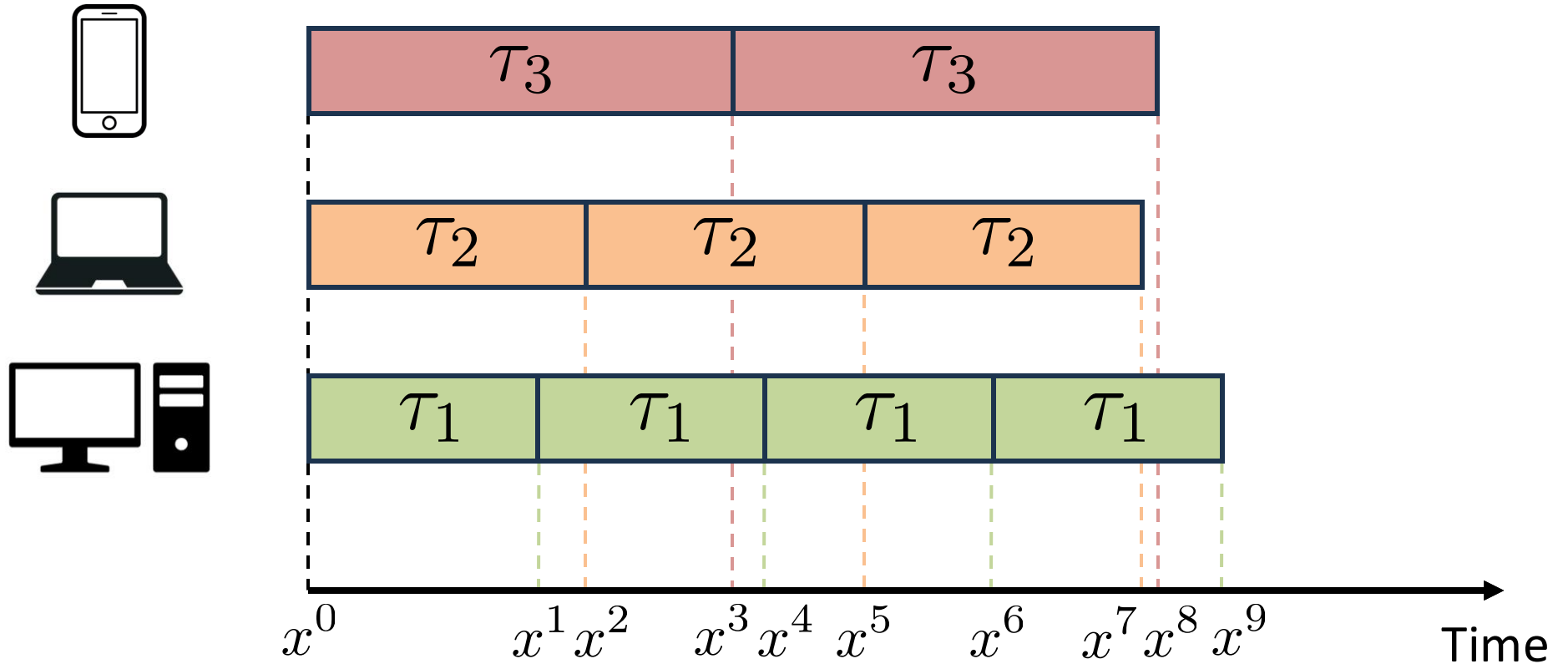


$$x^{k+1} = x^k - \gamma \frac{1}{B} \sum_{j=1}^B \nabla f(x^k; \xi_j^k)$$



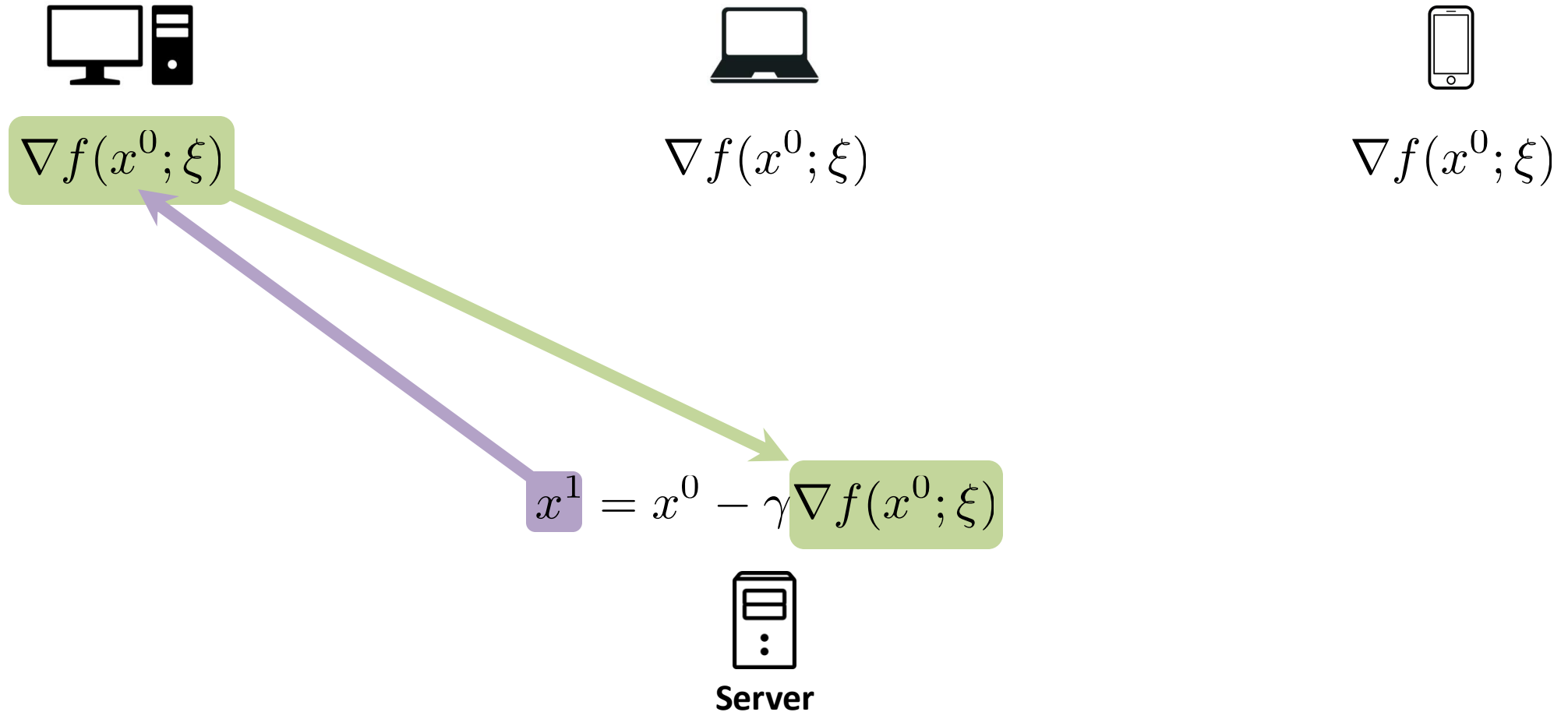
# Asynchronous SGD

## Remove the synchronization

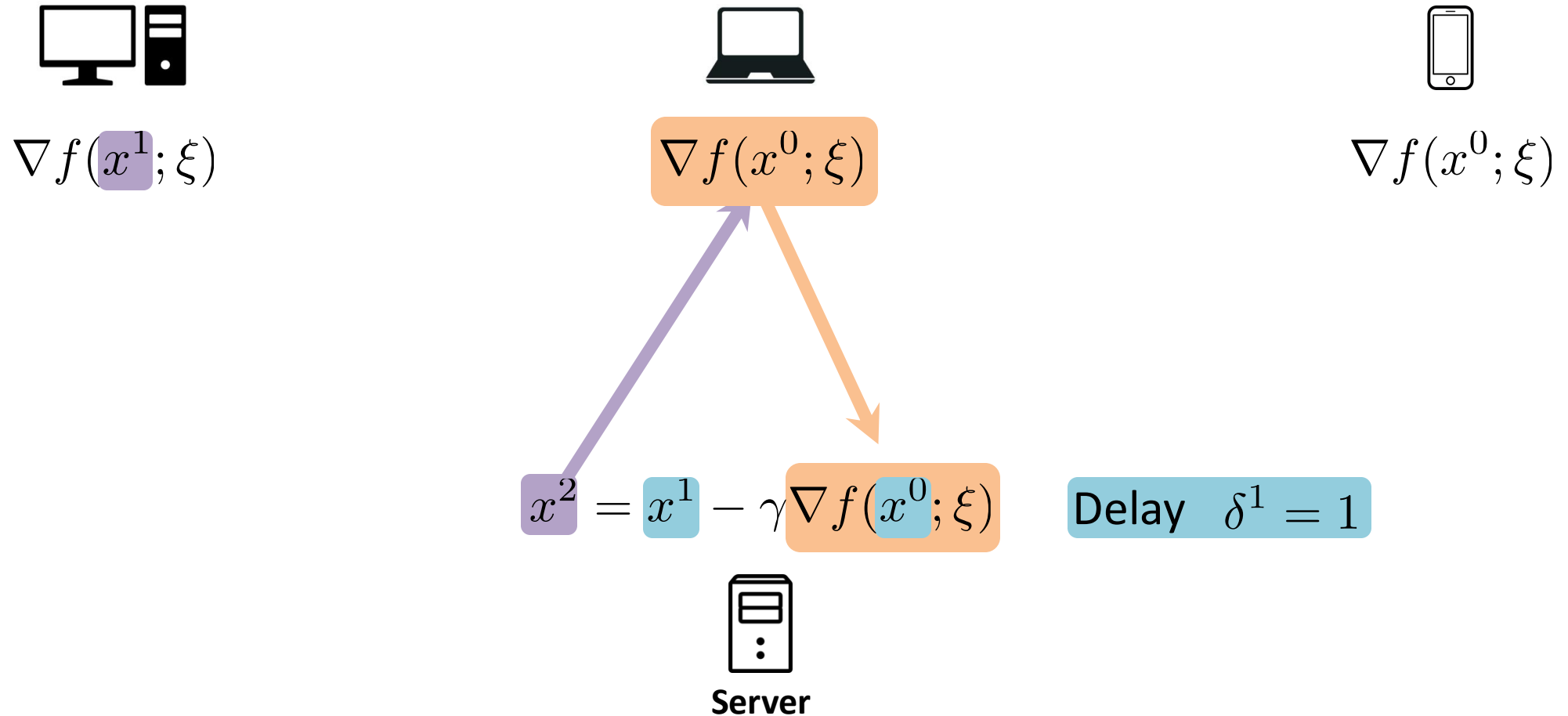


$$x^{k+1} = x^k - \gamma g(x^k)$$


# Updates of Asynchronous SGD has delayed stochastic gradients





# Updates of Asynchronous SGD has delayed stochastic gradients



# Updates of Asynchronous SGD has delayed stochastic gradients


$$\nabla f(x^1; \xi)$$


