Data Culture: Intro into Machine Learning Linear classification. ERM. Figures of merits

Alexey Artemov^{1,2}

¹ Yandex LLC ² National Research University Higher School of Economics

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Lecture overview

- ▶ The classification task
- Linear models for classification
- The perceptron
- ► Empirical risk minimization
- ▶ Logistic regression
- ▶ Figures of merits
- (maybe) Linear discriminant analysis

This lecture is largely based on material from

- ► C. M. Bishop. Pattern recognition and machine learning. Chapter 4. Linear models for classification. (practical)
- S. Shalev-Shwartz, S. Ben-David. Understanding machine learning:
 From theory to algorithms. Chapter 2. A gentle start. (theoretical)

The binary classification task

- ▶ An unknown distribution D generates instances $(\mathbf{x}_1, \mathbf{x}_2, \ldots)$
- An unknown function $f: \mathbb{X} \to \mathbb{Y}$ generates labels (y_1, y_2, \ldots) for them such that $y_i = f(\mathbf{x}_i)$, and $y_i \in \{-1, +1\}$
- ▶ The classification problem: choose a plausible hypothesis (classifier) $h: \mathbb{X} \to \mathbb{Y}$ from the hypothesis space \mathbb{H}
- ► The error of the classifier h is the probability (over D) that it will fail

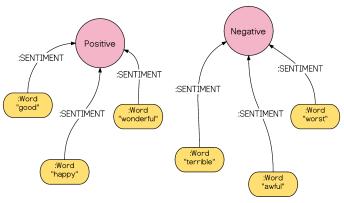
$$Q(h, D) = \Pr_{\mathbf{x} \sim D}[f(\mathbf{x}) \neq h(\mathbf{x})]$$

usually estimated by the accuracy metric

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} [f(\mathbf{x}_i) \neq h(\mathbf{x}_i)]$$

Examples of real-world binary classification tasks

Sentiment analysis "i believe that these are the best looking longest wearing pants you will ever find"

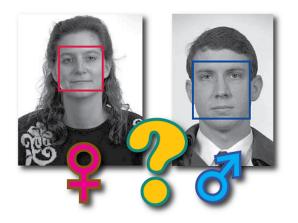


Picture credit:

http://kvangundy.com/wp/sentiment-analysis-amazon-reviews-using-neo4j/

Examples of real-world binary classification tasks

► Gender classification using face images

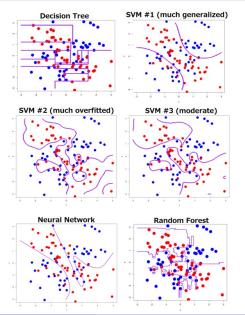


Examples of real-world binary classification tasks

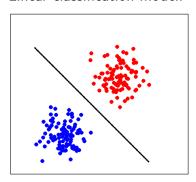
Road segmentation for self-driving cars



The classifier: decision boundaries



Linear classification model:



Linear models for classification

- ▶ Have features $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$
- ► Linear model: $h(\mathbf{x}) = \operatorname{sign}\left(\sum_{i=1}^{d} w_i x_i + w_0\right) = \operatorname{sign}\left(\mathbf{w}^{\mathsf{T}}\mathbf{x} + w_0\right)$
- ▶ Weight feature activations to get a single scalar quantity
- ▶ If quantity is above some threshold, decide that the input vector is a positive example is the input class
- ▶ The learning problem is discrete over $\mathbf{w} \in \mathbb{R}^d$:

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} [\operatorname{sign}(\mathbf{w}^{\mathsf{T}} \mathbf{x}_i) \neq h(\mathbf{x}_i)] \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

The history of perceptrons

- Popularized by Frank Rosenblatt in 1960's
 - ► Have a very powerful learning algorithm
 - ► Lots of grand claims were made for what they could learn to do
- ► In 1969, Minsky and Papert published a book called "Perceptrons" that analyzed what perceptrons could do and showed their limitations
 - Many people thought that these limitations applied to all neural network models
- ▶ The Perceptron algorithm is still used today

The Perceptron algorithm: inference

Compute activation:

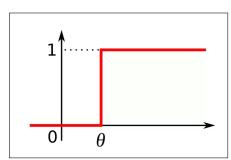
$$z = \sum_{i=1}^{d} w_i x_i + w_0$$

Compute answer:

$$y = \begin{cases} 1, & \text{if } z \geqslant 0, \\ 0, & \text{otherwise.} \end{cases}$$

or (as before)

$$y = \mathrm{sign}(z) = \begin{cases} +1, & \text{if } z \geqslant 0, \\ -1, & \text{otherwise}. \end{cases}$$



The Perceptron algorithm: learning

- Add an extra component with value 1 to each input vector
- ► Pick training instances using any policy that will ensure every training case will get picked
 - ▶ If the output unit is correct, leave its weights alone.
 - ▶ If the output unit incorrectly outputs a zero, add the input vector to the weight vector.
 - ▶ If the output unit incorrectly outputs a one, **subtract** the input vector to the weight vector.
- ► This is guaranteed to find a set of weights w that gets the right answer for all the training cases if such set exists.
- But does such set exist?..

