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# Title:

# Software Description

The project overall involves creating a software program that enables the writing robot to "draw out" text, based on a given file and text input. This program will read and interpret font data from SingleStrokeFont.txt, scale the text defined by the user input, and generate movement commands in G-code format to then be sent to the Arduino that controls the robotic arm’s movements.

All code must be developed using git for version control. This should include up to date commits as the project progresses for both documentations and codes. Also, an initial commit for the skeleton of the skeleton code.

As specified, the software must read the font data from the ‘SingleStrokeFont.txt’ file. After it is read, each character within the font file should be stored in a dynamic memory allocation, to free up the memory space once the robot has finished writing. This also ensures that the software has sufficient memory space and for the program to run at a faster time.

The program should ask the user to input the height of the text ranging from 4mm to 10mm. Create a function that adjusts the X and Y coordinates from the font file by a scale factor of to properly draw out the specified height in real life.

The code should read another text file that is obtained from the user keyboard’s input to draw out the text written within the file. The program should be able to process a file containing text of any length. This can be done by also storing it in a dynamic memory allocation to ensure there’s sufficient memory to run the software and automatically provides the right size array.

For each character within the text file, create a function that translates the font data into G-code commands. This function should include that each new letter that is instructed to be drawn, it must be offset in the X direction so that the letters won’t overlap each other. This is done by the starting position of the next character corresponds to the last position of the previous letter written. Another section to include within this function is to ensure that each text line are drawn with the space of 5mm apart from each other. This is prompted by the LF (ASCII 10) and CR (ASCII 13) codes respectively in the text file.

Finally a function that sends the G-code commands to the Arduino. These commands are then sent to the Arduino to communicate whether to raise or lower the pen and to control the arm’s movements to specific X-Y coordinates. The relevant commands of G-code that is related to the project is shown in Table 1. Once the pen finishes drawing, it should return to the point at origin (0,0) and rest once the pen is in a raised position.

|  |  |
| --- | --- |
| Command | Description |
| F1000 | feed rate, 1000 mm min−1 |
| G0 X Y | Move to the position X,Y |
| G1 X Y | Draw a straight line from the last position to X,Y |
| M3 | Turn on Spindle |
| S0 | Pen up |
| S1000 | Pen down |

**Table 1**: The relevant G-codes needed for the project.

# Project Files

(Maximum 1 page)

# Key Data Items

|  |  |  |
| --- | --- | --- |
| Name | Data type | Rationale |
|  |  |  |
|  |  |  |

Extend table as required

# Functions

|  |
| --- |
| **void LoadFontData(char FontFile)**  Parameters: FontFile – Accessing the font data file to then store in the ‘CharacterData’ structure  Return Value: break if unsuccessful, 1 if it is successful |
| **void GenerateGcode(char \*text, float height, char \*buffer)**  Parameters: char \* text – Pointer to a string of text to convert into G-code.  Float height – Float value indicating the height of the font in mm  char \*buffer – Character array for storing generated G-code commands.  Return Value – 1 if it is successful, 0 if failed |

# Testing Information

|  |  |  |  |
| --- | --- | --- | --- |
| Function | Test Case | Test Data | Expected Output |
|  |  |  |  |
|  |  |  |  |

*Extend table as required. Note that ‘Function’ includes main()*

# Flowchart(s)

May be included as separate pdf