$$\nabla f(x^2; \xi)$$

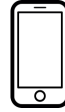

$$\nabla f(x^0; \xi)$$

$$x^3 = x^2 - \gamma \nabla f(x^0; \xi)$$

Delay  $\delta^2 = 2$



# Updates of Asynchronous SGD has delayed stochastic gradients



$$x^{k+1} = x^k - \gamma \nabla f(x^{k-\delta^k}; \xi)$$

Delay  $\delta^k$



Server

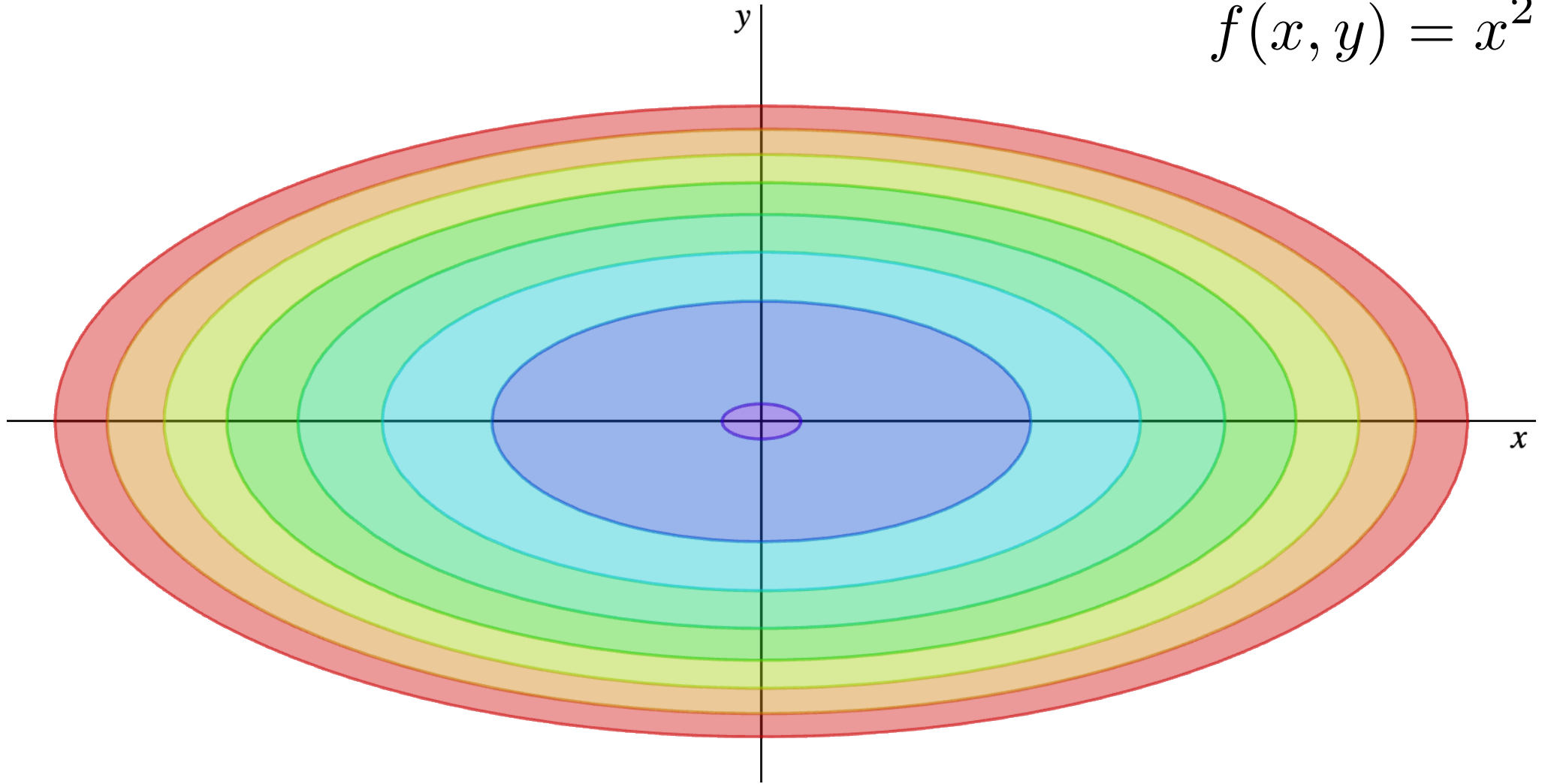


Niu, et al. (2011).

HOGWILD!: A lock-free approach to parallelizing stochastic gradient descent.