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The Perceptron algorithm: formalism

- Initialise weights randomly
- Iterate with updates

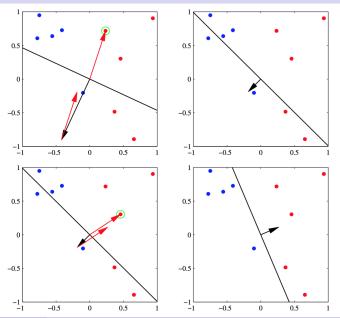
$$\mathbf{w}^{(i+1)} \leftarrow \mathbf{w}^{(i)} + y_{(i)}\mathbf{x}_{(i)}[\mathsf{sign}(\mathbf{w}^{(i)\intercal}\mathbf{x}_{(i)}) \neq y_{(i)}]$$

where $(\mathbf{x}_{(i)}, y_{(i)})$ is the example selected at iteration i

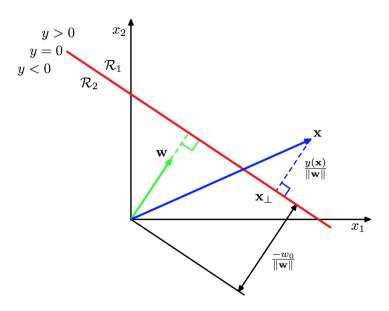
- ▶ Stop when all examples are correctly classified
- ▶ Introduce the perceptron criterion $E_{\mathsf{P}}(\mathbf{w}) = -\sum_k \mathbf{w}^{\intercal} \mathbf{x}_k y_k$
- ▶ Iterations become (pick $(\mathbf{x}_{(i)}, y_{(i)})$ via SGD)

$$\mathbf{w}^{(i+1)} \leftarrow \mathbf{w}^{(i)} - \eta \nabla_{\mathbf{w}} E_{\mathsf{P}}(\mathbf{w})|_{\mathbf{w} = \mathbf{w}^{(i)}} =$$
$$= \mathbf{w}^{(i)} + y_{(i)} \mathbf{x}_{(i)}$$

The Perceptron algorithm: geometrical motivation



Linear classifier: geometrical interpretation



Empirical Risk Minimization framework

- lacktriangle Given a labeled sample $X^\ell = ig\{(\mathbf{x}_i,y_i)ig\}_{i=1}^\ell$ and some candidate h
 - Suppose $\mathbf{x}_i \in \mathbb{R}^n \equiv \mathbb{X}, \quad y_i \in \{-1, +1\} \equiv \mathbb{Y}$
- ightharpoonup Define the empirical error (aka the empirical risk) of h as

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} [f(\mathbf{x}_i) \neq h(\mathbf{x}_i)]$$

(the proportion of sample points on which h errs)

- ▶ $ERM(X^{\ell})$ find h the minimizes $Q(h, X^{\ell})$
- ► No learning is possible without applying prior knowledge
- ▶ A hypothesis class ℍ is a set of hypotheses
- lacktriangle Re-define the ERM rule by searching only inside such a class ${\mathbb H}$
- ▶ $\mathrm{ERM}_{\mathbb{H}}(X^{\ell})$ picks a classifier $h \in \mathbb{H}$ that minimizes the empirical error over members of \mathbb{H}

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Guarantees for ERM

Theorem 1 (Guaranteed success for $\mathrm{ERM}_{\mathbb{H}}$)

- ► Let ℍ be a finite class.
- Let the unknown labeling rule, f, be a member of \mathbb{H} .
- ► Then
 - for every $\varepsilon, \delta > 0$, if $m > (\log(|\mathbb{H}|) + \log(1/\delta))/\varepsilon$,
 - with probability $> 1 \delta$ (over the choice of X^{ℓ}),
 - any $ERM_{\mathbb{H}}$ hypothesis has error below ε .

Linear models for classification

- Linear model: $h(\mathbf{x}) = \operatorname{sign}\left(\sum_{i=1}^d w_i x_i + w_0\right) = \operatorname{sign}\left(\mathbf{w}^{\mathsf{T}}\mathbf{x} + w_0\right)$
- ▶ The learning problem is discrete over $\mathbf{w} \in \mathbb{R}^d$:

$$Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} [\operatorname{sign}(\mathbf{w}^{\mathsf{T}} \mathbf{x}_i) \neq f(\mathbf{x}_i)] \to \min_{\mathbf{w} \in \mathbb{R}^d}$$

(cannot optimize using gradient descent, as the gradient is zero almost everywhere!)

- ▶ The solution: optimize a differentiable *upper bound* for $Q(h, X^{\ell})!$
- ▶ $Q(h, X^{\ell})$ can be written using $Q(h, X^{\ell}) = \frac{1}{\ell} \sum_{i=1}^{\ell} L(M_i)$ where $L(M_i) = [M_i < 0] \equiv [y_i \mathbf{w}^{\mathsf{T}} \mathbf{x}_i < 0]$
- Upper-bounding L(M) yields upper bounds for $Q(h,X^\ell)$

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Linear models for classification: upper bounds

Multiple approximations to accuracy loss

$$L_1(M) = \log(1 + e^{-M})$$

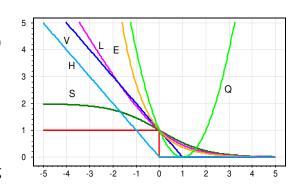
$$\begin{array}{l}
 L_{\mathsf{H}}(M) = \\
 \max(0, 1 - M)
\end{array}$$

▶
$$L_{P}(M) = \max(0, -M)$$

▶
$$L_{\mathsf{F}}(M) = e^{-M}$$

$$L_{S}(M) = 2/(1 + e^{M})$$

give rise to various learning algorithms



The logistic regression model

- ▶ Training set $X^{\ell} = \{(\mathbf{x}_i, y_i)\}_{i=1}^{\ell}$ where $y_i \in \{-1, +1\}$
- ▶ We seek an algorithm h such that $h(\mathbf{x}) = P(y = +1|\mathbf{x})$
- lacktriangle A probability that an instance (\mathbf{x}_i,y_i) is encountered in X^ℓ

$$h(\mathbf{x}_i)^{[y_i=+1]} (1 - h(\mathbf{x}_i))^{[y_i=-1]}$$

▶ Entire X^{ℓ} likelihood:

$$L(X^{\ell}) = \prod_{i=1}^{\ell} h(\mathbf{x}_i)^{[y_i = +1]} (1 - h(\mathbf{x}_i))^{[y_i = -1]}$$

is often written via log-likelihood (of which the negative is log-loss or cross-entropy)

$$\log L(X^{\ell}) = \sum_{i=1}^{\ell} [y_i = +1] \log h(\mathbf{x}_i) + [y_i = -1] \log(1 - h(\mathbf{x}_i))$$

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The logistic regression model

▶ The choice of *h*: sigmoid function

$$h(\mathbf{x}) = \sigma(\mathbf{w}^{\mathsf{T}}\mathbf{x})$$

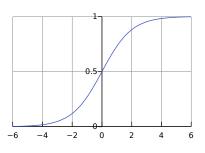
where $\sigma(x) \in [0,1]$

 Typical choice: the logistic function

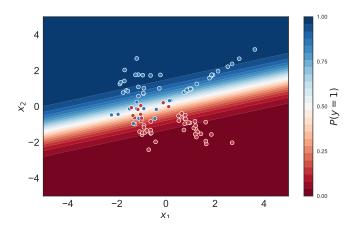
$$\sigma(\mathbf{w}^{\mathsf{T}}\mathbf{x}) = \frac{1}{1 + \exp(-\mathbf{w}^{\mathsf{T}}\mathbf{x})}$$

 Plugging the logistic function into the loss yields

$$\sum_{i=1}^{\ell} (1 + \exp(\mathbf{w}^{\mathsf{T}} \mathbf{x})) \to \min_{\mathbf{w} \in \mathbb{R}^d}$$



The logistic regression model



Classification quality evaluation: accuracy

- ▶ Given a labeled sample $X^{\ell} = \{(\mathbf{x}_i, y_i)\}_{i=1}^{\ell}$, $y_i \in \{-1, +1\}$, and some candidate h, how well does h perform on X^{ℓ} ?
- ▶ Let a(x) = [h(x) > t]
- ► Obvious choice: accuracy

$$\mathsf{accuracy}(a, X^\ell) = \frac{1}{\ell} \sum_{i=1}^\ell [a(\mathbf{x}_i) = y_i]$$