Asynchronous SGD can get wild:  
delays can degrade performance

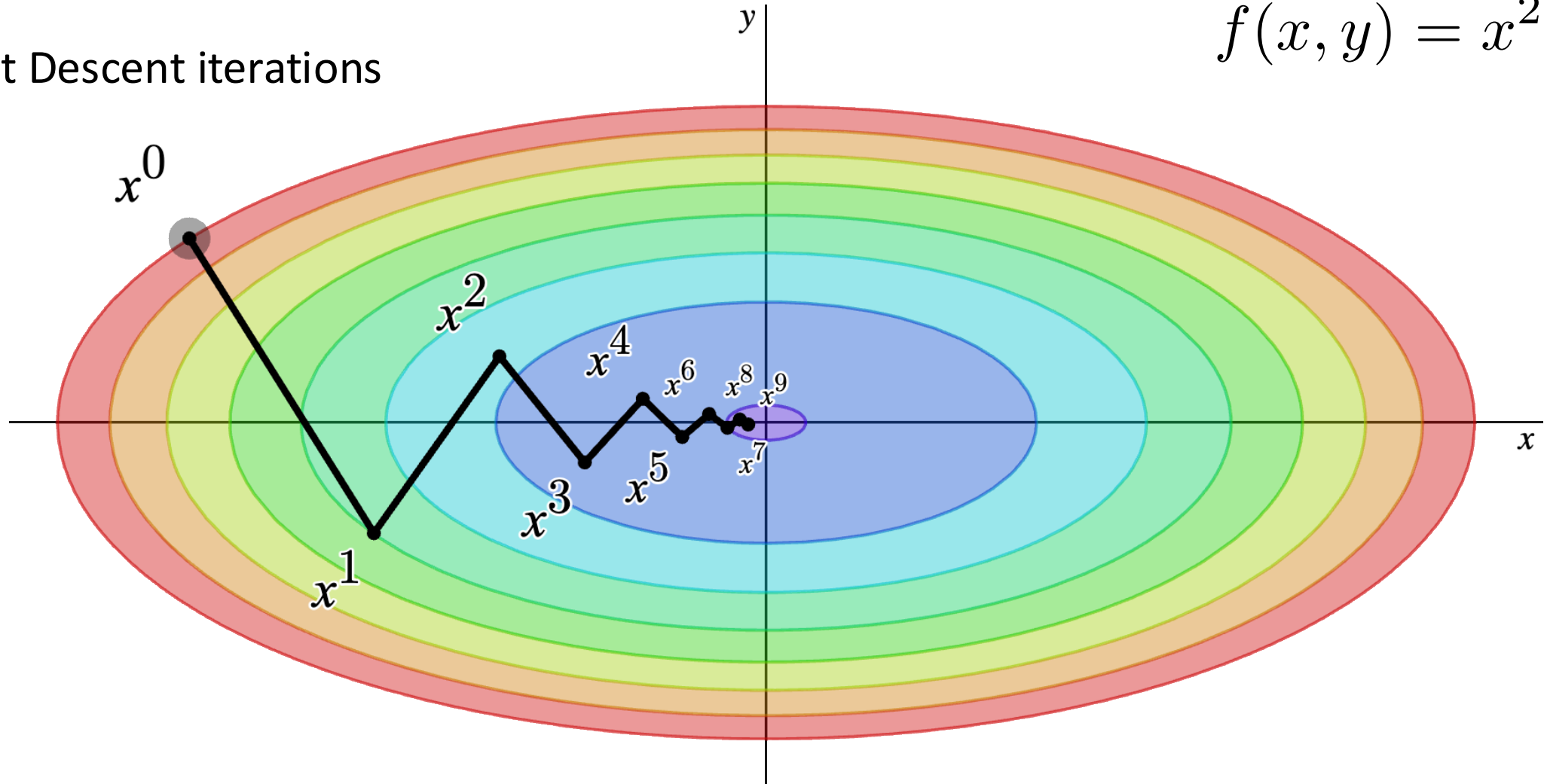
$$f(x, y) = x^2 + 5y^2$$



# Asynchronous SGD can get wild: delays can degrade performance

Gradient Descent iterations

$$f(x, y) = x^2 + 5y^2$$

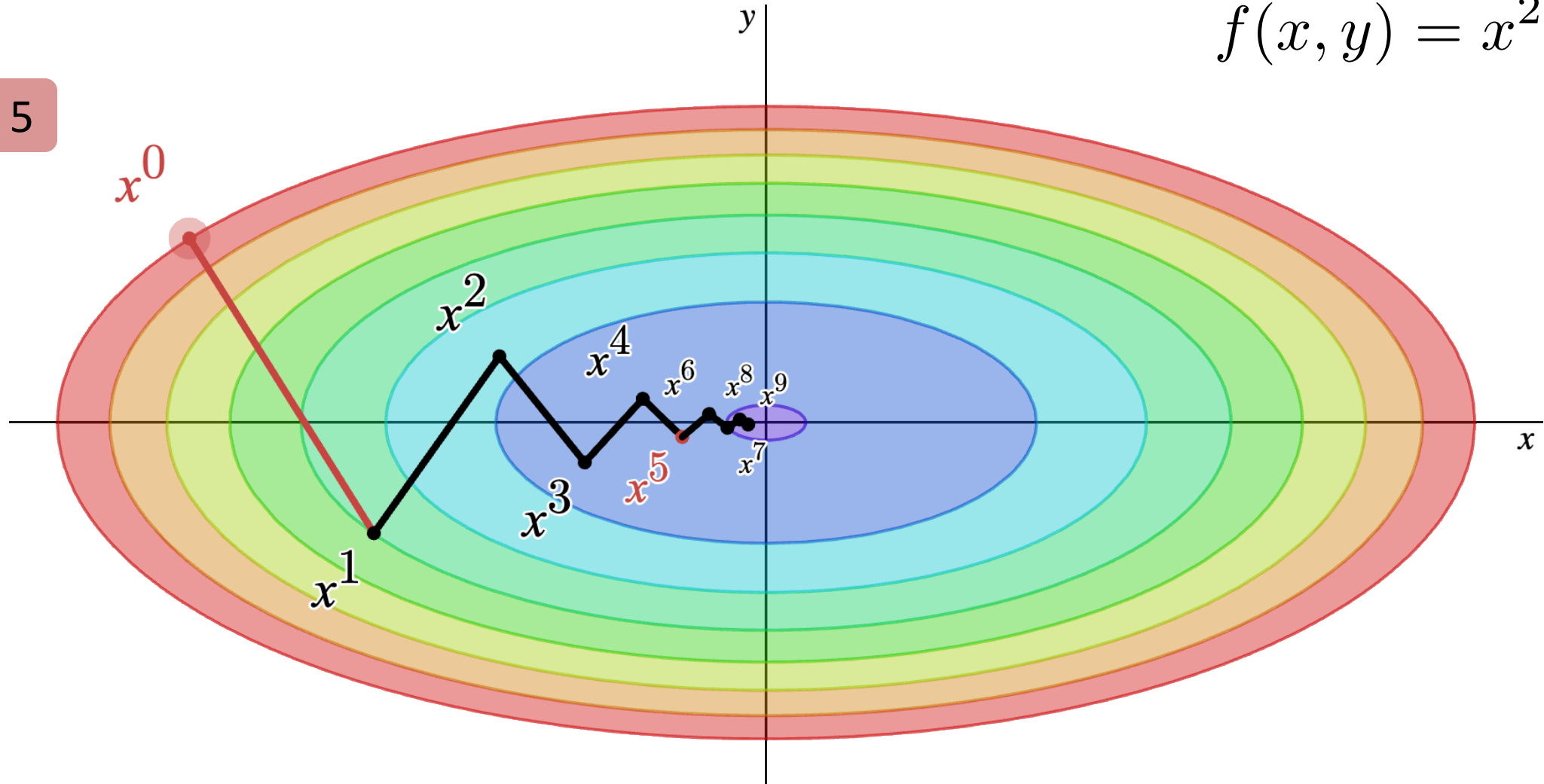




# Asynchronous SGD can get wild: delays can degrade performance

$$f(x, y) = x^2 + 5y^2$$

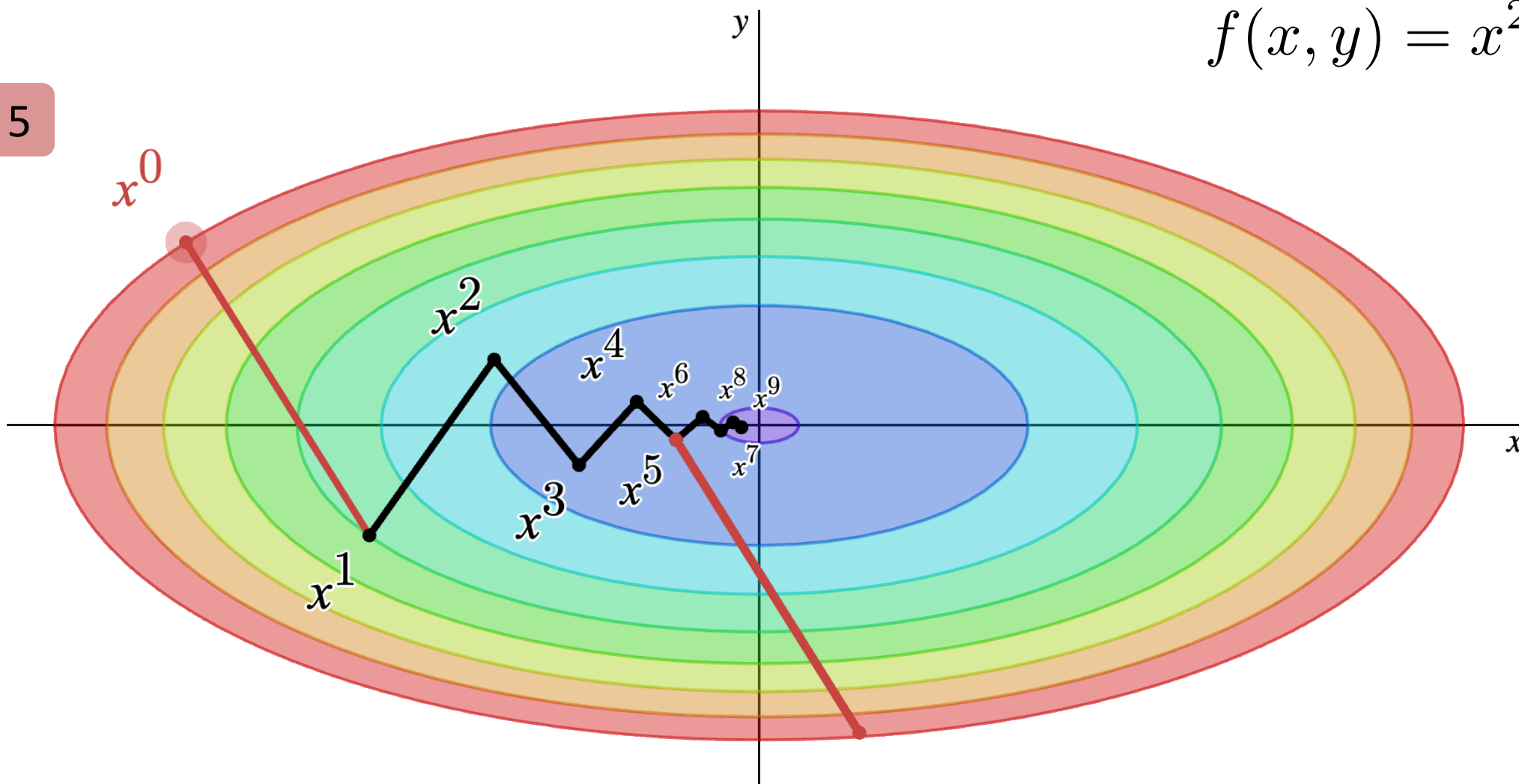
Delay = 5



# Asynchronous SGD can get wild: delays can degrade performance

$$f(x, y) = x^2 + 5y^2$$

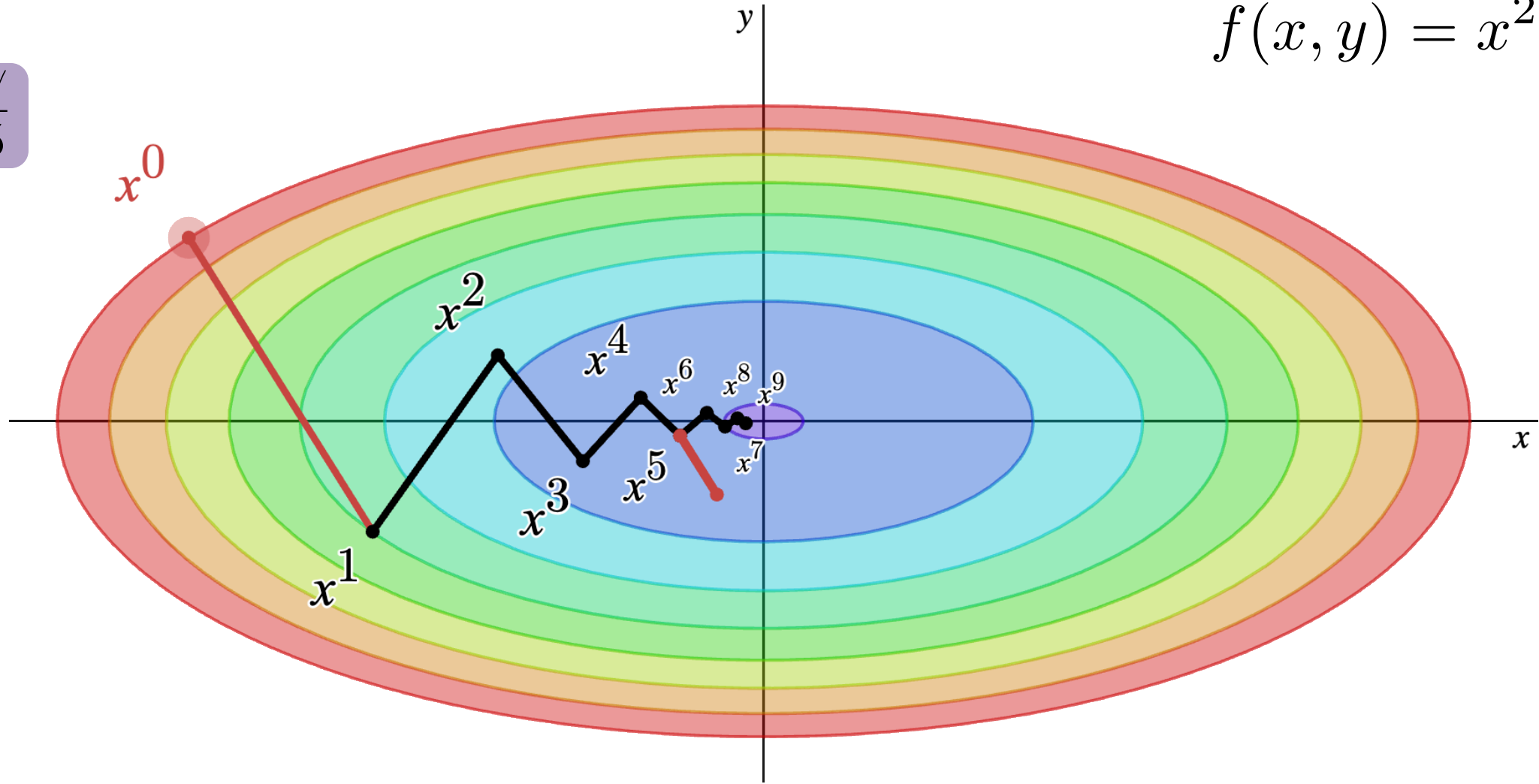