▶ Bad for imbalanced data: for $\ell = 1000$, $n_- = \sum_{i=1}^{\ell} [y = -1] = 50$, $n_+ = \sum_{i=1}^{\ell} [y = +1] = 950$, a trivial rule $h(\mathbf{x}) = +1$ would yield accuracy $(a, X^{\ell}) = 0.95$

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Classification quality: confusion matrix

	y = 1	y = -1
		False Positive (FP)
a(x) = -1	False negative (FN)	True Negative (TN)

More informative criteria:

$$\begin{aligned} & \text{precision} = \frac{\text{TP}}{\text{TP} + \text{FP}}, \\ & \text{recall} = \frac{\text{TP}}{\text{TP} + \text{FN}} \end{aligned}$$

▶ While accuracy can be expressed, too

$$\mathsf{accuracy} = \frac{\mathsf{TP} + \mathsf{TN}}{\mathsf{TP} + \mathsf{FP} + \mathsf{FN} + \mathsf{TN}}$$

Classification quality: operating curves

- ▶ Often $h(\mathbf{x})$ is more valuable than its thresholded version a(x) = [h(x) > t]
- ► Consider two-dimensional space with coordinates

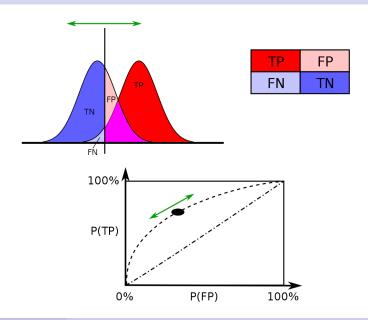
$$\mathsf{FPR} = \frac{\mathsf{FP}}{\mathsf{FP} + \mathsf{TN}}, \qquad \mathsf{TPR} = \frac{\mathsf{TP}}{\mathsf{TP} + \mathsf{FN}},$$

corresponding to various choices of the threshold t

- ► The plot TPR(FPR) is called the receiver operating characteristic (or ROC) curve
- ► Area under curve (ROC-AUC) reflects classification quality

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Receiver operating characteristic curve



Linear discriminant analysis [R. Fisher, 1936]

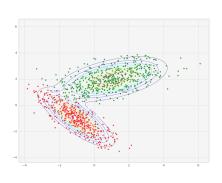
- ▶ Training set $X^{\ell} = \left\{ (\mathbf{x}_i, y_i) \right\}_{i=1}^{\ell} \text{ where } y_i \in \left\{ -1, +1 \right\}$
- ► The model:

$$P(\mathbf{x}_i|y_i = -1) = \mathcal{N}(\boldsymbol{\mu}_-, \boldsymbol{\Sigma}_-),$$

$$P(\mathbf{x}_i|y_i = +1) = \mathcal{N}(\boldsymbol{\mu}_+, \boldsymbol{\Sigma}_+)$$

 Minimize error probability via Neyman-Pearson lemma

$$\frac{P(\mathbf{x}|y_i = +1)}{P(\mathbf{x}|y_i = -1)} > t$$



Linear discriminant analysis [R. Fisher, 1936]

Log-likelihood ratio

$$\log P(\mathbf{x}|y_i = +1) - \log P(\mathbf{x}|y_i = -1) > T$$

Recall that

$$P(\mathbf{x}|y_i = \pm 1) = \frac{1}{\sqrt{2\pi|\mathbf{\Sigma}_{\pm}|}} \exp\{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_{\pm})^{\mathsf{T}} \boldsymbol{\Sigma}_{\pm}^{-1}(\mathbf{x} - \boldsymbol{\mu}_{\pm})\}$$

lacktriangle When $\Sigma_+ = \Sigma_- = \Sigma$, the optimal solution is

$$\mathbf{x}^{\mathsf{T}} \mathbf{\Sigma}^{-1} (\boldsymbol{\mu}_{+} - \boldsymbol{\mu}_{-}) > \frac{1}{2} (T - (\boldsymbol{\mu}_{+} - \boldsymbol{\mu}_{-})^{\mathsf{T}} \mathbf{\Sigma}^{-1} (\boldsymbol{\mu}_{+} - \boldsymbol{\mu}_{-}))$$

which has the form $\mathbf{w}^{\mathsf{T}}\mathbf{x} > c$

Homoscedastic case: linear discriminant hyperplane

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Linear discriminant analysis