Delay = 5



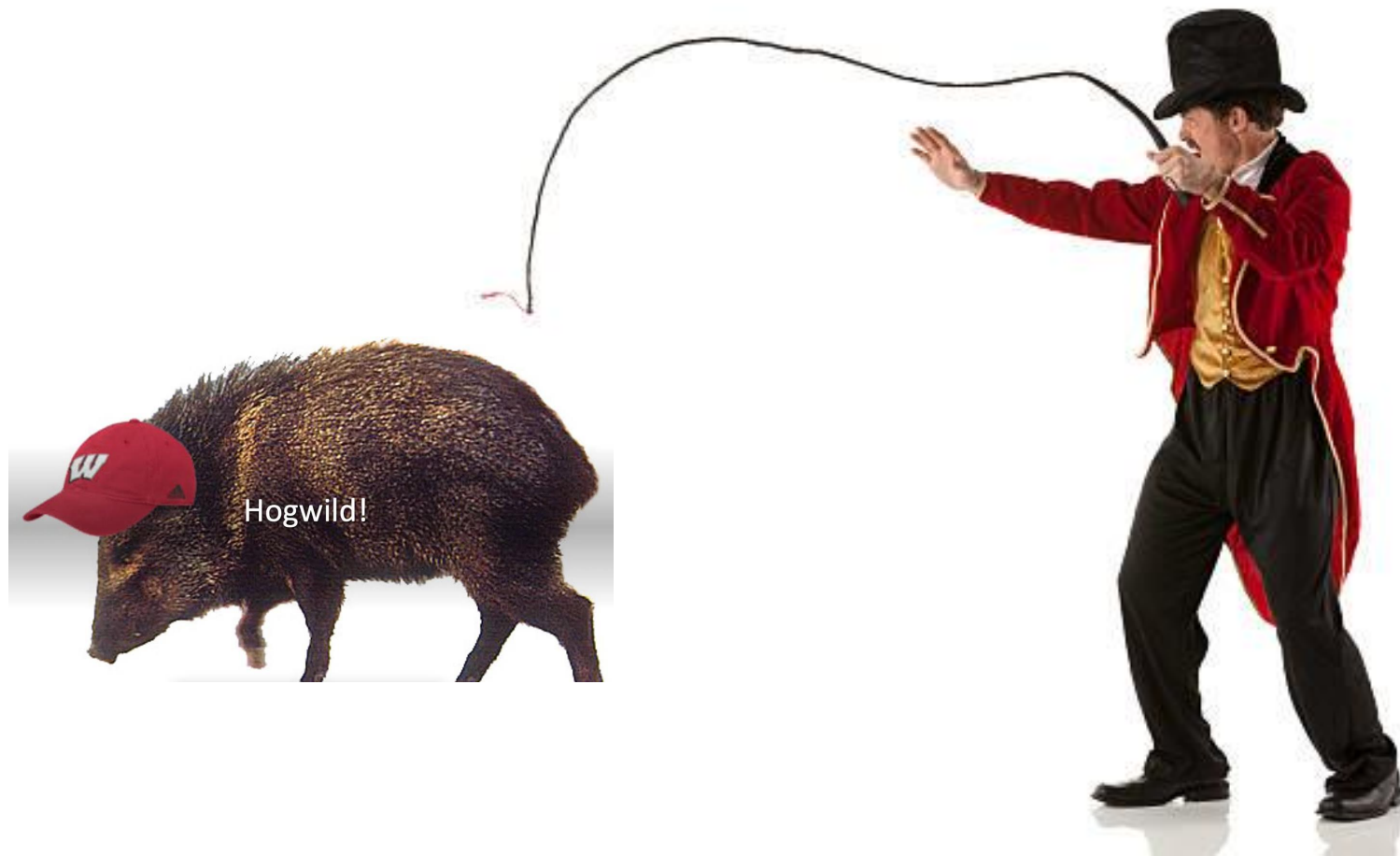
How to fix this?  
Make the stepsize smaller

$$\gamma = \frac{\gamma}{5}$$

$$f(x, y) = x^2 + 5y^2$$



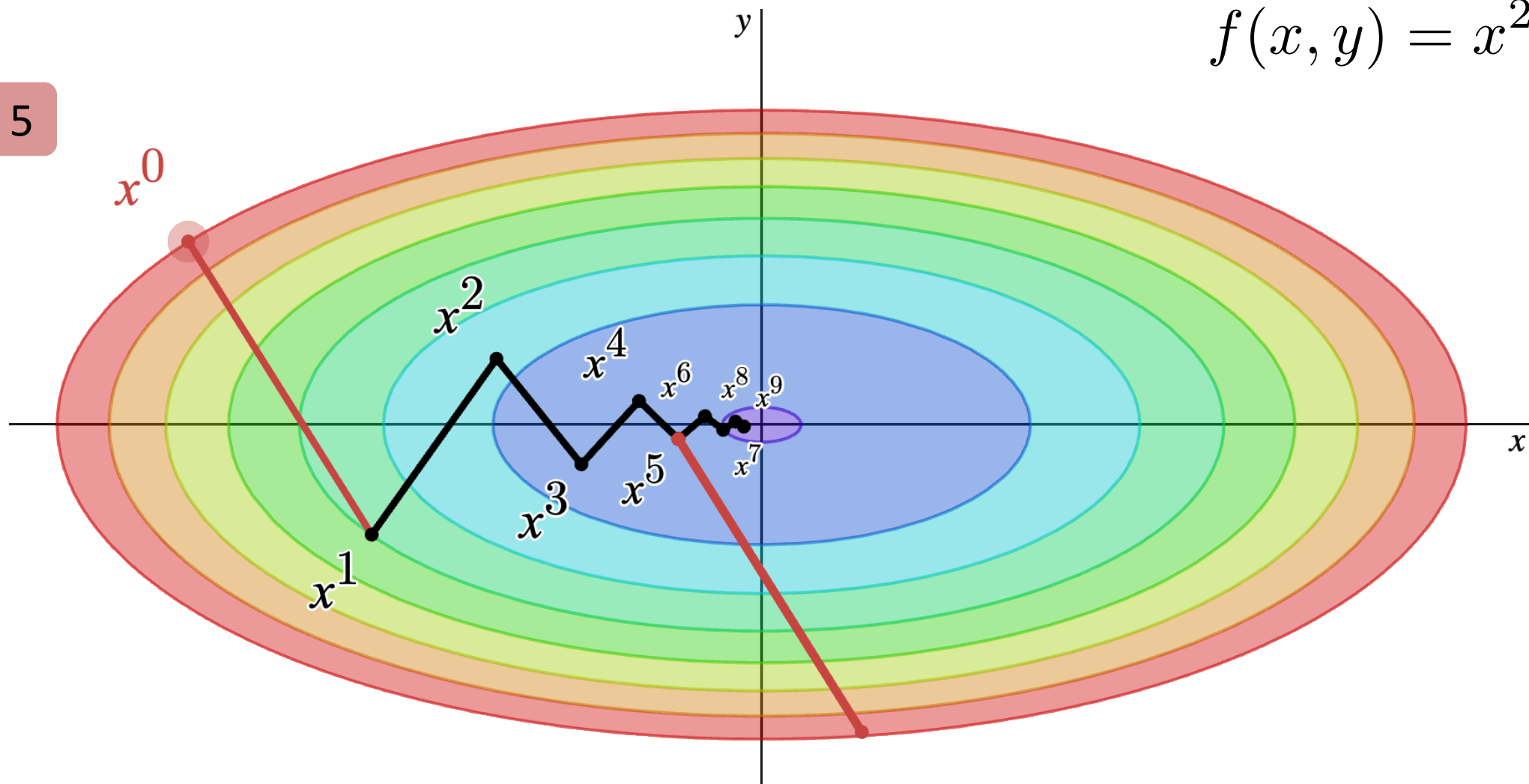
Asynchronous SGD is too wild:  
Ringmaster ASGD *tames* it



# The smaller the delay, the better the gradient

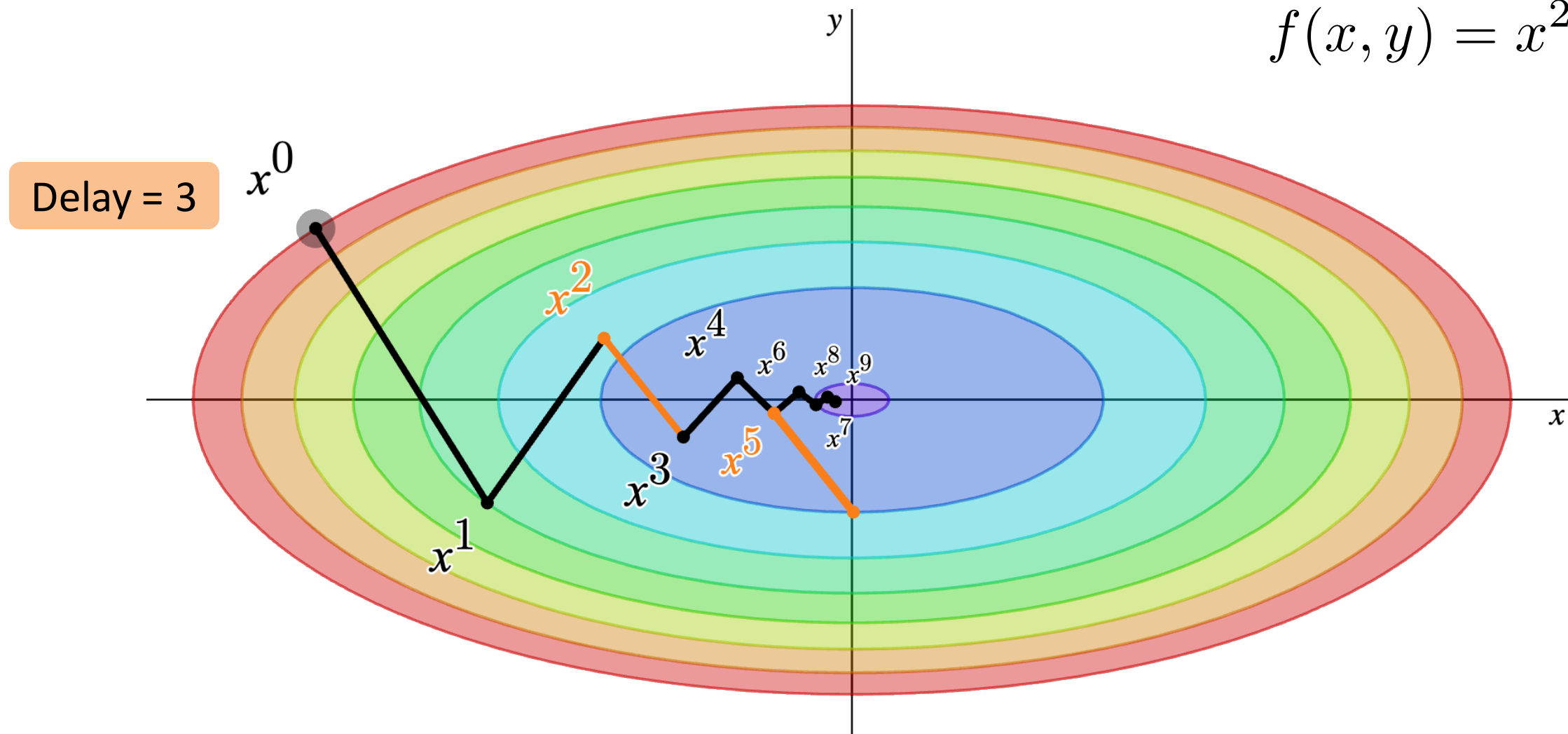
$$f(x, y) = x^2 + 5y^2$$

Delay = 5



The smaller the delay,  
the better the gradient

$$f(x, y) = x^2 + 5y^2$$



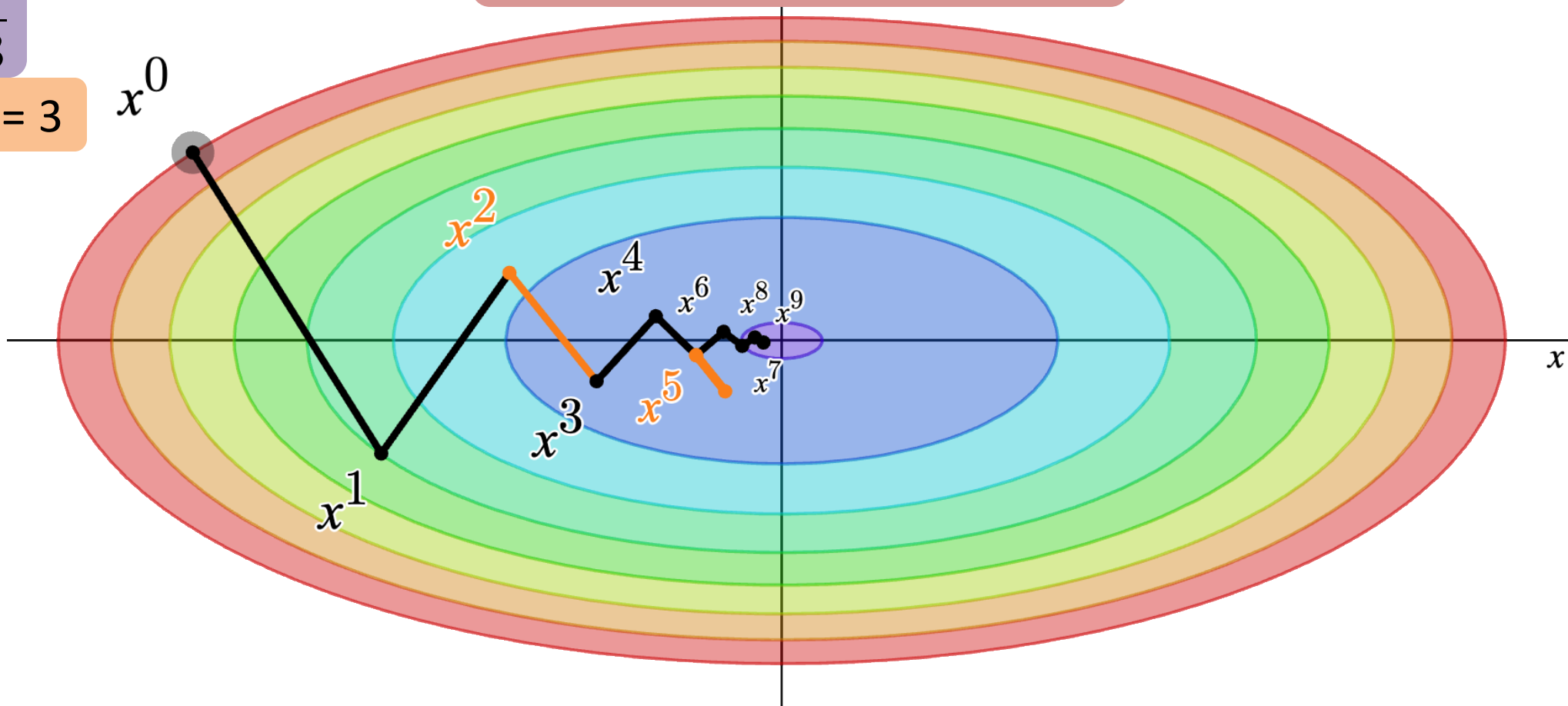
# The smaller the delay, the better the gradient

How can we reduce the delay?

$$f(x, y) = x^2 + 5y^2$$

$$\gamma = \frac{\gamma}{3}$$

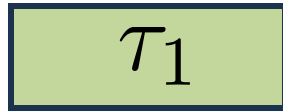
Delay = 3



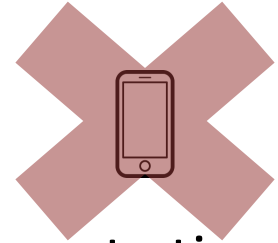
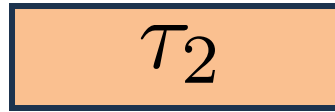
# Naive approach: Remove slow workers



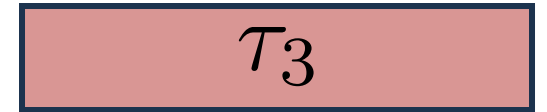
Compute time =  $\tau_1$



Compute time =  $\tau_2$



Compute time =  $\tau_3$



Server



# Naive approach: Remove slow workers

Use only the first

$$m_{\star} = \arg \min_{m \in [n]} \left\{ \left( \frac{1}{m} \sum_{i=1}^m \frac{1}{\tau_i} \right)^{-1} \left( 1 + \frac{\sigma^2}{m\varepsilon} \right) \right\}$$

fastest workers

$$\mathbb{E} [\|\nabla f(x; \xi) - \nabla f(x)\|^2] \leq \sigma^2$$

$$\mathbb{E} [\|\nabla f(x)\|^2] \leq \varepsilon$$

Problem:  $\tau_i$ -s may be unknown and dynamic

# Ringmaster ASGD:

## Have a threshold on delays



If:  $\delta^k < R$

$$x^{k+1} = x^k - \gamma \nabla f \left( x^{k-\delta^k}; \xi_i^{k-\delta^k} \right)$$

Else: Ignore the gradient and send the current point  $x^k$  to the worker



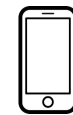
Server

$$\nabla f \left( x^{k-\delta^k}; \xi_i^{k-\delta^k} \right)$$



# Ringmaster ASGD:

## Have a threshold on delays



How to choose the delay threshold  $R$

If:  $\delta^k < R$

$$x^{k+1} = x^k - \gamma \nabla f \left( x^{k-\delta^k}; \xi_i^{k-\delta^k} \right)$$

Else: Ignore the gradient and send the current point  $x^k$  to the worker

$$\nabla f \left( x^k; \xi_i^k \right)$$



Server

# Certain threshold choices in Ringmaster ASGD recover previous methods

$$R = \max \left\{ 1, \left\lceil \frac{\sigma^2}{\varepsilon} \right\rceil \right\}$$

$R = 1$   
Hero SGD

Sweet spot

$R = \infty$   
HOGWILD!



# Theoretical results validate our intuition

$$\mathcal{O}\left(\frac{\boxed{R}}{\varepsilon} + \frac{\sigma^2}{\varepsilon^2}\right)$$

Number of iterations

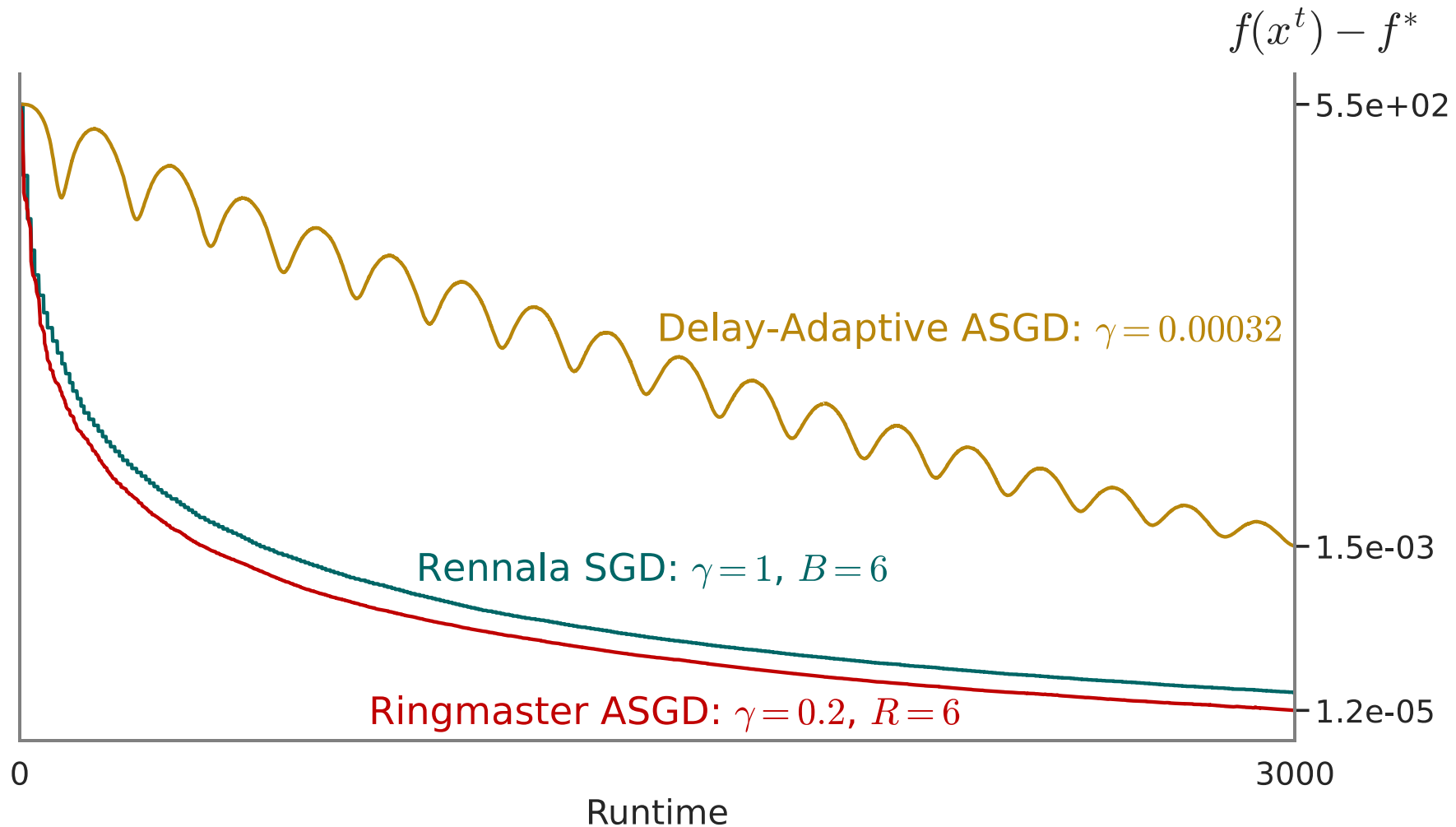
$$\mathcal{O}\left(\min_{m \in [n]} \left[ \left( \frac{1}{m} \sum_{i=1}^m \frac{1}{\tau_i} \right)^{-1} \left( \frac{1}{\varepsilon} + \frac{\sigma^2}{\boxed{m\varepsilon^2}} \right) \right] \right)$$

Time complexity

non-decreasing

decreasing

# Ringmaster ASGD outperforms existing baselines



# Recap of what we have covered

$$\min_{x \in \mathbb{R}^d} \{f(x) := \mathbb{E}_{\xi \sim \mathcal{D}} [f(x; \xi)]\}$$

Problem setup


Optimization objective

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$$\min_{x \in \mathbb{R}^d} \{f(x) := \mathbb{E}_{\xi \sim \mathcal{D}} [f(x; \xi)]\}$$




$\nabla f(x; \xi)$

Compute time = 

$\tau_1$




$\nabla f(x; \xi)$

Compute time = 

$\tau_2$



$\nabla f(x; \xi)$

Compute time = 

$\tau_3$

## Problem setup

Optimization objective

Heterogenous system




# Recap of what we have covered

$$\min_{x \in \mathbb{R}^d} \{f(x) := \mathbb{E}_{\xi \sim \mathcal{D}} [f(x; \xi)]\}$$




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$$\nabla f(x; \xi)$$

Compute time = 

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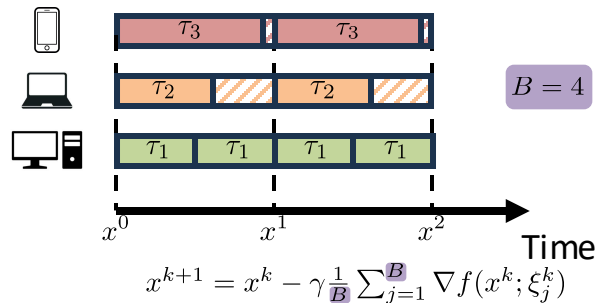
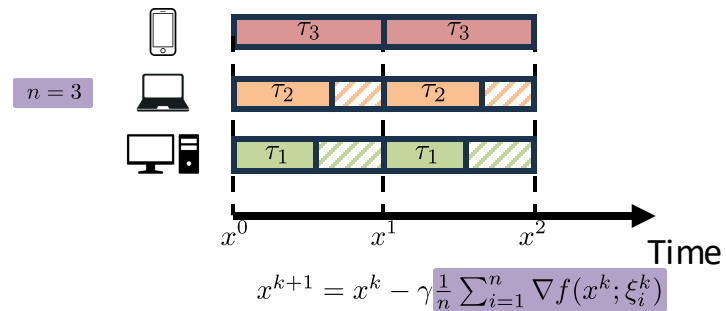
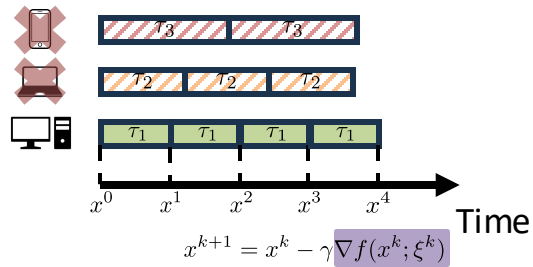
Optimization objective

Heterogenous system

Method (SGD)

$$x^{k+1} = x^k - \gamma g(x^k)$$

# Recap of what we have covered



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Optimization objective

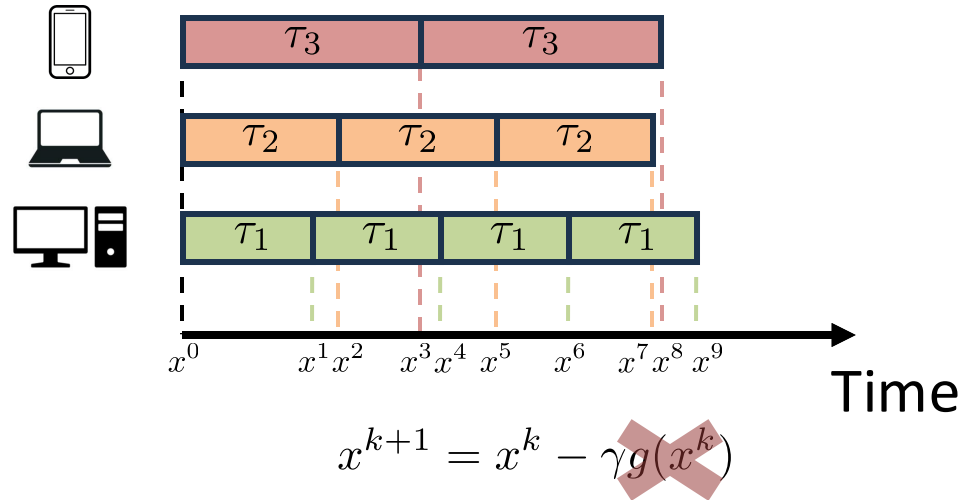
Heterogenous system

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## Different ways of parallelizing SGD

Synchronized approaches

# Recap of what we have covered



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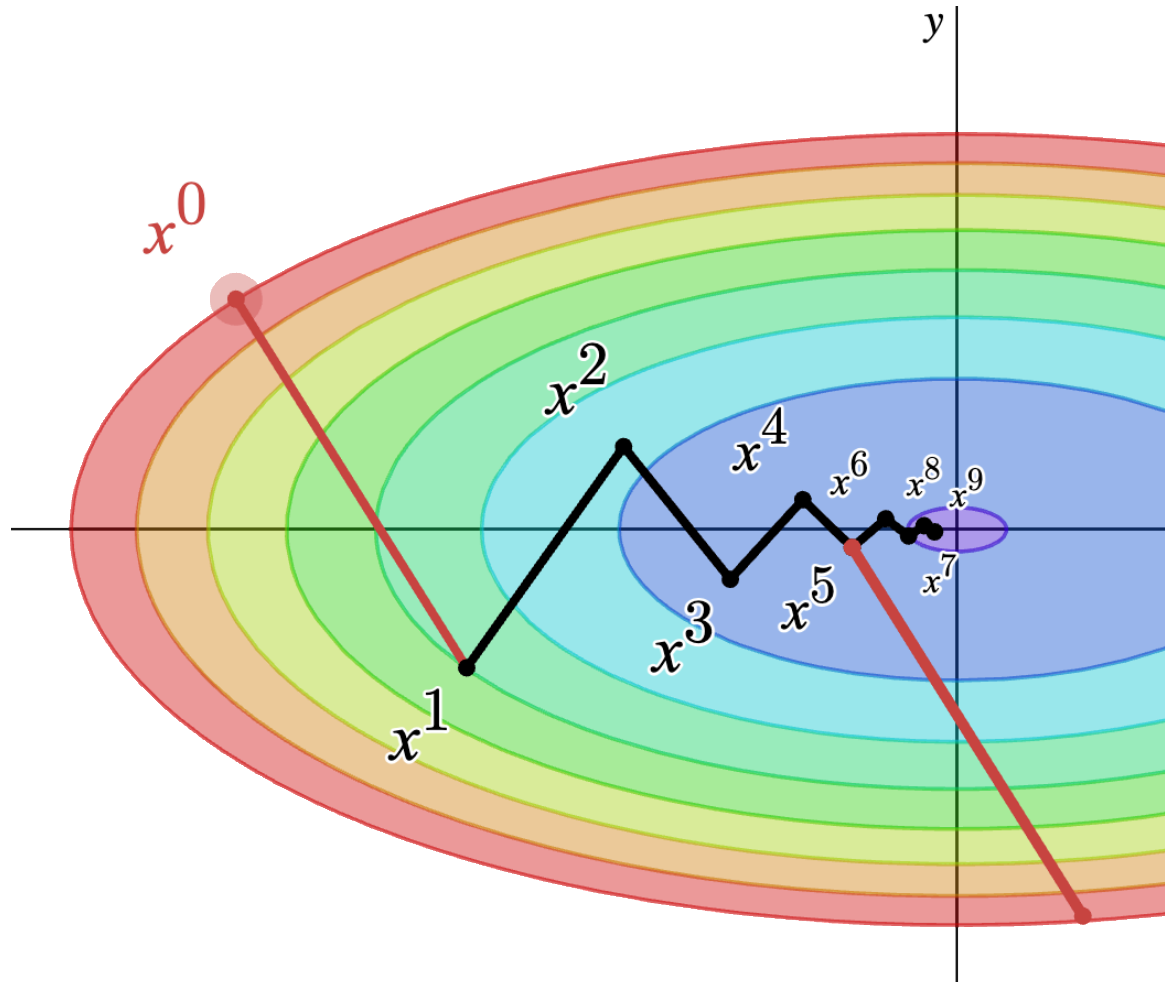
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## Problem setup

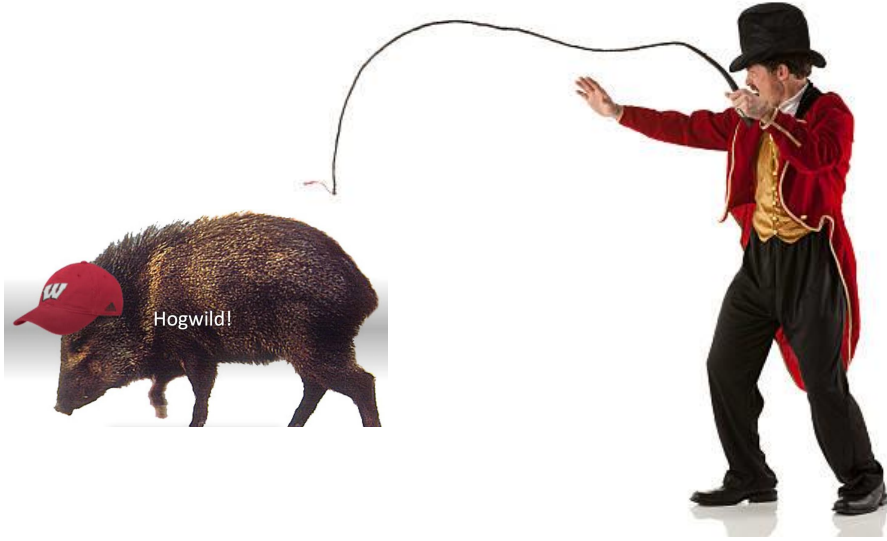
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## Problems of ASGD

## Ringmaster ASGD



Alexander Tyurin  
Skoltech



Peter Richtárik  
KAUST

# Closely related papers

Artavazd Maranjyan, Omar Shaikh Omar, Peter Richtárik (2024)

**MindFlayer: Efficient asynchronous parallel SGD in the presence of heterogeneous and random worker compute times**

Artavazd Maranjyan, El Mehdi Saad, Peter Richtarik, and Francesco Orabona (2025)

**ATA: Adaptive Task Allocation for Efficient Resource Management in Distributed Machine Learning**

